

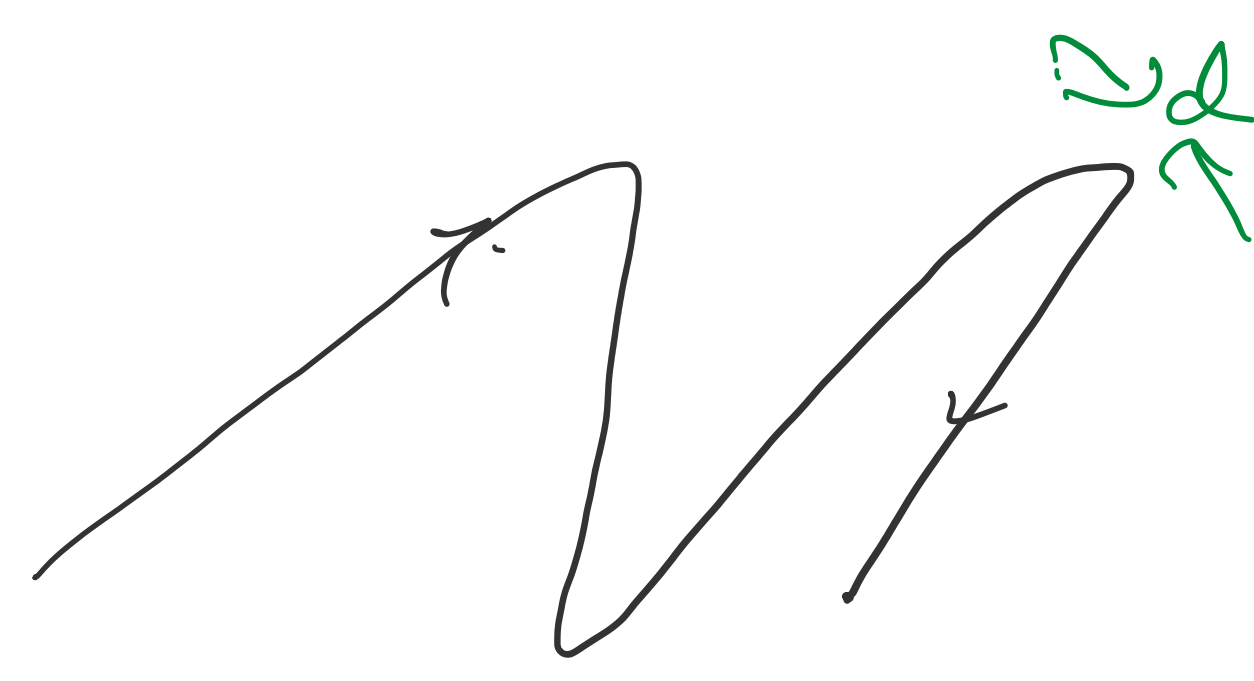
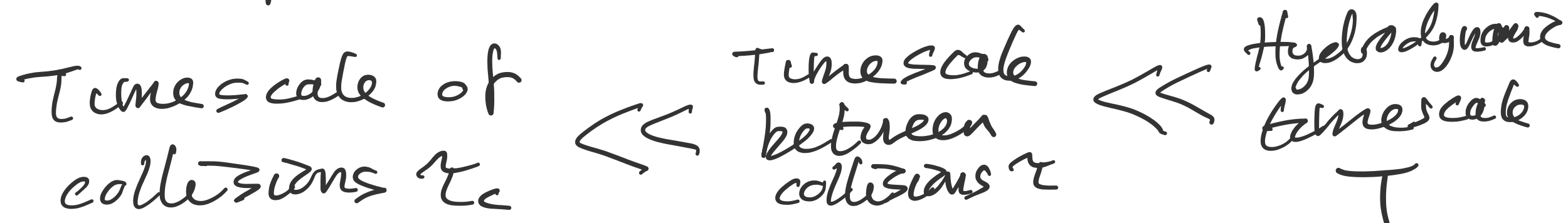
Kinetic theory lecture 1

Reduced probabilistic description of $N \gg 1$ interacting particles.

