

FINITE ELEMENT ANALYSIS OF CAUCHY–BORN APPROXIMATIONS TO ATOMISTIC MODELS

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ABSTRACT. This paper is devoted to a new finite element consistency analysis of Cauchy–Born approximations to atomistic models of crystalline materials in two and three space dimensions. Through this approach new “atomistic Cauchy–Born” models are introduced and analyzed. These intermediate models can be seen as first level atomistic/quasicontinuum approximations in the sense that they involve only short-range interactions. The analysis and the models developed herein are expected to be useful in the design of coupled atomistic/continuum methods in more than one dimension. Taking full advantage of the symmetries of the atomistic lattice we show that the consistency error of the models considered both in energies and in dual $W^{1,p}$ type norms is $\mathcal{O}(\varepsilon^2)$, where ε denotes the interatomic distance in the lattice.

1. INTRODUCTION

Modern multiscale methods for the simulation of materials introduce several coupling mechanisms of the *atomistic* and the *continuum* descriptions aiming at the design of methods of “atomistic” accuracy with “continuum” cost. To understand these mechanisms and the behavior of the coupled models is a challenge both from the modeling point of view and from the computational perspective. It is known, for example, that ad-hoc coupling of models may lead to undesirable computational artifacts [16, 28]. The development of the mathematical foundations of coupled multiscale models therefore seems necessary. Although the mathematical theory of multiscale models is still quite limited at present, it is hoped that, ultimately, the availability of a comprehensive mathematical theory of multiscale models will enhance the development of efficient, accurate and robust numerical algorithms for multiscale models. Indeed, the area of multiscale simulations in materials science is a very active field; see, for example, the review articles [29, 10]. In particular, a problem that has received considerable attention from the engineering as well as from the mathematical point of view is the atomistic-to-continuum passage (cf. [25, 9, 26, 2, 24, 32, 21]), and the corresponding coupled methods for crystalline materials (cf. [39, 7, 23, 10, 8, 4, 3, 5, 6, 15, 14, 36, 17, 16, 27, 30, 18, 19, 20, 35, 28, 37, 38, 43, 44, 1, 22, 34, 35, 42, 41]).

Much of the literature on atomistic/continuum coupling in crystals is concerned with the “quasicontinuum” method [39] and its variants. In these methods, in regions of interest in the material (strong deformations, defects) the atomistic model is kept, while in regions of smooth deformations the atomistic model is replaced with a continuum model discretized by finite elements. Despite the increasing number of papers concerned with the numerical analysis of these methods, satisfactory analytical results are available in one space dimension only; in two and three space dimensions the precise formulation of efficient coupling methods is still in its infancy.

This paper is devoted to a novel finite element consistency analysis of Cauchy–Born approximations to atomistic models of crystalline materials in two and three space dimensions. Through this approach new “atomistic Cauchy–Born” models are introduced and analyzed. These intermediate models can be seen as first level atomistic/quasicontinuum approximations in the sense that they involve only short-range interactions. The analysis and the models developed herein are expected to be useful in the design of coupled atomistic/continuum methods in several space dimensions. Specifically, we concentrate on the comparison of an atomistic model and its continuum Cauchy–Born approximation, as in [9, 24]; however, in contrast with the “finite-difference”-style analysis in [9, 24], here we develop a theoretical framework in the spirit of finite-element methods. Taking full advantage of the symmetries we show that the consistency error of the models considered in dual $W^{1,p}$ type norms is $\mathcal{O}(\varepsilon^2)$, ε being the interatomic distance. As a consequence we provide an alternative finite element proof of the second order consistency result of the continuum Cauchy–Born model derived by E & Ming [24] using finite difference techniques. In addition we derive consistency results for the energies, by showing that all models considered have energies that are $\mathcal{O}(\varepsilon^2)$ close to each other. The first consistency results of the energies for the continuum Cauchy–Born model approximating the atomistic model were derived in Blanc, LeBris & Lions [9]. Our approach is based on the introduction and analysis of intermediate “atomistic Cauchy–Born” models. Since, most of the recent results concerning the construction and analysis of various quasicontinuum methods in one space dimension were based on the properties and the proper comparison of a similar intermediate atomistic Cauchy–Born model involving only short-range interactions we expect that our approach can provide the appropriate analytical framework for the construction and analysis of various atomistic/continuum methods in multiple space dimensions.

