

VI. Nonlinear First-Order PDE

General form

$$F(Du, u, x) = 0, \quad x \in \Omega \subset \mathbb{R}^n \text{ open}$$

$$F: \mathbb{R} \times \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R} \text{ Given}$$

- Nonlinearity \Rightarrow **No** simple formula for solutions
- Remarkably, we can often employ calculus to glean fairly detailed information about solutions

Examples

① Clairaut's Eq. in differential geometry.

$$x \cdot Du + f(Du) = u$$

② The eikonal Eq. in Geometric Optics

$$|Du| = 1$$

③ Hamilton-Jacobi Eq.

$$U_t + H(Du) = 0$$

④ Conservation Laws.

$$U_t + \operatorname{div} f(u) = 0$$

$f: \mathbb{R} \rightarrow \mathbb{R}^n$ is given

§6.1. Quasilinear Equations

§6.1.1. The Case of 2 Independent Variables

$$(*) \quad a(u, x, y) u_x + b(u, x, y) u_y = c(u, x, y)$$

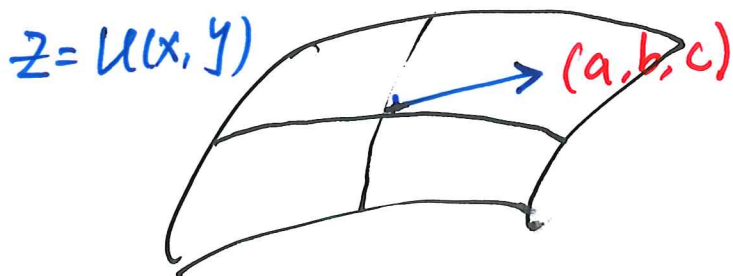
Integral Surfaces: $u = u(x, y)$ can be represented by a surface $z = u(x, y)$ in the xyz -space:



The surfaces that are tangent to the direction of the vector (a, b, c) at each point on the surfaces.

$$(u_x, u_y, -1) \cdot \underline{(a, b, c)} = 0$$

characteristic direction



Characteristic Curves:

At each point, the curves are tangent to the characteristic direction (a, b, c)

↳ Along a characteristic curve

$$\frac{dx}{a(z, x, y)} = \frac{dy}{b(z, x, y)} = \frac{dz}{c(z, x, y)} = dt$$



Characteristic ODE

$$\left\{ \begin{array}{l} \frac{dx}{dt} = a(z, x, y) \\ \frac{dy}{dt} = b(z, x, y) \\ \frac{dz}{dt} = c(z, x, y) \end{array} \right.$$

If $a, b, c \in C^1$.

↳ ODE Theory

\exists 1 $(x(t), y(t), z(t))$ through each point (x_0, y_0, z_0) for any $t \in (-\delta, \delta)$, for some $\delta > 0$.

Theorem 6.1

Surface $S: z = u(x, y)$ formed as a union of characteristic curves

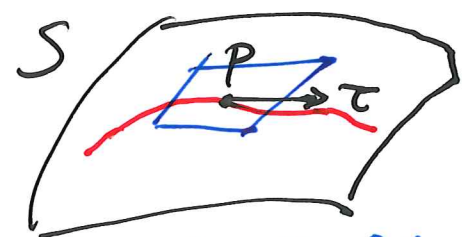


$S: z = u(x, y)$ is an integral surface

Proof

" \Rightarrow "

$\forall P \in S,$



\exists a characteristic curve $\gamma \subset S, P \in \gamma.$

\hookrightarrow The tangent $\tau = (a, b, c)$ to γ at P lies in the tangent plane of S at $P.$

$\hookrightarrow \tau = (a, b, c)$ is the Char. direction

$\hookrightarrow S$ is the integral surface

Proof (Conti.)

" \Leftarrow " claim: $\forall P = (x_0, y_0, z_0) \in S$

$\hookrightarrow \exists$ 1 characteristic curve

$$\gamma = (x(t), y(t), z(t))$$

with $(x, y, z)|_{t=t_0} = (x_0, y_0, z_0)$

$\hookrightarrow \gamma$ lies completely on S

\Downarrow

Through every point $P \in S$, there passes a characteristic curve contained in S .

Proof of Claim. $\gamma = (x(t), y(t), z(t))$

with

$$\left\{ \begin{aligned} \frac{dx}{dt} &= a(z, x, y), \\ \frac{dy}{dt} &= b(z, x, y), \\ \frac{dz}{dt} &= c(z, x, y), \end{aligned} \right.$$

$$(x, y, z)|_{t=t_0} = (x_0, y_0, z_0)$$

Let

$$\begin{cases} U(t) = z(t) - u(x(t), y(t)) \\ U(t_0) = 0 \end{cases} \leftarrow \boxed{P \in S}$$

↳

$$\frac{dU}{dt} = c(U + u(x, y), x, y)$$

$$- u_x(x, y) a(U + u(x, y), x, y)$$

$$- u_y(x, y) b(U + u(x, y), x, y)$$

$$U(t_0) = 0$$

Uniqueness

$$U(t) \equiv 0.$$

$$\hookrightarrow z(t) = u(x(t), y(t))$$

$$\hookrightarrow \gamma \subset S.$$

⇒ A general solution $u = u(x, y)$ of (*)
 is the integral surface $z = u(x, y)$
 formed as the union of
characteristic curves.

Cauchy Problem

$$(*) \left\{ \begin{array}{l} a(u, x, y) u_x + b(u, x, y) u_y = c(u, x, y) \\ u(f(s), g(s)) = h(s) \end{array} \right.$$

where $\Gamma: x=f(s), y=g(s), z=h(s)$
is a curve in xyz -space

\Leftrightarrow Seek an integral surface
containing the given curve Γ .

