

PDE-CDT Core Course

Analysis of Partial Differential Equations-Part III

Lecture 4

**EPSRC Centre for Doctoral Training in
Partial Differential Equations**

Trinity Term

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Course format: Teaching Course (TT)

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Hyperbolic Systems of Conservation Laws

$$\begin{cases} \frac{\partial}{\partial t} u_1 + \frac{\partial}{\partial x} f_1(u_1, \dots, u_m) = 0, \\ \dots \dots \\ \frac{\partial}{\partial t} u_m + \frac{\partial}{\partial x} f_m(u_1, \dots, u_m) = 0, \end{cases}$$

$$\mathbf{u}_t + \mathbf{f}(\mathbf{u})_x = 0$$

$\mathbf{u} = (u_1, \dots, u_m)^\top \in \mathbb{R}^m$ conserved quantities

$\mathbf{f}(\mathbf{u}) = (f_1(\mathbf{u}), \dots, f_m(\mathbf{u}))^\top$ fluxes

Hyperbolic Systems

$$\mathbf{u}_t + \mathbf{f}(\mathbf{u})_x = 0$$

$$\mathbf{u} = \mathbf{u}(t, x) \in \mathbb{R}^m$$

$$\mathbf{u}_t + \mathbf{A}(\mathbf{u})\mathbf{u}_x = 0$$

$$\mathbf{A}(\mathbf{u}) = \nabla \mathbf{f}(\mathbf{u})$$

The system is **strictly hyperbolic** if each $m \times m$ matrix $\mathbf{A}(\mathbf{u})$ has real distinct eigenvalues

$$\lambda_1(\mathbf{u}) < \lambda_2(\mathbf{u}) < \cdots < \lambda_m(\mathbf{u})$$

Right eigenvectors $\mathbf{r}_1(\mathbf{u}), \dots, \mathbf{r}_m(\mathbf{u})$ (column vectors)
Left eigenvectors $\mathbf{l}_1(\mathbf{u}), \dots, \mathbf{l}_m(\mathbf{u})$ (row vectors)

$$\mathbf{A}\mathbf{r}_i = \lambda_i \mathbf{r}_i \quad \mathbf{l}_i \mathbf{A} = \lambda_i \mathbf{l}_i$$

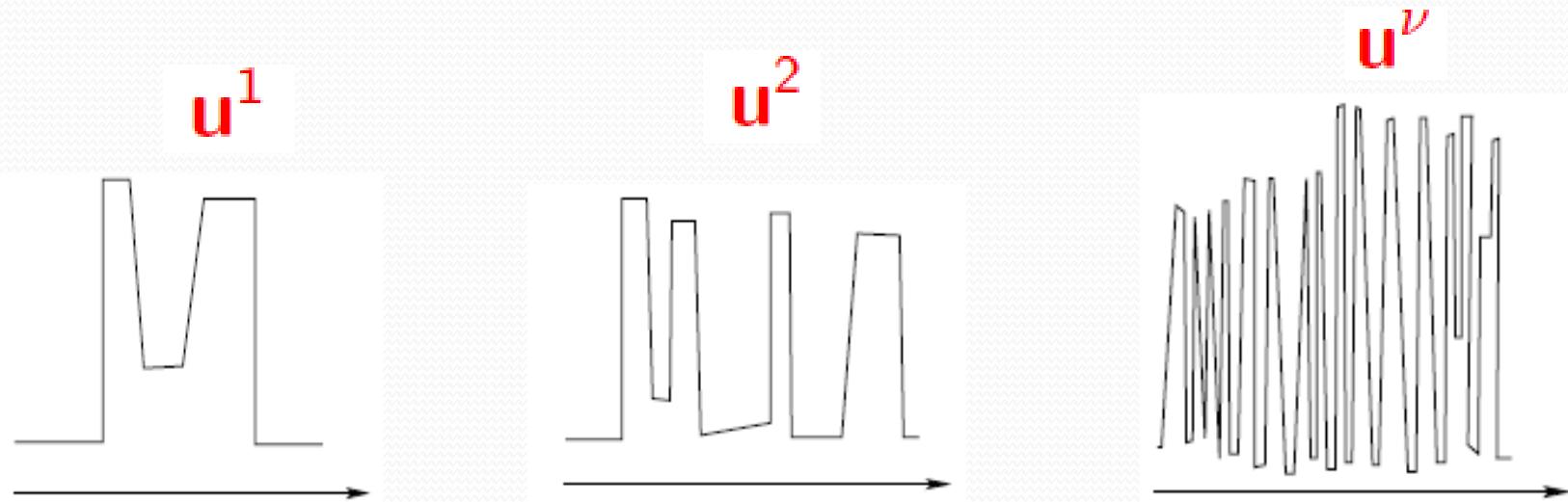
Choose the bases so that

$$\mathbf{l}_i \cdot \mathbf{r}_j = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Global in Time Solutions to the Cauchy Problem

$$\mathbf{u}_t + \mathbf{f}(\mathbf{u})_x = 0, \quad \mathbf{u}(0, x) = \mathbf{u}(x)$$

- Construct a sequence of approximate solutions $\{\mathbf{u}^\nu\}_{\nu \geq 1}$
- Show that (a subsequence) converges: $\mathbf{u}^\nu \rightarrow \mathbf{u}$ in L^1_{loc}
- Show that the limit \mathbf{u} is an entropy solution.



Need: a-priori bound on the total variation (J. Glimm, 1965)

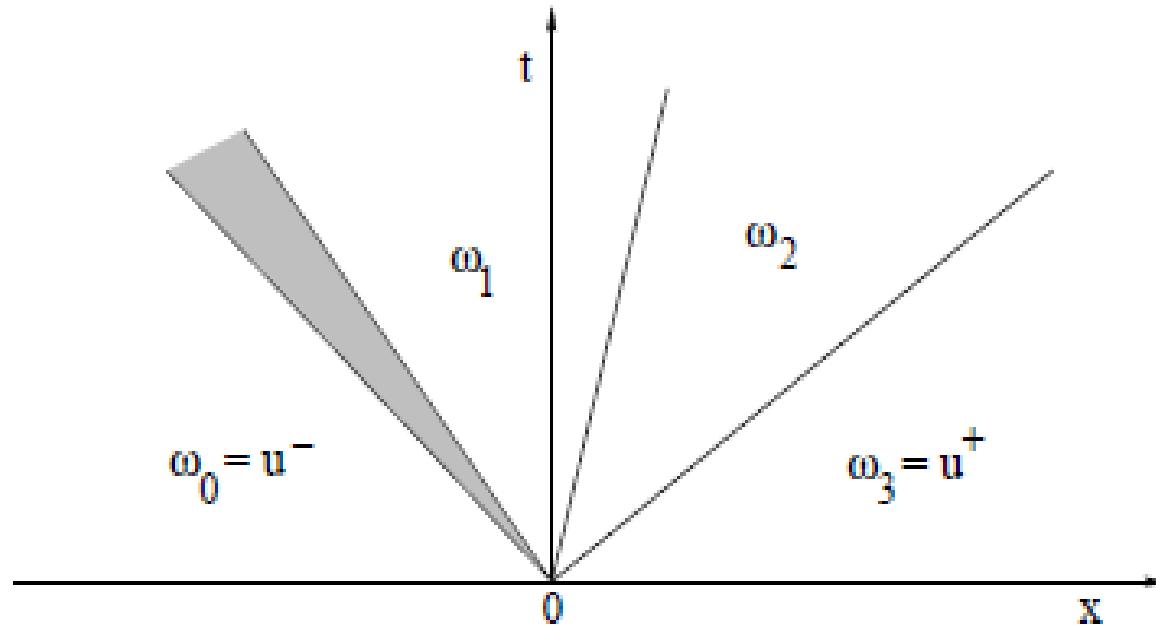
Building Block: The Riemann Problem

$$\mathbf{u}_t + \mathbf{f}(\mathbf{u})_x = 0, \quad \mathbf{u}(0, x) = \begin{cases} \mathbf{u}^- & x < 0 \\ \mathbf{u}^+ & x > 0 \end{cases}$$

- B. Riemann 1860: 2×2 Isentropic Euler equations
- P. Lax 1957: $m \times m$ systems (+ special assumptions)
- T.-P. Liu 1975: $m \times m$ systems (generic case)

*The Riemann solutions are also the vanishing viscosity limits for general hyperbolic systems, possibly non-conservative

Solution to the Riemann problem

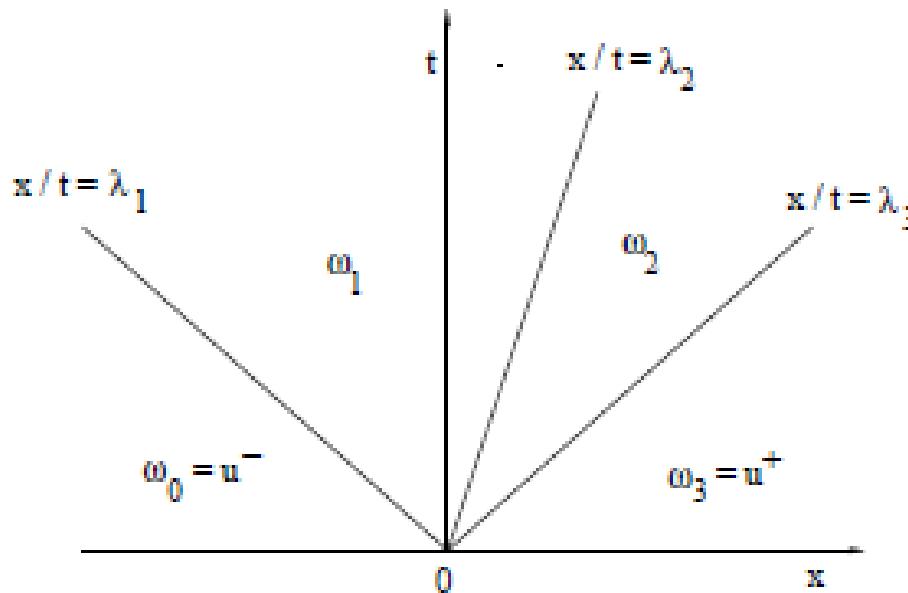


- is invariant w.r.t. rescaling symmetry: $u^\theta(t, x) \doteq u(\theta t, \theta x)$ $\theta > 0$
- describes local behavior of BV solutions near each point (t_0, x_0)
- describes large-time asymptotics as $t \rightarrow +\infty$ (for small total variation)

Riemann Problem for Linear Systems

$$u_t + A u_x = 0$$

$$u(0, x) = \begin{cases} u^- & \text{if } x < 0 \\ u^+ & \text{if } x > 0 \end{cases}$$



$$u^+ - u^- = \sum_{j=1}^n c_j r_j \quad (\text{sum of eigenvectors of } A)$$

$$\text{intermediate states : } \omega_i \doteq u^- + \sum_{j \leq i} c_j r_j$$

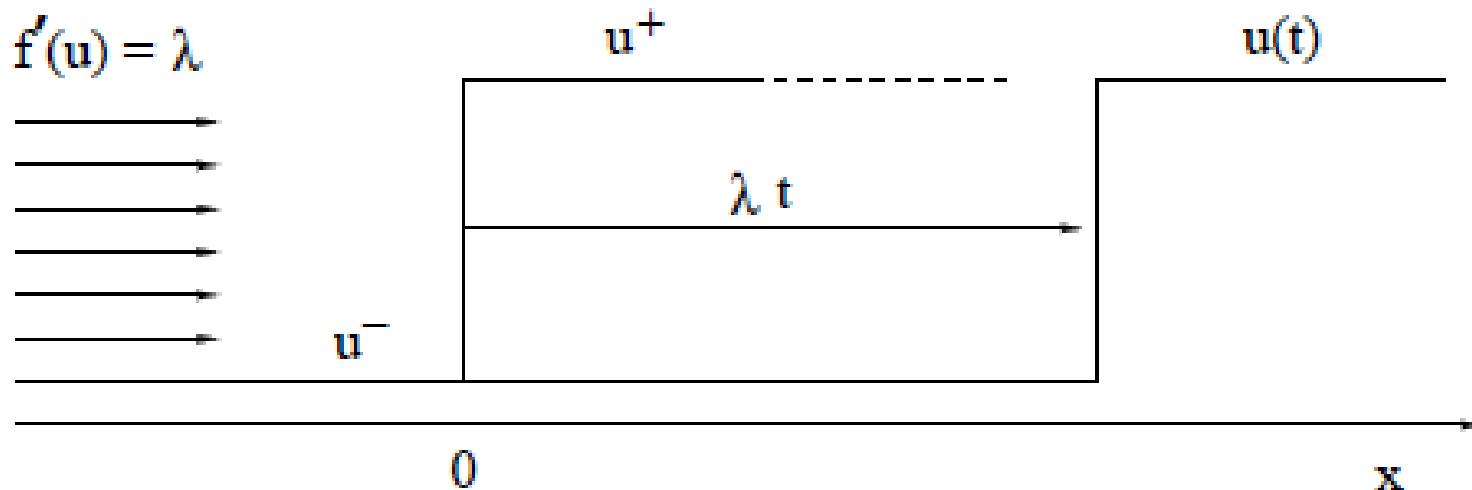
i-th jump: $\omega_i - \omega_{i-1} = c_i r_i$ travels with speed λ_i

Scalar Conservation Law

$$u_t + f(u)_x = 0 \quad u \in \mathbb{R}$$

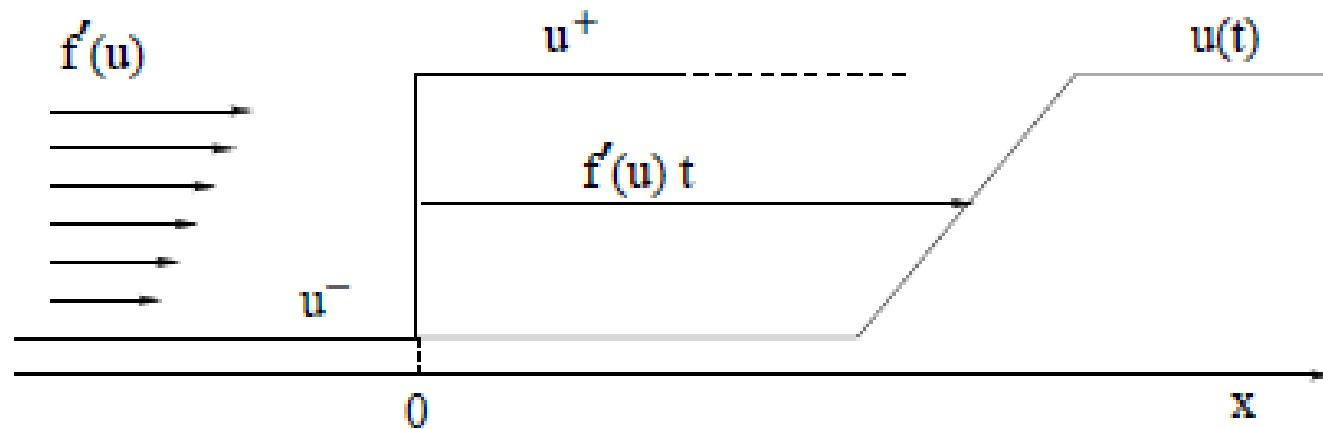
CASE 1: Linear flux: $f(u) = \lambda u$.