1.1. Notation. *Lattice, discrete domain, continuum domain.* We consider a simple d -dimensional lattice, which is generated by d linearly independent vectors of \mathbb{R}^d , $d = 2, 3$. For simplicity of the exposition we assume that the lattice $\mathcal{L}_{\text{entire}}$ is generated by the unit coordinate vectors e_1, \dots, e_d of \mathbb{R}^d . The extension of the consistency analysis developed in this paper to include any d linearly independent vectors of \mathbb{R}^d is straightforward, since the general case can be obtained by applying an affine map. We note however that, unlike consistency, stability can be sensitive to the specific lattice structure (e.g. rectangular or triangular); see, [24], for example. We will consider discrete periodic functions on $\mathcal{L}_{\text{entire}}$ defined over a ‘periodic domain’ \mathcal{L} . More precisely, let

$$\begin{aligned} \mathcal{L} := \{ \ell = (\ell_1, \dots, \ell_d) = n_1 e_1 + \dots + n_d e_d : \\ (n_1, \dots, n_d) \in \mathbb{Z}^d \cap [-N_1 - 1, N_1] \times \dots \times [-N_d - 1, N_d] \}. \end{aligned}$$

The actual configuration of the atoms is thus a subset of \mathbb{R}^d , which we call *discrete domain* and denote by Ω_{discr} ; the corresponding *continuum domain* is denoted by Ω ; i.e.,

$$\begin{aligned} \Omega_{\text{discr}} &:= \{ x_\ell = (x_{\ell_1}, \dots, x_{\ell_d}) = \varepsilon \ell, \quad \ell \in \mathcal{L}, \}, \\ \Omega &:= \{ x \in [x_{-N_1-1}, x_{N_1}] \times \dots \times [x_{-N_d-1}, x_{N_d}] \}^o. \end{aligned}$$

Here \mathcal{O}^o denotes the interior of the set \mathcal{O}^o . Note that a possible confusion in the notation may arise when $\ell_i = i$, $i = 1, \dots, d$, since by x_i we denote the coordinates of the continuum variable x ; see below. It will be clear however from the analysis which is the continuum variable.

Functions and spaces. We consider atomistic deformations

$$\begin{aligned} y_\ell &= y(x_\ell), \quad \ell \in \mathcal{L} \quad \text{of the form} \\ y_\ell &= F x_\ell + v_\ell, \quad \text{with } v_\ell = v(x_\ell) \text{ periodic with respect to } \mathcal{L}. \end{aligned}$$

Here F is a constant $d \times d$ matrix with $\det F > 0$. The corresponding spaces for y and v are denoted by \mathcal{X} and \mathcal{V} and are defined as follows:

$$\begin{aligned}\mathcal{X} &:= \{y : \mathfrak{L} \rightarrow \mathbb{R}^d, \quad y_\ell = Fx_\ell + v_\ell, \quad v \in \mathcal{V}, \quad \ell \in \mathfrak{L}\}, \\ \mathcal{V} &:= \{u : \mathfrak{L} \rightarrow \mathbb{R}^d, \quad u_\ell = u(x_\ell) \quad \text{periodic with zero average with respect to } \mathfrak{L}\}.\end{aligned}$$

For functions $y, v : \mathfrak{L} \rightarrow \mathbb{R}^d$ we define the inner product

$$\langle y, v \rangle_\varepsilon := \varepsilon^d \sum_{\ell \in \mathfrak{L}} y_\ell \cdot v_\ell.$$

For a positive real number s and $1 \leq p \leq \infty$ we denote by $W^{s,p}(\Omega, \mathbb{R}^d)$ the usual Sobolev space of functions $y : \Omega \rightarrow \mathbb{R}^d$; we shall use the same symbol for discrete functions defined on the lattice and for continuum functions. It will be clear from the context which of the two is intended in a specific instance. Further by $W_{\#}^{s,p}(\Omega, \mathbb{R}^d)$ we denote the corresponding Sobolev space of periodic functions with basic period Ω . By $\langle \cdot, \cdot \rangle$ we denote the standard $L^2(\Omega)$ inner product. The space corresponding to \mathcal{X} in which the minimizers of the continuum problem are sought is

$$\begin{aligned}X &:= \{y : \Omega \rightarrow \mathbb{R}^d, \quad y(x) = Fx + v(x), \quad v \in V\}, \quad \text{where} \\ V &:= \{u : \Omega \rightarrow \mathbb{R}^d, \quad u \in W^{k,p}(\Omega, \mathbb{R}^d) \cap W_{\#}^{1,p}(\Omega, \mathbb{R}^d), \quad \int_{\Omega} u \, dx = 0\}.\end{aligned}$$

Henceforth, for the sake of notational simplicity, we shall suppress the symbol \mathbb{R}^d in our notation for Sobolev spaces, and will simply write $W^{s,p}(\Omega)$ and $W_{\#}^{s,p}(\Omega)$.

