

Five things you can do with a surface in PT

Consider Minkowski 4-space M , embedded in its complexification $\mathbb{C}M$. The following five geometrical structures in M , or $\mathbb{C}M$, are essentially equivalent:

- (1) a shear-free ray congruence \mathcal{R} in M ,
- (2) an oriented timelike 2-surface \mathcal{T} in M
(ie. an oriented string history),
- (3) a complex null hypersurface \mathcal{N} in $\mathbb{C}M$,
- (4) a complex null 2-surface \mathcal{U} in $\mathbb{C}M$,
- (5) another shear-free ray congruence \mathcal{R}^* in M .

(NB: a "ray" is a "null geodesic")

The word "essentially" in the above assertion is a little difficult to be precise about. In essence, what I mean by "essentially" here is a combination of the following three qualifications: (a) "in general", (b) "locally", and (c) "in the analytic case". However, we must be careful about the sense in which (b) is intended: certainly not local to a particular region of $\mathbb{C}M$; local in twistor space is more to the point. Moreover, we must also be a little cautious about the meaning of (a) in conjunction with (c). These matters should become clearer in a moment.

In short, the equivalence between (1), (2), (3), (4), and (5) arises from the fact that each provides a different space-time interpretation (in M or in $\mathbb{C}M$) of a holomorphic surface \mathcal{S} in PT . Before explaining this, it will clarify matters a little if I give the space-time relations between (1), (2), (3), (4), and (5) directly.

The equivalence between (2) and (3) is explained if we first think of a spacelike 2-surface instead of a timelike one. Such a surface is always (locally) the intersection of two real null hypersurfaces (generated by the rays meeting the 2-surface orthogonally). Complexifying this, we see that a complex (non-null) surface \mathcal{T} is (locally) uniquely the intersection of two complex null hypersurfaces

\mathcal{N} and $\tilde{\mathcal{N}}$. If \mathcal{T} is to be real, the unordered pair of hypersurfaces $(\mathcal{N}, \tilde{\mathcal{N}})$ must go to itself under complex conjugation. There are two ways for this to happen:
 (i) $\mathcal{N} = \bar{\mathcal{N}}$ and $\tilde{\mathcal{N}} = \overline{\tilde{\mathcal{N}}}$ — when \mathcal{T} is spacelike — and
 (ii) $\tilde{\mathcal{N}} = \bar{\mathcal{N}}$ — when \mathcal{T} is timelike. Thus, a real timelike \mathcal{T} , being the real intersection of \mathcal{N} with $\bar{\mathcal{N}}$, is simply the set of real points of \mathcal{N} . The choice of orientation of \mathcal{T} corresponds to the selection of \mathcal{N} rather than $\bar{\mathcal{N}}$; this orientation is reversed when \mathcal{N} is replaced by $\bar{\mathcal{N}}$.

As for the complex 2-surface \mathcal{U} of (4), it may be interpreted as the (primary) caustic of \mathcal{N} . Thus, \mathcal{U} represents the locus of points of \mathcal{N} at which generators of \mathcal{N} intersect neighbouring generators of \mathcal{N} . Starting from the complex null 2-surface \mathcal{U} , we can generate \mathcal{N} as the locus of rays which touch \mathcal{U} . To put this another way, noting that any regular point of \mathcal{U} has a unique null tangent to \mathcal{U} there, we find that (most of) \mathcal{N} is generated by the rays through such points in the direction of these null tangents.

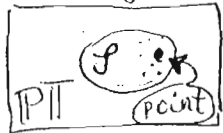
The relation between (1) and (2) is obtained through the fact that the real caustic of a (generic) shear-free ray congruence \mathcal{R} in \mathcal{M} is a timelike 2-surface \mathcal{T} . (For example, in the case of the "Kerr-black-hole" congruence \mathcal{R} in \mathcal{M} , \mathcal{T} describes the history of the ring singularity.) In fact, \mathcal{T} is a secondary caustic of \mathcal{R} . The primary caustic of \mathcal{R} — or, rather, of its complexification $\mathbb{C}\mathcal{R}$ — is the pair of complex null hypersurfaces $\mathcal{N}, \bar{\mathcal{N}}$, and this largely expresses the relation between (1) and (3). More completely, we can say that \mathcal{R} is the family of real rays lying in those α -planes which contain a generator of \mathcal{N} . Equivalently (by complex conjugation), \mathcal{R} consists of real rays in β -planes through generators of $\bar{\mathcal{N}}$. The relation between (1) and (4) can be directly obtained from the fact that \mathcal{R} consists of the real rays in α -planes touching \mathcal{U} .