Let $(f(s), g(s), h(s)) \in C^1(O(s_0))$
 $P_0 = (x_0, y_0, z_0) = (f(s_0), g(s_0), h(s_0))$
 $a(z, x, y), b(z, x, y), c(z, x, y) \in C^1(O(P_0))$

n.b.h.d

Theorem 6.2. \exists 1 solution of (*)

$$u(x, y) \in C^1(O(x_0, y_0))$$

provided that

$$J := \begin{vmatrix} f'(s_0) & g'(s_0) \\ a(z_0, x_0, y_0) & b(z_0, x_0, y_0) \end{vmatrix} \neq 0$$

Proof 1. Local Existence

Consider

$$\begin{cases} \frac{dx}{dt} = a(z, x, y), \\ \frac{dy}{dt} = b(z, x, y), \\ \frac{dz}{dt} = c(z, x, y), \\ (x, y, z)|_{t=0} = (f(s), g(s), h(s)) \end{cases}$$

ODE Theory \rightarrow

\exists 1 solution

$$\begin{cases} x = X(s, t), \\ y = Y(s, t), \\ z = Z(s, t), \end{cases}$$

s.t. $(X(s, t), Y(s, t), Z(s, t)) \in C^1(O(s_0, 0))$

$\forall (x, y) \in \mathcal{O}(x_0, y_0)$ n.b.h.d of (x_0, y_0) 116

Consider

$$\left\{ \begin{array}{l} X(s, t) = x, \\ Y(s, t) = y, \\ X(s_0, 0) = x_0, \\ Y(s_0, 0) = y_0, \end{array} \right.$$

Since $J = \begin{vmatrix} X_s(s_0, 0) & Y_s(s_0, 0) \\ X_t(s_0, 0) & Y_t(s_0, 0) \end{vmatrix} \neq 0.$

Implicit
function theorem

$$\Rightarrow \exists 1. (S(x, y), T(x, y)) \text{ s.t.}$$

$\in C^1(\mathcal{O}(x_0, y_0))$

$$\left\{ \begin{array}{l} S = S(x, y), \\ t = T(x, y), \\ (S(x_0, y_0), T(x_0, y_0)) = (s_0, 0) \end{array} \right.$$

Define

$$u = u(x, y) = z(S(x, y), T(x, y))$$



u is a solution of $(*)$.

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2. Uniqueness: Follows from Claim

Any integral surface through Γ
has to contain the characteristic
curve through the points of Γ ,
hence has to contain

$$\Sigma: x = X(s, t), y = Y(s, t), z = Z(s, t).$$

\hookrightarrow locally has to be identical
with the surface Σ

□

Remarks

① $J \neq 0$ is essential for the local existence

② Special Case: Linear PDE

$$a(x, y) u_x + b(x, y) u_y = c(x, y) u + d(x, y)$$

↳ The system of 3 characteristic ODEs reduces to

$$\left\{ \begin{array}{l} \frac{dx}{dt} = a(x, y) \\ \frac{dy}{dt} = b(x, y) \end{array} \right. \quad \text{or} \quad \frac{dy}{dx} = \frac{b(x, y)}{a(x, y)}$$

Called Characteristic Projections

or more commonly, "Characteristics"
 i.e. Projections onto the xy-plane
 of the characteristic curves in the
xyz-space.

Examples

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$$1. \begin{cases} U_y + c U_x = 0, \\ U|_{y=0} = h(x) \end{cases}$$

Initial curve $\Gamma: x=s, y=0, z=h(s)$

Char. ODE

$$\begin{cases} \frac{dx}{dt} = c, \\ \frac{dy}{dt} = 1, \\ \frac{dz}{dt} = 0, \\ (x, y, z)|_{t=0} = (s, 0, h(s)) \end{cases}$$

$$\begin{cases} x = X(s, t) = ct + s \\ y = Y(s, t) = t \\ z = Z(s, t) = h(s) \end{cases} \rightarrow s = x - cy$$

$$\rightarrow z = h(x - cy)$$

$$\rightarrow \boxed{u(x, y) = h(x - cy)} \quad \text{Solution}$$

Examples (Conti).

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$$2. \begin{cases} U_y + U U_x = 0, \\ U|_{y=0} = h(x) \in C^1 \end{cases}$$

Initial curve $\Gamma: x=s, y=0, z=h(s).$

Char. ODE

$$\begin{cases} \frac{dx}{dt} = z, \\ \frac{dy}{dt} = 1, \\ \frac{dz}{dt} = 0, \\ (x, y, z)|_{t=0} = (s, 0, h(s)) \end{cases}$$

$$\begin{cases} x = X(s, t) = s + h(s)t \\ y = Y(s, t) = t \\ z = Z(s, t) = h(s) \end{cases} \begin{cases} t = y \\ s + h(s)y = x \end{cases} \begin{cases} \hookrightarrow \text{for } |h| \ll 1 \\ s = S(x, y) \end{cases}$$

$$\hookrightarrow \boxed{U(x, y) = h(S(x, y))}$$

III

$$\boxed{U = h(x - Uy)}$$

Nonlinearity

§ 6.1.2. The Case of n Indept. Variables

$$\sum_{j=1}^n a_j(u, x_1, \dots, x_n) u_{x_j} = C(u, x_1, \dots, x_n)$$

$n \geq 3$

Characteristic Curves

$$\left\{ \begin{array}{l} \frac{dx_j}{dt} = a_j(z, x_1, \dots, x_n), \quad j=1, 2, \dots, n \\ \frac{dz}{dt} = C(z, x_1, \dots, x_n). \\ x_j|_{t=0} = f_j(s_1, \dots, s_{n-1}) \\ z|_{t=0} = h(s_1, \dots, s_{n-1}) \end{array} \right.$$

where $u(f_1, \dots, f_n) = h$ (Initial condition)

$$\left\{ \begin{array}{l} x_j = X_j(s_1, \dots, s_{n-1}, t), \quad j=1, 2, \dots, n \\ z = Z(s_1, \dots, s_{n-1}, t) \end{array} \right.$$

LODE Theory

$$\text{If } J = \begin{vmatrix} \frac{\partial f_1}{\partial s_1} & \dots & \frac{\partial f_n}{\partial s_1} \\ \dots & \dots & \dots \\ \frac{\partial f_1}{\partial s_{m_1}} & \dots & \frac{\partial f_n}{\partial s_{m_1}} \\ \dots & \dots & \dots \\ a_1 & \dots & a_n \end{vmatrix} (s_1^0, \dots, s_{m_1}^0, 0) \neq 0.$$

IFT
 \Rightarrow

$$\begin{cases} s_j = S_j(x_1, \dots, x_n), & j=1, \dots, n-1 \\ t = T(x_1, \dots, x_n) \end{cases}$$

