Deterministic Particle Methods for Diffusions

Deterministic Particle Methods for Aggregation-Diffusions

Interaction-Driven Dynamics for Collective Behavior: Derivation, Model Hierarchies and Pattern Stability

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Imperial College London

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Deterministic Particle Methods for Diffusions

Deterministic Particle Methods for Aggregation-Diffusions

Outline

Problem & Motivation

• Minimization of the Interaction Energy

2 Deterministic Particle Methods for Diffusions

- Γ-Convergence
- Numerical Scheme and Simulations

3 Deterministic Particle Methods for Aggregation-Diffusions

- Approximation
- The Keller-Segel Model

Problem & Motivation	Deterministic Particle Method
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Deterministic Particle Methods for Aggregation-Diffusions

Minimization of the Interaction Energy

Outline

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Minimization of the Interaction Energy

Aggregation for particles - Continuum Model

One particle attracted/repelled by a fixed location x = a

 $\dot{X} = -\nabla U(X - a)$ $U(x) = U(-x), U(0) = 0, U \in C(\mathbb{R}^d, \mathbb{R}) \cap C^1(\mathbb{R}^d/\{0\}, \mathbb{R})$



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Multiple particles attracted by one another

$$\dot{X}_i = -\sum_{j \neq i} m_j \nabla U(X_i - X_j)$$



 $\rho(t, x) =$ density of particle at time *t*

$$v(x) = -\int_{\mathbb{R}^d} \nabla U(x-y) \ \rho(y) dy$$

So $v = -\nabla U * \rho$:

 $\begin{cases} \rho_t + \operatorname{div} \rho v = 0\\ v = -\nabla U * \rho \end{cases}$

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Minimization of the Interaction Energy

Formal Gradient Flow

Basic Properties

- Conservation of the center of mass.
- **2** Liapunov Functional: Gradient flow of

$$\mathcal{F}[\rho] = \frac{1}{2} \iint U(x - y) \ \rho(x) \ \rho(y) \ dxdy$$

with respect to the Wasserstein distance *W*₂. (C., McCann, Villani; RMI 2003, ARMA 2006).

The macroscopic equation can be rewritten as

$$\frac{\partial \rho}{\partial t}(t,x) = \operatorname{div}\left(\rho(t,x)\nabla\left[\frac{\delta \mathcal{F}}{\delta \rho}(t,x)\right]\right) \ .$$

with entropy dissipation:

$$\frac{\mathrm{d}}{\mathrm{d}t}\mathcal{F}[\rho(t)] = -\int_{\mathbb{R}^2} \rho(t,x) \left| \nabla \frac{\delta \mathcal{F}}{\delta \rho}(t,x) \right|^2 \, dx \, .$$

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Minimization of the Interaction Energy

Sliding down in a Energy Landscape

Finite Dimensional Gradient flows

A *gradient flow* in \mathbb{R}^d defined by an energy \mathcal{F} is given by

$$\frac{dx_t}{dt} = -\nabla \mathcal{F}(x_t) \,.$$

It is the continuous version of the *steepest descent* on the energy landscape determined by \mathcal{F} given by the implicit Euler scheme: given a time step Δt and an approximation to the solution at time $t_k = k\Delta t$, we find the approximation at time t_{k+1} by solving

$$x_{k+1} = x_k - \Delta t \nabla \mathcal{F}(x_{k+1}) \,.$$

which is equivalent under convexity conditions to the following variational problem: Solve

$$x_{k+1} = \arg\min_{x \in \mathbb{R}^d} \left\{ \frac{1}{2\Delta t} |x - x_k|^2 + \mathcal{F}(x) \right\}$$

with $|\cdot|$ the euclidean norm.

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Minimization of the Interaction Energy

JKO scheme (Jordan-Kinderlehrer-Otto)

A discrete time approximation of the PDE is obtained by solving a sequences of variational problem.

