

Gradient Flows: Qualitative Properties & Numerical Schemes

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Outline

- 1 Gradient Flows
 - Models
 - Gradient flows
 - Evolving diffeomorphisms
- 2 Numerical schemes
 - Explicit/Implicit-in-time discretization
 - Initialization & Full Algorithm
- 3 2D Simulations
 - Diffusions
 - Merging
 - Blow-up

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Nonlinear continuity equations

Let us consider a time dependent unknown probability density $\rho(t, \cdot)$ on a domain $\Omega \subset \mathbb{R}^d$, which satisfies the nonlinear continuity equation

$$\partial_t \rho = -\nabla \cdot (\rho u) := \nabla \cdot (\rho \nabla [U'(\rho) + V + W * \rho]).$$

- $U : \mathbb{R}^+ \rightarrow \mathbb{R}$ denotes the internal energy.
- $V : \mathbb{R}^d \rightarrow \mathbb{R}$ is the confining potential.
- $W : \mathbb{R}^d \rightarrow \mathbb{R}$ corresponds to an interaction potential.

Nonlinear velocity is given by $u = -\nabla \frac{\delta \mathcal{F}}{\delta \rho}$, where \mathcal{F} denotes the free energy or entropy functional

$$\mathcal{F}(\rho) = \int_{\mathbb{R}^d} U(\rho) dx + \int_{\mathbb{R}^d} V(x) \rho(x) dx + \frac{1}{2} \int_{\mathbb{R}^d \times \mathbb{R}^d} W(x-y) \rho(x) \rho(y) dx dy.$$

Free energy is decreasing along trajectories

$$\frac{d}{dt} \mathcal{F}(\rho)(t) = - \int_{\mathbb{R}^d} \rho(x, t) |u(x, t)|^2 dx.$$

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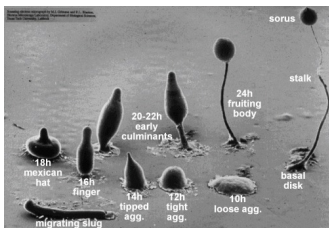
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Nonlinear continuity equations

Included models:

- $U(s) = s \log s$, $V = 0$, $W = 0$ heat equation.
- $U(s) = \frac{1}{m-1} s^m$, $V = W = 0$ porous medium ($m > 1$) or fast diffusion ($0 < m < 1$).
- $U(s) = s \log s$, V given, $W = 0$, Fokker Planck equations.
- $U(s) = s \log s$, $V = 0$, W given, Patlak-Keller-Segel model.
- $U = 0$, $V = 0$, $W = \log(-|x|)$ or $W = \frac{1}{2}|x|^2 - \frac{1}{4}|x|^4$ correspond to attraction-(repulsion) potentials in swarming, herding and aggregation models.



(a) Dictyostelium discoideum



(b) Fish school

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Gradient flow formalism¹

- Solutions ρ can be constructed by the following variational scheme:

$$\rho_{\Delta t}^{n+1} \in \arg \inf_{\rho \in \mathcal{K}} \left\{ \frac{1}{2\Delta t} d_2^2(\rho_{\Delta t}^n, \rho) + \mathcal{F}(\rho) \right\},$$

with $\mathcal{K} = \{\rho \in L_+^1(\mathbb{R}^d) : \int_{\mathbb{R}^d} \rho(x) dx = M, |x|^2 \rho \in L^1(\mathbb{R}^d)\}$.

- Quadratic Euclidean Wasserstein distance d_W between two probability measures μ and ν ,

$$d_2^2(\mu, \nu) := \inf_{T: \nu = T\#\mu} \int_{\mathbb{R}^d} |x - T(x)|^2 d\mu(x).$$

- Variational scheme corresponds to the time discretization of an abstract gradient flow in the space of probability measures.
- Solutions can be constructed by this variational scheme; naturally preserve positivity and the free-energy decreasing property.

¹Jordan, Kinderlehrer and Otto (1999); Otto (1996, 2001); Ambrosio, Gigli and Savare (2005); Villani(2003).....