Jump travels with speed λ (contact discontinuity)

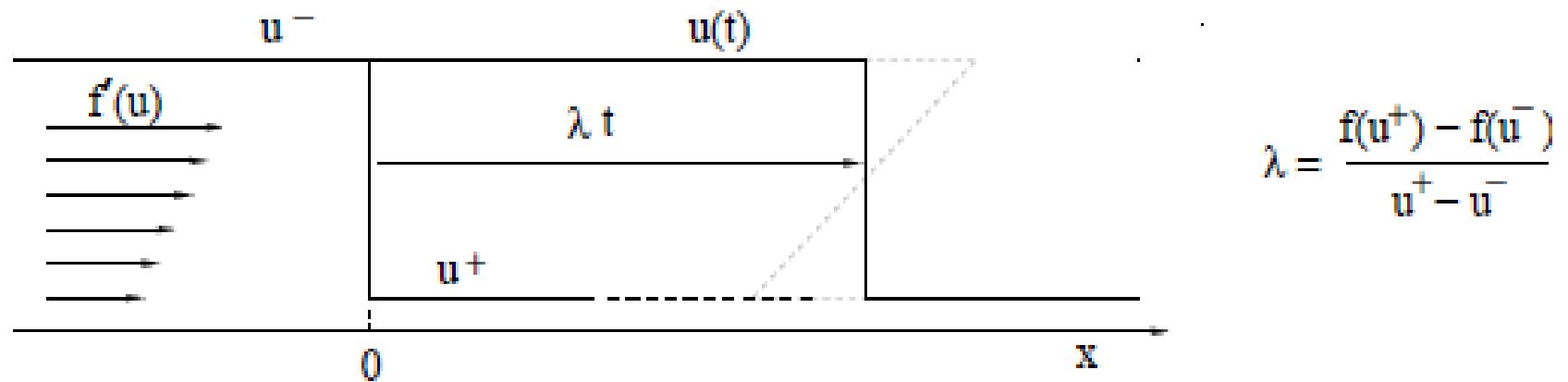


CASE 2: the flux f is convex, so that $u \mapsto f'(u)$ is increasing.

$u^+ > u^- \implies$ centered rarefaction wave



$u^+ < u^- \implies$ stable shock



A class of nonlinear hyperbolic systems

$$u_t + f(u)_x = 0$$

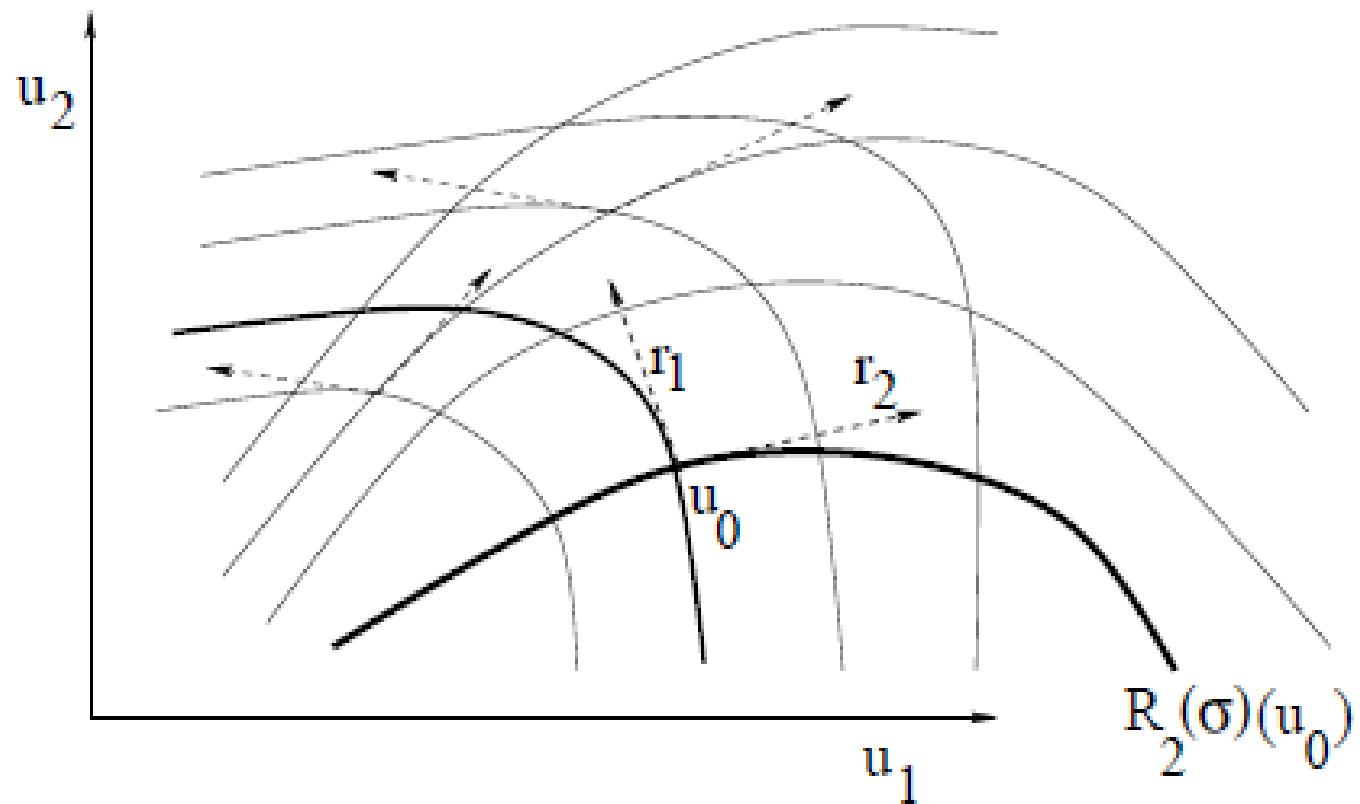
$$A(u) = Df(u) \quad A(u)r_i(u) = \lambda_i(u)r_i(u)$$

Assumption (H) (P.Lax, 1957): Each i -th characteristic field is

- either **genuinely nonlinear**, so that $\nabla \lambda_i \cdot r_i > 0$ for all u
- or **linearly degenerate**, so that $\nabla \lambda_i \cdot r_i = 0$ for all u

genuinely nonlinear \Rightarrow characteristic speed $\lambda_i(u)$ is strictly increasing along integral curves of the eigenvectors r_i

linearly degenerate \Rightarrow characteristic speed $\lambda_i(u)$ is constant along integral curves of the eigenvectors r_i



Shock and Rarefaction curves

$$u_t + f(u)_x = 0 \quad A(u) = Df(u)$$

i-rarefaction curve through u_0 : $\sigma \mapsto R_i(\sigma)(u_0)$

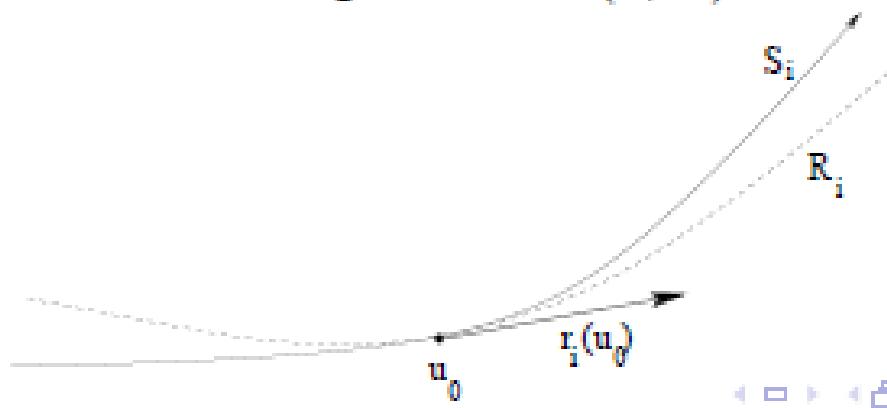
= integral curve of the field of eigenvectors r_i through u_0

$$\frac{du}{d\sigma} = r_i(u), \quad u(0) = u_0$$

i-shock curve through u_0 : $\sigma \mapsto S_i(\sigma)(u_0)$

= set of points u connected to u_0 by an i -shock, so that

$u - u_0$ is an i-eigenvector of the averaged matrix $A(u, u_0)$



Elementary waves

$$u_t + f(u)_x = 0 \quad u(0, x) = \begin{cases} u^- & \text{if } x < 0 \\ u^+ & \text{if } x > 0 \end{cases}$$

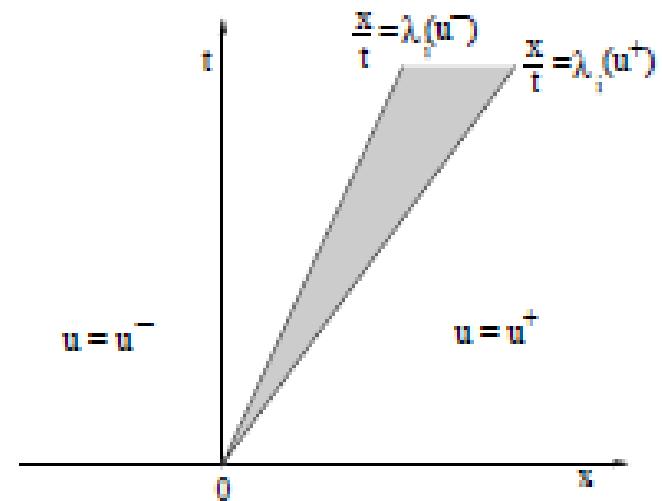
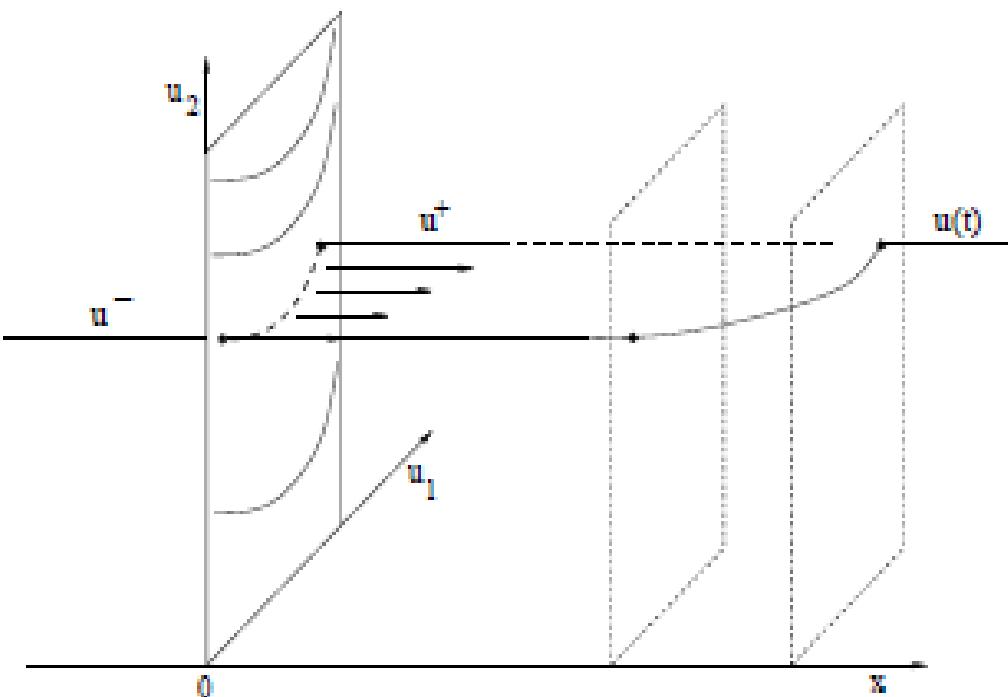
CASE 1 (Centered rarefaction wave). Let the i -th field be genuinely nonlinear.