Difference quotients and derivatives. We will use the notation

$$\overline{D}_\eta y_\ell := \frac{y_{\ell+\eta} - y_\ell}{\varepsilon}, \quad \ell, \ell + \eta \in \mathfrak{L},$$

for the difference quotient (discrete derivative) in the direction of the vector η . For functions defined on the continuum domain, the following notation is used

$$\begin{aligned}(1.1) \quad \partial_{\zeta_i} \phi(\zeta) &:= \frac{\partial \phi(\zeta_1, \dots, \zeta_d)}{\partial \zeta_i}, \quad \zeta = (\zeta_1, \dots, \zeta_d), \\ \nabla_{\zeta} \phi(\zeta) &:= \left\{ \partial_{\zeta_i} \phi(\zeta) \right\}_i, \\ \partial_\alpha v(x) &:= \frac{\partial v(x)}{\partial x_\alpha}, \\ \nabla u(x) &:= \left\{ \frac{\partial u^i(x)}{\partial x_\alpha} \right\}_{i\alpha}.\end{aligned}$$

To avoid confusion we distinguish between derivatives with respect to arguments, denoted by ∂_{ζ_i} , which usually appear in composite functions, and derivatives with respect to the spatial variable x_i , denoted by the symbol ∂_i .

Atomistic and Cauchy-Born potential. We consider the atomistic potential

$$(1.2) \quad \Phi^a(y) := \varepsilon^d \sum_{\ell \in \mathfrak{L}} \sum_{\eta \in R} \phi_\eta(\overline{D}_\eta y_\ell),$$

where R is a given finite set of interaction vectors. We allow the potential to vary with the type of bond, i.e., ϕ_η may vary with η . On the other hand we assume standard conditions on the potential away from zero (cf. [9]): ϕ_η are functions defined on $\mathbb{R}^d \setminus \{0\}$, which are smooth for any ζ , $|\zeta| > \rho$. In fact we assume that there exist $C_{\rho,k} = C(\rho, k) \geq 0$, such that $|D_\zeta^k \phi_\eta(\zeta)| \leq C_{\rho,k}$, for $|\zeta| > \rho$, and a multi-index k of length

$|k| \leq 3$. Notice that we have not imposed any symmetry hypotheses on the potentials ϕ_η . In order to explore the consistency of the Cauchy–Born approximation, we will consider sufficiently smooth diffeomorphisms y on Ω . The assumption that y is 1–1 is natural since it excludes interpenetration. In addition, it leads to the lower bound $|\overline{D}_\eta y_\ell| \geq \alpha(y, \eta) > 0$, [9], which is required in the course of bounding derivatives of $\phi_\eta(\overline{D}_\eta y_\ell)$. It will be assumed throughout the paper that whenever the potential is applied to a smooth function y , y is a diffeomorphism on the domain Ω .

For a given field of external forces $f : \mathfrak{L} \rightarrow \mathbb{R}^d$, where $f_\ell = f(x_\ell)$, the atomistic problem reads as follows:

$$(1.3) \quad \begin{aligned} &\text{find a local minimizer } y^a \text{ in } \mathcal{X} \text{ of :} \\ &\Phi^a(y) - \langle f, y \rangle_\varepsilon. \end{aligned}$$

If such a minimizer exists, then

$$\langle D\Phi^a(y^a), v \rangle_\varepsilon = \langle f, v \rangle_\varepsilon, \quad \text{for all } v \in \mathcal{V},$$

where

$$(1.4) \quad \begin{aligned} \langle D\Phi^a(y), v \rangle_\varepsilon &:= \varepsilon^d \sum_{\ell \in \mathfrak{L}} \sum_{\eta \in R} \sum_{i=1}^d \partial_{\zeta_i} \phi_\eta(\overline{D}_\eta y_\ell) [\overline{D}_\eta v_\ell]_i \\ &= \varepsilon^d \sum_{\ell \in \mathfrak{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\overline{D}_\eta y_\ell) \cdot \overline{D}_\eta v_\ell. \end{aligned}$$

Throughout the rest of the paper we shall use the summation convention for repeated indices.