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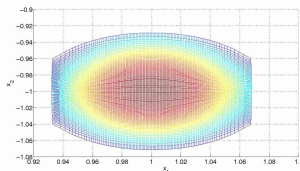
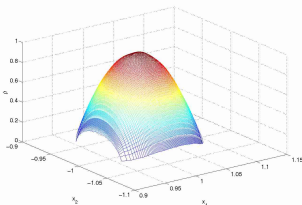
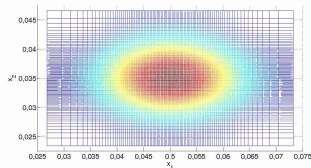
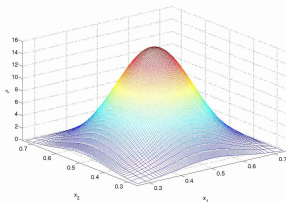
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Gradient flow formalism

For a given diffeomorphism $\Phi \in \mathcal{D}$ the corresponding density $\rho \in \mathcal{K}$ is given by

$$\rho = \Phi \# \mathcal{L}^d \llcorner_{\Omega} \text{ which is equivalent to } \rho(\Phi(x)) \det(D\Phi) = 1 \text{ on } \Omega$$

for sufficiently smooth functions.



Gradient flow formalism

- Let Ω and $\tilde{\Omega}$ be smooth, open, bounded and connected subsets of \mathbb{R}^d . We denote by $\Phi \in \mathcal{D}$ the set of diffeomorphisms from $\bar{\Omega}$ to $\bar{\tilde{\Omega}}$ (mapping $\partial\Omega$ onto $\partial\tilde{\Omega}$).
- Doing the change of variables by the diffeomorphism $\rho = \Phi\#\mathcal{L}^d$, we get

$$\mathcal{I}(\Phi) = \int_{\Omega} \Psi(\det D\Phi) dx + \int_{\Omega} V(\Phi(x)) dx + \frac{1}{2} \int_{\Omega} \int_{\Omega} W(\Phi(x) - \Phi(y)) dx dy.$$

with $\Psi(s) = s U(1/s)$ for all $s > 0$.

Classic L^2 -gradient flow: Evans, Savin and Gangbo (2004)

$$\Phi_{\Delta t}^{n+1} \in \arg \inf_{\Phi \in \mathcal{D}} \left\{ \frac{1}{2\Delta t} \|\Phi_{\Delta t}^n - \Phi\|_{L^2(\Omega)}^2 + \mathcal{I}(\Phi) \right\}$$

converges to solutions of the PDE

$$\begin{aligned} \frac{\partial \Phi}{\partial t} &:= u(t) \star \Phi \\ &= \nabla \cdot [\Psi'(\det D\Phi)(\text{cof } D\Phi)^T] - \nabla V \circ \Phi - \int_{\Omega} \nabla W(\Phi(x) - \Phi(y)) dy, \end{aligned}$$

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Generalization of Gradient flow formalism

Let us denote by $c(x, y) : \mathbb{R}^d \times \mathbb{R}^d \longrightarrow \mathbb{R}^+$ with c is radially symmetric as $c(x, y) = c(x - y) = c(|x - y|)$.

Generalized gradient flow

Several authors (Agueh, Ambrosio-Gigli-Savaré, McCann-Puel) proved for different costs that the scheme

$$\rho_{\Delta t}^{n+1} \in \arg \inf_{\rho \in \mathcal{K}_c} \left\{ \Delta t \inf_{\Pi \in \Gamma(\rho_{\Delta t}^n, \rho)} \left\{ \int_{\mathbb{R}^d \times \mathbb{R}^d} c \left(\frac{x - y}{\Delta t} \right) d\Pi(x, y) \right\} + \mathcal{F}(\rho) \right\},$$

where $\Gamma(\rho_{\Delta t}^n, \rho)$ is the set of measures in the product space $\mathbb{R}^d \times \mathbb{R}^d$ with marginals $\rho_{\Delta t}^n$ and ρ respectively, is convergent to a solution of the PDE

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The p -Laplacian equation and the doubly nonlinear equation.-

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left[|\nabla \rho^m|^{p-2} \nabla \rho^m \right],$$

with $1 < p < \infty$, $m \geq m_c := \frac{d-p}{d(p-1)}$. The cost is given by $c(x) = |x|^q/q$ with q the conjugate exponent of p and the internal energy given by

$$U(s) = \begin{cases} \frac{1}{p-1} s \ln s & \text{if } m = \frac{1}{p-1} \\ \frac{ms^\gamma}{\gamma(\gamma-1)}, \gamma = m + \frac{p-2}{p-1} & \text{if } m \neq \frac{1}{p-1}. \end{cases}$$