If $u^+ = R_i(\sigma)(u^-)$ for some $\sigma > 0$, then

$$u(t, x) = \begin{cases} u^- & \text{if } x < t\lambda_i(u^-), \\ R_i(s)(u^-) & \text{if } x = t\lambda_i(s) \quad s \in [0, \sigma] \\ u^+ & \text{if } x > t\lambda_i(u^+) \end{cases}$$

is a weak solution of the Riemann problem

A centered rarefaction wave



CASE 2 (Shock or contact discontinuity). Assume that

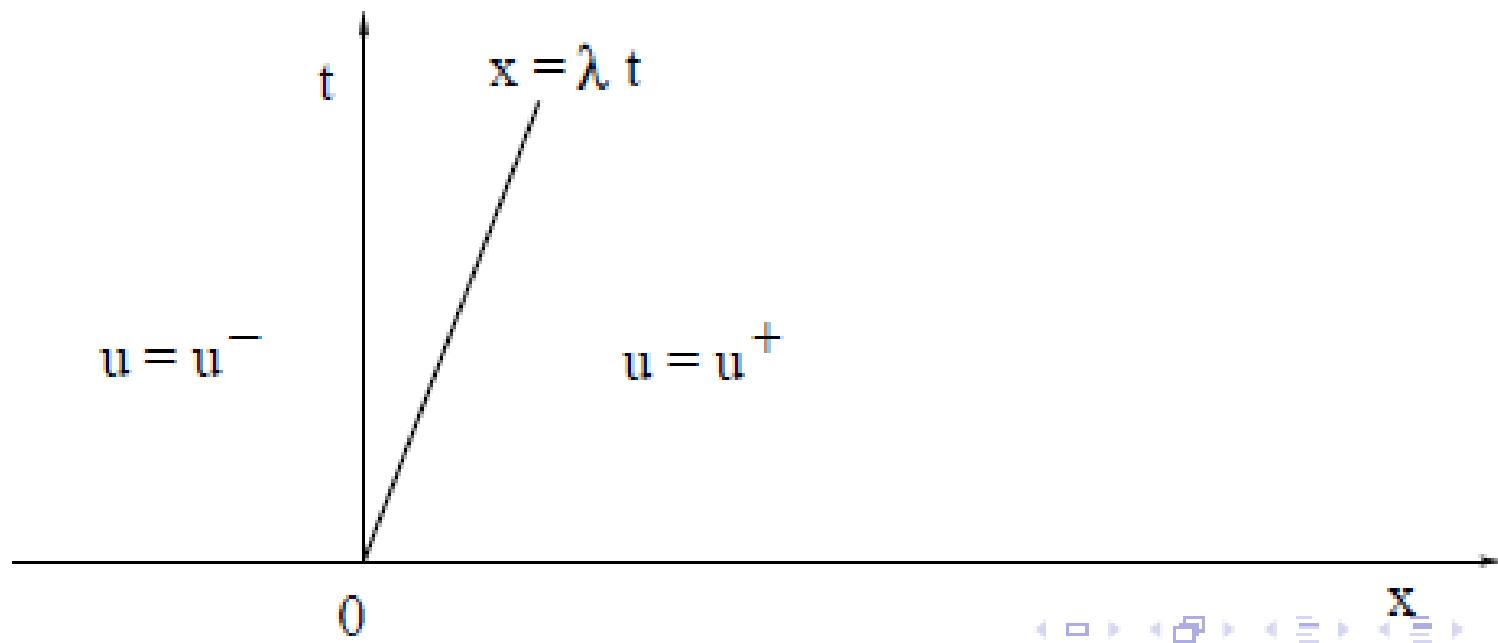
$u^+ = S_i(\sigma)(u^-)$ for some i, σ . Let $\lambda = \lambda_i(u^-, u^+)$ be the shock speed.

Then the function

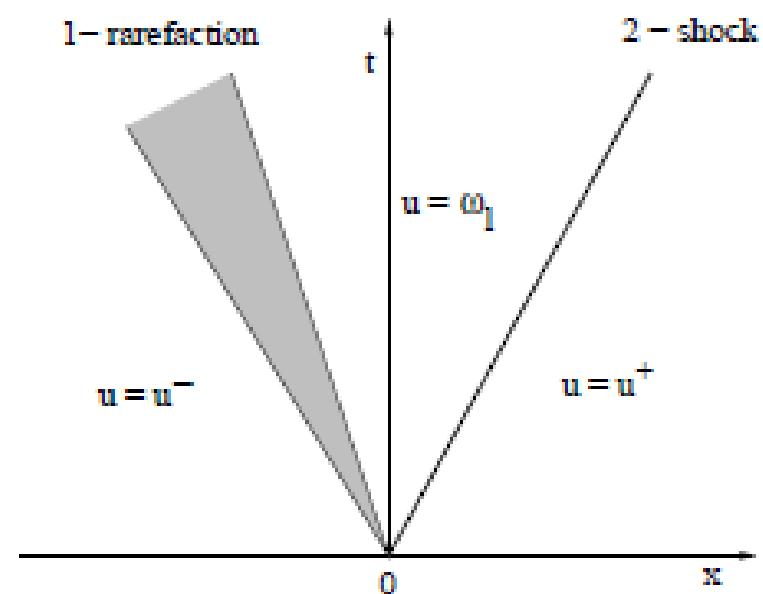
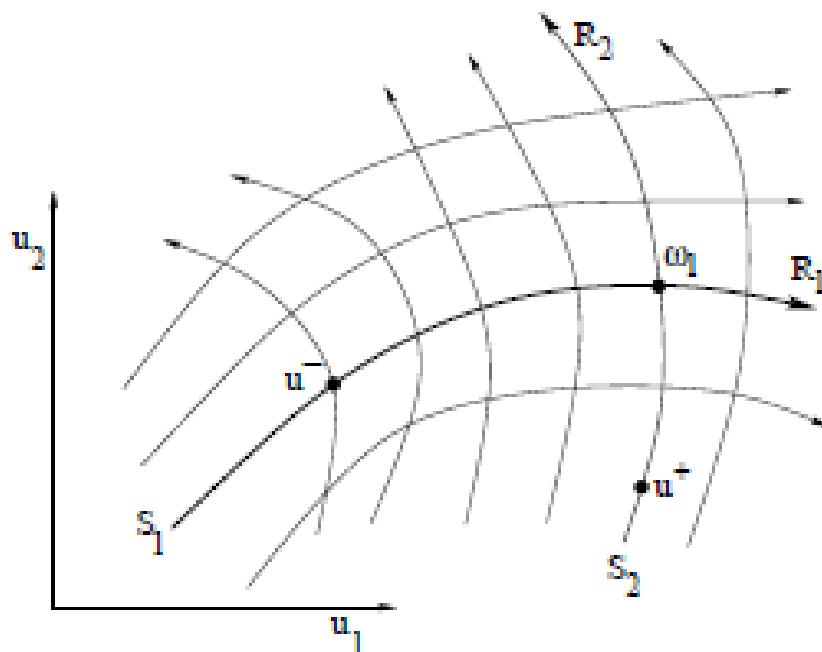
$$u(t, x) = \begin{cases} u^- & \text{if } x < \lambda t, \\ u^+ & \text{if } x > \lambda t, \end{cases}$$

is a weak solution to the Riemann problem.

In the genuinely nonlinear case, this shock is admissible (i.e., it satisfies the Lax condition and the Liu condition) iff $\sigma < 0$.



Solution to a 2×2 Riemann problem



Solution of the general Riemann problem (P. Lax, 1957)

$$u_t + f(u)_x = 0 \quad u(0, x) = \begin{cases} u^- & \text{if } x < 0 \\ u^+ & \text{if } x > 0 \end{cases}$$

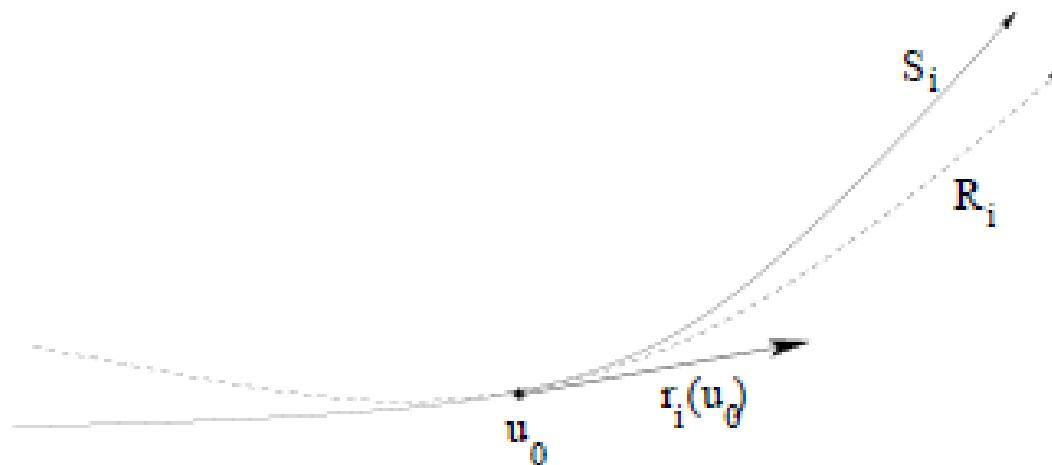
Problem: Find states $\omega_0, \omega_1, \dots, \omega_m$ such that

$$\omega_0 = \mathbf{u}^- \quad \omega_m = \mathbf{u}^+$$

and every couple ω_{i-1}, ω_i are connected by an elementary wave (shock or rarefaction)

$$\left\{ \begin{array}{ll} \text{either } \omega_i = R_i(\sigma_i)(\omega_{i-1}) & \sigma_i \geq 0 \\ \text{or } \omega_i = S_i(\sigma_i)(\omega_{i-1}) & \sigma_i < 0 \end{array} \right.$$

define: $\Psi_i(\sigma)(u) = \begin{cases} R_i(\sigma)(u) & \text{if } \sigma \geq 0 \\ S_i(\sigma)(u) & \text{if } \sigma < 0 \end{cases}$



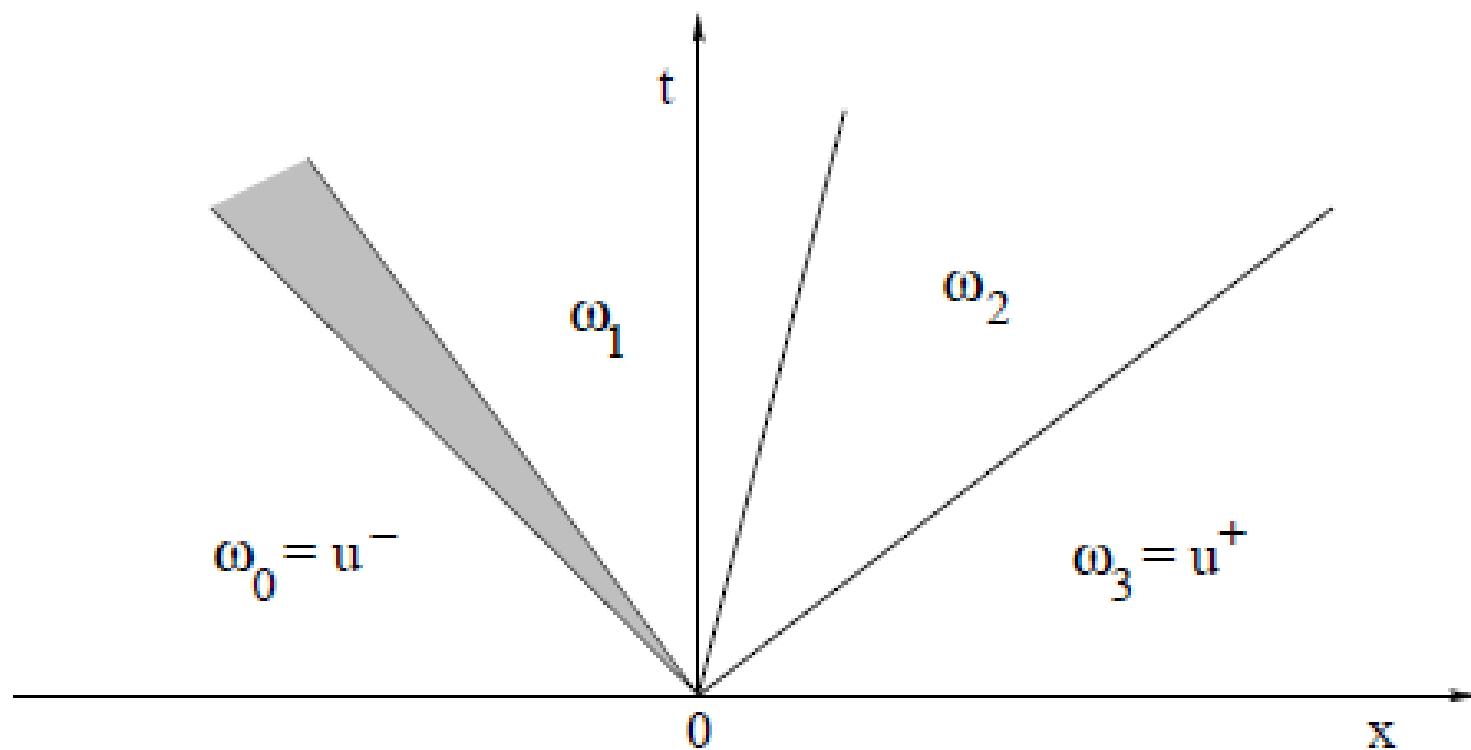
$$(\sigma_1, \sigma_2, \dots, \sigma_n) \mapsto \Psi_n(\sigma_n) \circ \dots \circ \Psi_2(\sigma_2) \circ \Psi_1(\sigma_1)(u^-)$$

Jacobian matrix at the origin: $J \doteq \left(\begin{array}{c|c|c|c} r_1(u^-) & r_2(u^-) & \cdots & r_n(u^-) \end{array} \right)$
 always has full rank

If $|u^+ - u^-|$ is small, then the implicit function theorem yields existence and uniqueness of the intermediate states $\omega_0, \omega_1, \dots, \omega_n$

General solution of the Riemann problem

Concatenation of elementary waves (shocks, rarefactions, or contact discontinuities)



Global solution to the Cauchy problem

$$u_t + f(u)_x = 0, \quad u(0, x) = \bar{u}(x)$$

Theorem (Glimm, 1965).