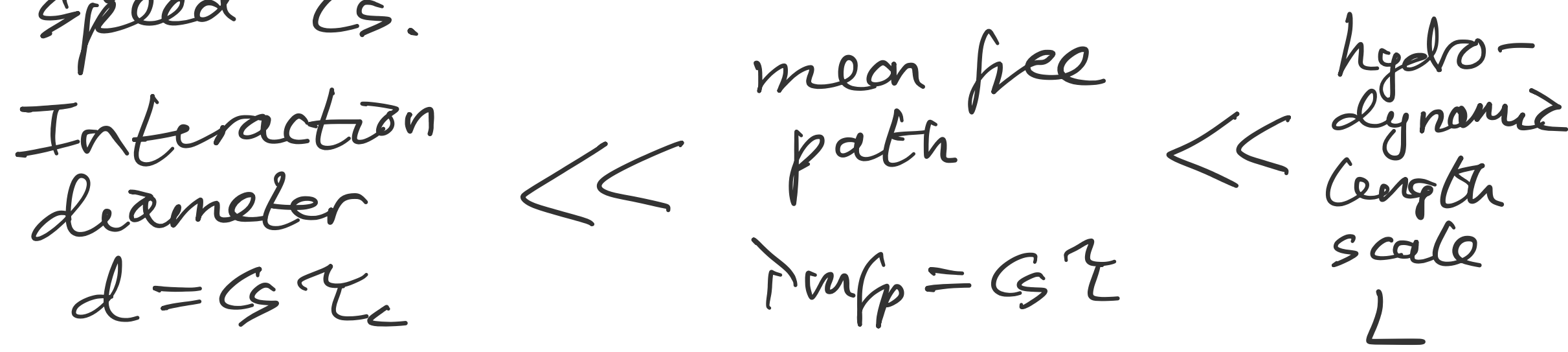
Avogadro's number: 6×10^{23} particles per mole.

In principle $6N$ ODEs, but not practical.

To do better, we rely on a separation of scales.



Typical particle speed is the sound speed c_s .



Picture: free flight for distance λ_{mfp} , sharp bends of diameter d . Boltzmann regime

Opposite Coulomb/Vlasov picture has gently swerving trajectories from weak long-range interactions.

Boltzmann equation describes systems in the Boltzmann-Grad limit:

number density $n \rightarrow \infty$

interaction diameter $d \rightarrow 0$

with $\lambda_{mfp} = O\left(\frac{1}{nd^2}\right) \rightarrow$ finite & nonzero

Think of "hard spheres" of diameter d

In one mean free path, each sweeps out a cylinder of volume

$$\frac{\pi}{4} d^2 \lambda_{mfp}$$

n particles must fill a unit volume

$$\frac{\pi}{4} n d^2 \lambda_{mfp} = 1$$

The Boltzmann-Grad limit $\Rightarrow nd^3 \rightarrow 0$

so the system is dilute

We start with Newton's laws for N particles, a reversible Hamiltonian system, and derive the irreversible Boltzmann and Navier-Stokes equations.

Three levels of description:

N -particle Hamiltonian system

$6N$ ODEs for $\underline{p}_i, \underline{q}_i \quad i=1, \dots, N$

Boltzmann equation for the 1-particle distribution $f_1(\underline{x}, \underline{v}, t)$, one integro-differential equation.

Navier-Stokes, five PDEs in 3D for $\rho(\underline{x}, t), \underline{u}(\underline{x}, t), T(\underline{x}, t)$.

II N -particle Hamiltonian mechanics

system of N particles, positions \underline{x}_i and velocities \underline{v}_i , mass m .

Canonical coordinates $\underline{p}_i = m \underline{v}_i$
 $\underline{q}_i = \underline{x}_i$

Potential $\Phi(\underline{x}_1, \dots, \underline{x}_N)$

$$\text{Hamiltonian } \mathcal{H} = \sum_{i=1}^N \frac{|\underline{p}_i|^2}{2m} + \Phi(\underline{q}_1, \dots, \underline{q}_N)$$

$$\text{Hamilton's equations } \dot{\underline{q}}_i = \frac{\partial \mathcal{H}}{\partial \underline{p}_i}$$

$$\dot{\underline{p}}_i = -\frac{\partial \mathcal{H}}{\partial \underline{q}_i}$$

Rewrite in Poisson bracket form as

$$\dot{\underline{q}}_i = \{ \underline{q}_i, \mathcal{H} \} \quad \text{and} \quad \dot{\underline{p}}_i = \{ \underline{p}_i, \mathcal{H} \},$$

and more generally, for any

$$F(\underline{q}, \underline{p}, t) \quad \text{with} \quad \underline{q} = (\underline{q}_1, \dots, \underline{q}_N)$$

$$\underline{p} = (\underline{p}_1, \dots, \underline{p}_N)$$

$$\frac{dF}{dt} = \frac{\partial F}{\partial t} + \{ F, \mathcal{H} \}$$

where

$$\{ A, B \} = \sum_{i=1}^N \frac{\partial A}{\partial \underline{q}_i} \frac{\partial B}{\partial \underline{p}_i} - \frac{\partial B}{\partial \underline{q}_i} \frac{\partial A}{\partial \underline{p}_i}$$

Accounts for any explicit time-dependence, such as $F = t$.

