

# On a particular case of the bisymmetric equation for quasigroups

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## Abstract

We characterize the solutions of the equation

$$D(G(x, y), G(u, v)) = G(D(x, u), T(y, v)) \quad (1)$$

where  $D$ ,  $G$  and  $T$  are quasigroups. We also discuss the particular case when  $D = T$ .

## 1 Introduction and Notations

A *quasigroup* on a set  $Q$  is an operation  $(\cdot) : Q \times Q \rightarrow Q$  such that for any  $a, b \in Q$ , there are unique  $x, y$  such that  $a \cdot x = b$  and  $y \cdot a = b$ . In this paper, we use small letters for elements of  $Q$  and capital letters for quasigroups. We use greek letters for permutations on  $Q$ . If  $x \in Q$  and  $\alpha$  is a permutation on  $Q$ , we write  $\alpha(x)$  for the image of  $x$  by  $\alpha$ . We write  $\beta\alpha$  for the composition of  $\alpha$  and  $\beta$ , where  $\alpha$  is applied first.

Two quasigroups  $\oplus$  and  $\otimes$  on a same set  $Q$  are *isotopic* if there exist three permutations  $\alpha, \beta, \gamma$  of  $Q$  such that for any  $x, y \in Q$ , we have  $x \otimes y = (x\alpha \oplus y\beta)\gamma^{-1}$ . When  $(Q, +)$  is an Abelian group and  $\alpha$  is a permutation on  $Q$ , we say that  $\alpha$  is *additive* for  $+$  if for any  $x, y \in Q$ , we have  $\alpha(x + y) = \alpha(x) + \alpha(y)$ . When  $\alpha$  and  $\beta$  are two permutations on the same set  $Q$ , we say that  $\alpha$  and  $\beta$  commute if for all  $x \in Q$ , we have  $\alpha\beta(x) = \beta\alpha(x)$ .

Functional equations on quasigroups have been previously considered in [1, 2, 3]. In [1], Aczél, Belousov and Hosszú studied various quasigroup equations, including the generalized bisymmetry equation

$$A(B(x, y), C(u, v)) = D(E(x, u), F(y, v)).$$

They showed that for any solution of this equation, all the quasigroups  $A, B, C, D, E, F$  are isotopic to the same Abelian group. Here, we show that the additional constraints  $B = C = D$ ,  $A = E$  imply some additivity and commutativity properties.

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## 2 Our Results

Let  $G, D, T$  satisfying (1). From Theorem 3 in Aczél, Belousov, Hosszú [1], there exist an Abelian group  $+$  and 6 permutations  $\psi, \epsilon, \delta, \varphi, \beta, \gamma$  such that

$$G(x, y) = \psi(x) + \epsilon(y), \quad D(x, y) = \delta(x) + \varphi(y), \quad T(x, y) = \epsilon^{-1}(\beta(x) + \gamma(y)). \quad (2)$$

Let  $-$  be such that  $x + y = z \Leftrightarrow x = z - y$ , and let  $e$  be the neutral element of  $+$ .

**Proposition 1** *Let  $G, D, T$  be three quasigroups. These quasigroups satisfy*

$$D(G(x, y), G(u, v)) = G(D(x, u), T(y, v))$$

*if and only if there exist an Abelian group  $+$ , two constants  $k_1, k_2$  and four permutations  $\hat{\psi}, \hat{\delta}, \hat{\varphi}, \epsilon$  such that the three permutations  $\hat{\psi}, \hat{\delta}$  and  $\hat{\varphi}$  are additive for  $+$ , the permutation  $\hat{\psi}$  commutes with both  $\hat{\delta}$  and  $\hat{\varphi}$ , and*

$$\begin{aligned} G(x, y) &= \hat{\psi}(x) + \epsilon(y) + k_1, \\ D(x, y) &= \hat{\delta}(x) + \hat{\varphi}(y) + k_2, \\ T(x, y) &= \epsilon^{-1} \left( \hat{\delta}\epsilon(x) + \hat{\varphi}\epsilon(y) + k_3 \right), \end{aligned}$$

where  $k_3 := \hat{\delta}(k_1) + \hat{\varphi}(k_1) - k_1 + k_2 - \hat{\psi}(k_2)$ .