- Choose a time step Δt .
- Solve

$$\rho_{k+1} = \arg\min_{\rho \in \mathcal{P}_2^o(\mathbb{R}^d)} \left\{ \frac{1}{2\Delta t} W_2^2(\rho, \rho_k) + \mathcal{F}(\rho) \right\}$$

• As $\Delta t \rightarrow 0$ it converges to the solution of a weak form of

 $\begin{cases} \rho_t + \operatorname{div} \rho v = 0\\ v = -\nabla U * \rho \end{cases}$

The convergence for smooth C^1 potentials U with at most quadratic growth at infinity given in "Gradient Flow in Metric Spaces" book by Ambrosio, Gigli, Savaré, 2005.

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Minimization of the Interaction Energy

How to deal with concentrations?

Let U(x) = k(|x|) be a radial fully attractive potential with its only possible singularity located at zero such that



- Given an initial condition in $L^1 \cap L^\infty$ (Bertozzi, C., Laurent; Nonlinearity

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Let U(x) = k(|x|) be a radial fully attractive potential with its only possible singularity located at zero such that

No-Osgood condition:

$$\int_0^L \frac{dr}{k'(r)} < +\infty,$$

- Given an initial condition in $L^1 \cap L^\infty$ (Bertozzi, C., Laurent; Nonlinearity 2009) or in $L^1 \cap L^p$ for p > d/(d-1) (Bertozzi, Laurent, Rosado; CPAM 2011), the solutions blow up in finite time.
- Assume additionally that U is λ-convex: U(x) λ/2 |x|² is convex, then one can construct a well-posedness theory for measures going over the blow-up time in a unique way (C., Di Francesco, Figalli, Laurent, Slepcev; Duke MJ 2012). This assumption restrict the possible singularities at the origin, U(x) ≃ |x|^α locally at 0, with 1 ≤ α < 2, for instance.
- The solutions are doomed to a Total Collapse on their center of mass in finite time. Blow-up time generically different from Total Collapse time.

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Γ -Convergence

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Γ-Convergence

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 Γ -Convergence

Internal Energy

$$E\colon \mathcal{P}(\mathbb{R}^d) o \mathbb{R} \cup \{-\infty, +\infty\}$$
 by

$$E(\rho) = \begin{cases} \int_{\mathbb{R}} H(\rho(x)) \, dx \text{ if } \rho \in \mathcal{P}_{\mathrm{ac},2}(\mathbb{R}^d) \\ +\infty \quad \text{otherwise} \end{cases}$$

where $H: [0, \infty) \to \mathbb{R}$ is the density of *internal energy* satisfying H(0) = 0.

Let us consider N particles in \mathbb{R}^d denoted by $x_N := (x_{1,N}, \ldots, x_{N,N}) \in \mathbb{R}^{Nd}$, where N is a positive integer. For all $i \in \{1, \ldots, N\}$, let us write $B_{i,N} := B(x_{i,N}, R_{i,N})$ the open ball of centre $x_{i,N}$ and radius

$$R_{i,N} = rac{1}{2} \min_{j
eq i} |x_{i,N} - x_{j,N}|.$$

For these *N* particles consider

$$ho_N = rac{1}{N} \sum_{i=1}^N rac{1}{|B_{i,N}|} \chi_{B_{i,N}},$$

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Approximated Internal Energy

Given

$$\mathcal{A}_N(\mathbb{R}^d) = \left\{ \mu \in \mathcal{P}(\mathbb{R}^d) \text{ such that } \exists x_N \in \mathbb{R}^{Nd}, \mu = \delta_{x_N}
ight\}.$$

The discrete energy $E_N \colon \mathcal{A}_N(\mathbb{R}^d) \to \mathbb{R} \cup \{-\infty, +\infty\}$ by

$$E_N(\mu) = \int_{\mathbb{R}} H\left(rac{1}{N}\sum_{i=1}^Nrac{1}{|B_{i,N}|}\chi_{B_{i,N}}(x)
ight)\,\mathrm{d}x,$$

where $B_{i,N} = B(x_{i,N}, R_{i,N})$ with x_N satisfying $\mu = \delta_{x_N}$. Note that

$$|B_{i,N}| = C_d R_{i,N}^d = \frac{C_d}{2} (\min_{j \neq i} |x_{i,N} - x_{j,N}|)^d,$$

where $C_d = |B(0, 1)|$ is the volume of the unit ball in dimension *d*. We clearly have $E(\rho_N) = E_N(\mu)$.