\hookrightarrow

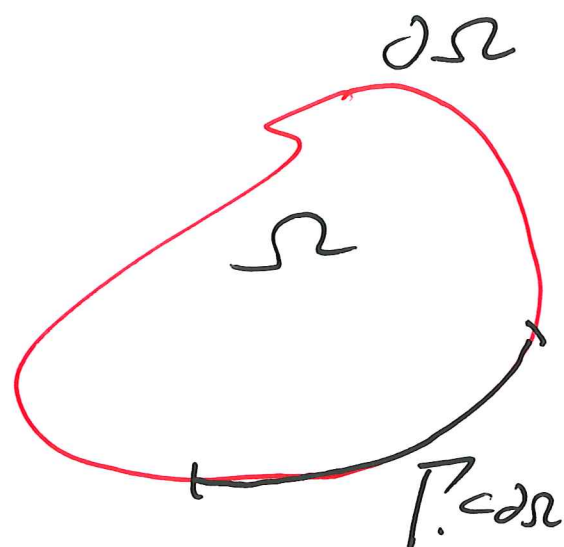
$$u(x) = Z(S_1(x), \dots, S_{n-1}(x), T(x))$$

is a solution of
the problem

$$\begin{cases} \sum_{j=1}^n a_j(u, x) u_{x_j} = C(u, x) \\ u(f_1, f_2, \dots, f_n) = h \end{cases}$$

§6.2 General Nonlinear First-Order PDE.

$$(*) \quad F(Du, u, x) = 0.$$



Problem. Find solutions of $(*)$
in Ω , subject to the
boundary condition
 $u|_{\Gamma} = g(x)$

Read @ § 3.1 - § 3.3.

in Evans's book

⊙ chapter 2 in Courant-Hilbert's
book, Vol. II

VII. Introduction to Conservation Laws

$$\left\{ \begin{array}{l} u_t + F(u)_x = 0 \\ u|_{t=0} = g \end{array} \right. \quad \mathbb{R} \times (0, \infty)$$

$$\left\{ \begin{array}{l} F: \mathbb{R} \rightarrow \mathbb{R} \\ g: \mathbb{R} \rightarrow \mathbb{R} \end{array} \right. \quad \text{are given}$$

$u: \mathbb{R} \times [0, \infty) \rightarrow \mathbb{R}$ is the unknown

§ 7.1 Method of Characteristics

$$U_t + F'(u) U_x = 0, \quad U|_{t=0} = g(x)$$

Characteristic ODEs

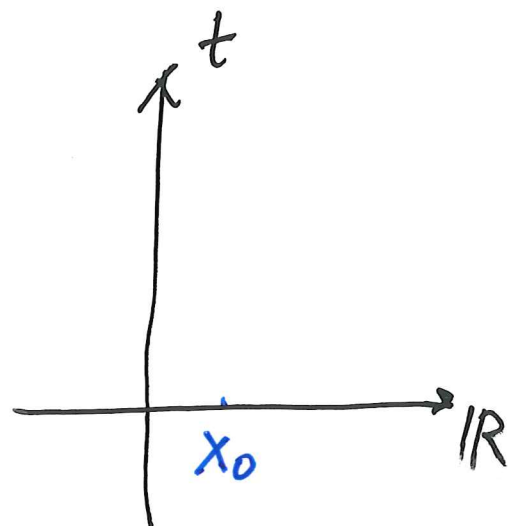
$$\begin{cases} \frac{dx}{d\tau} = F'(z(\tau)), \\ \frac{dt}{d\tau} = 1, \quad \longleftrightarrow \tau = t \\ \frac{dz(\tau)}{d\tau} = 0, \end{cases}$$

$$\begin{cases} \frac{dx(t)}{dt} = F'(z(t)), \\ \frac{dz(t)}{dt} = 0, \\ (x, z)|_{t=0} = (x_0, g(x_0)) \end{cases}$$

$$\begin{cases} z(t) = g(x_0), \\ x(t) = F'(g(x_0)) t + x_0 \end{cases}$$

$$u(x(t), t) = z(t) = g(x(t) - t F'(u(x(t), t)))$$

$$\boxed{u = g(x - t F'(u))}$$



$$u = g(x - tF'(u))$$

Implicit Function Thm

If

$$1 + t g'(x - tF'(u)) \cdot F''(u) \neq 0$$

$\hookrightarrow \exists$ 1 classical solution
 $u = u(x, t)$.

Ex 1. $\left\{ \begin{array}{l} F''(u) \geq 0 \quad (\text{Convex}) \\ g'(x) \geq 0 \end{array} \right.$

\hookrightarrow The problem $\begin{cases} u_t + F(u)_x = 0, \\ u|_{t=0} = g(x) \end{cases}$

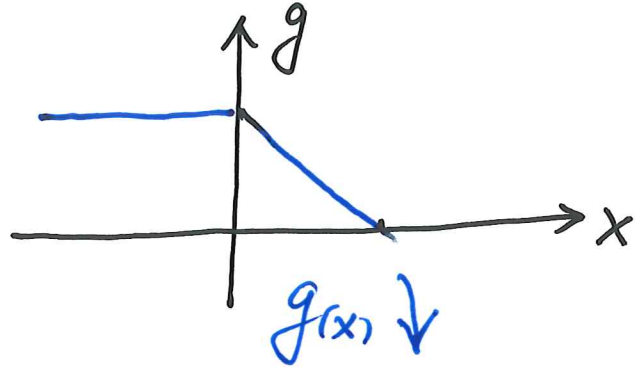
has a unique global classical solution

* **But**, in general, \exists only local-in-time classical solution.