IV Reduced s-particle distribution functions

The N-particle distribution

$$P(\underline{q}_1, \dots, \underline{q}_N, \underline{p}_1, \dots, \underline{p}_N, t)$$

offers no simplification over the 6N ODEs, rather the reverse...

We can recover the ODE system by taking P to be a product of s-functions corresponding to the initial conditions:

$$P(\underline{q}, \underline{p}, t=0) = \delta^3(\underline{q}_1 - \underline{q}_1^{(0)}) \delta^3(\underline{p}_1 - \underline{p}_1^{(0)}) \dots \delta^3(\underline{q}_N - \underline{q}_N^{(0)}) \delta^3(\underline{p}_N - \underline{p}_N^{(0)})$$

where $\delta^3 \ni$ the 3D δ -function.

Assuming P is normalized to be a probability density function (PDF)

$$\int dV_1 \dots dV_N P(\underline{q}, \underline{p}, t) = 1,$$

we can define normalized reduced or marginal PDFs as

$$P_1(\underline{q}_1, \underline{p}_1, t) = \int dV_2 \dots dV_N P(\underline{q}, \underline{p}, t).$$

$$P_2(\underline{q}_1, \underline{q}_2, \underline{p}_1, \underline{p}_2, t) = \int dV_3 \dots dV_N P(\underline{q}, \underline{p}, t),$$

$$P_s(\underline{q}_1, \dots, \underline{q}_s, \underline{p}_1, \dots, \underline{p}_s, t) = \int dV_{s+1} \dots dV_N P(\underline{q}, \underline{p}, t)$$

If the particles are indistinguishable, these functions are all symmetric under permutations of their arguments, e.g.

$$P_2(\underline{q}_1, \underline{q}_2, \underline{p}_1, \underline{p}_2, t) = P_2(\underline{q}_2, \underline{q}_1, \underline{p}_2, \underline{p}_1, t)$$

on swapping particle 1 and particle 2.

In kinetic theory it's more common to use the s-particle distribution function f_s . The first of these is

$$f_1(\underline{p}', \underline{q}', t) = \left\langle \sum_{i=1}^N \delta^3(\underline{p}' - \underline{p}_i) \delta^3(\underline{q}' - \underline{q}_i) \right\rangle$$

each in 3D

$$= N \int dV_2 \dots dV_N P(\underline{q}_1, \underline{q}_2, \dots, \underline{q}_N, \underline{p}', \underline{p}_2, \dots, \underline{p}_N, t)$$

where the N comes from the particles being indistinguishable, so it doesn't matter which is "particle 1".

In a plasma, one would define an f_i for each species and sum over just the particles of a particular species.

More generally

$$f_s(\underline{q}_1, \underline{q}_2, \dots, \underline{q}_s, \underline{p}_1, \underline{p}_2, \dots, \underline{p}_s, t) = \frac{N!}{(N-s)!} P_s(\underline{q}_1, \dots, \underline{q}_s, \underline{p}_1, \dots, \underline{p}_s, t)$$

We can choose "particle 1" in N ways, in the first slots of f_s , then "particle 2" in $N-1$ ways etc, giving

$$\frac{N!}{(N-s)!} = N(N-1) \dots (N-s+1)$$

ways to choose s particles from N .

Coming up: specialise to 2-particle potentials so

$$H = \sum_{i=1}^N \frac{|\underline{p}_i|^2}{2m} + \sum_{1 \leq i < j \leq N} \phi(|\underline{q}_i - \underline{q}_j|)$$

Consistent with only 2-particle interactions being significant in a dilute gas under the Boltzmann-Grad scaling.

A good conceptual model is the Lennard-Jones potential, $1/r^6$ attraction and a $1/r^{12}$ repulsion.

$1/r^6$ comes from fluctuating partial charges (van der Waals)

$1/r^{12}$ models the Pauli exclusion principle repulsion.

$1/r^5$ repulsion, called "Maxwell molecules". Nice theoretical simplification, but a bit too soft.

Hard spheres

III Liouville's theorem: N -particle distributions

Properties we can measure for a system are some limited set of observables $O(\underline{q}, \underline{p})$, e.g. fluid density or velocity averaged over little regions of space & time.

The ergodic hypothesis says that a finite time average is the same as taking an average over an ensemble of many such N -particle systems, reproducing the same observables but differing in fine details.