The corresponding Cauchy–Born stored energy function is

$$W(F) = W_{CB}(F) := \sum_{\eta \in R} \phi_\eta(F \eta).$$

Then, the continuum Cauchy–Born model is stated as follows:

$$(1.5) \quad \begin{aligned} &\text{find a local minimizer } y^{CB} \text{ in } X \text{ of :} \\ &\Phi^{CB}(y) - \langle f, y \rangle, \end{aligned}$$

where the external forces f are appropriately related to the discrete external forces and

$$\Phi^{CB}(y) := \int_{\Omega} W_{CB}(\nabla y(x)) \, dx.$$

If such a minimizer exists, then

$$(1.6) \quad \langle D\Phi^{CB}(y^{CB}), v \rangle = \langle f, v \rangle, \quad \text{for all } v \in V,$$

where

$$\langle D\Phi^{CB}(y), v \rangle = \int_{\Omega} S_{i\alpha}(\nabla y(x)) \frac{\partial v^i(x)}{\partial x_\alpha} \, dx = \int_{\Omega} S_{i\alpha}(\nabla y(x)) \partial_\alpha v^i(x) \, dx, \quad v \in V.$$

Here the stress tensor S is defined, as usual, by

$$S := \left\{ \frac{\partial W(F)}{\partial F_{i\alpha}} \right\}_{i\alpha}.$$

A simple calculation yields the following relation between the stress tensor and the atomistic potential:

$$\begin{aligned}
S_{i\alpha} &= \frac{\partial W(\mathbf{F})}{\partial F_{i\alpha}} = \frac{\partial}{\partial F_{i\alpha}} \sum_{\eta \in R} \phi_\eta(\mathbf{F} \eta) \\
(1.7) \quad &= \frac{\partial}{\partial F_{i\alpha}} \sum_{\eta \in R} \phi_\eta(F_{j\beta} \eta_\beta) = \sum_{\eta \in R} \partial_{\zeta_i} \phi_\eta(F_{j\beta} \eta_\beta) \frac{\partial}{\partial F_{i\alpha}} F_{j\beta} \eta_\beta \\
&= \sum_{\eta \in R} \partial_{\zeta_i} \phi_\eta(\mathbf{F} \eta) \eta_\alpha.
\end{aligned}$$

1.2. Main results. The question whether, and under what conditions, the continuum Cauchy–Born model (1.5) approximates (1.3) is very delicate. The analytical assessment of the quality of an approximating scheme in Numerical Analysis is based on the notions of consistency, stability and convergence. Consistency essentially refers to the extent to which an exact smooth solution fails to satisfy the numerical scheme. Given that the stability of the approximating scheme is satisfactory, usually the consistency error determines the order and therefore the quality of the approximation. It is to be noted that the consistency error depends in an essential manner on the norm we use to measure it. The choice of the norm is, in turn, dictated by the chosen method of stability/convergence analysis.

In this paper we focus on the consistency analysis of Cauchy–Born approximations. We then briefly discuss the consequences of our results in the convergence analysis. To be more precise, let us assume that y is a smooth solution of the Cauchy–Born problem (1.6). Then, our goal is to quantify the size of

$$\langle D\Phi^a(y), v \rangle_\varepsilon - \langle f, v \rangle_\varepsilon, \quad \text{for all } v \in \mathcal{V} \quad \text{such that } \|v\|_{W^{1,p}(\Omega)} = 1.$$

Here by $\|v\|_{W^{1,p}(\Omega)}$ we denote the $W^{1,p}$ norm of the bilinear interpolant of $v \in \mathcal{V}$. In addition, y is identified with its bilinear interpolant. Elements of \mathcal{V} will be identified with elements of the finite element space \mathbf{V}_ε , see Section 2 for the precise definitions. Modulo a data approximation error in f , it suffices to estimate

$$\mathcal{C}_V(y) := \sup \left\{ |\langle D\Phi^a(y), v \rangle_\varepsilon - \langle D\Phi^{CB}(y), v \rangle| : v \in \mathcal{V} \quad \text{with } \|v\|_{W^{1,p}(\Omega)} = 1 \right\},$$

where in the last relation y is any smooth function. We shall refer to $\mathcal{C}_V(y)$ as the *variational consistency error*. Similarly, one can define the *energy consistency error*

$$\mathcal{C}_\mathcal{E}(y) := |\Phi^a(y) - \Phi^{CB}(y)|.$$

Our aim is to show that both consistency errors are of *second order* in the lattice spacing ε ; cf. Sections 4 and 5. Our assumptions on the potentials and on y are standard; see the discussion following equation (1.2). Related results for energy consistency and variational consistency in the case of a single potential $\phi_\eta = \phi$ were derived by Blanc, LeBris & Lions [9] and by E & Ming [24], respectively. In [9] boundary effects were taken into account.