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 Γ -Convergence

Γ -Convergence Result

• Logarithmic Entropy: Given

$$E_N(\mu) = -rac{1}{N}\sum_{i=1}^N \log\left(rac{NC_d}{2^d}\left(\min_{j
eq i}|x_{i,N}-x_{j,N}|
ight)^d
ight)\,,$$

then it Γ -converges in d_2 to the logarithmic entropy $E[\mu]$.

• Nonlinear Entropy: The same holds for

$$E_N(\mu) = \int_{\mathbb{R}} \frac{1}{(m-1)N^m} \left(\sum_{i=1}^N \frac{1}{|B_{i,N}|} \chi_{B_{i,N}}(x) \right)^m dx$$

 Γ -converging to

$$E(
ho) = \int_{\mathbb{R}} rac{
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Numerical Scheme and Simulations

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Numerical Scheme and Simulations

Discrete JKO scheme

For any *N* particles in \mathbb{R}^d , we denote their weights by $w = (w_1, \ldots, w_N) \in \mathbb{R}^N$, which we assume to satisfy $\sum_{i=1}^N w_i = 1$ and $w_i \ge 0$ for all $i \in \{1, \ldots, N\}$. For any such $w \in \mathbb{R}^N$, define

$$\mathcal{P}_w(\mathbb{R}^d) = \left\{ \rho \in \mathcal{P}(\mathbb{R}^d) \text{ such that } \exists x = (x_1, \dots, x_N) \in \mathbb{R}^{Nd}, \rho = \sum_{i=1}^N \frac{w_i}{|B(x_i, R_i)|} \chi_{B(x_i, R_i)} \right\}$$

where

$$R_i=\frac{1}{2}\min_{j\neq i}|x_i-x_j|.$$

Note that

$$|B(x_i,R_i)| = C_d R_i^d = \frac{C_d}{2} \left(\min_{j \neq i} |x_i - x_j| \right)^d,$$

where $C_d = |B(0, 1)|$ is the volume of the unit ball of dimension *d*.

Discrete Particle JKO scheme:

$$F(\tilde{
ho}) = rac{1}{2\Delta t} d_2^2(
ho, \tilde{
ho}) + E(\tilde{
ho}), \qquad \longrightarrow \qquad F_N(\tilde{
ho}) = \sum_{i=1}^N w_i rac{(x_i - \tilde{x}_i)^2}{2\Delta t} + E_N(\tilde{
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where $C_d = |B(0, 1)|$ is the volume of the unit ball of dimension *d*.

Discrete Particle JKO scheme:

$$F(\tilde{\rho}) = \frac{1}{2\Delta t} d_2^2(\rho, \tilde{\rho}) + E(\tilde{\rho}), \qquad \longrightarrow \qquad F_N(\tilde{\rho}) = \sum_{i=1}^N w_i \frac{(x_i - \tilde{x}_i)^2}{2\Delta t} + E_N(\tilde{\rho}),$$

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Deterministic Particle Methods for Aggregation-Diffusions (d = 1)

Consider the gradient flow

$$\frac{\mathrm{d}\rho}{\mathrm{d}t}(t) = -\nabla_{\mathcal{P}_{\mathrm{ac},2}(\mathbb{R})} E(\rho(t)) \quad \text{on } \mathbb{R}_+.$$

 $\rho \colon \mathbb{R}_+ \to \mathcal{P}_{\mathrm{ac},2}(\mathbb{R})$ and $\nabla_{\mathcal{P}_{\mathrm{ac},2}(\mathbb{R})}$ is the 2-Wasserstein gradient:

$$\nabla_{\mathcal{P}_{\mathrm{ac},2}(\mathbb{R})} E(\rho) = -\nabla \cdot \left(\rho \nabla \frac{\delta E}{\delta \rho}\right) \quad \text{for any } \rho \in \mathcal{P}_{\mathrm{ac},2}(\mathbb{R})$$

where $\frac{\delta E}{\delta \rho}$ is the first variation density of E at point ρ .