Generalization of Gradient flow formalism

The relativistic heat equation.-

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left(\rho \frac{\nabla \rho}{\sqrt{\rho^2 + |\nabla \rho|^2}} \right) = \nabla \cdot \left(\rho \frac{\nabla \log \rho}{\sqrt{1 + |\nabla \log \rho|^2}} \right).$$

Here, the cost function is given by

$$c(x) = \begin{cases} 1 - \sqrt{1 - |x|^2} & \text{if } |x| \leq 1 \\ +\infty & \text{if } |x| > 1. \end{cases},$$

with $c^*(x) = \sqrt{1 + |x|^2} - 1$ and the logarithmic entropy functional.

Lagrangian Coordinates

- PDE for the evolving diffeomorphisms Φ is the Lagrangian coordinate representation of the original Eulerian formulation for ρ , in 1D it is the monotone rearrangement.
- Heat equation

$$\frac{\partial \rho}{\partial t} = \rho_{xx} \quad \Rightarrow \quad \frac{\partial \Phi}{\partial t} = -\frac{\partial}{\partial x} \left(\frac{1}{\Phi_x} \right) = \frac{\Phi_{xx}}{(\Phi_x)^2},$$

- Porous medium equation

$$\frac{\partial \rho}{\partial t} = \partial_{xx}(\rho^m) \quad \Rightarrow \quad \frac{\partial \Phi}{\partial t} = -\frac{\partial}{\partial x} \left(\frac{1}{(\Phi_x)^m} \right) = m \frac{\Phi_{xx}}{(\Phi_x)^{m+1}}.$$

- Relativistic heat equation

$$\rho_t = \left(\rho \frac{\rho_x}{\sqrt{\rho^2 + |\rho_x|^2}} \right)_x \quad \Rightarrow \quad \Phi_t = \left(\frac{\Phi_x}{\sqrt{\Phi^4 + |\Phi_x|^2}} \right)_x.$$

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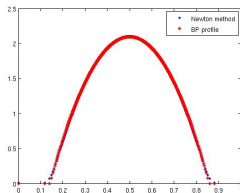
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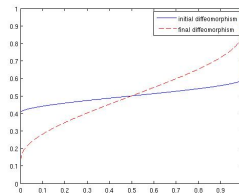
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1D Diffusion: Simulations

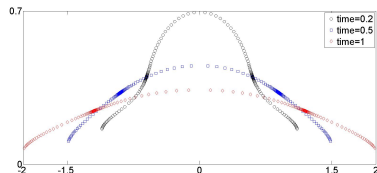
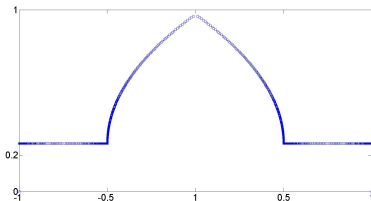
1D simulation of the PME for $m = 2$ and the relativistic equation:

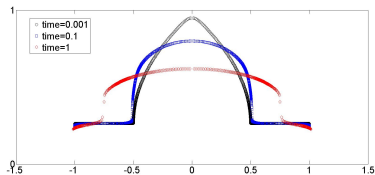
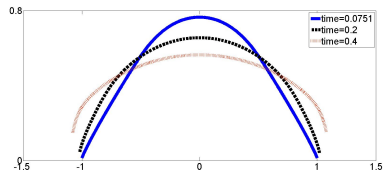
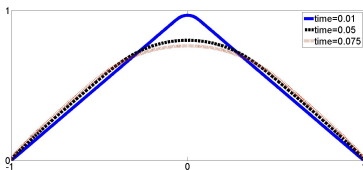


(c) Density ρ



(d) Diffeomorphism Φ



$m \neq 1$ 

Why do we make our life so much harder ?