We note that our second order consistency results do not require symmetry of the potentials. Thus, Theorem 4.2, where we show that $\mathcal{C}_\mathcal{E}(y) = \mathcal{O}(\varepsilon^2)$ can be seen as an extension of Theorem 1 in [9] where under similar assumptions on the potential it was proved that $\mathcal{C}_\mathcal{E}(y) \rightarrow 0$ as $\varepsilon \rightarrow 0$. The estimate $\mathcal{C}_\mathcal{E}(y) = \mathcal{O}(\varepsilon^2)$ for symmetric potentials was proved in Theorem 3 of [9] allowing infinite-range interactions. Regarding variational consistency, it was shown in [24] by asymptotic methods, still under the assumption of symmetric potentials, that $|\langle D\Phi^a(y), v \rangle_\varepsilon - \langle D\Phi^{CB}(y), v \rangle| \leq C(y, v)\varepsilon^2$, with $C(y, v)$ depending on higher order derivatives of y and v .

Our main contribution in this paper is the analytical approach proposed, which is based on finite element analysis, and the new construction of an intermediate “atomistic Cauchy–Born” model. The analysis of [9] and [24] is based on finite difference techniques and on the direct comparison of the atomistic and

continuum Cauchy–Born models. The proposed “atomistic Cauchy–Born” model, see Section 2.3, is not the standard model that one gets by replacing in the atomistic potential long-range interactions by short-range ones. As was mentioned before, the available results concerning the construction and analysis of various quasicontinuum methods in *one space dimension* were heavily based on the use of intermediate atomistic Cauchy–Born models. The definition of these intermediate models is obvious in one dimension but, as our analysis shows, this is not so in multiple space dimensions. The finite element approach taken in this paper is a natural choice for coupled methods, since, by construction, atomistic/continuum coupling methods assume finite element discretization of the continuum region. We therefore expect that our approach can provide the appropriate analytical framework for the construction and analysis of various atomistic/continuum methods in multiple space dimensions, which is at present lacking.

The paper is organized as follows. Section 2 is devoted to the introduction of the finite element notation and the construction of the atomistic Cauchy–Born model starting from the continuum model and performing appropriate approximation steps. In Section 3 we show that the atomistic model approximates the atomistic Cauchy–Born model with the desired accuracy. The use of the mesh symmetries is important in the analysis. Section 4 provides our main results in the two-dimensional case regarding the order of accuracy of the energy and variational consistencies related to the comparison of the atomistic and Cauchy–Born continuum models. Section 5 is devoted to the extension of our results to three space dimensions. Finally, in Section 6 we briefly discuss the applicability of our results in the convergence analysis, under suitable stability hypotheses.

2. CONSTRUCTION OF AN ATOMISTIC CAUCHY–BORN MODEL

In the sequel we provide a link between the continuum model and the atomistic model by introducing an intermediate model, which we call *atomistic Cauchy–Born model (A-CB)*. To derive this model, we start from the continuum model and perform appropriate approximation steps, which finally yield the A-CB. The final model has consistency error of the order $\mathcal{O}(\varepsilon^2)$ compared to the continuum Cauchy–Born model. In the next section we show that the A-CB has $\mathcal{O}(\varepsilon^2)$ consistency error compared to the original atomistic model.

Bilinear finite elements on the lattice. Let V_ε be the space of continuous piecewise bilinear periodic functions on the lattice \mathfrak{L} . More precisely, let

$$\begin{aligned} \mathcal{T} &:= \{K \subset \Omega : K = (x_{\ell_1}, x_{\ell_1+1}) \times (x_{\ell_2}, x_{\ell_2+1}), \quad x_\ell = (x_{\ell_1}, x_{\ell_2}) \in \Omega_{\text{discr}}\}, \\ V_\varepsilon &:= \{v : \bar{\Omega} \rightarrow \mathbb{R}^2, \quad v \in C(\bar{\Omega}), \quad v|_K \in \mathbb{Q}_1(K) \text{ and } v_\ell = v(x_\ell) \quad \text{periodic with respect to } \mathfrak{L}\}, \end{aligned}$$

where $\mathbb{Q}_1(K)$ denotes the set of all bilinear functions on K ; i.e., $v|_K(x) = \alpha_0 + \alpha_1 x_1 + \alpha_2 x_2 + \alpha_3 x_1 x_2$. It is then well known that the elements of the linear space V_ε can be expressed in terms of the *nodal basis functions*, $\Psi_\ell = \Psi_\ell(x)$, $\ell \in \mathfrak{L}$, as

$$v(x) = \sum_{\ell \in \mathfrak{L}} v_\ell \Psi_\ell(x) = \sum_{\ell \in \mathfrak{L}} v_\ell \Psi_{\ell_1}(x_1) \Psi_{\ell_2}(x_2), \quad v_\ell = v(x_\ell),$$

where we have used the fact that $\Psi_\ell(x)$ can be written as the tensor product of the standard one-dimensional piecewise linear hat functions $x_1 \mapsto \Psi_{\ell_1}(x_1)$ and $x_2 \mapsto \Psi_{\ell_2}(x_2)$ with respect to the x_1 and x_2 variable, respectively. Here $\Psi_{\ell_1}(x_{\tilde{\ell}_1}) = \delta_{\ell_1 \tilde{\ell}_1}$ and $\Psi_{\ell_2}(x_{\tilde{\ell}_2}) = \delta_{\ell_2 \tilde{\ell}_2}$.