Ex 2
$$\begin{cases} U_t + \left(\frac{U^2}{2}\right)_x = 0, & \mathbb{R} \times (0, \infty) \\ U|_{t=0} = g(x) = \begin{cases} 1, & x \leq 0 \\ 1-x, & 0 \leq x \leq 1 \\ 0, & x \geq 1 \end{cases} \end{cases}$$

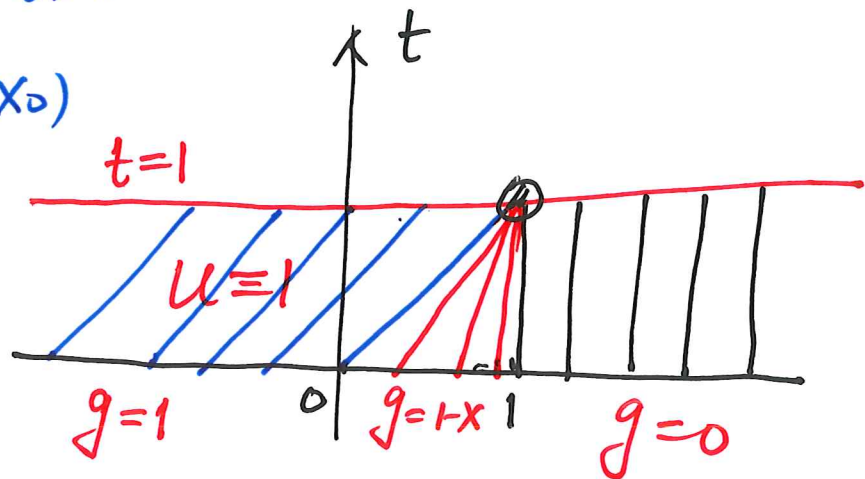
$F(u) = \frac{u^2}{2}$

$F'(u) = u$



$\hookrightarrow \forall x_0 \in \mathbb{R}$

$$\begin{cases} X(t) = x_0 + g(x_0)t \\ U = z(t) = g(x_0) \end{cases}$$



$0 \leq x_0 \leq 1$:

$$\begin{cases} X(t) = x_0 + (1-x_0)t = x_0(1-t) + t \\ U = z(t) = 1-x_0 \end{cases}$$

$\hookrightarrow X_0 = \frac{x-t}{1-t}$

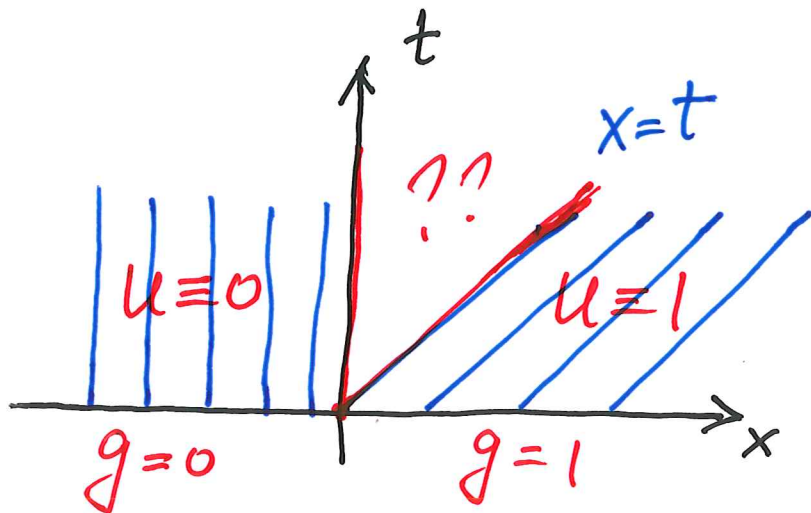
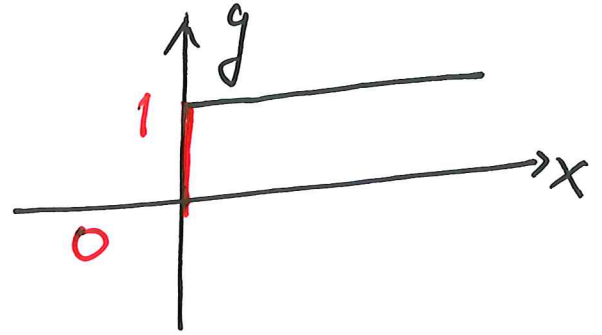
$$U = 1 - \frac{x-t}{1-t} = \frac{1-t-(x-t)}{1-t} = \frac{1-x}{1-t}$$

$$U(x,t) = \begin{cases} 1 & x \leq t, 0 \leq t \leq 1 \\ \frac{1-x}{1-t} & t \leq x \leq 1, 0 \leq t \leq 1 \\ 0 & x \geq 1, 0 \leq t \leq 1 \end{cases} \Rightarrow \boxed{t > 1?} \quad ??$$

Ex 3
$$\begin{cases} u_t + \left(\frac{u^2}{2}\right)_x = 0 & \mathbb{R} \times (0, \infty), \\ u|_{t=0} = g(x) = \begin{cases} 0 & x < 0, \\ 1 & x > 0 \end{cases} \end{cases}$$

$\forall x_0 \in \mathbb{R}$

$$\begin{cases} x(t) = x_0 + g(x_0)t, \\ u = z(t) = g(x_0) \end{cases}$$



* No points of the sector $\{0 < x < t\}$

can be reached by the characteristics
originating from the x -axis and

carrying the initial data.

— fails to provide any information
within the sector $\{0 < x < t\}$.

§ 7.2. Shocks, Entropy Condition

$$\begin{cases} u_t + F(u)_x = 0, \\ u|_{t=0} = g(x) \end{cases}$$

* PDE does not make sense unless u is differentiable

? \Rightarrow a way to interpret a less regular function as "solving" the Cauchy problem ?

Integral Solutions (Weak Solutions)

$$u \in L^\infty(\mathbb{R} \times (0, \infty)) :$$

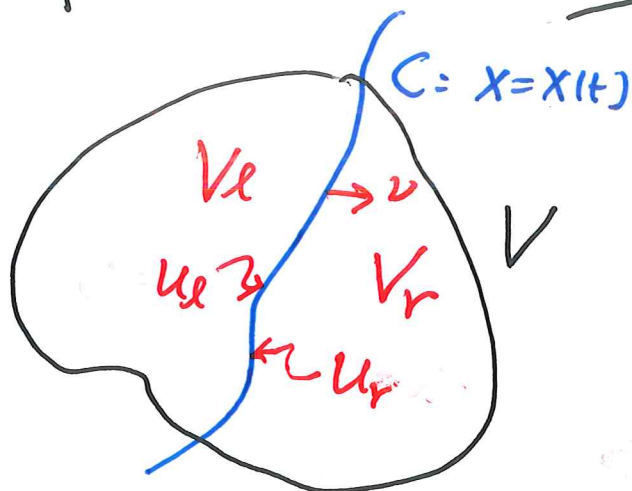
$$(*) \quad \int_0^\infty \int_{-\infty}^\infty (u \varphi_t + F(u) \varphi_x) dx dt + \int_{-\infty}^\infty g(x) \varphi(x, 0) dx = 0$$

for any test function $\varphi \in C_c^1(\mathbb{R} \times [0, \infty))$.