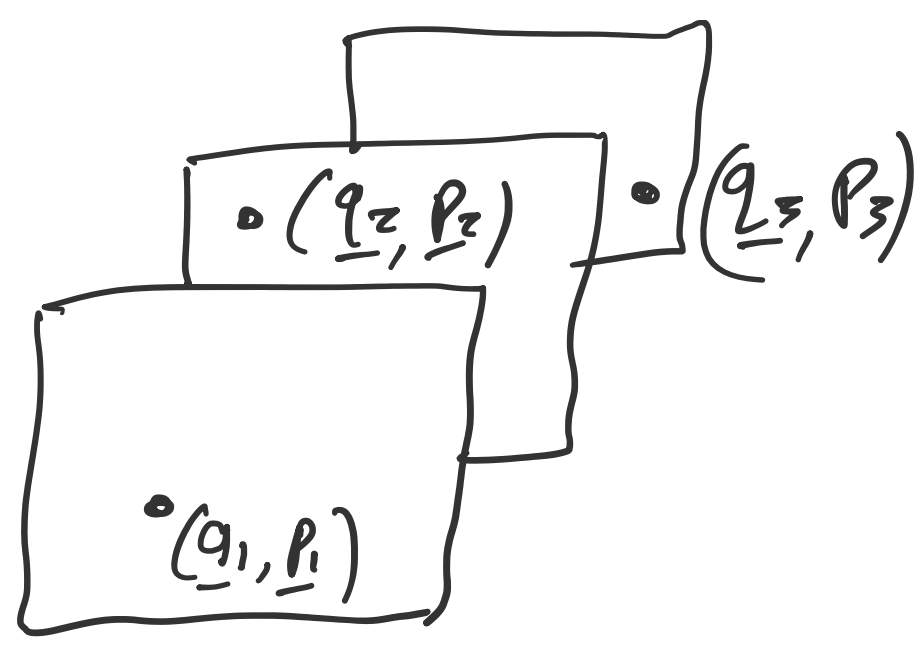
We can represent this ensemble by a density $\rho(\underline{q}_1, \dots, \underline{q}_N, \underline{p}_1, \dots, \underline{p}_N, t)$ in $6N$ -dimensional phase space.

We can use ρ to define ensemble averages for any function $O(\underline{q}, \underline{p})$:

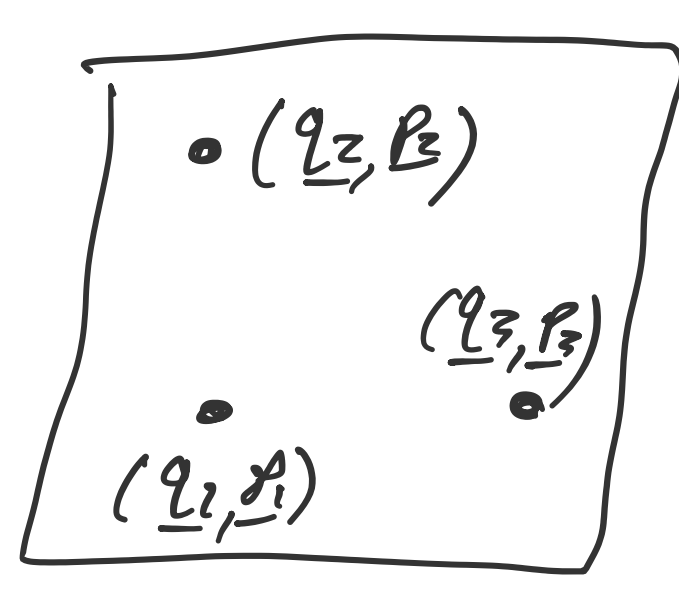
$$\langle O \rangle = \int dV_1 \dots dV_N \rho(\underline{q}, \underline{p}, t) O(\underline{q}, \underline{p})$$

where $dV_i = d\underline{q}_i d\underline{p}_i$ is the $6D$ volume element associated with particle i .

Two ways to look at phase space:



(natural for ρ)



(natural for f , see later)

