

Quantum Electrodynamical Birdtracks

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I. Introduction

This paper provides a diagrammatic version of the Feynman-Dyson derivation of non-commutative electromagnetism from quantum mechanical formalism [1], [2]. Our spin-network formalism lays bare the structure of this result.

Here is a statement of the main result in conventional notation. $X = (X_1, X_2, X_3)$ denotes a vector of non-commutative coordinates, each a differentiable function of time t . Let $\dot{X} = (\dot{X}_1, \dot{X}_2, \dot{X}_3)$ denote the vector of time derivatives of these functions. Let κ be a non-zero scalar. Assume the axioms below:

$$\left. \begin{array}{l} (1) \quad [X_i, X_j] = 0 \quad \text{for all } i, j. \\ (2) \quad [X_i, \dot{X}_j] = \kappa \delta_{ij} \end{array} \right\}$$

Here $[X, Y] = XY - YX$ and

$$\delta_{ij} = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j. \end{cases}$$

Then there exist fields E and H such that

$$(a) \ddot{\mathbf{X}} = \mathbf{E} + \dot{\mathbf{X}} \times \mathbf{H}$$

$$(b) \nabla \cdot \mathbf{H} = 0$$

$$(c) \frac{\partial \mathbf{H}}{\partial t} + \nabla \times \mathbf{E} = 0.$$

In fact, we can take $\mathbf{H} = \frac{1}{\kappa} \dot{\mathbf{X}} \times \dot{\mathbf{X}}$ where this denotes the non-commutative vector cross product.

In this paper we give a new proof of this result. These methods apply equally well to the discrete framework employed in [2].

Section II reviews notation and defines the non-commutative vector calculus via abstract tensor diagrams. Section III contains the promised derivation. Section IV discusses problems and questions arising from this work.

II. Vectors, Abstract Tensors and The Epsilon

A vector $A = (A_1, A_2, A_3)$ will be indicated by $\underset{\curvearrowright}{A}$ or \textcircled{A} where the arc denotes

the index. Multi-indexed objects have multiple arcs. Thus $i \cap_j = \delta_{ij}$ and $\int_i^i = \delta_j^i$. Compare [3].

We sum over repeated indices.

Such indices correspond to arcs without free ends.

$$\text{For example, } \bigcirc = \sum_{i=1}^3 \underset{i}{\cap}_i = \sum_{i=1}^3 \delta_{ii} = 3.$$

$$A \cdot B = \sum_{i=1}^3 A_i B_i = \underbrace{A B}.$$

Let $\begin{array}{c} i \quad j \\ \diagdown \quad / \\ \cdot \\ | \\ k \end{array} = \epsilon_{ijk} = \begin{cases} \text{sgn}(ijk) & \text{if } ijk \text{ distinct} \\ 0 & \text{otherwise} \end{cases}.$

Then $\boxed{A \times B = A \underbrace{B}} \quad \text{since}$

$$(A \times B)_k = \sum_{i,j} \epsilon_{ijk} A_i B_j.$$

Note that in a non-commutative context

$$(A \times A)_k = \sum_{i,j} \epsilon_{ijk} A_i A_j$$

$$(A \times A)_1 = [A_2, A_3]$$

$$(A \times A)_2 = [A_3, A_1]$$

$$(A \times A)_3 = [A_1, A_2].$$

Thus, we can no longer assert $A \times A = 0$, unless the coordinates of A commute with one another.

We shall use the axioms stated in the introduction. Thus $X \times X = 0$ is equivalent to the first axiom. The second axiom states that $[X_i, \dot{X}_j] = \kappa \delta_{ij}$.

Thus $\frac{1}{\kappa} [X_i, \dot{X}_j] = \partial X_i / \partial X_j$. This means that if F is any function of these non-commuting variables, we can define

$$\boxed{\frac{\partial F}{\partial X_i} = \frac{1}{\kappa} [F, \dot{X}_i]}.$$

Thus $\nabla \cdot A = \sum_i \frac{\partial A_i}{\partial x_i} = \frac{1}{\kappa} [A, \dot{X}]$ and

$\nabla \times F = -\frac{1}{\kappa} F \dot{X}$ $\left(\nabla \times F = \partial F = \frac{1}{\kappa} [F, \dot{X}] \right)$

With these definitions, we can proceed to work out the details on non-commutative vector calculus.