Q: What is the implication of this definition?

x, t
 $\rightarrow x$

- $V \subset \mathbb{R} \times (0, \infty)$ open
- $V = V_e \cup V_r$
- $u = u(x, t)$ is smooth on either side of C



$$v = (v^1, v^2) = \frac{(1, -x'(t))}{\sqrt{1+(x'(t))^2}}$$

\hookrightarrow $u_t + F(u)_x = 0 \quad \forall (x, t) \in V_e \text{ or } V_r$

But the traces of u on the sides of C : $u_e \neq u_r$

$\forall \varphi \in C_c^1(V)$, i.e. $\text{supp } \varphi \subset\subset V$.

$$0 = \int_0^\infty \int_{-\infty}^\infty (u \varphi_t + F(u) \varphi_x) dx dt$$

$$= \underbrace{\iint_{V_e} (u \varphi_t + F(u) \varphi_x) dx dt}_{//} + \underbrace{\iint_{V_r} (u \varphi_t + F(u) \varphi_x) dx dt}_{//}$$

$$- \iint_{V_e} (u_t + F(u)_x) \varphi dx dt + \int_{\partial V_e} (u_e v^2 + F(u_e) v^1) \varphi ds$$

$$- \int_{\partial V_r} (u_r v^2 + F(u_r) v^1) \varphi ds$$

$$\hookrightarrow \int_C [(F(u_e) - F(u_r))v^1 + (u_e - u_r)v^2] \varphi ds = 0$$

$$\hookrightarrow (F(u_e) - F(u_r))v^1 + (u_e - u_r)v^2 = 0$$

along C

$$\hookrightarrow x'(t)(u_e - u_r) = F(u_e) - F(u_r)$$

along C

Rankine-Hugoniot Jump Condition
along the discontinuity

$$\sigma[u] = [F(u)]$$

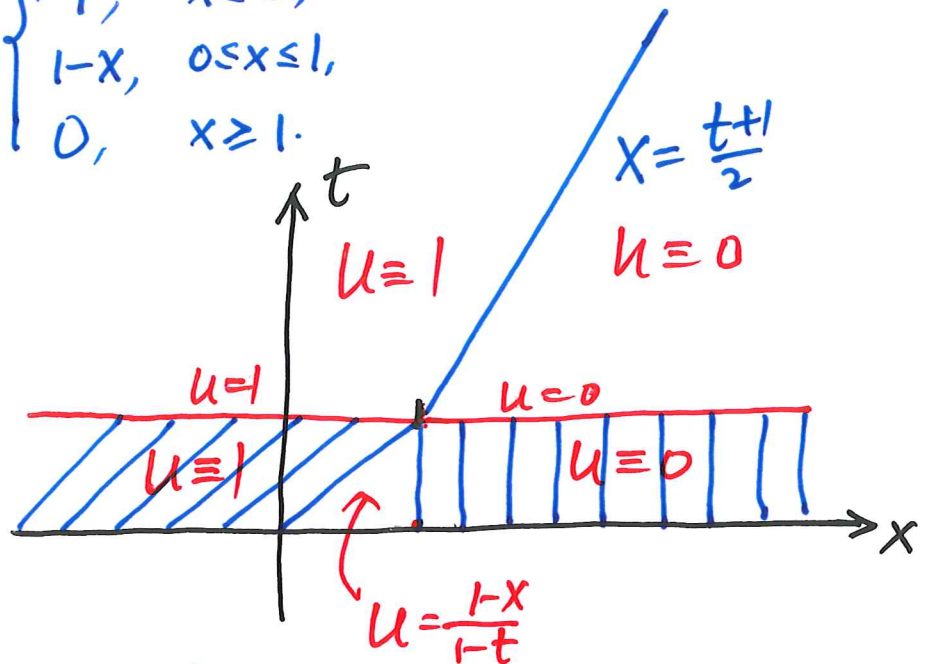
$\sigma = x'(t)$: The speed of the discontinuity curve

$[u] = u_r - u_e$: Jump in u across C .

$[F(u)] = F(u_r) - F(u_e)$: Jump in $F(u)$ across C .

Ex 2.
$$F(u) = \frac{u^2}{2}$$

$$g(x) = \begin{cases} 1, & x \leq 0, \\ 1-x, & 0 \leq x \leq 1, \\ 0, & x \geq 1. \end{cases}$$



$$\sigma = \frac{[F(u)]}{[u]} = \frac{0 - \frac{1}{2}}{0 - 1} = \frac{1}{2} = \frac{dx(t)}{dt}, \quad x(1) = 1,$$

$$\hookrightarrow \boxed{x = X(t) = \frac{t+1}{2}}$$

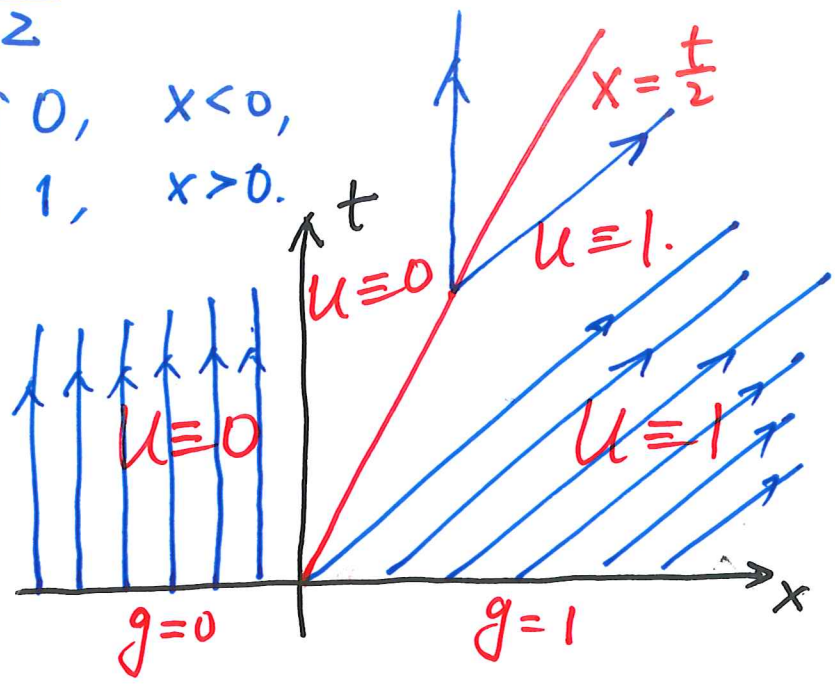
$$u(x, t) = \begin{cases} 1, & x < \frac{t+1}{2}, \\ 0, & x > \frac{t+1}{2}. \end{cases}$$

is an integral solution for $t > 1$

\hookrightarrow global solution

Ex 3.