2.1. Preliminaries. We shall make frequent use of the following version of the Bramble–Hilbert lemma [13, Theorem 4.1.3]. Its proof is completely straightforward and is therefore omitted.

Lemma 2.1. *Let \mathcal{O} be a bounded open set in \mathbb{R}^d and suppose that $1 \leq p \leq \infty$ and $s \geq 0$. Suppose further that ζ is a linear functional on a linear subspace \mathbb{H} of $W^{s,p}(\mathcal{O})$ with the following property:*

$$\exists C_0 > 0 \quad \forall v \in \mathbb{H} : |\zeta(v)| \leq C_0 \|v\|_{W^{s,p}(\mathcal{O})}.$$

Then, for any $w \in \mathbb{H}$ and any set $\mathbb{S} \subset \text{Ker}(\zeta)$ we have that $|\zeta(w)| \leq C_0 \inf_{\varphi \in \mathbb{S}} \|w - \varphi\|_{W^{s,p}(\mathcal{O})}$.

If, in addition, there exists a positive constant C_1 , independent of $\text{diam}(\mathcal{O})$, and a real number $t > s$ such that

$$\inf_{\varphi \in \mathbb{S}} \|w - \varphi\|_{W^{s,p}(\mathcal{O})} \leq C_1 (\text{diam}(\mathcal{O}))^{t-s} [w]_{W^{t,p}(\mathcal{O})} \quad \forall w \in W^{t,p}(\mathcal{O}),$$

where $[\cdot]$ is a seminorm on $W^{t,p}(\mathcal{O})$, then

$$|\zeta(w)| \leq C_0 C_1 (\text{diam}(\mathcal{O}))^{t-s} [w]_{W^{t,p}(\mathcal{O})} \quad \forall w \in \mathbb{H} \cap W^{t,p}(\mathcal{O}).$$

We note that when $\mathcal{O} = K$, $\mathbb{S} = \mathbb{Q}_1(K)$ (with $\mathbb{Q}_1(K)$ as defined above when $d = 2$ and a completely analogous definition when $d = 3$; cf. Section 5), $s = 0, 1$, $1 \leq p \leq \infty$ and with $Q_A w \in \mathbb{Q}_1(K)$ signifying the averaged Taylor polynomial of a smooth function w introduced in [11, Section 4.6], we have that

$$\|w - Q_A w\|_{W^{s,p}(K)} \leq C_1 \varepsilon^{2-s} \sum_{\alpha=1}^d \|\partial_\alpha^2 w\|_{L^p(K)},$$

where C_1 is a positive constant independent of ε . Due to the fact that we work on $\mathbb{Q}_1(K)$ the right-hand side of this estimate involves only part of the standard $W^{2,p}(K)$ seminorm, see [11, Section 4.6] for a proof and a related discussion. Thus, for a linear functional ζ that vanishes on $\mathbb{S} = \mathbb{Q}_1(K)$ and such that $|\zeta(w)| \leq C_0 \|w\|_{L^p(K)}$ for all $w \in \mathbb{H} = C(\overline{K})$, we have from Lemma 2.1 with $s = 0$, $t = 2$ and $1 \leq p \leq \infty$ that

$$(2.1) \quad |\zeta(w)| \leq C_0 C_1 \varepsilon^2 \sum_{\alpha=1}^d \|\partial_\alpha^2 w\|_{L^p(K)} \quad \forall w \in C(\overline{K}) \cap W^{2,p}(K).$$

Next, we observe that in $\mathbb{Q}_1(K)$ the following inverse inequality holds: for $1 \leq p \leq \infty$ and $1 \leq q \leq \infty$, there exists a constant $\gamma_{s,p,q}$ such that

$$(2.2) \quad \|\varphi\|_{W^{s,q}(K)} \leq \gamma_{s,p,q} \varepsilon^{d/q-d/p} \|\varphi\|_{W^{s,p}(K)}, \quad \varphi \in \mathbb{Q}_1(K), \quad s = 0, 1.$$