Assume:

- system is strictly hyperbolic
- each characteristic field is either linearly degenerate or genuinely nonlinear

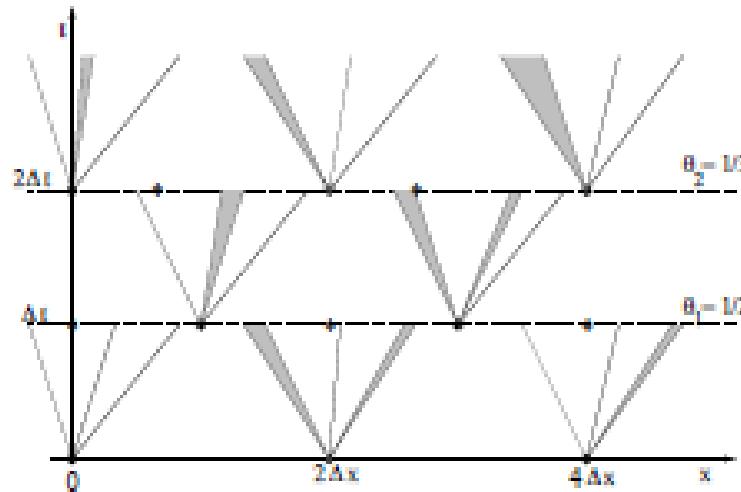
Then there exists a constant $\delta > 0$ such that, for every initial condition $\bar{u} \in L^1(\mathbb{R}; \mathbb{R}^n)$ with

$$\text{Tot.Var.}(\bar{u}) \leq \delta,$$

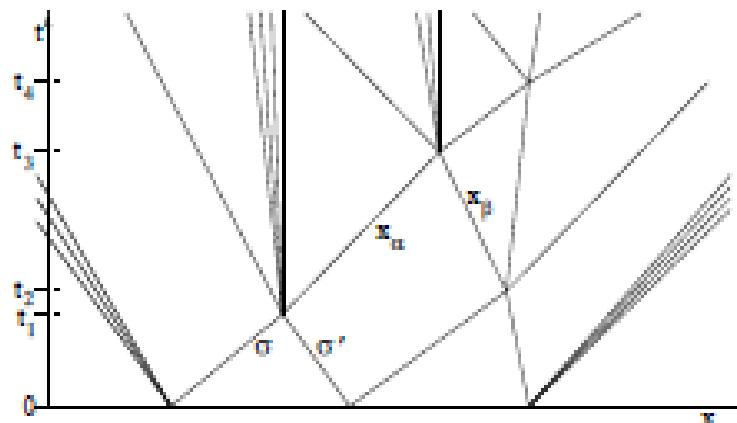
the Cauchy problem has an entropy admissible weak solution $u = u(t, x)$ defined for all $t \geq 0$.

Construction of a sequence of approximate solutions by piecing together solutions of Riemann problems

- on a fixed grid in t - x plane (Glimm scheme)

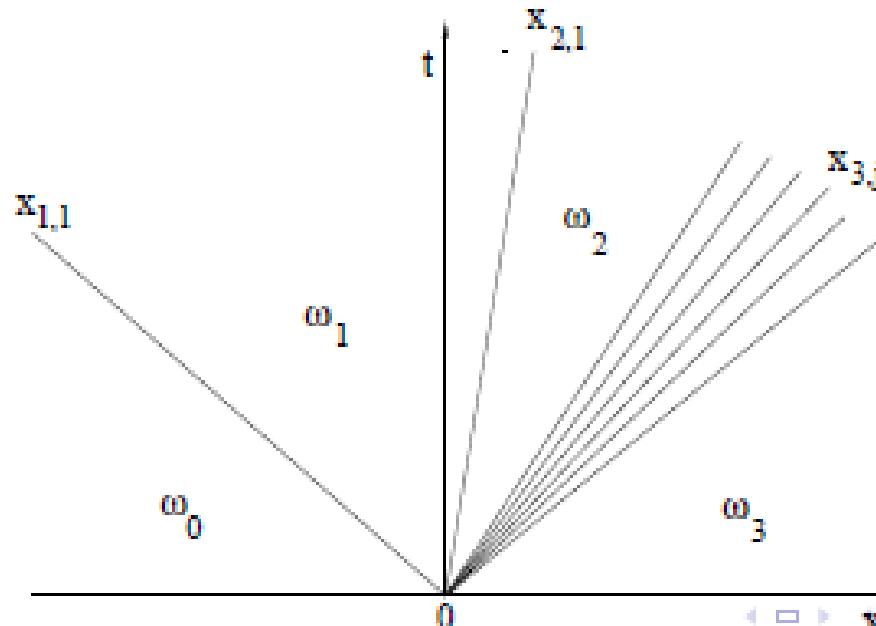
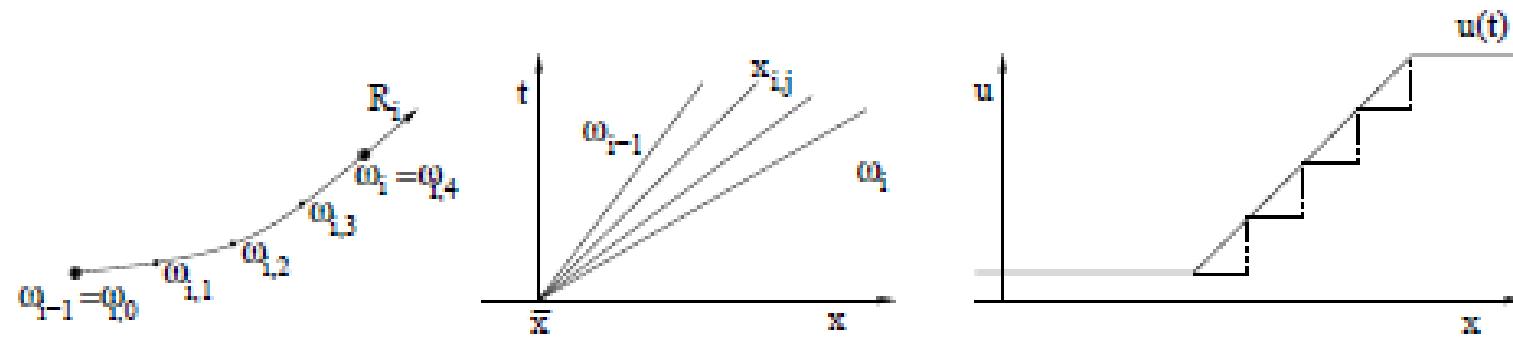


- at points where fronts interact (front tracking)

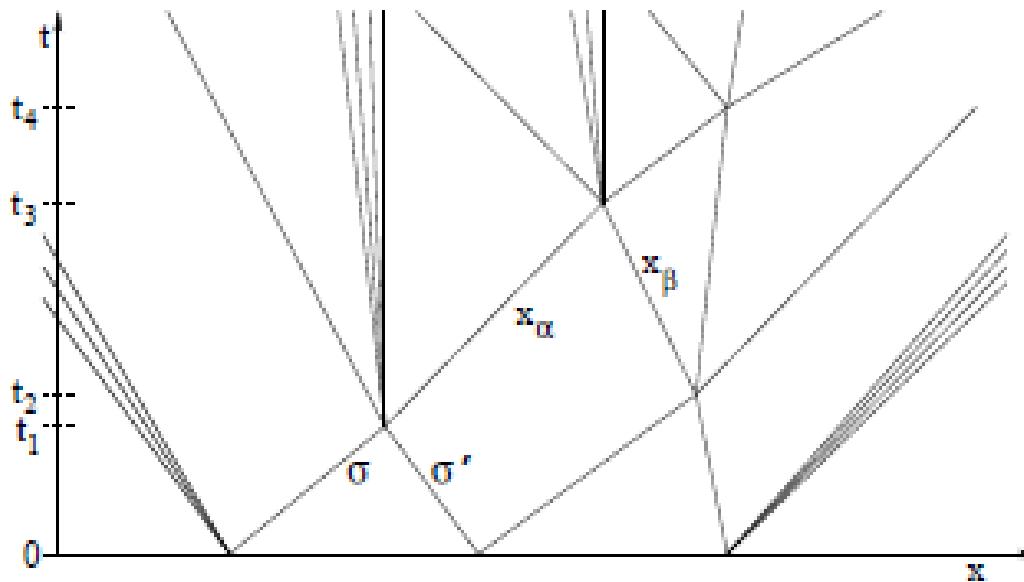


Piecewise constant approximate solution to a Riemann problem

replace centered rarefaction waves with piecewise constant rarefaction fans



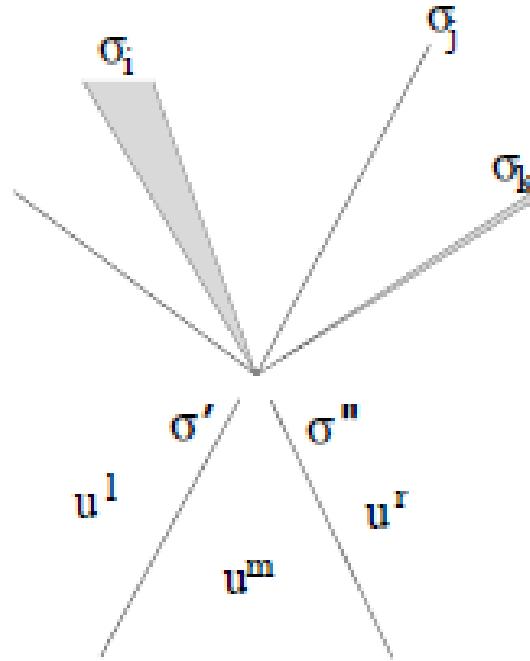
Front Tracking Approximations



- Approximate the initial data \bar{u} with a piecewise constant function
- Construct a piecewise constant approximate solution to each Riemann problem at $t = 0$
- at each time t_j where two fronts interact, construct a piecewise constant approximate solution to the new Riemann problem ...
- NEED TO CHECK: $\left\{ \begin{array}{l} \text{- total variation remains small} \\ \text{- number of wave fronts remains finite} \end{array} \right.$

Interaction estimates

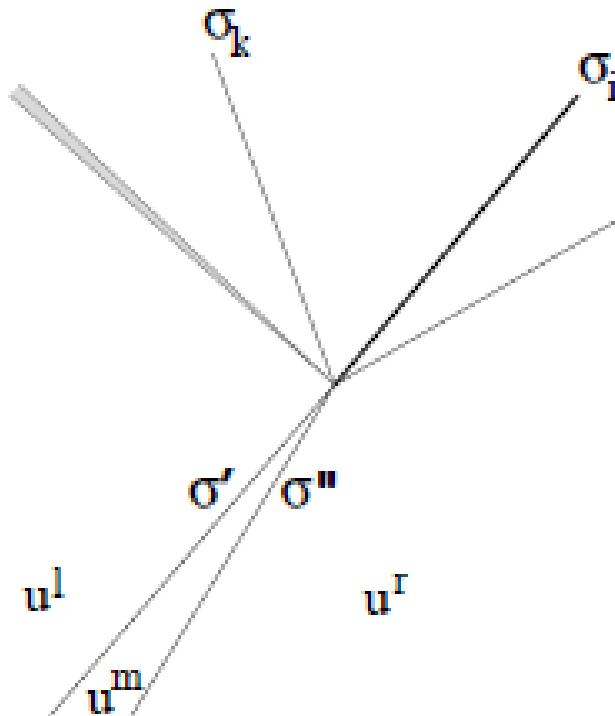
GOAL: estimate the strengths of the waves in the solution of a Riemann problem, depending on the strengths of the two interacting waves σ' , σ''



Incoming: a j -wave of strength σ' and an i -wave of strength σ''

Outgoing: waves of strengths $\sigma_1, \dots, \sigma_m$. Then

$$|\sigma_i - \sigma''| + |\sigma_j - \sigma'| + \sum_{k \neq i,j} |\sigma_k| = O(1) \cdot |\sigma' \sigma''|$$



Incoming: two i -waves of strengths σ' and σ''