The key to calculations is the basic epsilon identity:

$$\sum_i \epsilon_{abi} \epsilon_{icd} = -\delta_d^a \delta_c^b + \delta_c^a \delta_d^b$$

$$\Leftrightarrow \left(\text{Y-junction} \right) = - \left(\text{X-junction} \right) + \left(\text{X-junction} \right)$$

For example,

$$A \times (B \times C) = A \cdot B \cdot C = -A \cdot C \cdot B + A \cdot B \cdot C$$

In the commutative case, this reduces directly to: $A \times (B \times C) = -(A \cdot B)C + (A \cdot C)B$.

In the non-commutative case we are left with $A \times (B \times C) = -(A \cdot B)C + A \cdot B \cdot C$.

The network formalism articulates the non-commutative vector analysis.

III. Non-Commutative Electromagnetism

As explained in sections I and II, we assume coordinates X such that

$$(1) \quad \left[\underset{\downarrow}{X}, \underset{\downarrow}{X} \right] = 0$$

$$(2) \quad \left[\underset{\downarrow}{X}, \underset{\downarrow}{\dot{X}} \right] = \kappa \cap .$$

In section II we showed that (1) $\Leftrightarrow X \times X = 0$, and defined differentiation so that (2) implied

$$\frac{\partial}{\partial X_i} = \left[\underset{\downarrow}{}, \underset{\downarrow}{\dot{X}_i} \right] / \kappa .$$
 We now define the

fields H and E by the formulas

$$\left. \begin{aligned} H &= \frac{1}{\kappa} \underset{\downarrow}{\dot{X}} \underset{\downarrow}{\dot{X}} = \frac{1}{\kappa} \dot{X} \times \dot{X}, \\ E &= \ddot{X} - \dot{X} \times H \end{aligned} \right\} .$$

Our first task is to show that neither E nor H have any dependence on \dot{X} . Since (2) (above) holds, this is equivalent to showing that $\left[\underset{\downarrow}{E}, \underset{\downarrow}{X} \right] = 0 = \left[\underset{\downarrow}{H}, \underset{\downarrow}{X} \right]$.

Lemma 1. $\kappa \underset{\downarrow}{H} = \left[\underset{\downarrow}{X}, \underset{\downarrow}{\ddot{X}} \right]$

Proof. $\underset{\downarrow}{H} = \frac{1}{\kappa} \underset{\downarrow}{\dot{X}} \underset{\downarrow}{\dot{X}} = -\frac{1}{\kappa} \underset{\downarrow}{\dot{X}} \underset{\downarrow}{\dot{X}} + \frac{1}{\kappa} \underset{\downarrow}{\dot{X}} \underset{\downarrow}{\dot{X}}$

$$= -\frac{1}{\kappa} \left[\underset{\downarrow}{\dot{X}}, \underset{\downarrow}{\dot{X}} \right]$$

$$= \frac{1}{\kappa} \left[\underset{\downarrow}{X}, \underset{\downarrow}{\ddot{X}} \right] \quad \left(\left[\underset{\downarrow}{X}, \underset{\downarrow}{\dot{X}} \right] = 0 \right) //$$

Lemma 2. $[E, X] = [H, X] = 0$.

Proof. $[H, X] = \frac{1}{\kappa} \dot{X} \dot{X} X - \frac{1}{\kappa} X \dot{X} \dot{X}$

$$= \frac{1}{\kappa} \dot{X} [\dot{X}, X] - \frac{1}{\kappa} [X, \dot{X}] \dot{X}$$

$$= -\dot{X} - \dot{X} = 0 //$$

$$[X, E] = [X, \ddot{X}] - X \dot{X} H + \dot{X} H X$$

$$= X H - [X, \dot{X}] H + \dot{X} [H, X]$$

$$= X H - \kappa H + 0$$

$$= 0 //$$

Remark. Lemma 2 implies that E and H are functions only of X_1, X_2, X_3 . Hence $E X E = H X H = 0$, since $X X X = 0$.