For more general inverse inequalities involving variable degree derivatives we refer to [11, Section 4.5]. We note that (2.2) follows by a simple homogeneity argument on \mathbb{Q}_1 . We will use the following consequence of (2.2): if $w \in \mathbf{V}_\varepsilon$, and $\alpha_K \geq 0$, then, for $1/p + 1/q = 1$,

$$(2.3) \quad \begin{aligned} \sum_{K \in \mathcal{T}} |K| \alpha_K \|\partial_\alpha w\|_{L^\infty(K)} &\leq \gamma_{1,p,\infty} \left\{ \sum_{K \in \mathcal{T}} |K| \alpha_K^q \right\}^{1/q} \|w\|_{W^{1,p}(\Omega)}, \quad w \in \mathbf{V}_\varepsilon, \quad q \neq \infty, \\ \sum_{K \in \mathcal{T}} |K| \alpha_K \|\partial_\alpha w\|_{L^\infty(K)} &\leq \gamma_{1,1,\infty} \max_{K \in \mathcal{T}} \alpha_K \|w\|_{W^{1,1}(\Omega)}, \quad w \in \mathbf{V}_\varepsilon, \quad q = \infty. \end{aligned}$$

Indeed, these inequalities follow by Hölder's inequality and by noting that, thanks to (2.2),

$$(2.4) \quad \begin{aligned} \left\{ \sum_{K \in \mathcal{T}} |K| \|\partial_\alpha w\|_{L^\infty(K)}^p \right\}^{1/p} &\leq \left\{ \sum_{K \in \mathcal{T}} |K| \gamma_{1,p,\infty}^p (\varepsilon^{-d/p})^p \|w\|_{W^{1,p}(K)}^p \right\}^{1/p} \\ &= \gamma_{1,p,\infty} \|w\|_{W^{1,p}(\Omega)}. \end{aligned}$$

2.2. Consistency analysis of the Cauchy–Born model: $d = 2$. Suppose that $v \in \mathbf{V}_\varepsilon$ and let y be a sufficiently smooth function. Our aim is to approximate

$$\langle D\Phi^{CB}(y), v \rangle = \int_{\Omega} S_{i\alpha}(\nabla y(x)) \frac{\partial v^i(x)}{\partial x_\alpha} dx = \int_{\Omega} S_{i\alpha}(\nabla y(x)) \partial_\alpha v^i(x) dx, \quad v \in \mathbf{V}_\varepsilon.$$

It suffices to consider a (generic) term of the above sum. To simplify the notation we drop the vector indices and let $g(\nabla y)$ be the part that corresponds to the stress tensor. In the sequel we will consider

$$\int_{\Omega} g(\nabla y(x)) \partial_1 v(x) dx, \quad v \in \mathbf{V}_\varepsilon.$$

Recall that, since $v \in \mathbf{V}_\varepsilon$, we have that

$$v(x) = \sum_{\ell \in \mathfrak{L}} v_{(\ell_1, \ell_2)} \Psi_{\ell_1}(x_1) \Psi_{\ell_2}(x_2), \quad \ell = (\ell_1, \ell_2) \in \mathfrak{L}, \quad v_\ell = v(x_\ell).$$

Thus

$$\begin{aligned} \partial_1 v(x) &= \sum_{\ell \in \mathfrak{L}} v_{(\ell_1, \ell_2)} \frac{1}{\varepsilon} \left(\mathbf{1}_{[x_{\ell_1-1}, x_{\ell_1}]}(x_1) - \mathbf{1}_{[x_{\ell_1}, x_{\ell_1+1}]}(x_1) \right) \Psi_{\ell_2}(x_2) \\ &= \sum_{\ell \in \mathfrak{L}} \frac{1}{\varepsilon} \left(v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right) \mathbf{1}_{[x_{\ell_1}, x_{\ell_1+1}]}(x_1) \Psi_{\ell_2}(x_2). \end{aligned}$$

Therefore, by defining

$$G(x) := G(x_1, x_2) = \int_{x_{-N_1-1}}^{x_1} g(\nabla y(x'_1, x_2)) dx'_1,$$

we have that

$$\begin{aligned} \int_{\Omega} g(\nabla y(x)) \partial_1 v(x) dx &= \frac{1}{\varepsilon} \sum_{\ell \in \mathfrak{L}} \int_{\Omega} g(\nabla y(x)) \left(v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right) \mathbf{1}_{[x_{\ell_1}, x_{\ell_1+1}]}(x_1) \Psi_{\ell_2}(x_2) dx \\ &= \frac{1}{\varepsilon} \sum_{\ell \in \mathfrak{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) dx_1 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \Psi_{\ell_2}(x_2) \right\} dx_2 \\ &= \frac{1}{\varepsilon} \sum_{\ell \in \mathfrak{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[G(x_{\ell_1+1}, x_2) - G(x_{\ell_1}, x_2) \right] \Psi_{\ell_2}(x_2) dx_2 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \\ &= \frac{1}{\varepsilon} \sum_{\ell \in \mathfrak{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[G(x_{\ell_1+1}, x_2) - G(x_{\ell_1}, x_2) \right] \left(\Psi_{\ell_2}(x_2) - \frac{1}{2} \right) dx_2 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \\ &\quad + \frac{1}{\varepsilon} \sum_{\ell \in \mathfrak{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[G(x_{\ell_1+1}, x_2) - G(x_{\ell_1}, x_2) \right] \frac{1}{2} dx_2 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \\ &=: A_1 + A_2. \end{aligned}$$