$$\begin{cases} F(u) = \frac{u^2}{2} \\ g(x) = \begin{cases} 0, & x < 0, \\ 1, & x > 0. \end{cases} \end{cases}$$

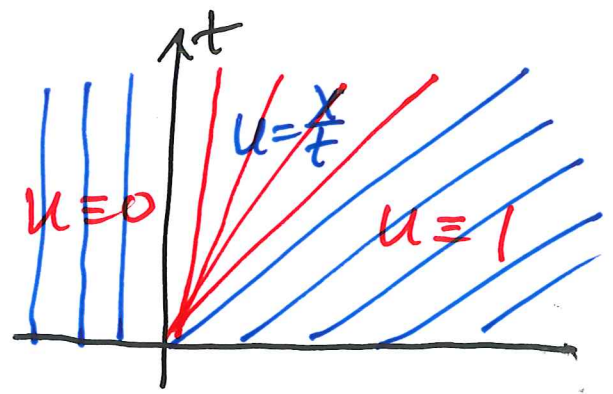


$$\begin{cases} \frac{dx}{dt} = \frac{[F(u)]}{[u]} = \frac{\frac{1}{2} - 0}{1 - 0} = \frac{1}{2} \\ X(0) = 0 \end{cases} \Rightarrow X = X(t) = \frac{1}{2}t$$

↳ $u_1(x,t) = \begin{cases} 0, & x < \frac{t}{2}, \\ 1, & x > \frac{t}{2} \end{cases}$ is an integral solution.
? physical?

Another solution

$$u_2(x,t) = \begin{cases} 1, & x > t, \\ \frac{x}{t}, & 0 < x < t, \\ 0, & x < 0 \end{cases}$$



is also an integral solution!!!

* Nonuniqueness of integral solutions!!

↳ Require additional criteria to single out the physically relevant solution.

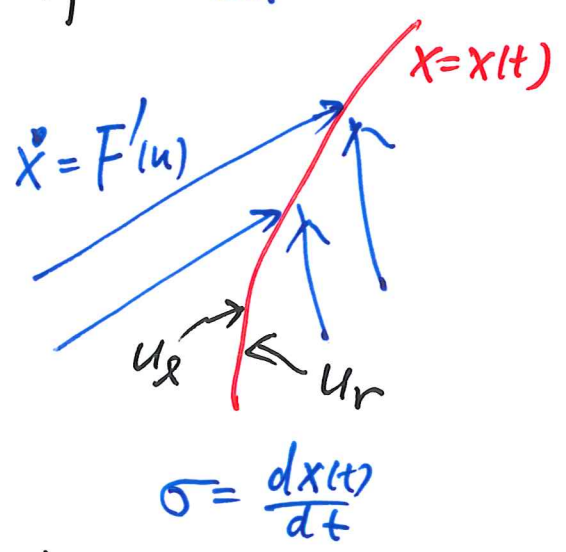
Entropy Condition, Entropy Solutions

Requirement (Stability): Entropy Solutions

Piecewise smooth integral solutions with the property that, if we move backwards in time t along any characteristic, we will never encounter any discontinuity curve for u .

$F'(u_l) > \sigma > F'(u_r)$

Lax Entropy Condition



Shocks

A curve of discontinuity for u satisfying

- R-H Condition
- Lax Entropy Condition

If $F''(u) > 0 \rightarrow F'(u) \uparrow u \Rightarrow u_l > u_r$

Ex 2

$$u(x,t) = \begin{cases} 1 & x \leq t, 0 \leq t \leq 1 \\ \frac{1-x}{1-t} & t \leq x \leq 1, 0 \leq t \leq 1 \\ 0 & x \geq 1, 0 \leq t \leq 1 \\ \hline 1 & x < \frac{t+1}{2}, t > 1 \\ 0 & x > \frac{t+1}{2}, t > 1 \end{cases} \quad 0 \leq t \leq 1$$

is an entropy solution.

Ex 3

$$u_1(x,t) = \begin{cases} 0, & x < \frac{t}{2}, \\ 1, & x > \frac{t}{2}. \end{cases}$$

is **NOT** an entropy solution.