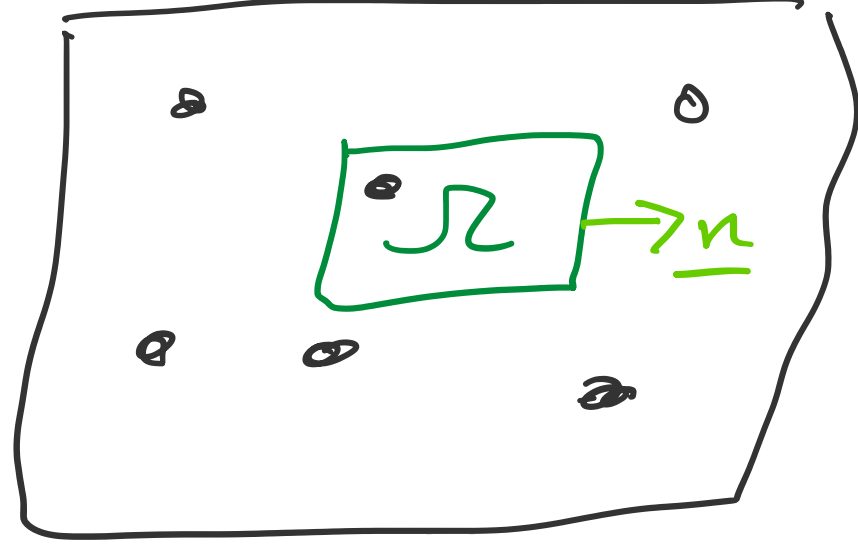
Liouville's theorem says that the evolution of ρ corresponds to a volume-preserving flow in phase space.

Consider a fixed volume Ω in phase space with boundary $\partial\Omega$.

The number of particles inside Ω is

$$n_\Omega = \int_\Omega dV \rho(\underline{q}, \underline{p}, t)$$

where $dV = dV_1 \dots dV_N$.



n_Ω is the expectation of an indicator function that's 1 for $(\underline{q}, \underline{p}) \in \Omega$, 0 otherwise.

As Ω is fixed,

$$\frac{dn_\Omega}{dt} = \int_\Omega dV \frac{\partial \rho}{\partial t}$$

This must equal the change due to the flux of particles across $\partial\Omega$.

$$\frac{dn_\Omega}{dt} = - \int_{\partial\Omega} dS \underline{n} \cdot \underline{\dot{z}} \rho, \quad \underline{z} = (\underline{q}, \underline{p})$$

where \underline{n} is the outward unit normal on $\partial\Omega$ and $\underline{\dot{z}} = (\dot{\underline{q}}, \dot{\underline{p}})$.

Using the divergence theorem:

$$\frac{dn_\Omega}{dt} = - \int_\Omega dV \nabla_{\underline{z}} \cdot (\underline{\dot{z}} \rho)$$

This must coincide with the first expression for $\frac{dn_\Omega}{dt}$ for all fixed volumes Ω so

$$\frac{\partial \rho}{\partial t} + \nabla_{\underline{z}} \cdot (\underline{\dot{z}} \rho) = 0.$$

Unpacking the \underline{z} notation:

$$\frac{\partial \rho}{\partial t} + \sum_{i=1}^N \left[\frac{\partial}{\partial q_i} \cdot (\dot{q}_i \rho) + \frac{\partial}{\partial p_i} \cdot (\dot{p}_i \rho) \right] = 0,$$

$$\frac{\partial \rho}{\partial t} + \sum_{i=1}^N \left[\frac{\partial}{\partial q_i} \cdot \left(\frac{\partial H}{\partial p_i} \rho \right) + \frac{\partial}{\partial p_i} \cdot \left(-\frac{\partial H}{\partial q_i} \rho \right) \right] = 0$$

$$\frac{\partial \rho}{\partial t} + \sum_{i=1}^N \left[\frac{\partial H}{\partial p_i} \cdot \frac{\partial \rho}{\partial q_i} - \frac{\partial H}{\partial q_i} \cdot \frac{\partial \rho}{\partial p_i} + \rho \left(\frac{\partial}{\partial q_i} \cdot \frac{\partial H}{\partial p_i} - \frac{\partial}{\partial p_i} \cdot \frac{\partial H}{\partial q_i} \right) \right] = 0$$

= 0 as $\frac{\partial^2 H}{\partial q_i \partial p_i} = \frac{\partial^2 H}{\partial p_i \partial q_i}$

$$\frac{\partial \rho}{\partial t} + \{ \rho, H \} = 0.$$

Along trajectories in phase space

$$\frac{d\rho}{dt} = \frac{\partial \rho}{\partial t} + \{ \rho, H \} = 0.$$

The particle trajectories define the characteristics for Liouville's equation as a PDE.

This is closely linked to reversibility: phase space volumes neither expand nor contract as they evolve.

More precisely, if $\rho(\underline{q}, \underline{p}, t)$ solves Liouville's equation, so does $\rho(\underline{q}, -\underline{p}, -t)$.

Exercise: show that

$$\frac{d}{dt} \langle O \rangle = \langle \{ O, H \} \rangle$$

for any observable $O(\underline{q}, \underline{p})$.

Classical analogue of Ehrenfest's theorem in quantum mechanics.