Finally, the ray congruence \mathcal{R}^* of (5) is obtained simply by reversing the orientation of \mathcal{T} , i.e. by replacing \mathcal{N} by $\bar{\mathcal{N}}$, so that

\mathcal{R}^* consists of the real rays in β -planes containing generators of \mathcal{N} — or, equivalently, touching \mathcal{U} — or in α -planes containing generators of \mathcal{N} . (In the case of a Kerr black hole congruence, \mathcal{R}^* is related to \mathcal{R} simply by having the opposite angular momentum, but in general \mathcal{R}^* will look completely different from \mathcal{R} .)

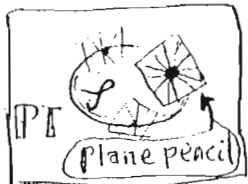
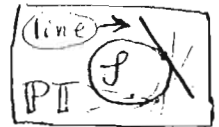
Let us now see how all this relates to a holomorphic surface \mathcal{S} in \mathbb{PT} . The well-known Kerr theorem (see Spinors and Space-time Vol. 2, pp. 200-203) asserts that any real (analytic) shear-free ray congruence \mathcal{R} in \mathbb{M} consists of the rays represented by the intersection with $\mathbb{PN}(-I)$ of a holomorphic surface $\mathcal{S} \subset \mathbb{PT}$. Moreover, \mathcal{S} is determined by \mathcal{R} . Thus, (1) is equivalent to a holomorphic surface \mathcal{S} in \mathbb{PT} . Closely related is the representation of the whole of \mathcal{S} , in complex space-time terms, as a 2-parameter family of α -planes in \mathbb{CM} (where \mathcal{R} consists of the real rays in these α -planes).

This particular (complex) space-time description interprets



\mathcal{S} as a system of points.

Another way of interpreting \mathcal{S} is in terms of the lines which touch it. This is a 3-parameter family of lines. These lines correspond to the points of \mathbb{CM} which lie on some hypersurface — in fact, the null hypersurface \mathcal{N} . The generators



of \mathcal{N} correspond to the plane pencils of lines touching \mathcal{S} at fixed points. Thus, (3) is also equivalent to \mathcal{S} . We can also represent

\mathcal{S} in terms of the 2-complex parameter family of planes which touch \mathcal{S} . This gives a 2-parameter family of



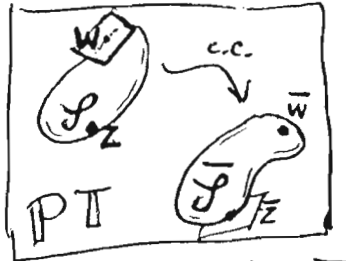
β -planes in \mathbb{CM} , and the intersections of these β -planes with \mathbb{M} provide another shear-free ray congruence in \mathbb{M} , namely \mathcal{R}^* .

As for the complex null surface \mathcal{U} , its points

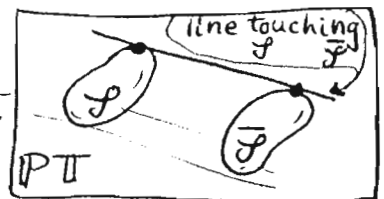
correspond to lines in \mathbb{P}^2 which have three-point contact with \mathcal{S} (i.e. they are not simply tangent to \mathcal{S} , but touch it to higher order). These lines constitute a 2-parameter family — giving \mathcal{U} as a 2-surface. At a general point of \mathcal{S} , there are two such lines in the plane pencil of tangent lines there. Thus, a general generator of \mathcal{N} meets \mathcal{U} in two distinct points. This shows how (4) is equivalent to \mathcal{S} .