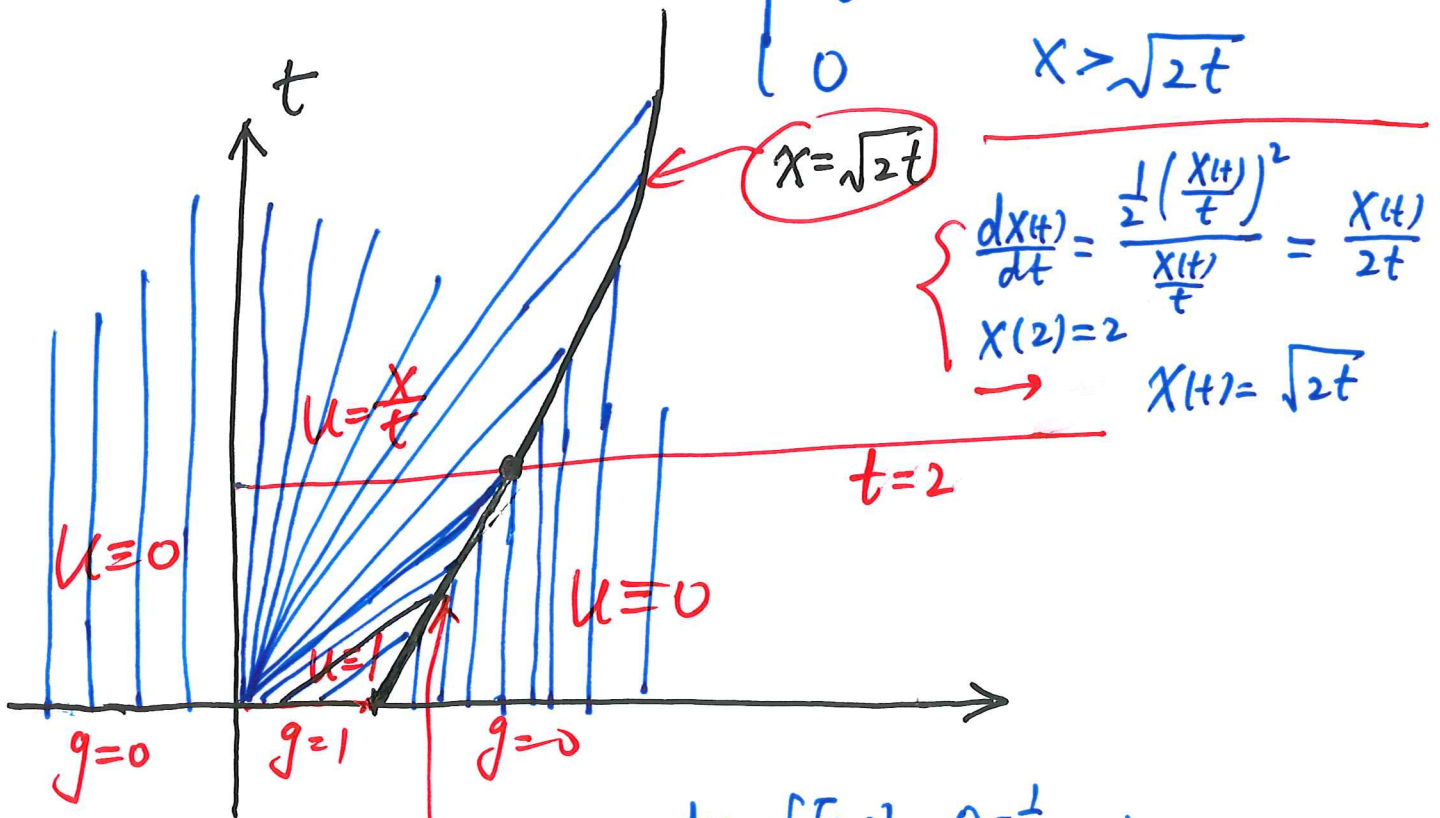
Ex 4
$$\begin{cases} u_t + \left(\frac{u^2}{2}\right)_x = 0, \\ u|_{t=0} = g(x) = \begin{cases} 0 & x < 0 \\ 1 & 0 \leq x \leq 1 \\ 0 & x > 1 \end{cases} \end{cases}$$

$\forall x_0 \in \mathbb{R}$

Characteristics
$$\begin{cases} X(t) = x_0 + g(x_0)t \\ u = g(x_0) \end{cases}$$

$0 \leq t \leq 2$
$$u(x,t) = \begin{cases} 0 & x < 0 \\ \frac{x}{t} & 0 < x < t \\ 1 & t < x < 1 + \frac{t}{2} \\ 0 & x > 1 + \frac{t}{2} \end{cases}$$

$t > 2$
$$u(x,t) = \begin{cases} 0 & x < 0 \\ \frac{x}{t} & 0 < x < \sqrt{2t} \\ 0 & x > \sqrt{2t} \end{cases}$$



$$\frac{dx(t)}{dt} = \frac{\frac{1}{2} \left(\frac{x(t)}{t}\right)^2}{\frac{x(t)}{t}} = \frac{x(t)}{2t}$$

$x(2) = 2 \rightarrow x(t) = \sqrt{2t}$

$x = 1 + \frac{t}{2}$

$$\frac{dx}{dt} = \frac{[F(u)]}{[u]} = \frac{0 - \frac{1}{2}}{0 - 1} = \frac{1}{2}$$

$x - 1 = \frac{1}{2}t, \quad x = 1 + \frac{1}{2}t$

§ 7.3 Lax-Oleinik Formula

$$(*) \quad \begin{cases} u_t + F(u)_x = 0, \\ u|_{t=0} = g(x) \end{cases} \quad F(0) = 0 \text{ (w.o.l.g.)}$$

Theorem 7.1 Assume $\begin{cases} F''(u) > 0, \\ g \in L^\infty(\mathbb{R}) \end{cases}$

Denote $\begin{cases} G = (F')^{-1} \\ L(\xi) = \xi G(\xi) - F(G(\xi)) = F^* \end{cases}$

\hookrightarrow (i) $\forall t > 0, \exists$ a unique point $y(x, t)$ for all but at most countable many values of $x \in \mathbb{R}$ such that

$$\min_{y \in \mathbb{R}} \left\{ tL\left(\frac{x-y}{t}\right) + \int_0^y g(z) dz \right\} = tL\left(\frac{x-y(x,t)}{t}\right) + \int_0^{y(x,t)} g(z) dz$$

$$\max_{p \in \mathbb{R}} \{ p\xi - F(p) \}$$

(ii) The mapping $x \mapsto y(x, t)$ is nondecreasing

(iii) $\forall t > 0$

$$u(x, t) = \frac{\partial}{\partial x} \left[\min_{y \in \mathbb{R}} \left\{ tL\left(\frac{x-y}{t}\right) + \int_0^y g(z) dz \right\} \right] = G\left(\frac{x-y(x,t)}{t}\right) \text{ for a.e. } x.$$

(iv) $u(x, t)$ is an integral solution of $(*)$.

(v) $\exists C > 0$ s.t.

$$U(x+z, t) - U(x, t) \leq \frac{C}{t} z,$$

$$\forall t > 0, x, z \in \mathbb{R}, z > 0$$

§7.4. Entropy Solutions, Uniqueness

Entropy solutions. $U \in L^\infty(\mathbb{R} \times (0, \infty))$ of (*):

$$(i) \int_0^\infty \int_{-\infty}^\infty (U \varphi_t + F(U) \varphi_x) dx dt + \int_{-\infty}^\infty g(x) \varphi(x, 0) dx = 0$$

$$\forall \varphi \in C_c^1(\mathbb{R} \times [0, \infty))$$

$$(ii) U(x+z, t) - U(x, t) \leq C \left(1 + \frac{1}{t}\right) z$$

for some constant $C \geq 0$, a.e. $x, z \in \mathbb{R}, t > 0$, $z > 0$.