- **Automatic mesh adaptation** and mesh merging in regions of high density.
- **A Dirac Delta corresponds to a degeneration of the transport map** - numerically more tractable than blow-up for densities.
- **Energy dissipation and positivity.**

Entropy Dissipation in a bounded domain for Φ :

$$\frac{d}{dt} \mathcal{I}(\Phi(t)) = - \int_{\Omega} |u(t) * \Phi|^2 dx - \int_{\partial\Omega} \Psi'(\det D\Phi) \eta^T (\text{cof } D\Phi)^T \frac{\partial\Phi}{\partial t} dx$$

from which, we conclude that the natural boundary condition associated to the variational scheme for Φ is:

$$\eta^T (\text{cof } D\Phi)^T \frac{\partial\Phi}{\partial t} = (\text{cof } D\Phi) \eta \cdot \frac{\partial\Phi}{\partial t} = 0 \quad \text{on } \partial\Omega.$$

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Boundary conditions

- BC's in Lagrangian formulation are

$$n^T (\text{cof } D\Phi)^T \frac{\partial \Phi}{\partial t} = (\text{cof } D\Phi)n \cdot \frac{\partial \Phi}{\partial t} = 0.$$

- On the square $\Omega = [-1, 1]^2$ these boundary conditions translate to

$$\begin{aligned} \frac{\partial \Phi_1}{\partial t} \frac{\partial \Phi_2}{\partial x_2} - \frac{\partial \Phi_2}{\partial t} \frac{\partial \Phi_1}{\partial x_1} &= 0 \text{ for } x_1 = -1, x_1 = 1 \\ -\frac{\partial \Phi_1}{\partial t} \frac{\partial \Phi_1}{\partial x_2} + \frac{\partial \Phi_2}{\partial t} \frac{\partial \Phi_1}{\partial x_1} &= 0 \text{ for } x_2 = -1, x_2 = 1. \end{aligned}$$

- Consider only diffeomorphisms which map each edge of $\partial\Omega$ to the corresponding one of $\partial\tilde{\Omega}$ without rotation. This reduces to

$$\begin{aligned} \Phi_1(t, \pm 1) &= \pm 1 & \frac{\partial \Phi_2}{\partial t} \frac{\partial \Phi_2}{\partial x_1} &= 0 \text{ for } x_1 = \pm 1 \\ \Phi_2(t, \pm 1) &= \pm 1 & \frac{\partial \Phi_1}{\partial t} \frac{\partial \Phi_1}{\partial x_2} &= 0 \text{ for } x_2 = \pm 1. \end{aligned}$$

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Implicit Euler scheme: Minimization then discretization

$$\frac{\Phi^{n+1} - \Phi^n}{\Delta t} = \nabla \cdot [\Psi'(\det D\Phi^{n+1})(\operatorname{cof} D\Phi^{n+1})^T] + \nabla V \circ \Phi^{n+1} + \int \nabla W(\Phi^{n+1}(x) - \Phi^{n+1}(y)) dy$$

- Conforming finite element discretization

$$\begin{aligned} F(\Phi^{n+1}, \varphi) &= \frac{1}{\Delta t} \int_{\Omega} (\Phi^{n+1} - \Phi^n) \varphi(x) dx - \int \nabla V(\Phi^{n+1}) \varphi(x) dx \\ &\quad - \int_{\Omega} \left[\int_{\Omega} \nabla W(\Phi^{n+1}(x) - \Phi^{n+1}(y)) dy \right] \varphi(x) dx \\ &\quad + \int_{\Omega} \Psi'(\det D\Phi^{n+1})(\operatorname{cof} D\Phi^{n+1})^T \nabla \varphi(x) dx. \end{aligned}$$

- One can use the lowest order H^1 conforming finite elements, i.e.

$$\Phi(x_1, x_2) = \sum_k \begin{pmatrix} \Phi_k^1 \\ \Phi_k^2 \end{pmatrix} \varphi_k(x_1, x_2).$$

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- Full discretization by finite differences and quadrature formulas for the derivatives and integral for interactions, (C.-Moll, SISC 2009).
- To avoid problems at the boundaries with approximation with second derivatives, we need to be careful.

Let us consider a discretization $\Phi_{i,j}$ on a uniform symmetric cartesian grid $\Omega = [-1, 1]^2$ of Φ with mesh sizes $\Delta x = \Delta x_1 = \Delta x_2 = 2/N$. Let us introduce the following notations

$$(D^{\leftarrow} \Phi)_{i,j} = \frac{1}{\Delta x} (\Phi_{i,j} - \Phi_{i-1,j}) \quad , \quad (D^{\rightarrow} \Phi)_{i,j} = \frac{1}{\Delta x} (\Phi_{i+1,j} - \Phi_{i,j})$$

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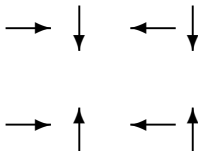


Figure : Schematic representation of the order of derivatives approximation.

