

Homework problems, days 1-4

1. Complex projective space $\mathbb{C}\mathbb{P}^n$ is the set of 1-dimensional vector subspaces of \mathbb{C}^{n+1} . Points in $\mathbb{C}\mathbb{P}^n$ are written $[z_0, \dots, z_n]$ for (z_0, \dots, z_n) in $\mathbb{C}^{n+1} \setminus \{0\}$, where $[z_0, \dots, z_n] = \mathbb{C} \cdot (z_0, \dots, z_n) \subseteq \mathbb{C}^{n+1}$, and $[\lambda z_0, \dots, \lambda z_n] = [z_0, \dots, z_n]$ for $\lambda \in \mathbb{C}^* = \mathbb{C} \setminus \{0\}$. Equivalently, $\mathbb{C}\mathbb{P}^n = (\mathbb{C}^{n+1} \setminus \{0\})/\mathbb{C}^*$, where \mathbb{C}^* acts by $\lambda : (z_0, \dots, z_n) \mapsto (\lambda z_0, \dots, \lambda z_n)$. It has the quotient topology induced from the surjective projection $\pi : \mathbb{C}^{n+1} \setminus \{0\} \rightarrow \mathbb{C}\mathbb{P}^n$, $\pi : (z_0, \dots, z_n) \mapsto [z_0, \dots, z_n]$.

Write down an explicit atlas on $\mathbb{C}\mathbb{P}^n$, compute the transition functions between charts, and prove that it makes $\mathbb{C}\mathbb{P}^n$ into a smooth $2n$ -dimensional manifold. (Hint: use $n + 1$ charts (U_i, ϕ_i) for $i = 0, \dots, n$, such that $\phi_i(U_i)$ is the open subset of $[z_0, \dots, z_n] \in \mathbb{C}\mathbb{P}^n$ with $z_i \neq 0$ — try fixing $z_i = 1$.)

2. Let X, Y be manifolds. Show carefully that $X \times Y$ has a unique manifold structure such that if $(U, \phi), (V, \psi)$ are charts on X, Y then $(U \times V, \phi \times \psi)$ is a chart on $X \times Y$, and $\dim(X \times Y) = \dim X + \dim Y$.

3(a) Let X be the sphere $\mathcal{S}^n = \{(x_0, \dots, x_n) \in \mathbb{R}^{n+1} : x_0^2 + \dots + x_n^2 = 1\}$. Explain why we may identify

$$T_{(x_0, \dots, x_n)}\mathcal{S}^n \cong \{(y_0, \dots, y_n) \in \mathbb{R}^{n+1} : x_0 y_0 + \dots + x_n y_n = 0\}.$$

(b) By identifying $\mathbb{R}^{2k+2} \cong \mathbb{C}^{k+1}$, show that any odd-dimensional sphere \mathcal{S}^{2k+1} has a nonvanishing vector field $v \in C^\infty(T\mathcal{S}^{2k+1})$ (i.e. $v \neq 0$ at every point).

For discussion: can the same thing hold for even-dimensional spheres \mathcal{S}^{2k} ?

4. Let X be a manifold and $v, w \in C^\infty(TX)$. Suppose (x_1, \dots, x_n) are local coordinates on an open set $U \subseteq X$, so that we may write $v = v_1 \frac{\partial}{\partial x_1} + \dots + v_n \frac{\partial}{\partial x_n}$ and $w = w_1 \frac{\partial}{\partial x_1} + \dots + w_n \frac{\partial}{\partial x_n}$ on U , for $v_i, w_j : U \rightarrow \mathbb{R}$ smooth.

Define the Lie bracket $[v, w] \in C^\infty(TX)$ by

$$[v, w] = \sum_{i,j=1}^n \left(v_i \frac{\partial w_j}{\partial x_i} \cdot \frac{\partial}{\partial x_j} - w_j \frac{\partial v_i}{\partial x_j} \cdot \frac{\partial}{\partial x_i} \right) \quad \text{on } U. \tag{1}$$

Prove that this is independent of choice of local coordinates. That is, if (y_1, \dots, y_n) is another local coordinate system on $V \subseteq X$, then (1) and its analogue for $(y_1, \dots, y_n), V$ define the same vector field on $U \cap V$.

5. Take $\alpha \in \Lambda^k V$ where $\dim V = n$ and consider the linear map $A_\alpha : \Lambda^{n-k} V \rightarrow \Lambda^n V$ defined by $A_\alpha(\beta) = \alpha \wedge \beta$.

(i) Show that if $\alpha \neq 0$, then $A_\alpha \neq 0$.

(ii) Prove that the map $\alpha \mapsto A_\alpha$ is an isomorphism from $\Lambda^k V$ to the vector space $\text{Hom}(\Lambda^{n-k} V, \Lambda^n V)$ of linear maps from $\Lambda^{n-k} V$ to $\Lambda^n V$. Thus if we choose an isomorphism $\Lambda^n V \cong \mathbb{R}$ we get isomorphisms $\Lambda^k V \cong (\Lambda^{n-k} V)^*$.

6. Let $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ be defined by $F(x, y, z) = (xy, yz, zx)$. Calculate $F^*(x dy \wedge dz)$ and $F^*(x dy + y dz)$.

7.(a) Prove explicitly that the de Rham cohomology groups of \mathbb{R} are $H^0(\mathbb{R}) \cong \mathbb{R}$ and $H^1(\mathbb{R}) = 0$.

(b) Similarly, for $\mathcal{S}^1 = \mathbb{R}/\mathbb{Z}$, prove explicitly that $H^0(\mathcal{S}^1) \cong \mathbb{R}$ and $H^1(\mathcal{S}^1) \cong \mathbb{R}$.

Hint: Write $\Omega^0(\mathbb{R}) = \{f(x) \mid f : \mathbb{R} \rightarrow \mathbb{R} \text{ is smooth}\}$, and $\Omega^1(\mathbb{R}) = \{g(x)dx \mid g : \mathbb{R} \rightarrow \mathbb{R} \text{ is smooth}\}$, so that $d : \Omega^0(\mathbb{R}) \rightarrow \Omega^1(\mathbb{R})$ maps $f(x) \mapsto \frac{df}{dx}(x)dx$. For \mathcal{S}^1 , do the same, except that f, g are \mathbb{Z} -periodic, $f(x) = f(x + n)$ for $n \in \mathbb{Z}$.

8. Show that the product $X \times Y$ of two orientable manifolds is orientable.

9. Is $\mathcal{S}^2 \times \mathbb{R}\mathbb{P}^2$ orientable? What about $\mathbb{R}\mathbb{P}^2 \times \mathbb{R}\mathbb{P}^2$?

10. A *Riemann surface* is defined as a 2-dimensional manifold X with an atlas $\{(U_i, \phi_i) : i \in I\}$ whose transition maps $\phi_j^{-1} \circ \phi_i$ for $i, j \in I$ are maps from an open set $\phi_i^{-1}(\phi_j(U_j))$ of $\mathbb{C} = \mathbb{R}^2$ to another open set $\phi_j^{-1}(\phi_i(U_i))$ which are *holomorphic* and invertible. By considering the Jacobian of $\phi_j^{-1} \circ \phi_i$, show that a Riemann surface is orientable.