 $E: \mathcal{P}_{\mathrm{ac},2}(\mathbb{R}) \to \overline{\mathbb{R}} \text{ is the energy functional}$ $E(\rho) = \int_{\mathbb{R}} \left(H(\rho(x)) + U * \rho(x) \right) \, \mathrm{d}x \quad \text{for any } \rho \in \mathcal{P}_{\mathrm{ac},2}(\mathbb{R}),$

where $H: [0, \infty) \to \mathbb{R}$ is the **density of internal energy** and $U: \mathbb{R} \to \mathbb{R} \cup \{+\infty\}$ a symmetric **interaction potential**.

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Approximation

Deterministic Particle Methods for Aggregation-Diffusions

Take any $N \ge 2$ increasingly ordered particles $\{x_1, \ldots, x_N\} \subset \mathbb{R}$ with weights $\{w_i, \ldots, w_N\} \subset (0, 1)$.

The diffusion part of the energy is not defined on Dirac masses, so spread out the mass of each particle: write $B_i := B_{R_i}(x_i)$ the open ball of centre x_i and radius

$$R_i = \frac{1}{2}\min(\Delta x_{i+1}, \Delta x_i) ,$$

and define

$$\rho_N = \sum_{i=1}^N rac{w_i \chi_{\mathcal{B}_i}}{d_i} \in \mathcal{P}_{\mathrm{ac},2}(\mathbb{R}) ,$$

where $d_i := |B_i|$.

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Assume H(0) = 0 and compute

$$\int_{\mathbb{R}} H(\rho_N(x)) \, \mathrm{d}x = \int_{\mathbb{R}} H\left(\frac{1}{N} \sum_{i=1}^N \frac{\chi_{B_i}(x)}{|B_i|}\right) \, \mathrm{d}x = \sum_{i=1}^N d_i H\left(\frac{w_i}{d_i}\right)$$

Define now the **discrete energy** $E_N \colon \mathbb{R}^N \to \overline{\mathbb{R}}$ by

$$E_N(x) = \sum_{i=1}^N d_i H\left(\frac{w_i}{d_i}\right) + \frac{1}{2} \sum_{\substack{i=1\\j\neq i}}^N \sum_{\substack{j=1\\j\neq i}}^N w_i w_j U(x_i - x_j), \quad x \in \mathbb{R}^N$$

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We define a discrete gradient flow:

$$w \frac{\mathrm{d}x}{\mathrm{d}t}(t) \in -\partial E_N(x(t)) \quad \text{for all } t \in \mathbb{R}_+,$$

where $w \frac{dx}{dt}$ is the vector $(w_1x_1, \ldots, w_Nx_N) \in \mathbb{R}^N$ if we write $x := (x_1, \ldots, x_N)$, and ∂ stands for the subdifferential.

$$E_N \colon \mathbb{R}^N \to \overline{\mathbb{R}} \text{ is the discrete energy functional}$$
$$E_N(x) = \sum_{i=1}^N d_i H\left(\frac{w_i}{d_i}\right) + \frac{1}{2} \sum_{\substack{i=1\\j \neq i}}^N \sum_{\substack{j=1\\j \neq i}}^N w_i w_j U(x_i - x_j)$$
for all $x \in \mathbb{R}^N$.

Remark. The gradient flow has here the structure of a **differential inclusion** since the discrete energy E_N has no well-defined gradient because of the presence of the minimum function (in d_i).

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$$E_{N}(x) = \sum_{i=1}^{N} d_{i}H\left(\frac{w_{i}}{d_{i}}\right) + \frac{1}{2}\sum_{i=1}^{N}\sum_{\substack{j=1\\j\neq i}}^{N} w_{i}w_{j}U(x_{i} - x_{j})$$
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Definition (*p*-approximation of minimum function). Let us define, for any p > 0, the function $\min_p : [0, \infty)^2 \to [0, \infty)$ as

$$\min_p(x,y) = \begin{cases} \left(\frac{x^{-p} + y^{-p}}{2}\right)^{-1/p} & \text{for all } x, y \in (0,\infty) \\ 0 & \text{otherwise} \end{cases}.$$

We define the *p*-approximated discrete energy by

$$E_{N,p} = \sum_{i=1}^{N} w_i \log \frac{w_i}{d_{i,p}} + \frac{1}{2} \sum_{i=1}^{N} \sum_{\substack{j=1\\j \neq i}}^{N} w_i w_j U(x_i - x_j)$$

where $d_{i,p} := \min_p(\Delta x_{i+1}, \Delta x_i)$, for all $i \in \{1, \ldots, N\}$.