When we additionally impose  $T = D$ , we get

**Proposition 2** *Let  $G, D$  be two quasigroups. These quasigroups satisfy*

$$D(G(x, y), G(u, v)) = G(D(x, u), D(y, v)) \quad (3)$$

*if and only if there exist an Abelian group  $+$ , two constants  $k_1, k_2$  and four permutations  $\hat{\psi}, \hat{\delta}, \hat{\varphi}, \hat{\epsilon}$ , all of them additive for  $+$ , such that both  $\hat{\psi}$  and  $\hat{\epsilon}$  commute with both  $\hat{\delta}$  and  $\hat{\varphi}$ ,*

$$\hat{\delta}(k_1) + \hat{\varphi}(k_1) + k_2 = \hat{\psi}(k_2) + \hat{\epsilon}(k_2) + k_1$$

and

$$\begin{aligned} G(x, y) &= \hat{\psi}(x) + \hat{\epsilon}(y) + k_1, \\ D(x, y) &= \hat{\delta}(x) + \hat{\varphi}(y) + k_2. \end{aligned}$$

## 3 Proof of Proposition 1

Proving that any  $G, D, T$  defined as in Proposition 1 satisfy Equation (1) is a straightforward check. We now prove that any solution of Equation (1) is as in Proposition 1.

From Equations (1) and (2), we get

$$\delta(\psi(x) + \epsilon(y)) + \varphi(\psi(u) + \epsilon(v)) = \psi(\delta(x) + \varphi(u)) + \beta(y) + \gamma(v). \quad (4)$$

When  $x = \psi^{-1}(e)$ , Equation (4) gives

$$\delta\epsilon(y) - \beta(y) = \psi(\delta\psi^{-1}(e) + \varphi(u)) + \gamma(v) - \varphi(\psi(u) + \epsilon(v)).$$

Since this equation must be satisfied for any  $y, u, v$ , the left and right terms must be equal to a constant value  $c_1$ . We deduce

$$\delta\epsilon(y) - \beta(y) = c_1. \quad (5)$$

Taking  $y = \beta^{-1}(e)$ , we get

$$c_1 = \delta\epsilon\beta^{-1}(e).$$

Similarly when  $u = \psi^{-1}(e)$ , Equation (4) gives

$$\varphi\epsilon(v) - \gamma(v) = \psi(\delta(x) + \varphi\psi^{-1}(e)) + \beta(y) - \delta(\psi(x) + \epsilon(y))$$

hence

$$\varphi\epsilon(v) - \gamma(v) = c_2, \quad (6)$$

where

$$c_2 = \varphi\epsilon\gamma^{-1}(e).$$

Substituting Equations (5) and (6) in Equation (4), we get

$$\delta(\psi(x) + \epsilon(y)) + \varphi(\psi(u) + \epsilon(v)) = \psi(\delta(x) + \varphi(u)) + \delta\epsilon(y) - c_1 + \varphi\epsilon(v) - c_2.$$

We deduce the following functional equation in  $\delta, \psi$  and  $\varphi$  only

$$\delta(\psi(x) + y) + \varphi(\psi(u) + v) = \psi(\delta(x) + \varphi(u)) + \delta(y) + \varphi(v) - c_1 - c_2. \quad (7)$$

Taking  $v = e$  and  $x = \delta^{-1}(e)$ , we get

$$\psi\varphi(u) - \varphi\psi(u) = \delta(\psi\delta^{-1}(e) + y) - \delta(y) - \varphi(e) + c_1 + c_2,$$

which implies

$$\psi\varphi(u) - \varphi\psi(u) = c_3, \quad (8)$$

where

$$c_3 = \psi\varphi\psi^{-1}\varphi^{-1}(e).$$

Similarly substituting  $y = e$  and  $u = \varphi^{-1}(e)$  in Equation (7), we get

$$\psi\delta(x) - \delta\psi(x) = \varphi(\psi\varphi^{-1}(e) + v) - \delta(e) - \varphi(v) + c_1 + c_2,$$

which implies

$$\psi\delta(x) - \delta\psi(x) = c_4, \quad (9)$$

where

$$c_4 = \psi\delta\psi^{-1}\delta^{-1}(e).$$

Equation (7) may be re-written as

$$\delta(\delta^{-1}(x) + \delta^{-1}(y)) + \varphi(\varphi^{-1}(u) + \varphi^{-1}(v)) = \psi(\delta\psi^{-1}\delta^{-1}(x) + \varphi\psi^{-1}\varphi^{-1}(u)) + y + v - c_1 - c_2.$$