Outgoing: waves of strengths $\sigma_1, \dots, \sigma_m$. Then

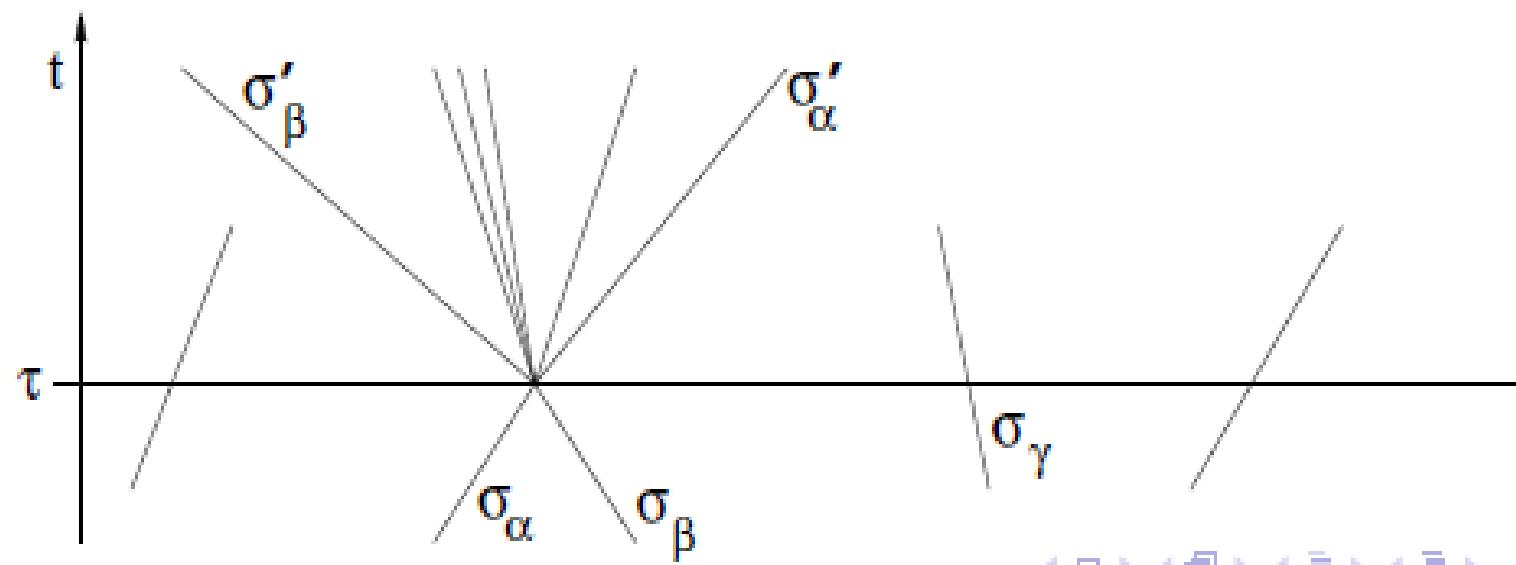
$$|\sigma_i - \sigma' - \sigma''| + \sum_{k \neq i} |\sigma_k| = \mathcal{O}(1) \cdot |\sigma' \sigma''| (|\sigma'| + |\sigma''|)$$

Glimm functionals

Total strength of waves: $V(t) \doteq \sum_{\alpha} |\sigma_{\alpha}|$

Wave interaction potential: $Q(t) \doteq \sum_{(\alpha, \beta) \in A} |\sigma_{\alpha} \sigma_{\beta}|$

$A \doteq$ couples of *approaching* wave fronts



Changes in V, Q at time τ when the fronts $\sigma_\alpha, \sigma_\beta$ interact:

$$\Delta V(\tau) = \mathcal{O}(1)|\sigma_\alpha \sigma_\beta|$$

$$\Delta Q(\tau) = -|\sigma_\alpha \sigma_\beta| + \mathcal{O}(1) \cdot V(\tau-) |\sigma_\alpha \sigma_\beta|$$

Choosing a constant C_0 large enough, the map

$$t \mapsto V(t) + C_0 Q(t)$$

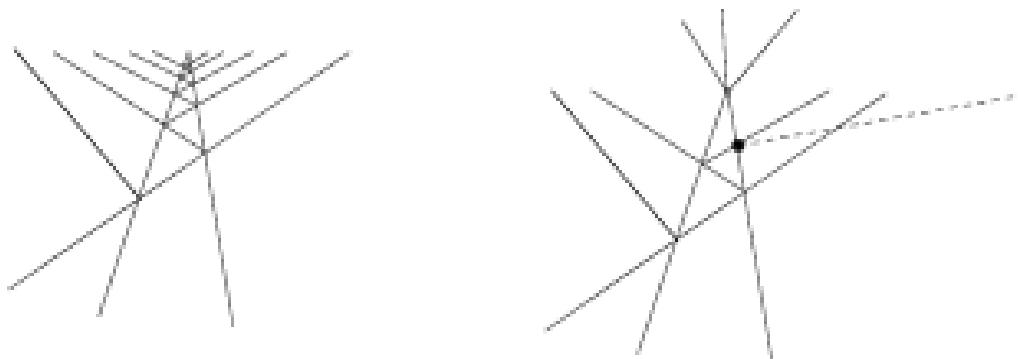
is nonincreasing, as long as V remains small

Total variation initially small \implies global BV bounds

$$\text{Tot.Var.}\{u(t, \cdot)\} \leq V(t) \leq V(0) + C_0 Q(0)$$

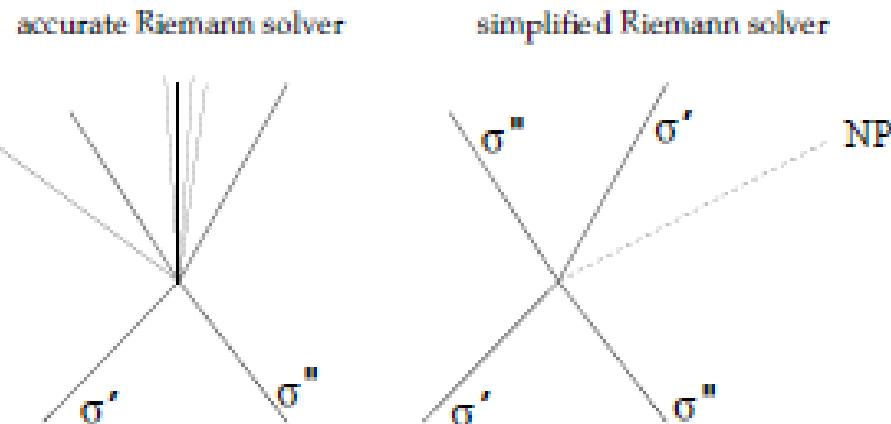
Front tracking approximations can be constructed for all $t \geq 0$

Keeping finite the number of wave fronts



At each interaction point, the **Accurate Riemann Solver** yields a solution, possibly introducing several new fronts

The total number of fronts can become infinite in finite time



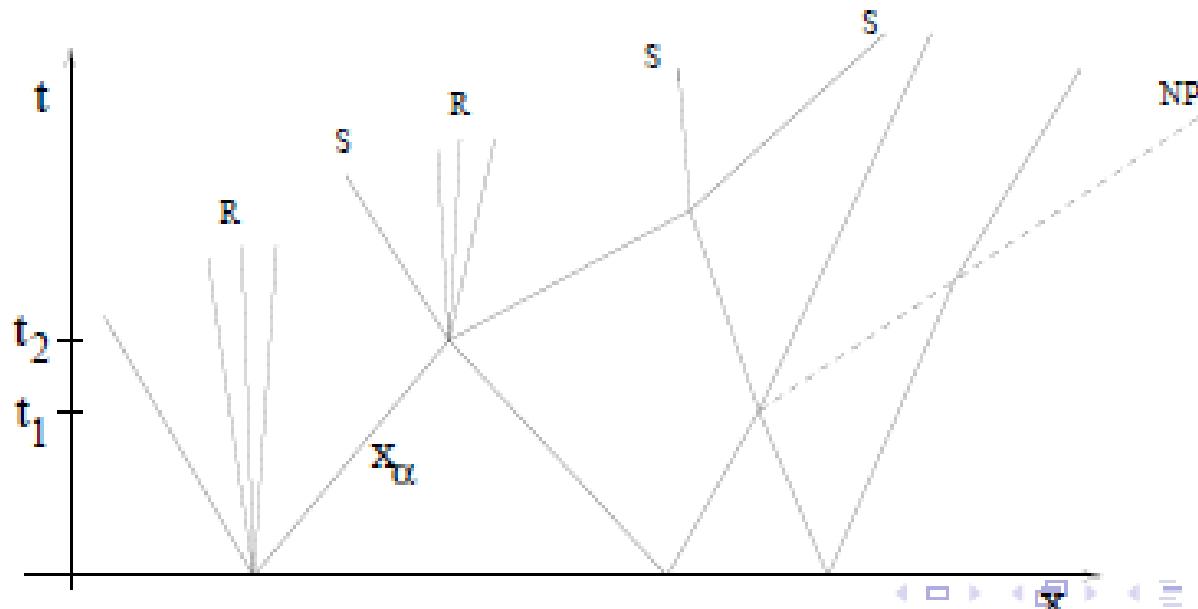
Need: a **Simplified Riemann Solver**, producing only one "*non-physical*" front

A sequence of approximate solutions

$$u_t + f(u)_x = 0 \quad u(0, x) = \bar{u}(x)$$

$(u_\nu)_{\nu \geq 1}$ sequence of approximate front tracking solutions

- initial data satisfy $\|u_\nu(0, \cdot) - \bar{u}\|_{L^1} \leq \varepsilon_\nu \rightarrow 0$
- all shock fronts in u_ν are entropy-admissible
- each rarefaction front in u_ν has strength $\leq \varepsilon_\nu$
- at each time $t \geq 0$, the total strength of all non-physical fronts in $u_\nu(t, \cdot)$ is $\leq \varepsilon_\nu$



Existence of a convergent subsequence

$$\text{Tot.Var.}\{u_\nu(t, \cdot)\} \leq C$$

$$\begin{aligned}\|u_\nu(t) - u_\nu(s)\|_{L^1} &\leq (t-s) \cdot [\text{total strength of all wave fronts}] \cdot [\text{maximum speed}] \\ &\leq L \cdot (t-s)\end{aligned}$$

Helly's compactness theorem \implies a subsequence converges

$$u_\nu \rightarrow u \quad \text{in } L^1_{loc}$$

Claim: $u = \lim_{\nu \rightarrow \infty} u_\nu$ is a weak solution

$$\iint \left\{ \phi_t u + \phi_x f(u) \right\} dxdt = 0 \quad \phi \in \mathcal{C}_c^1([0, \infty[\times \mathbb{R})$$

Need to show:

$$\lim_{\nu \rightarrow \infty} \iint \left\{ \phi_t u_\nu + \phi_x f(u_\nu) \right\} dxdt = 0$$

$$\int_0^\infty \int_{-\infty}^\infty \left\{ \phi_t(t, x) u_\nu(t, x) + \phi_x(t, x) f(u_\nu(t, x)) \right\} dx dt \\ = \sum_j \int_{\partial \Gamma_j} \Phi_\nu \cdot \mathbf{n} \, d\sigma$$

$$\limsup_{\nu \rightarrow \infty} \left| \sum_j \int_{\partial \Gamma_j} \Phi_\nu \cdot \mathbf{n} \, d\sigma \right| \\ \leq \limsup_{\nu \rightarrow \infty} \left| \sum_{\alpha \in \mathcal{S} \cup \mathcal{R} \cup \mathcal{NP}} \left[\dot{x}_\alpha(t) \cdot \Delta u_\nu(t, x_\alpha) - \Delta f(u_\nu(t, x_\alpha)) \right] \phi(t, x_\alpha(t)) \right| \\ \leq \left(\max_{t, x} |\phi(t, x)| \right) \cdot \limsup_{\nu \rightarrow \infty} \left\{ \mathcal{O}(1) \cdot \sum_{\alpha \in \mathcal{R}} \varepsilon_\nu |\sigma_\alpha| + \mathcal{O}(1) \cdot \sum_{\alpha \in \mathcal{NP}} |\sigma_\alpha| \right\} \\ = 0$$

The Glimm scheme

$$u_t + f(u)_x = 0 \quad u(0, x) = \bar{u}(x)$$

Assume: all characteristic speeds satisfy $\lambda_i(u) \in [0, 1]$

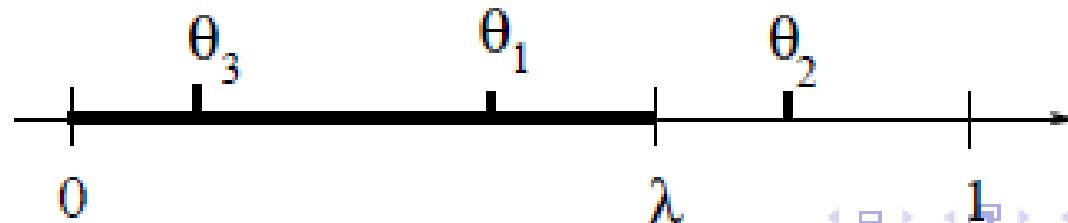
This is not restrictive. If $\lambda_i(u) \in [-M, M]$, simply change coordinates:

$$y = x + Mt, \quad \tau = 2Mt$$

Choose:

- a grid in the t - x plane with step size $\Delta t = \Delta x$
- a sequence of numbers $\theta_1, \theta_2, \theta_3, \dots$ uniformly distributed over $[0, 1]$

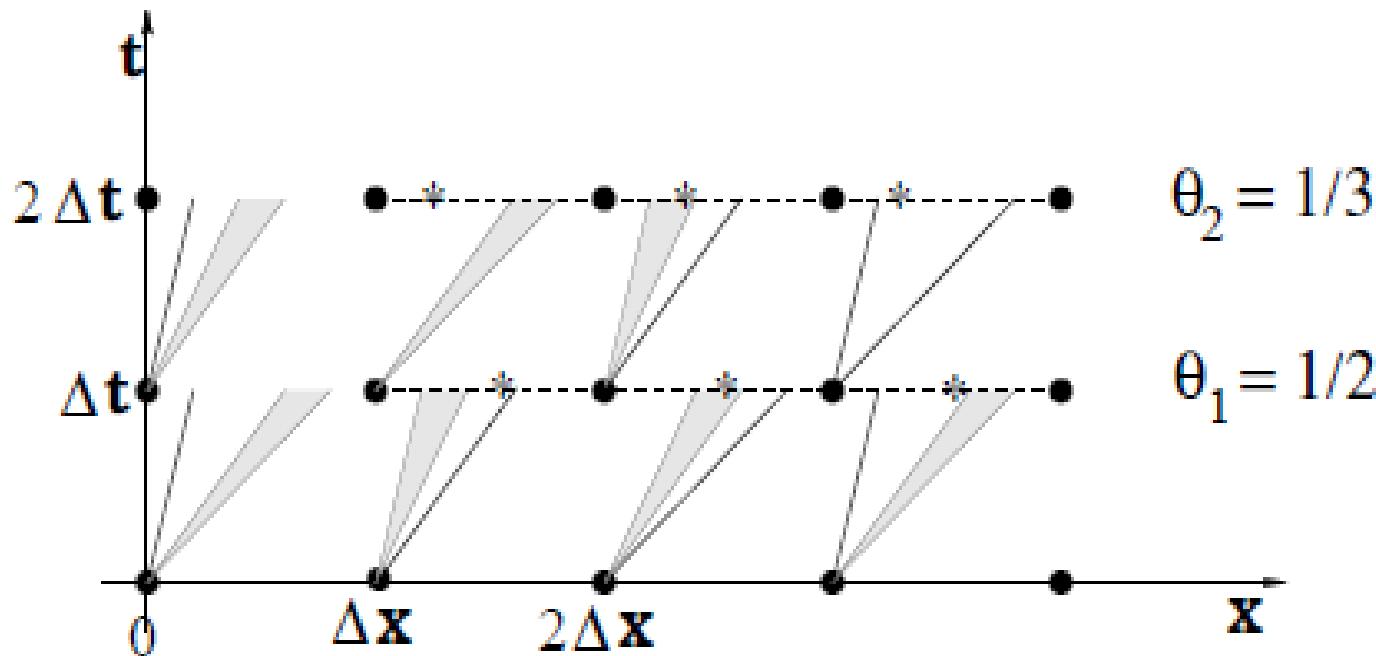
$$\lim_{N \rightarrow \infty} \frac{\#\{j : 1 \leq j \leq N, \theta_j \in [0, \lambda]\}}{N} = \lambda \quad \text{for each } \lambda \in [0, 1].$$



Glimm approximations

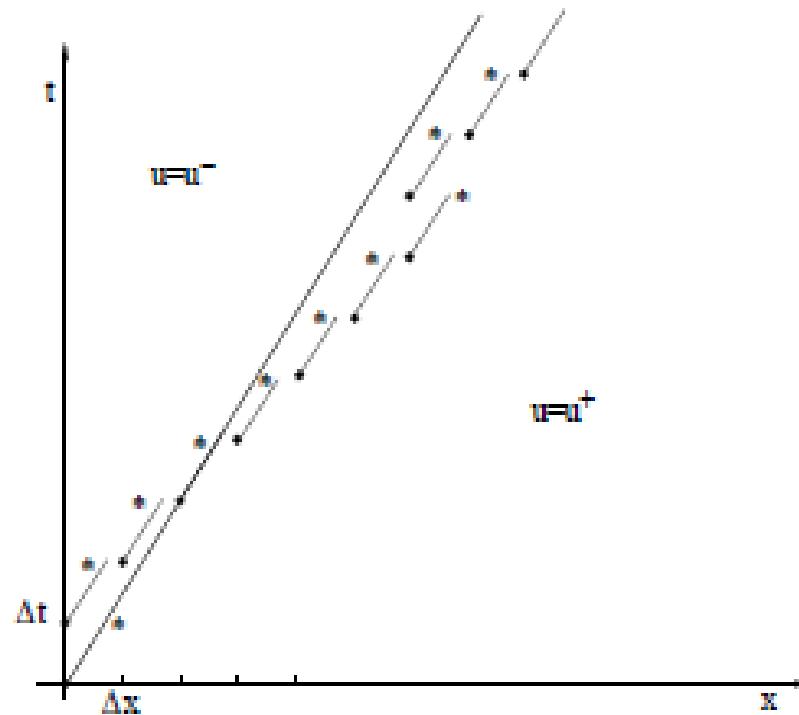
Grid points : $x_j = j \cdot \Delta x$, $t_k = k \cdot \Delta t$

- for each $k \geq 0$, $u(t_k, \cdot)$ is piecewise constant, with jumps at the points x_j . The Riemann problems are solved exactly, for $t_k \leq t < t_{k+1}$
- at time t_{k+1} the solution is again approximated by a piecewise constant function, by a sampling technique



Example: Glimm's scheme applied to a solution containing a single shock

$$U(t, x) = \begin{cases} u^+ & \text{if } x > \lambda t \\ u^- & \text{if } x < \lambda t \end{cases}$$



Fix $T > 0$, take $\Delta x = \Delta t = T/N$

$$\begin{aligned} x(T) &= \#\{j : 1 \leq j \leq N, \theta_j \in [0, \lambda]\} \cdot \Delta t \\ &= \frac{\#\{j : 1 \leq j \leq N, \theta_j \in [0, \lambda]\}}{N} \cdot T \rightarrow \lambda T \quad \text{as } N \rightarrow \infty \end{aligned}$$

Rate of convergence for Glimm approximations

Random sampling at points determined by the equidistributed sequence $(\theta_k)_{k \geq 1}$

$$\lim_{N \rightarrow \infty} \frac{\#\{j : 1 \leq j \leq N, \theta_j \in [0, \lambda]\}}{N} = \lambda \quad \text{for each } \lambda \in [0, 1].$$

Need fast convergence to uniform distribution. Achieved by choosing:

$$\theta_1 = 0.1, \dots, \theta_{759} = 0.957, \dots, \theta_{39022} = 0.22093, \dots$$

Convergence rate: $\lim_{\Delta x \rightarrow 0} \frac{\|u^{\text{Glimm}}(T, \cdot) - u^{\text{exact}}(T, \cdot)\|_{L^1}}{\sqrt{\Delta x} \cdot |\ln \Delta x|} = 0$

(A.Bressan & A.Marson, 1998)

Bressan, A.: **Hyperbolic Systems of Conservation Laws.
The One-Dimensional Cauchy Problem.**

Oxford University Press: Oxford, 2000.

Dafermos, C: **Hyperbolic Conservation Laws in Continuum Physics**, 3rd Edition, Springer-Verlag: Berlin, 2010.

Functional Analytic Approaches for the Existence Theory:

- Compensated Compactness
- Weak Convergence Methods
- Geometric Measure Arguments
-

1. C. M. Dafermos: **Hyperbolic Conservation Laws in Continuum Physics**, Third edition. Springer-Verlag: Berlin, 2010.
2. B. Dacorogna: **Weak Continuity and Weak Lower Semicontinuity of Nonlinear Functionals**, Lecture Notes in Mathematics, Vol. 922, 1-120, Springer-Verlag, 1982.
3. L. C. Evans: **Weak Convergence Methods for Nonlinear Partial Differential Equations**. CBMS-RCSM, 74. AMS: Providence, RI, 1990
4. D. Serre, La compacité par compensation pour les systèmes hyperboliques non linéaires de deux équations à une dimension d'espace. *J. Math. Pures Appl.* (9) 65 (1986), 423–468.
5. **The references cited therein, especially more recent references.**

Young Measures

$K \subset \mathbb{R}^m$, $\Omega \subset \mathbb{R}^n$ bounded open

$u^k: \Omega \rightarrow \mathbb{R}^m$ measurable

$u^k(y) \in K$, a.e.

$\Rightarrow \exists \{\nu_y \in \text{Prob.}(\mathbb{R}^m)\}_{y \in \Omega}$ s.t.

- $\boxed{\text{Supp } \nu_y \subset \bar{K}}$ $\forall y \in \Omega$

- $\forall f \in C(\mathbb{R}^m; \mathbb{R})$, $\exists \{u^{k_j}\}_{j=1}^\infty \subset \{u^k\}$.

$$\begin{aligned} w^*-lim f(u^{k_j}) &= \langle \nu_y(\lambda), f(\lambda) \rangle \\ &= \int f(\lambda) d\nu_y(\lambda) \end{aligned}$$

- $u^{k_j} \xrightarrow{\quad} u$ a.e. $\iff \nu_y(\lambda) = \int_{u(y)}(\lambda)$

Dirac mass

* This theorem can be extended to more general cases.

Remarks

1. The deviation between the Weak and Strong convergence is measured by the spreading of the support of ν_y .

$$\begin{aligned} & \|f(w^*\text{-}\lim u^k) - w^*\text{-}\lim f(u^k)\|_{L^\infty} \\ & \leq C \sup_y (\text{diam}(\text{supp } \nu_y)) \end{aligned}$$

↑ for $f \in \text{Lip}(\mathbb{R}^m; \mathbb{R})$

$$\begin{aligned} & \|f(w^*\text{-}\lim u^k) - w^*\text{-}\lim f(u^k)\|_{L^\infty} \\ & = \|f(\langle \nu_y, \lambda \rangle) - \langle \nu_y, f(\lambda) \rangle\|_{L^\infty} \\ & = \|\langle \nu_y, f(\lambda) - f(\langle \nu_y, \lambda \rangle) \rangle\|_{L^\infty} \\ & \leq C \|\langle \nu_y, |\lambda - \langle \nu_y, \lambda \rangle| \rangle\|_{L^\infty} \\ & \leq C \sup_y (\text{diam}(\text{supp } \nu_y)). \end{aligned}$$

Remarks

2. The Young measure family $\{\nu_y\}_{y \in \Omega}$ can be thought of as the limiting probability distribution of the values of $\{u^k(y)\}$ near the point y as $k \rightarrow \infty$.

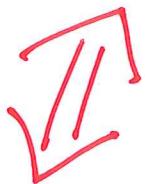
$\hookleftarrow \Omega \subset \mathbb{R}^n, y \in \Omega.$

$\hookrightarrow \exists \delta_0 > 0$ s.t. $B(y, \delta) \subset \Omega, 0 < \delta \leq \delta_0$

Define

$$\langle \nu_{y, \delta}^k, \phi \rangle = \frac{1}{|B(y, \delta)|} \int_{B(y, \delta)} \phi(u^k(x)) dx$$

$\forall \phi \in C_c(\mathbb{R}^m; \mathbb{R})$



$$\nu_{y, \delta}^k \stackrel{\Delta}{=} \frac{1}{|B(y, \delta)|} \delta_{u^k(x)} dx$$

\hookleftarrow

$$\boxed{\nu_y(\lambda) = \lim_{\delta \rightarrow 0} \lim_{k \rightarrow \infty} \nu_{y, \delta}^k}$$

Weak Continuity of

2x2 Determinants

$\Omega \subset \mathbb{R}_+ \times \mathbb{R}$ bounded open

$U^k: \Omega \rightarrow \mathbb{R}^4$ measurable

$$\left\{ \begin{array}{l} \text{w-lim}_{k \rightarrow \infty} U^k = U \quad \text{in } L^2(\Omega; \mathbb{R}^4) \\ \left\{ \begin{array}{l} \frac{\partial U_1^k}{\partial t} + \frac{\partial U_2^k}{\partial x} \\ \frac{\partial U_3^k}{\partial t} + \frac{\partial U_4^k}{\partial x} \end{array} \right. \end{array} \right.$$

Compact in $H_{loc}^1(\Omega)$

\Rightarrow

$$\begin{vmatrix} U_1^k & U_2^k \\ U_3^k & U_4^k \end{vmatrix} \longrightarrow \begin{vmatrix} U_1 & U_2 \\ U_3 & U_4 \end{vmatrix} D'$$

Subsequently

Another Form

$$U^k = (U_1^k, U_2^k) \in L^2(\Omega; \mathbb{R}^2)$$

$$W^k = (W_1^k, W_2^k) \in L^2(\Omega; \mathbb{R}^2)$$

$$\left\{ \begin{array}{l} \text{w-lim}_{k \rightarrow \infty} (U^k, W^k) = (U, W), \quad L^2(\Omega) \\ \left\{ \begin{array}{l} \text{div } U^k \\ \text{curl } W^k \end{array} \right. \quad \text{compact in } H_{loc}^1(\Omega) \end{array} \right.$$