If F is a function only of X_1, X_2, X_3 , then

$$\dot{F} = \frac{\partial F}{\partial t} + \sum_i \dot{X}_i \frac{\partial F}{\partial X_i} = \frac{\partial F}{\partial t} + \frac{1}{\kappa} \dot{X} [F, \dot{X}].$$

Thus

$$\frac{\partial H}{\partial t} = \dot{H} + \frac{1}{\kappa} \dot{X} [\dot{X}, H].$$

Lemma 3. $\nabla \cdot H = 0.$

$$\begin{aligned}
 \text{Proof. } \nabla \cdot H &= \frac{1}{\kappa} [H, \dot{X}] \\
 &= \frac{1}{\kappa} H \dot{X} - \frac{1}{\kappa} \dot{X} H \\
 &= \frac{1}{\kappa^2} \dot{X} \dot{X} \dot{X} - \frac{1}{\kappa^2} \dot{X} \dot{X} \dot{X} \\
 &= 0 \quad //
 \end{aligned}$$

Lemma 4. $\partial_t H + \nabla \times E = 0.$

$$\text{Proof. } \partial_t H = \dot{H} + \frac{1}{\kappa} \dot{X} [\dot{X}, H]$$

$$\dot{H} = \frac{1}{2\kappa} [\dot{X}, \dot{X}]^\cdot = \frac{1}{\kappa} [\ddot{X}, \dot{X}] = \frac{1}{\kappa} [E, \dot{X}] + \frac{1}{\kappa} [\dot{X} \times H, \dot{X}]$$

$$= -\nabla \times E + \frac{1}{\kappa} [\dot{X} H, \dot{X}]$$

$$= -\nabla \times E - \frac{1}{\kappa} [\dot{X} H, \dot{X}] + \frac{1}{\kappa} [\dot{X} H, \dot{X}]$$

$$= -\nabla \times E - \frac{1}{\kappa} \dot{X} H \dot{X} + \frac{1}{\kappa} \dot{X} \dot{X} H + \frac{1}{\kappa} \dot{X} H \dot{X} - \frac{1}{\kappa} \dot{X} \dot{X} H$$

$$\dot{H} = -\nabla \times E + \frac{1}{\kappa} \dot{X} [H, \dot{X}] - \frac{1}{\kappa} \dot{X} [H, \dot{X}] + \frac{1}{\kappa} [\dot{X}, \dot{X}] H$$

The third term vanishes because $\nabla \cdot H = 0.$

$$\begin{aligned}
 \text{Hence } \partial_t H + \nabla_x E &= \frac{1}{\kappa} [\dot{x}, \dot{x}] H \\
 &= \frac{1}{\kappa} \left\{ \dot{x} \dot{x} H - \dot{x} \dot{x} H \right\} \\
 &= \frac{1}{\kappa} \left\{ \dot{x} \dot{x} H \right\} = \mathbf{H} \mathbf{H} = \mathbf{H} \times \mathbf{H} = \mathbf{0} //
 \end{aligned}$$

IV. Discussion

In this entire derivation the only appearance of non-algebraic calculus is in the time derivative \dot{x} . This can also be made algebraic by choosing a formal discrete time-evolution operator \mathcal{T} so that $x' = \mathcal{T}^{-1} x \mathcal{T}$ denotes the next (discrete) time value of x . Then we can take $\dot{x} = \mathcal{T}(x' - x) = [x, \mathcal{T}]$ and proceed as before. This is a capsule summary of the approach taken by the author and Pierre Noyes in [2].

References

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3. R. Penrose, *Applications of negative dimensional tensors*. "Combinatorial Mathematics and Its Applications" edited by D. J. A. Welsh, Academic Press (1971), p. 221-244.