Using Equations (8) and (9), this leads to

$$\delta(\delta^{-1}(x) + \delta^{-1}(y)) + \varphi(\varphi^{-1}(u) + \varphi^{-1}(v)) = \psi(\psi^{-1}(x + c_4) + \psi^{-1}(u + c_3)) + y + v - c_1 - c_2. \quad (10)$$

Since  $+$  is Abelian, we can swap  $x$  and  $y$  or  $u$  and  $v$  without changing the left-hand term of Equation (10). We therefore obtain the following functional equation in  $\psi$  only:

$$\psi(\psi^{-1}(x \oplus c_4) + \psi^{-1}(u \oplus c_3)) + y + v = \psi(\psi^{-1}(y \oplus c_4) + \psi^{-1}(v \oplus c_3)) + x + u.$$

Replacing  $x$  by  $\psi(x) - c_4$ ,  $u$  by  $\psi(u) - c_3$ ,  $y$  by  $\psi(y) - c_4$  and  $v$  by  $\psi(v) - c_3$ , we get

$$\psi(x + u) - \psi(x) - \psi(u) = \psi(y + v) - \psi(y) - \psi(v),$$

hence

$$\psi(x \oplus u) - \psi(x) - \psi(u) = c_5 \tag{11}$$

for a constant  $c_5$  such that

$$c_5 = \psi(e + e) - \psi(e) - \psi(e) = e - \psi(e).$$

Using Equation (11), Equation (10) becomes

$$\delta(\delta^{-1}(x) + \delta^{-1}(y)) + \varphi(\varphi^{-1}(u) + \varphi^{-1}(v)) = x + y + u + v + c_4 + c_3 - \psi(e) - c_1 - c_2$$

or

$$\delta(x + y) - \delta(x) - \delta(y) = \varphi(u) + \varphi(v) - \varphi(u + v) + c_4 + c_3 - \psi(e) - c_1 - c_2. \tag{12}$$

This implies

$$\delta(x + y) - \delta(x) - \delta(y) = c_6 \tag{13}$$

where  $c_6 = e \ominus \delta(e)$ . On the other hand, Equation (12) also implies

$$\varphi(u) + \varphi(v) - \varphi(u + v) = c_7 \tag{14}$$

where  $c_7 = \varphi(e)$ . Let now

$$\hat{\psi} := \psi - \psi(e).$$

Equation (11) implies

$$\hat{\psi}(x \oplus u) = \psi(x \oplus u) - \psi(e) = \psi(x) + \psi(u) - 2\psi(e) = \hat{\psi}(x) + \hat{\psi}(u), \tag{15}$$

in other words  $\hat{\psi}$  is additive for  $+$ . Similarly, Equations (13) and (14) imply that  $\hat{\delta} := \delta - \delta(e)$  and  $\hat{\varphi} := \varphi - \varphi(e)$  are additive. Equation (8) and the additivity of  $\hat{\varphi}$  and  $\hat{\psi}$  now imply

$$\hat{\psi}\hat{\varphi}(u) + \hat{\psi}\varphi(e) + \psi(e) = \hat{\varphi}\hat{\psi}(u) + \hat{\varphi}\psi(e) + \varphi(e) + c_3.$$

For  $u = e$ , it follows that

$$\hat{\psi}\varphi(e) + \psi(e) = \hat{\varphi}\psi(e) + \varphi(e) + c_3$$

hence Equation (8) eventually implies that

$$\hat{\psi}\hat{\varphi}(u) = \hat{\varphi}\hat{\psi}(u),$$

in other words  $\hat{\psi}$  and  $\hat{\varphi}$  commute. Similarly, Equation (9) implies that  $\hat{\psi}$  and  $\hat{\delta}$  commute. By Equations (5) and (6), we have

$$\beta(x) + \gamma(y) = \delta\epsilon(x) - c_1 + \varphi\epsilon(y) - c_2 = \hat{\delta}\epsilon(x) + \hat{\varphi}\epsilon(y) + \delta(e) + \varphi(e) - c_1 - c_2.$$