Theorem 7.2 (Uniqueness of entropy solutions).

If F is convex and smooth.

$\rightarrow \exists$ 1 entropy solution of (*)

— up to a set of measure zero.

Riemann's Problem

$$u|_{t=0} = g(x) = \begin{cases} u_l, & \text{if } x < 0, \\ u_r, & \text{if } x > 0 \end{cases}$$

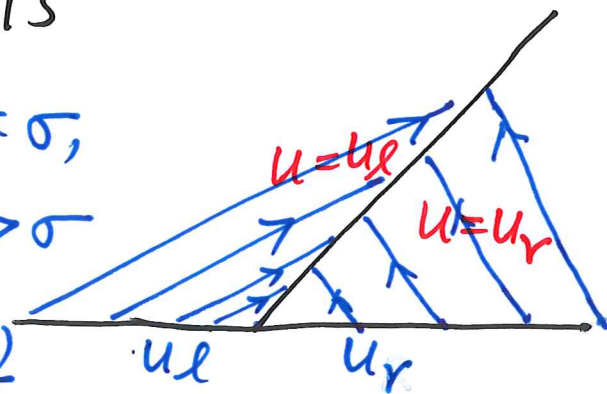
Assume: $F \in C^2$, $F''(u) > 0$, $G = (F')^{-1}$

Theorem 7.3. (Solution of the Riemann Problem)

(i) $u_l > u_r$: The unique entropy solution of the Riemann problem is

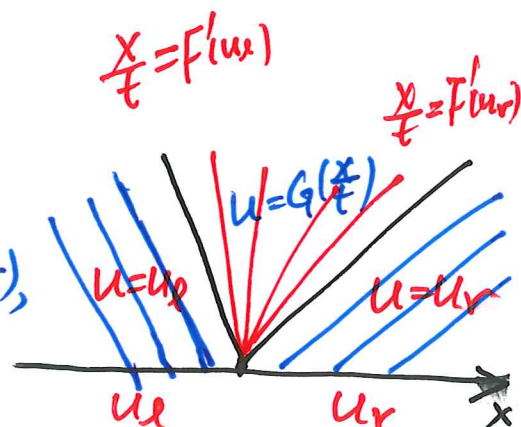
$$u(x, t) = \begin{cases} u_l, & \frac{x}{t} < \sigma, \\ u_r, & \frac{x}{t} > \sigma \end{cases}$$

$$\sigma = \frac{[F(u)]}{[u]} = \frac{F(u_r) - F(u_l)}{u_r - u_l}$$



(ii) $u_l < u_r$: The unique entropy solution of the Riemann problem is

$$u(x, t) = \begin{cases} u_l, & \frac{x}{t} < F'(u_l), \\ G\left(\frac{x}{t}\right), & F'(u_l) < \frac{x}{t} < F'(u_r), \\ u_r, & \frac{x}{t} > F'(u_r) \end{cases}$$



§ 7.5 Large Time Behavior

$F \in C^2, F''(u) \geq \theta > 0, F(0) = 0$ (W.D.L.G)

Asymptotics in L^∞ -norm: $g \in L^\infty(\mathbb{R}^n) \cap L^1(\mathbb{R}^n)$

$\hookrightarrow \exists C > 0$, s.t.

$|u(x,t)| \leq \frac{C}{\sqrt{t}}$

 $\forall x \in \mathbb{R}, t > 0$

Decay to N-Wave

$$\left\{ \begin{array}{l} \text{Supp } g \subset \subset \mathbb{R}, \\ p = -2 \min_{y \in \mathbb{R}} \int_{-\infty}^y g dx > 0, \\ q = 2 \max_{y \in \mathbb{R}} \int_y^{\infty} g dx > 0 \end{array} \right.$$

$\hookrightarrow \exists C > 0$, s.t.

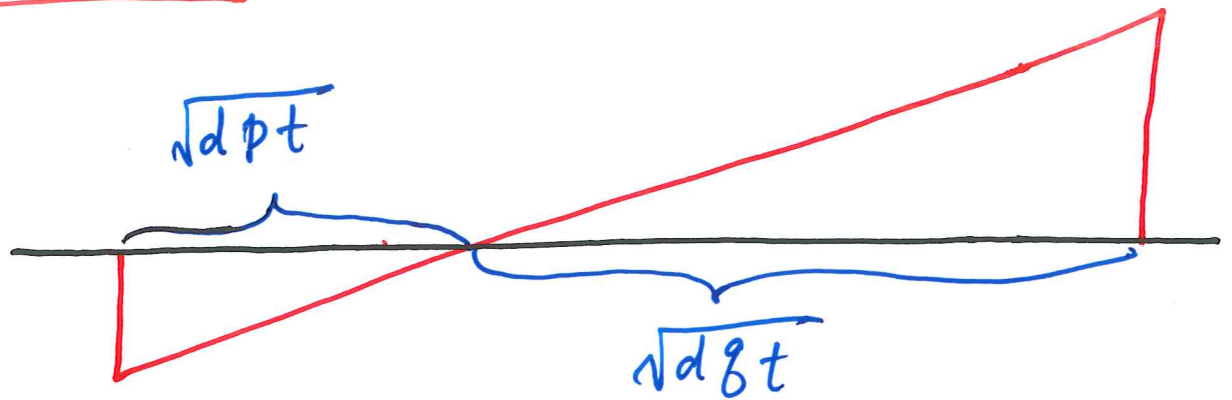
$$\int_{-\infty}^{\infty} |u(x,t) - N(x,t)| dx \leq \frac{C}{\sqrt{t}}, \quad \forall t > 0$$

where the N-wave:

$$N(x,t) = \begin{cases} \frac{1}{d} \left(\frac{x}{t} - \sigma \right), & \text{if } -\sqrt{d|pt} < x - \sigma t < \sqrt{d|qt} \\ 0, & \text{otherwise} \end{cases}$$

$\sigma = F'(0), d = F''(0) \rightarrow G'(\sigma) = \frac{1}{d}$

N-Wave



Read: { § 3.3-3.4 in Evans's book
Chapter 11

More References

1. J. Smoller, *Shock Waves and Reaction-Diffusion Equations*, Springer 1994
Part III. The Theory of shock waves
2. C. M. Dafermos, *Hyperbolic Conservation Laws in Continuum Physics*
Springer, 2010