Since for compactly supported densities, we have $\det(D\Phi) \rightarrow +\infty$ at the boundary, we impose that

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which reflects that $\Psi'(+\infty) = 0$.

Let us remark that the condition $\Psi'(\infty) = 0$ is equivalent to $f(0+) = 0$ with $f(s) = U(s) - sU'(s)$, and the nonlinear diffusion term is originally $\Delta f(\rho)$.

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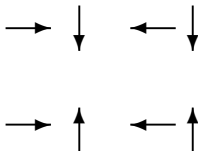


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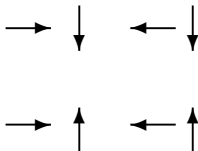


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Explicit schemes: Further comments

- We use explicit Euler if diffusive terms are present if not we use explicit 4th order RK schemes since the resulting approximation is a large ODE couple system, we see degeneracy of the long time asymptotics otherwise.
- The reported spatial discretization of the 2nd order terms leads to a CFL condition of the type

$$\|\Psi'(\det D\Phi)\|_{L^\infty} \frac{\Delta t}{\Delta x^2} \leq \frac{1}{2}.$$

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Calculating the initial diffeomorphism

Rectangular mesh: diffeomorphism can be constructed by subsequently solving two one-dimensional Monge-Kantorovich problems in x_1 and x_2 direction, (Angenent-Haker-Tannebaum).

Triangular mesh: No natural ordering !

The Monge-Ampère equation gives the optimal transportation plan $T = T(x)$: unique minimizing map is the gradient of a convex function u , i.e. $T_0 = \nabla\varphi$, which satisfies the MA equation

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Numerical simulations

Numerical solver:

- 1 Given an initial density $\rho_0 = \rho_0(x)$ calculate the corresponding initial diffeomorphism by either determining the solution of the Monge Ampere equation or by successive 1D transport maps.
- 2 Map the optimal transportation plan to the initial diffeomorphism $\Phi_0(x) = T_0$.
- 3 Apply the explicit-in-time discretization for $\Phi = \Phi(x, t)$.
- 4 Reconstruct the corresponding density $\rho = \rho(x, t)$ via

$$\rho(\Phi(x, t), t) \det(D\Phi(x, t)) = 1.$$

Outline

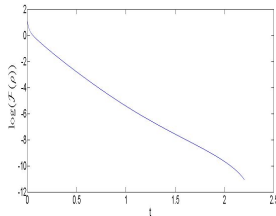
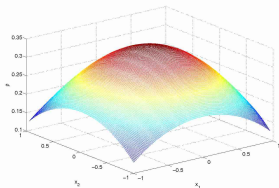
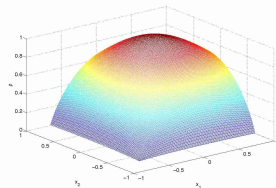
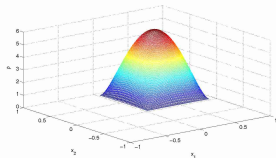
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Linear Fokker-Planck Equation

Linear Diffusion:

Starting with parabola initial data and with $U(s) = s \log s$, $V = |x|^2/2$ and $W = 0$:

$$\partial_t \rho = \nabla \cdot (\nabla \rho + x \rho).$$

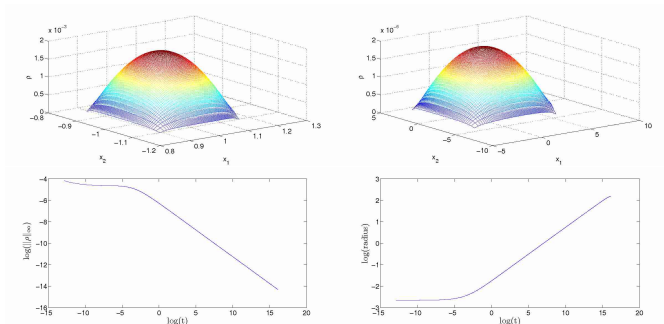


NonLinear Diffusion

Porous Medium Equation:

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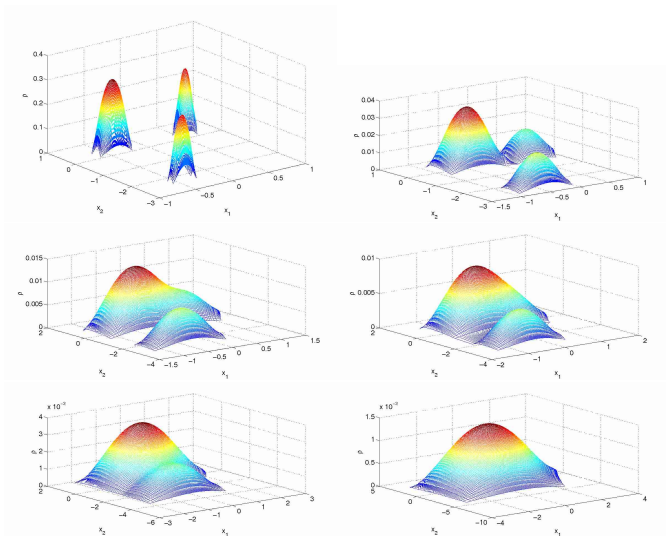
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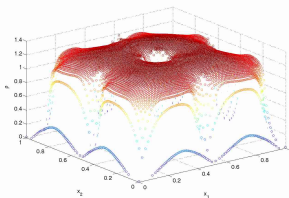
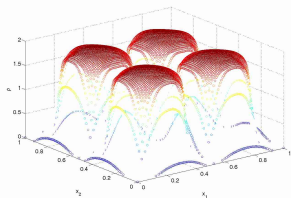
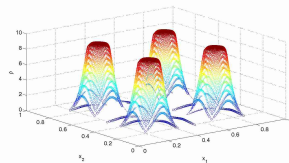
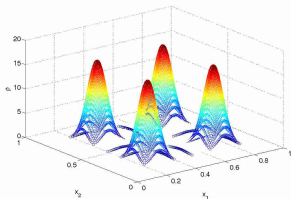
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Relativistic Heat Equation

Flux-Limited Diffusion:

$$\frac{\partial \rho}{\partial t} = \nabla \cdot \left(\rho \frac{\nabla \rho}{\sqrt{\rho^2 + |\nabla \rho|^2}} \right) = \nabla \cdot \left(\rho \frac{\nabla \log \rho}{\sqrt{1 + |\nabla \log \rho|^2}} \right).$$



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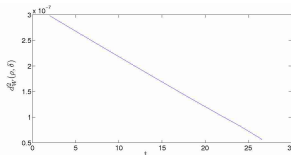
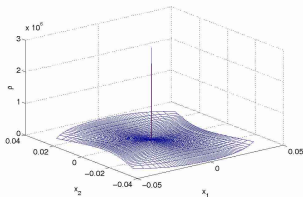
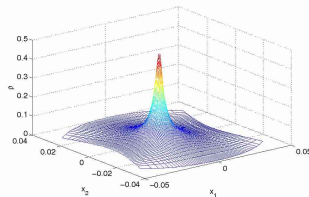
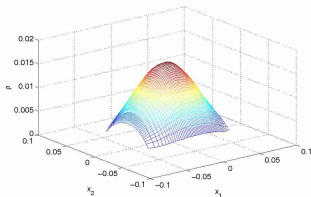
- 1 Gradient Flows
 - Models
 - Gradient flows
 - Evolving diffeomorphisms
- 2 Numerical schemes
 - Explicit/Implicit-in-time discretization
 - Initialization & Full Algorithm
- 3 2D Simulations
 - Diffusions
 - Merging
 - **Blow-up**

Swarming Model

Aggregation Equation:

Starting with parabola initial data and with $U(s) = 0$, $V = 0$, and $W(x) = -e^{-|x|}$:

$$\partial_t \rho = \nabla \cdot [(\nabla W * \rho) \rho].$$



Chemotaxis Model

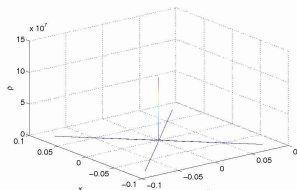
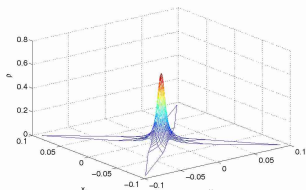
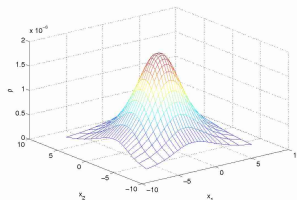
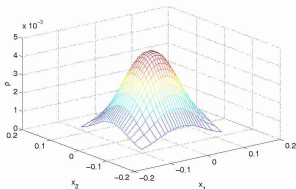
PKS Equation:

Starting with parabola initial data and with $U(s) = s \log s$, $V = 0$, and

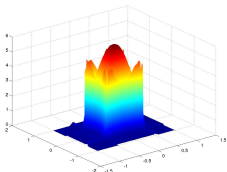
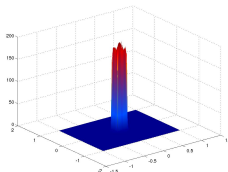
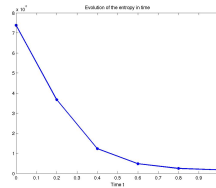
$$W(x) = \frac{\chi}{2\pi} \log |x|:$$

$$\partial_t \rho = \nabla \cdot [\nabla \rho + (\nabla W * \rho) \rho].$$

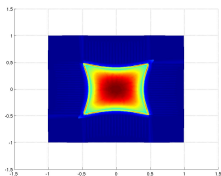
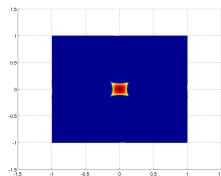
top right $\chi = 7\pi$ at $t = 500$, bottom left $\chi = 9\pi$ at $t = 0.025$, bottom right $\chi = 9\pi$ at $t = 0.02586440688$.



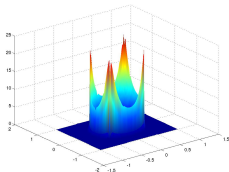
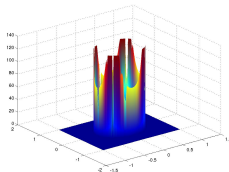
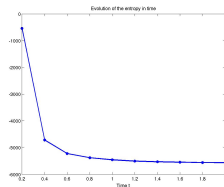
Attraction: $W(x) = \frac{1}{2}|x|^2$

(a) $t = 0.2$ (b) $t = 0.8$ 

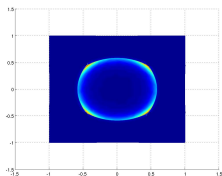
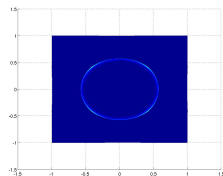
(c) Entropy

(d) $t = 0.2$ (e) $t = 0.8$

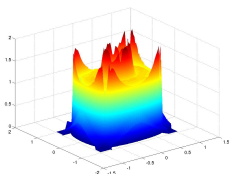
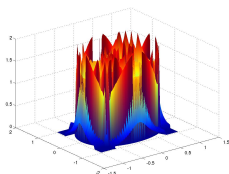
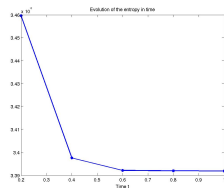
$$\text{Attraction-repulsion: } W(x) = -\frac{1}{2}|x|^2 + \frac{1}{4}|x|^4$$

(f) $t = 0.8$ (g) $t = 1.4$ 

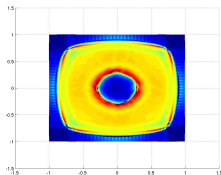
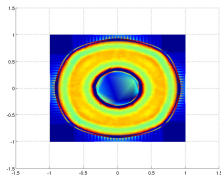
(h) Entropy

(i) $t = 0.8$ (j) $t = 1.4$

Attraction-repulsion: $W(x) = \frac{1}{2}|x|^2 - \ln(|x|)$,
 $V(x) = -\frac{1}{4} \ln(|x|)$

(k) $t = 0.4$ (l) $t = 1$ 

(m) Entropy

(n) $t = 0.4$ (o) $t = 1$

Conclusions

- The gradient flow interpretation induces a natural Lagrangian particle method on a grid or moving mesh method.
- It is a good solution to track accurately blow-up time and profiles and degenerate diffusion problems.
- It allows for merging of densities and finding stationary states for competing attractive-repulsive effects.
- Further improvements needs to be done to reconstruct better the density and to approximate the evolution of the diffeomorphisms with higher order accuracy.
- References:
 - ① C.-Moll (SISC 2009), C.-Caselles-Moll (PLMS 2013).
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