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The *p*-approximated discrete energy $E_{N,p}$ has a well-defined gradient.

The *p*-approximated gradient flows writes then as the ODE system

$$w_i \frac{\mathrm{d}x_i}{\mathrm{d}t}(t) = -\nabla_{x_i} E_{N,p}(x_1(t), \dots, x_N(t)) \quad \text{for all } t \in \mathbb{R}_+.$$

 $E_{N,p} \colon \mathbb{R}^N \to \overline{\mathbb{R}}$ is the *p*-approximated discrete energy functional

$$E_{N,p}(x) = \sum_{i=1}^{N} w_i \log \frac{w_i}{d_{i,p}} + \frac{1}{2} \sum_{\substack{i=1\\j \neq i}}^{N} \sum_{\substack{j=1\\j \neq i}}^{N} w_i w_j U(x_i - x_j)$$

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For the heat equation $(H(x) = x \log x \text{ and } W = 0)$ we are able to show that the *p*-approximated gradient flow converges to the continuum gradient flow in the Serfaty sense.¹

To find the solution to the *p*-approximated ODE system we use an explicit version of the following JKO scheme:

$$x^{n+1} := \operatorname*{argmin}_{x \in \mathbb{R}^N} \left(\sum_{i=1}^N w_i \frac{(x_i^n - x_i)^2}{2\Delta t} + E_{N,p}(x) \right) \,.$$

¹Carrillo, Huang, Patacchini, Sternberg, Wolansky, in preparation.

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The Keller-Segel Model

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The Keller-Segel equation $(H(x) = x \log x \text{ and } W(x) = 2\chi \log |x|)$.

$$\frac{\partial \rho}{\partial t} = \Delta \rho + 2\chi \nabla \cdot (\rho \nabla \log |\cdot| * \rho) \quad \text{on } \mathbb{R}_+ \times \mathbb{R},$$

where χ is an interaction parameter quantifying the "strength" of the attraction.

Write $M_2(t) := \int_{\mathbb{R}} |x|^2 d\rho(t, x)$. Theoretically, it is easy to check that

$$\frac{\mathrm{d}M_2}{\mathrm{d}t}(t) = 2(1-\chi) \quad \text{for all } t \in [0,\infty).$$

Thus we have three cases:

Subcritical. $\chi < 1$: solutions exist for all times; the diffusion wins over the attraction.

Critical. $\chi = 1$.

Supercritical. $\chi > 1$: solutions cease to exist after a finite time; the attraction wins over the diffusion.

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Write $M_2^{N,p}(t) := \int_{\mathbb{R}} |x|^2 d\rho_{N,p}(t,x)$, where $\rho_{N,p} = \sum_{i=1}^{N} \frac{w_i \chi_{B_i}}{d_{i,p}}$. Interestingly, using our *p*-approximated discrete gradient flow, we can compute $\frac{dM_2^{N,p}}{dt}(t) = 2(1-\chi) + \mathop{\mathcal{O}}_{N \to \infty}(1) \quad \text{for all } t \in [0,\infty).$

Adaptive time step. To catch blow-up we implement the following adaptive time step method.

- Initialize $\Delta t = 10^{-5}$ and fix $\varepsilon < 1$.
- (a) If $\Delta t > \frac{\varepsilon d_{i,p}}{2\left|\frac{dx_i}{dt}\right|}$, then define $\Delta t_i := \frac{\varepsilon d_{i,p}}{2\left|\frac{dx_i}{dt}\right|}$.
- Let *I* be the set of indices for which the if-loop above was entered. If $I = \emptyset$, then choose $\Delta t = \Delta t$. If $I \neq \emptyset$, then choose $\Delta t = \min_{i \in I} \Delta_i$.

If
$$\Delta t < 10^{-7}$$
, then stop.

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Figure : Evolution of second order moment with $\chi = 1.5$ and N = 100 (left). Evolution of positions before numerical blow-up with $\chi = 1.5$ and N = 50 (right).

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Videos.

Keller Segel – $\chi = 1.5$; N = 100; one Gaussian Keller Segel – $\chi = 3$; N = 100; two Gaussians