$\Rightarrow U^k \cdot W^k \longrightarrow U \cdot W \quad D'$

Div-Curl Lemma

$\Omega \subset \mathbb{R}^n$ open, bounded

$$p, q > 1, \quad \frac{1}{p} + \frac{1}{q} = 1$$

$$v^k \in L^p(\Omega; \mathbb{R}^n)$$

$$w^k \in L^q(\Omega; \mathbb{R}^n)$$

$$\begin{cases} v^k \rightharpoonup v \text{ weakly in } L^p(\Omega; \mathbb{R}^n) \\ w^k \rightharpoonup w \text{ weakly in } L^q(\Omega; \mathbb{R}^n). \end{cases}$$

$$\begin{cases} \operatorname{div} v^k \text{ compact in } W_{loc}^{-1, p}(\Omega; \mathbb{R}) \\ \operatorname{curl} w^k \text{ compact in } W_{loc}^{-1, q}(\Omega; \mathbb{R}). \end{cases}$$

$$\Rightarrow v^k \cdot w^k \rightharpoonup v \cdot w \quad D'$$

Compensated Compact

Embedding Lemma

$\Omega \subset \mathbb{R}^n$ bounded open



(Compact set of $W_{loc}^{-1, q}(\Omega)$)

\cap (Bounded set of $W_{loc}^{1, r}(\Omega)$)

C (Compact set of $W_{loc}^{-1, p}(\Omega)$)

for any $1 < q \leq p < r < \infty$

2×2 Hyperbolic Systems

of Conservation Laws

$$\begin{cases} u_t + f(u)_x = 0 & u \in \mathbb{R}^2 \\ u|_{t=0} = u_0(x) \end{cases}$$

Assume

- \exists a strictly convex entropy $\gamma_x(u)$,
 $\nabla^2 \gamma_x(u) > 0$
- \exists globally defined Riemann Invariants
 $w = (w_1, w_2) : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ s.t.

$$\nabla w_j(u) \parallel \ell_j(u)$$

↳ If $u \in C^1$

$$\boxed{\partial_t w_j + \lambda_j(u(w)) \partial_x w_j = 0}$$

Entropy Equation

Entropy $\eta(u)$,

Entropy Flux $f(u)$

$$\nabla^g f(u) = \nabla \eta(u) \cdot \nabla f(u)$$

$$(\lambda_j \nabla \eta - \nabla^g f) \cdot r_j = 0$$

↳

$$g_{w_j} = \lambda_j \eta_{w_j}$$

$$\eta_{w_1 w_2} - \frac{\lambda_1 w_2}{\lambda_2 - \lambda_1} \eta_{w_1} + \frac{\lambda_2 w_1}{\lambda_2 - \lambda_1} \eta_{w_2} = 0$$

Genuine Nonlinearity

$$\nabla \lambda_j(u) \cdot r_j(u) \neq 0, \quad j=1, 2.$$

\Leftrightarrow

$$\frac{\partial \lambda_j}{\partial w_j} \neq 0, \quad j=1, 2,$$

Method of Vanishing Viscosity

$$\begin{cases} u_t + f(u)_x = 0 & u \in \mathbb{R}^2 \\ u|_{t=0} = u_0(x) \in L^\infty \cap L^1(\mathbb{R}) \end{cases}$$

Viscosity Approximation

$$\begin{cases} u_t + f(u)_x = \varepsilon u_{xx} \\ u|_{t=0} = u_0^\varepsilon(x) \rightarrow u_0(x) \text{ a.e.} \end{cases}$$

↳ $u^\varepsilon = u^\varepsilon(t, x)$

Invariant Regions or L^P Estimates

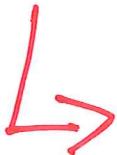
$$\|u^\varepsilon\|_{L^\infty} \leq C \quad \text{or} \quad \|u^\varepsilon\|_{L^p} \leq C$$

Dissipation Estimate

$$\|\sqrt{\varepsilon} u_x^\varepsilon\|_{L^2} \leq C \propto \varepsilon.$$

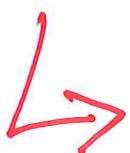
Dissipation Estimate

$$\nabla \bar{\eta}_{*}(u^\varepsilon)_x \left[u_t^\varepsilon + f(u^\varepsilon)_x = \varepsilon u_{xx}^\varepsilon \right]$$



$$\varepsilon (u_x^\varepsilon)^T \nabla \bar{\eta}_{*}(u^\varepsilon) u_x^\varepsilon \geq c_0 \varepsilon |u_x^\varepsilon|^2$$

$$= - \bar{\eta}_{*}(u^\varepsilon)_t - \bar{g}_{*}(u^\varepsilon)_x + \varepsilon \bar{\eta}_{*}(u^\varepsilon)_{xx}$$



$$c_0 \iint_0^T \varepsilon |u_x^\varepsilon|^2 dx dt$$

$$\leq \int \bar{\eta}_{*}(u_0^\varepsilon) dx - \int \bar{\eta}_{*}(u_{(T,x)}^\varepsilon) dx.$$

$$\leq \int \bar{\eta}_{*}(u_0^\varepsilon) dx \leq C \propto \varepsilon.$$

$$\cdot \bar{\eta}_{*}(u) = \eta_{*}(u) - \eta_{*}(0) - \nabla \eta(0) u \geq c_0 > 0$$

$$\bar{g}_{*}(u) = g_{*}(u) - g_{*}(0) - \nabla g(0) (f(u) - f(0)).$$

H^1 -Compactness

$$\eta(u^\varepsilon)_t + \varphi(u^\varepsilon)_x$$

$$= \varepsilon (\nabla \eta(u^\varepsilon) u_x^\varepsilon)_x - \varepsilon (u_x^\varepsilon)^T \nabla \tilde{\eta}(u^\varepsilon) u_x^\varepsilon$$

$$= I_1^\varepsilon + I_2^\varepsilon$$

$$\|I_1^\varepsilon\|_{H^1(\Omega)} \leq \sqrt{\varepsilon} \left\| \sqrt{\varepsilon} u_x^\varepsilon \right\|_{L^2} \left\| \nabla \eta(u^\varepsilon) \right\|_{L^\infty} \leq \sqrt{\varepsilon} C \rightarrow 0$$

$$\|I_2^\varepsilon\|_{L^1(\Omega)} \leq \|\nabla \tilde{\eta}(u^\varepsilon)\|_{L^\infty} \left\| \sqrt{\varepsilon} u_x^\varepsilon \right\|_{L^2}^2 \leq C$$

↳ I_2^ε compact in $W^{1,\frac{q}{2}}(\Omega)$, $1 < q < 2$

↳ $I_1^\varepsilon + I_2^\varepsilon$ compact in $W^{1,\frac{q}{2}}(\Omega)$, $1 < q < 2$

But

$\eta(u^\varepsilon)_t + \varphi(u^\varepsilon)_x$ bounded in $W^{1,\infty}(\Omega)$

Lemma

$\boxed{\eta(u^\varepsilon)_t + \varphi(u^\varepsilon)_x}$
is compact in H^1_{loc}

$\forall (\eta, \varphi) \in C^2$

Commutation Identity

for Young Measure. $\{V_{t,x}\}_{(t,x) \in \mathbb{R}_+^2}$



$$\{u^\varepsilon\}_{\varepsilon > 0}$$

- $\text{Supp } V_{t,x} \subset \mathbb{R}^2$

- For any entropy pairs (η, g) ,

$$(x) \quad \langle V_{t,x}, \begin{vmatrix} \eta_1 & g_1 \\ \eta_2 & g_2 \end{vmatrix} \rangle$$

$$= \begin{vmatrix} \langle V_{t,x}, \eta_1 \rangle & \langle V_{t,x}, g_1 \rangle \\ \langle V_{t,x}, \eta_2 \rangle & \langle V_{t,x}, g_2 \rangle \end{vmatrix}$$

a.e. (t,x)

\Rightarrow $V_{t,x} = \sum_{u(t,x)} (\lambda) ??$

- * If $f(u) = Au$ (linear)

\hookrightarrow (*) is trivial.

The imbalance of (*) is enforced by the nonlinearity of $f(u)$.

Proof of (*)

$\forall (\gamma_i, g_i) \in C, i=1, 2.$

$U^\varepsilon = (\gamma_1(u^\varepsilon), g_1(u^\varepsilon), \gamma_2(u^\varepsilon), g_2(u^\varepsilon))$ uniformly bdd

$\hookrightarrow \exists \{\varepsilon_k\}_{k=1}^{\infty}$, s.t. $\varepsilon_k \rightarrow 0$ as $k \rightarrow \infty$.

$U^{\varepsilon_k} \xrightarrow{*} (\langle v_{t,x}, \gamma_1(\lambda) \rangle, \langle v_{t,x}, g_1(\lambda) \rangle, \langle v_{t,x}, \gamma_2(\lambda) \rangle, \langle v_{t,x}, g_2(\lambda) \rangle)$

$$\begin{array}{ccc} \left| \begin{array}{cc} U_1^{\varepsilon_k} & U_2^{\varepsilon_k} \\ U_3^{\varepsilon_k} & U_4^{\varepsilon_k} \end{array} \right| & \xrightarrow{*} & \boxed{\begin{array}{c} \text{||} \\ U(t,x) \\ \langle v_{t,x}, \left| \begin{array}{c} \gamma_1(\lambda), g_1(\lambda) \\ \gamma_2(\lambda), g_2(\lambda) \end{array} \right. \rangle \end{array}} \end{array}$$

Div-Cuml

$$\left| \begin{array}{cc} U_1 & U_2 \\ U_3 & U_4 \end{array} \right| = \boxed{\begin{array}{cc} \langle v_{t,x}, \gamma_1(\lambda) \rangle & \langle v_{t,x}, g_1(\lambda) \rangle \\ \langle v_{t,x}, \gamma_2(\lambda) \rangle & \langle v_{t,x}, g_2(\lambda) \rangle \end{array}}$$

Reduction of the Young Measure:

C-14

Scalar Conservation Laws: $u^2 \xrightarrow{*} u, \text{ a.e.}$
 $\hookrightarrow u(t, x) = \langle v_{t,x}, \lambda \rangle$

$$\left\langle v_{t,x}, \begin{vmatrix} \eta_1(\lambda) & g_1(\lambda) \\ \eta_2(\lambda), & g_2(\lambda) \end{vmatrix} \right\rangle = \begin{vmatrix} \langle v_{t,x}, \eta_1(\lambda) \rangle & \langle v_{t,x}, g_1(\lambda) \rangle \\ \langle v_{t,x}, \eta_2(\lambda) \rangle & \langle v_{t,x}, g_2(\lambda) \rangle \end{vmatrix}$$

Choose: $(\eta_1(\lambda), g_1(\lambda)) = (\lambda - u(t, x), f(\lambda) - f(u(t, x)))$

$$(\eta_2(\lambda), g_2(\lambda)) = (f(\lambda) - f(u(t, x)), \int_{u(t, x)}^{\lambda} (f'(s))^2 ds)$$

$$\begin{aligned} \left\langle v_{t,x}, \begin{vmatrix} \lambda - u & f(\lambda) - f(u) \\ f(\lambda) - f(u) & \int_u^{\lambda} (f'(s))^2 ds \end{vmatrix} \right\rangle &= \\ &= \left| \begin{matrix} \boxed{\langle v_{t,x}, \lambda - u \rangle} = 0 & \langle v_{t,x}, f(\lambda) - f(u) \rangle \\ \langle v_{t,x}, f(\lambda) - f(u) \rangle & \langle v_{t,x}, \int_u^{\lambda} (f'(s))^2 ds \rangle \end{matrix} \right| \end{aligned}$$

$$\begin{aligned} \left\langle v_{t,x}, (\lambda - u) \int_u^{\lambda} (f'(s))^2 ds - (f(\lambda) - f(u))^2 \right\rangle \\ + \langle v_{t,x}, f(\lambda) - f(u) \rangle^2 = 0 \end{aligned}$$

$$\begin{aligned}
 & (\lambda-u) \int_u^\lambda (f'(s))^2 ds - (f(\lambda) - f(u))^2 \\
 &= (\lambda-u) \int_u^\lambda \left(f'(s) - \frac{1}{\lambda-u} \int_u^\lambda f'(z) dz \right)^2 ds \geq 0.
 \end{aligned}$$

\Rightarrow

$$\left\{
 \begin{array}{l}
 \langle v_{t,x}, f(\lambda) - f(u) \rangle = 0 \\
 \langle v_{t,x}, (\lambda-u) \int_u^\lambda \left(f'(s) - \frac{1}{\lambda-u} \int_u^\lambda f'(z) dz \right)^2 ds \rangle = 0
 \end{array}
 \right.$$

||

$$(\lambda-u) \int_u^\lambda \left(\int_u^\lambda f''(\lambda+\theta(s-z))(s-z) dz \right)^2 ds$$

\Rightarrow

- $\langle v_{t,x}, f(\lambda) \rangle = f(u(t,x))$

- If $f''(u) \geq 0$

\hookrightarrow $v_{t,x} = \nabla_{u(t,x)}$

The Goursat Entropy Pairs for 2×2 Hyperbolic Systems of Conservation Laws

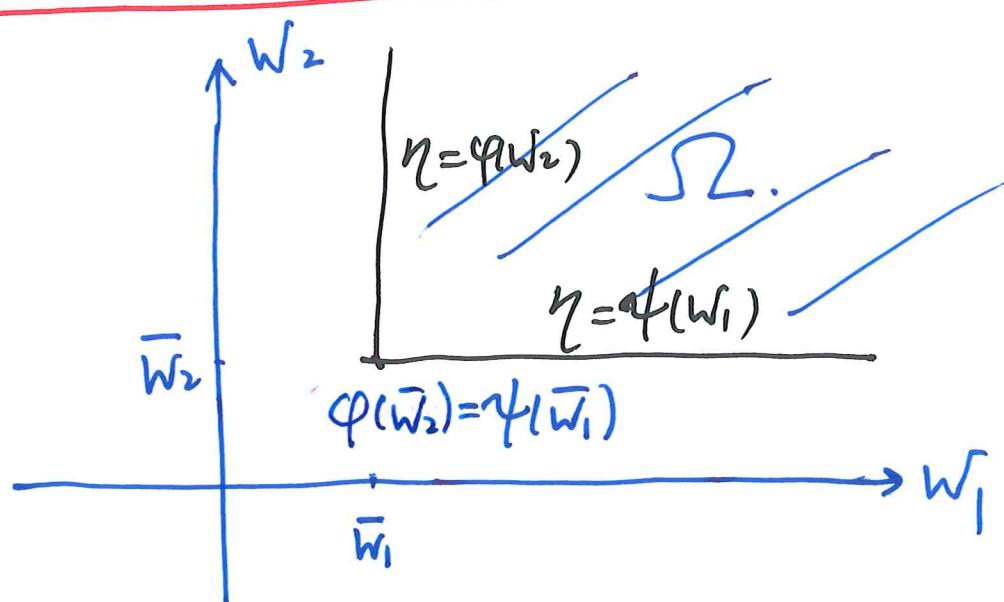
$$\eta_{w_1 w_2} - \frac{\lambda_1 w_2}{\lambda_2 - \lambda_1} \eta_{w_1} + \frac{\lambda_2 w_1}{\lambda_2 - \lambda_1} \eta_{w_2} = 0 \quad (*)$$

$$\eta_{w_j} = \lambda_j \eta_{w_j}$$

(**)

(***)

Goursat Problem for (*)



Well-posed!