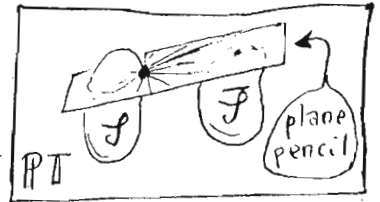
Let us return to \mathcal{R}^* . We can think of it as arising in another way. The 2-parameter family of planes touching \mathcal{S} can be represented as a surface in \mathbb{P}^3 which, by complex conjugation, provides us with a surface $\bar{\mathcal{S}}$ in \mathbb{P}^3 . Thus, whenever the plane W touches \mathcal{S} , the point \bar{W} lies on $\bar{\mathcal{S}}$. It follows that whenever a point Z lies on \mathcal{S} then the plane \bar{Z} touches $\bar{\mathcal{S}}$. We can call \mathcal{S} and $\bar{\mathcal{S}}$ reciprocal surfaces in \mathbb{P}^3 . (Note that $\bar{\mathcal{S}}$ is actually a holomorphic surface in \mathbb{P}^3 , though its relationship to \mathcal{S} is anti-holomorphic. If \mathcal{S} is given by the relation $f(z^\alpha) = 0$, with f homogeneous and holomorphic, then $\bar{f}(w_\alpha) = 0$ is a holomorphic equation for the envelope of $\bar{\mathcal{S}}$. The function \bar{f} is, of course, holomorphic because $\bar{f}(\bar{z}^\alpha) = \overline{f(z^\alpha)}$ is anti-holomorphic in z^α and therefore holomorphic in \bar{z}^α .) The surface $\bar{\mathcal{S}}$ gives rise to the congruence \mathcal{R}^* in M in exactly the same way as \mathcal{S} gives rise to \mathcal{R} . Moreover the null hypersurface \mathcal{N} corresponds to the family of lines in \mathbb{P}^3 which touch $\bar{\mathcal{S}}$.



We can now see how the timelike surface \mathcal{T} arises from \mathcal{S} . We recall that $\mathcal{T} = \mathcal{N} \cap \bar{\mathcal{N}} \cap M (= \mathcal{N} \cap M)$, so the points of \mathcal{T} correspond to the lines in \mathbb{P}^3 which touch both of \mathcal{S} and $\bar{\mathcal{S}}$. Moreover, the pair of surfaces $(\mathcal{S}, \bar{\mathcal{S}})$ provides a better insight into \mathcal{R} (and also \mathcal{R}^*) than either does individually, especially if one is concerned with the complexification $\mathbb{C}\mathcal{R}$ (or $\mathbb{C}\mathcal{R}$).



A complex ray belonging to $\mathbb{C}\mathcal{R}$ is represented in $\mathbb{P}\mathcal{T}$ as a plane pencil whose vertex lies on \mathcal{I} and whose plane touches $\overline{\mathcal{I}}$. (In the case of $\mathbb{C}\mathcal{R}^*$, the vertex lies on $\overline{\mathcal{I}}$ and the plane touches \mathcal{I} .)



Many of these considerations have some sort of analogue in curved (analytic) space-time \mathcal{M} , but where some of the constructions have to be understood in terms of an analytic (preferably spacelike) hypersurface $\mathcal{H} \subset \mathcal{M}$ and the corresponding hypersurface twistor space $\mathbb{P}\mathcal{T}(\mathcal{H})$. The notions of a complex null hypersurface \mathcal{N} , of its (primary) caustic which is a complex null 2-surface \mathcal{U} , of its complex conjugate $\overline{\mathcal{N}}$, and the timelike 2-surface \mathcal{I} of real points of \mathcal{N} all carry through without change. However, the notion of shear-freeness for a ray congruence must be taken relative to \mathcal{H} (i.e. at the intersections of the rays with \mathcal{H}). With this proviso, all the equivalences (1), (2), (3), (4), and (5) are still maintained and each of these structures can, in a certain sense, be thought of as representing a holomorphic 2-surface $\mathcal{S}(\mathcal{H})$ in $\mathbb{P}\mathcal{T}(\mathcal{H})$. If we consider the time-evolution of \mathcal{H} to some later hypersurface \mathcal{H}' , so that the twistor space changes to $\mathbb{P}\mathcal{T}(\mathcal{H}')$, we find that the ray congruence \mathcal{R} is not preserved in general. However, the complex null hypersurface \mathcal{N} remains unchanged in the evolution, and this fixes the precise way in which \mathcal{R} changes (observation due to George Sparling).

The fact that there is a clear-cut identification of a surface $\mathcal{S}(\mathcal{H}')$ in $\mathbb{P}\mathcal{T}(\mathcal{H}')$ with the original surface $\mathcal{S}(\mathcal{H})$ in $\mathbb{P}\mathcal{T}(\mathcal{H})$ is closely related to the fact that the cotangent bundle of $\mathbb{P}\mathcal{T}$ (essentially ambitwistor space) is preserved under evolution, \mathcal{I} having a well-defined lift into the bundle.

Most of the details of the above account (though not its particular emphasis) are to be found in my article Twistor geometry of light rays, *Class. Quantum Grav.* 14 (1997) A299-A323, in honour of Andrzej Trautman. ~ Roger Penrose