Defining  $k_1 := \psi(e)$ ,  $k_2 := \delta(e) + \varphi(e)$  and  $k_3 := \delta(e) + \varphi(e) - c_1 - c_2$ , we deduce from Equation (2) that

$$\begin{aligned} G(x, y) &= \hat{\psi}(x) + \epsilon(y) + k_1, \\ D(x, y) &= \hat{\delta}(x) + \hat{\varphi}(y) + k_2, \\ T(x, y) &= \epsilon^{-1} \left( \hat{\delta}\epsilon(x) + \hat{\varphi}\epsilon(y) + k_3 \right), \end{aligned}$$

with  $\hat{\psi}$ ,  $\hat{\delta}$  and  $\hat{\varphi}$  with the properties required. Using the additivity of  $\hat{\delta}$ ,  $\hat{\varphi}$  and  $\hat{\psi}$ , we compute

$$\begin{aligned} D(G(x, y), G(u, v)) &= \hat{\delta} \left( \hat{\psi}(x) + \epsilon(y) + k_1 \right) + \hat{\varphi} \left( \hat{\psi}(u) + \epsilon(v) + k_1 \right) + k_2 \\ &= \hat{\delta}\hat{\psi}(x) + \hat{\delta}\epsilon(y) + \hat{\delta}(k_1) + \hat{\varphi}\hat{\psi}(u) + \hat{\varphi}\epsilon(v) + \hat{\varphi}(k_1) + k_2 \end{aligned}$$

and

$$\begin{aligned} G(D(x, u), T(y, v)) &= \hat{\psi} \left( \hat{\delta}(x) + \hat{\varphi}(u) + k_2 \right) + (\hat{\delta}\epsilon(y) + \hat{\varphi}\epsilon(v) + k_3) + k_1. \\ &= \hat{\psi}\hat{\delta}(x) + \hat{\psi}\hat{\varphi}(u) + \hat{\psi}(k_2) + \hat{\delta}\epsilon(y) + \hat{\varphi}\epsilon(v) + k_3 + k_1. \end{aligned}$$

Since  $\hat{\psi}$  commutes with both  $\hat{\varphi}$  and  $\hat{\delta}$ , we deduce

$$\begin{aligned} G(D(x, u), T(y, v)) &= \hat{\delta}\hat{\psi}(x) + \hat{\varphi}\hat{\psi}(u) + \hat{\psi}(k_2) + \hat{\delta}\epsilon(y) + \hat{\varphi}\epsilon(v) + k_3 + k_1 \\ &= D(G(x, y), G(u, v)) + \hat{\psi}(k_2) + k_3 + k_1 - \hat{\delta}(k_1) - \hat{\varphi}(k_1) - k_2. \end{aligned}$$

Equation (1) then implies

$$k_3 = \hat{\delta}(k_1) + \hat{\varphi}(k_1) - k_1 + k_2 - \hat{\psi}(k_2).$$

This concludes the proof of Proposition 1.

## 4 Proof of Proposition 2

Proving that any  $G, D, T$  defined as in Proposition 2 satisfy Equation (3) is a straightforward check. We now prove that any solution of Equation (3) is as in Proposition 2. By Proposition 1, we have

$$G(x, y) = \hat{\psi}(x) + \hat{\epsilon}(y) + k_1, \quad D(x, y) = \hat{\delta}(x) + \hat{\varphi}(y) + k_2$$

for permutations  $\hat{\psi}, \hat{\delta}, \hat{\varphi}, \hat{\epsilon}$  such that  $\hat{\psi}, \hat{\delta}$  and  $\hat{\varphi}$  are additive for  $+$ , and moreover  $\hat{\psi}$  commutes with both  $\hat{\delta}$  and  $\hat{\varphi}$ . By symmetry of  $D$  and  $G$  in Equation (3),  $\hat{\epsilon}$  must also be distributive for  $+$  and it must commute with both  $\hat{\delta}$  and  $\hat{\varphi}$ . As in the proof of Proposition 1, we compute

$$D(G(x, y), G(u, v)) = \hat{\delta}\hat{\psi}(x) + \hat{\delta}\hat{\epsilon}(y) + \hat{\delta}(k_1) + \hat{\varphi}\hat{\psi}(u) + \hat{\varphi}\hat{\epsilon}(v) + \hat{\varphi}(k_1) + k_2.$$

Similarly, we have

$$G(D(x, y), D(u, v)) = \hat{\psi}\hat{\delta}(x) + \hat{\psi}\hat{\varphi}(u) + \hat{\varphi}(k_2) + \hat{\epsilon}\hat{\delta}(y) + \hat{\epsilon}\hat{\varphi}(v) + \hat{\epsilon}(k_2) + k_1.$$

Equation (3) then leads to

$$\hat{\delta}(k_1) + \hat{\varphi}(k_1) + k_2 = \hat{\psi}(k_2) + \hat{\epsilon}(k_2) + k_1.$$

This concludes the proof of Proposition 2.

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