Goursat Entropy Pairs

\exists two families of entropy pairs :

$$\left\{ \begin{array}{l} \eta_a(w) = I_1(w) a(w_1) + \int_{-\bar{w}_1}^{w_1} J_1(\xi; w) a(\xi) d\xi \\ g_a(w) = K_1(w) a(w_1) + \int_{-\bar{w}_1}^{w_1} L_1(\xi; w) a(\xi) d\xi \end{array} \right.$$

$$\left\{ \begin{array}{l} \eta_b(w) = I_2(w) b(w_2) + \int_{-\bar{w}_2}^{w_2} J_2(\xi; w) b(\xi) d\xi \\ g_b(w) = K_2(w) b(w_2) + \int_{-\bar{w}_2}^{w_2} L_2(\xi; w) b(\xi) d\xi \end{array} \right.$$

where (I_i, J_i, K_i, L_i) , $i=1, 2$, are unique smooth functions and independent of \bar{w}_1 and \bar{w}_2 :

$$\left\{ \begin{array}{l} I_i(w) > 0, \quad \left\{ \begin{array}{l} I_1(w_1, \bar{w}_2) = 1 \\ J_1(\xi; w_1, \bar{w}_2) = 0 \end{array} \right. \quad \left\{ \begin{array}{l} I_2(\bar{w}_1, w_2) = 1 \\ J_2(\xi; \bar{w}_1, w_2) = 0 \end{array} \right. \\ K_i = \lambda_i I_i \\ \frac{\partial K_i(w)}{\partial w_i} + L_i(w_i; w) = \lambda_i(w) \left(\frac{\partial I_i(w)}{\partial w_i} + J_i(w_i; w) \right) \\ \frac{\partial L_i(\xi; w)}{\partial w_i} = \lambda_i(w) \frac{\partial J_i(\xi; w)}{\partial w_i} \\ \frac{\partial K_i(w)}{\partial w_j} = \lambda_j(w) \frac{\partial I_i(w)}{\partial w_j}, \quad i \neq j \\ \frac{\partial L_i(\xi; w)}{\partial w_j} = \lambda_j(w) \frac{\partial J_i(\xi; w)}{\partial w_j} \end{array} \right.$$

Reduction of the Young Measure

Thm. If $\frac{\partial \lambda_j}{\partial w_j} \neq 0$, $j=1, 2$ (Genuinely Nonlinear)

$$\Rightarrow \nu_{t,x} = \delta_{u(t,x)}$$

Proof. If $\nu_{t,x} \neq \delta_{u(t,x)}$, we denote

$[\bar{w}_1, \bar{w}_1^+] \times [\bar{w}_2, \bar{w}_2^+]$ the smallest rectangle containing $\text{Supp } \nu_{t,x}$.

1. Claim: If $\bar{w}_1 < \bar{w}_1^+$, then $\exists c_1(t,x)$ s.t.

$$\langle v, g_a \rangle = c_1 \langle v, \eta_a \rangle$$

$\forall a \in C$, $a(w_1) = 0$ when $\begin{cases} w_1 \geq \bar{w}_1 \\ \text{or} \\ w_1 \leq \bar{w}_1 \end{cases}$ for $\bar{w}_1 \in (\bar{w}_1, \bar{w}_1^+)$

Choose $\begin{cases} a_0(w_1) = (\bar{w}_1 - w_1^*)_+, \quad w_1^* \geq \bar{w}_1, \quad |w_1^* - w_1^*| \ll 1 \\ a(w_1) = 0, \quad w_1 \geq \bar{w}_1 \end{cases}$

$$\hookrightarrow \begin{cases} \eta_{a_0}(w) > 0 & \forall w \in \{\bar{w}_1 < w_1 < w_1^+\} \cap \text{Supp } \nu \\ \eta_{a_0} g_a - \eta_a g_{a_0} = 0 \end{cases}$$

$$\hookrightarrow \langle v, \eta_{a_0} \rangle \langle v, g_a \rangle = \langle v, \eta_a \rangle \langle v, g_{a_0} \rangle$$

$$\hookrightarrow \langle v, g_a \rangle = G(\bar{w}_1) \langle v, \gamma_a \rangle$$

$\forall a \in C, \alpha(w_1) = 0, w_1 \geq \bar{w}_1.$

$$[C_1(\bar{w}_1) = \frac{\langle v, g_{a_0} \rangle}{\langle v, \gamma_{a_0} \rangle}]$$

Similarly, $\forall a \in C, \alpha(w_1) = 0$ when $w_1 \leq \bar{w}_1,$

$$\langle v, g_a \rangle = C_1(\bar{w}_1) \langle v, \gamma_a \rangle$$

- claim $C_1(\bar{w}_1) \neq \bar{w}_1.$

For any $\tilde{w}_1 \in (w_1^-, w_1^+),$ choose

$$\begin{cases} \alpha_1(w_1) = 0 & w_1 \leq \tilde{w}_1 \\ \alpha_2(w_1) = 0 & w_1 \geq \tilde{w}_1 \end{cases} \quad \text{for } \tilde{w}_1 < \bar{w}_1$$

$$\begin{cases} \alpha_1(w_1) = 0 & w_1 \geq \tilde{w}_1 \\ \alpha_2(w_1) = 0 & w_1 \leq \bar{w}_1 \end{cases} \quad \text{for } \tilde{w}_1 > \bar{w}_1$$

$$\Rightarrow \gamma_{a_1} g_{a_2} - \gamma_{a_2} g_{a_1} = 0$$

$$\hookrightarrow C_1(\bar{w}_1) = C_1(\tilde{w}_1)$$

2. claim If $\bar{w}_2 < w_2^+$, then $\exists C_2(t, x)$ s.t. (20)

$$\langle v, g_b \rangle = C_2 \langle v, \eta_b \rangle$$

$\forall b \in C$, $b(w_2) = 0$ when $\begin{cases} w_2 \geq \bar{w}_2 \\ \text{or} \\ w_2 \leq \bar{w}_2 \end{cases}$ $\bar{w}_2 \in (\bar{w}_2, w_2^+)$

3. $\forall \alpha \in (\bar{w}_1, w_1^+)$, choose w_1^*, \bar{w}_1 s.t.

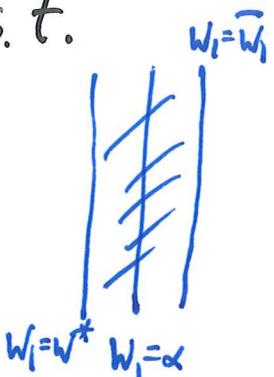
$$w_1^* < \alpha < \bar{w}_1, \quad \bar{w}_1 - w_1^* \ll 1$$

Choose (η_a, g_a) : $a(w_1) = (w_1 - w_1^*)_+$

choose $(\bar{\eta}_a, \bar{g}_a)$: $\bar{a}(w_1) = (w_1 - \bar{w}_1)_-$



$$\boxed{\begin{aligned} \langle v, \eta_a g_{\bar{a}} - \bar{\eta}_a g_a \rangle &= \langle v, \eta_a \rangle \langle v, g_{\bar{a}} \rangle - \langle v, \bar{\eta}_a \rangle \langle v, g_a \rangle \\ &= 0 \end{aligned}}$$



We know that, On $\{w_1 < w_1^*\} \cup \{w_1 > \bar{w}_1\}$,

$$\eta_a g_{\bar{a}} - \bar{\eta}_a g_a = 0$$

On $\{w_1^* \leq w_1 \leq \bar{w}_1\}$.

$$\left\{ \begin{array}{l} \eta_a(w) = I_1(w)(w_1 - w_1^*) + \frac{1}{2} J_1(\alpha; w)(w_1 - w_1^*)^2 + O(|w_1 - w_1^*|^3) \\ g_a(w) = K_1(w)(w_1 - w_1^*) + \frac{1}{2} L_1(\alpha; w)(w_1 - w_1^*)^2 + O(|w_1 - w_1^*|^3) \end{array} \right.$$

$$\left\{ \begin{array}{l} \eta_{\bar{a}}(w) = I_1(w)(\bar{w}_1 - w_1) + \frac{1}{2} J_1(\alpha; w)(\bar{w}_1 - w_1)^2 + O(|w_1 - w_1^*|^3) \\ g_{\bar{a}}(w) = K_1(w)(\bar{w}_1 - w_1) - \frac{1}{2} L_1(\alpha; w)(\bar{w}_1 - w_1)^2 + O(|w_1 - w_1^*|^3) \end{array} \right.$$

$$\begin{aligned} & (\eta_a g_{\bar{a}} - \eta_{\bar{a}} g_a)(w) \\ &= \frac{1}{2} (\bar{w}_1 - w_1^*)(\bar{w}_1 - w_1)(w_1 - w_1^*) \left(I^2 \frac{\partial \lambda_1}{\partial w_1} \right) (\alpha, w_2) \\ &\quad + O((\bar{w}_1 - w_1^*)^2 (\bar{w}_1 - w_1)(w_1 - w_1^*)) \end{aligned}$$

$$\Rightarrow \langle v, (\bar{w}_1 - w_1)_+ (w_1 - w_1^*)_+ \left(\underbrace{\left(I^2 \frac{\partial \lambda_1}{\partial w_1} \right)}_{*} (\alpha, w_2) + O(|\bar{w}_1 - w_1^*|) \right) \rangle = 0$$

$$\Rightarrow \text{Supp } v \cap \{w_1^* \leq w_1 \leq \bar{w}_1\} = \emptyset \quad \text{And} \quad \begin{cases} w_1^* < \bar{w}_1 \\ |\bar{w}_1 - w_1^*| \ll 1. \end{cases}$$

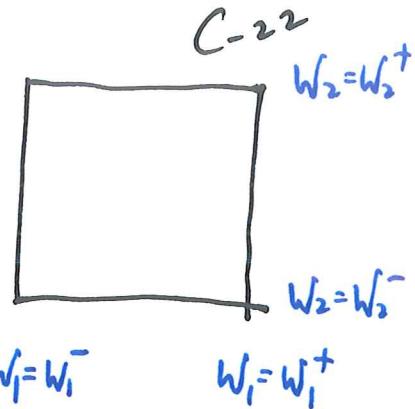
$$\hookrightarrow \text{Supp } v \cap \{w_1^- < w_1 < w_1^+\} = \emptyset$$

Similarly,

$$\hookrightarrow \text{Supp } v \cap \{w_2^- < w_2 < w_2^+\} = \emptyset$$

4. If

$$\text{Supp } \nu \cap \left(\{w_1 = w_1^\pm\} \cup \{w_2 = w_2^\pm\} \right) \neq \emptyset$$



for example

$$\text{Supp } \nu \cap \{w_1 = w_1^-\} \neq \emptyset$$

↗

$$\nu(\{w_1 = w_1^-\}) \neq 0$$

then we follow Step 3 to choose

$$\alpha = w_1^-, \quad \bar{w}_1 = w_1^- + \varepsilon, \quad w_1^* = w_1^- - \varepsilon.$$

to conclude

$$\text{Supp } \nu \cap \{w_1^- - \varepsilon \leq w_1 \leq w_1^- + \varepsilon\} = \emptyset$$

for sufficiently small $\varepsilon > 0$

↳ Contradiction

5. Conclusion

$$\text{Supp } \nu \cap \left([w_1^-, w_1^+] \times [w_2^-, w_2^+] \right) = \emptyset$$

↳ Contradiction

⇒

$$V_{t,x} = \sum_{U(t,x)} \quad \text{Single point support.}$$