In the next lemma we show that A_1 is second order accurate with respect to ε . We refer to [40] for a similar result.

Lemma 2.2. *Let y be a smooth function; then*

$$\left| \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[G(x_{\ell_1+1}, x_2) - G(x_{\ell_1}, x_2) \right] \left(\Psi_{\ell_2}(x_2) - \frac{1}{2} \right) dx_2 \right| \leq C(y) |K| \varepsilon^2.$$

Proof. It suffices to consider the functional

$$\zeta(G) = \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[G(x_{\ell_1+1}, x_2) - G(x_{\ell_1}, x_2) \right] \left(\Psi_{\ell_2}(x_2) - \frac{1}{2} \right) dx_2, \quad G \in C(\overline{K \cup K_{e_1}}),$$

where K_{e_1} is the element that shares the edge $[x_\ell, x_{\ell+e_1}]$ with K , and to observe that

$$\zeta(\varphi) = 0 \quad \text{for all } \varphi \in \mathbb{P}_2.$$

Indeed, if

$$\varphi = x_1^m \quad \text{then} \quad \zeta(\varphi) = \left[(x_{\ell_1+1})^m - (x_{\ell_1})^m \right] \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left(\Psi_{\ell_2}(x_2) - \frac{1}{2} \right) dx_2 = 0, \quad \text{and if}$$

$$\varphi = x_2^m \quad \text{then} \quad \zeta(\varphi) = \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[(x_2)^m - (x_2)^m \right] \left(\Psi_{\ell_2}(x_2) - \frac{1}{2} \right) dx_2 = 0.$$

Finally, for $\varphi = x_1(x_2 - x_{\ell_2})$,

$$\zeta(\varphi) = \left[x_{\ell_1+1} - x_{\ell_1} \right] \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} (x_2 - x_{\ell_2}) \left(\Psi_{\ell_2}(x_2) - \frac{1}{2} \right) dx_2 = 0.$$

Next we observe that by Lemma 2.1 we have, for any $\varphi \in \mathbb{P}_2$, that

$$\begin{aligned} |\zeta(G)| &\leq C \max_{x_{\ell_1} \leq s \leq x_{\ell_1+1}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} |G(s, x_2) - \varphi(s, x_2)| dx_2 \\ &\leq C\varepsilon \|G - \varphi\|_{L^\infty(K \cup K_{e_1})} \quad \forall G \in C(\overline{K \cup K_{e_1}}), \end{aligned}$$

The proof is completed by using standard approximation properties of \mathbb{P}_2 (see, [11]) to bound $\inf_{\varphi \in \mathbb{P}_2} \|G - \varphi\|_{L^\infty(K \cup K_{e_1})}$ by $C(y) \varepsilon^3$ and noting that $|K| = |K_{e_1}| = \varepsilon^2$. \square

The term A_2 requires further simplification. To this end, we note that

$$\begin{aligned} A_2 &= \frac{1}{2\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left[G(x_{\ell_1+1}, x_2) - G(x_{\ell_1}, x_2) \right] dx_2 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \\ &= \frac{1}{2\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) dx_1 \right\} dx_2 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \\ &= \frac{1}{2\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2}}^{x_{\ell_2+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) dx_1 \right\} dx_2 \left[v_{(\ell_1+1, \ell_2)} - v_{(\ell_1, \ell_2)} \right] \\ &\quad + \frac{1}{2\varepsilon} \sum_{\ell' \in \mathcal{L}} \int_{x_{\ell'_2}}^{x_{\ell'_2+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) dx_1 \right\} dx_2 \left[v_{(\ell_1+1, \ell'_2+1)} - v_{(\ell_1, \ell'_2+1)} \right] \\ &= \sum_{K \in \mathcal{T}} \int_K g(\nabla y(x)) dx \frac{1}{2} \left\{ \bar{D}_{e_1} v_\ell + \bar{D}_{e_1} v_{\ell+e_2} \right\}, \end{aligned}$$

where $\ell' = (\ell_1, \ell'_2)$. We shall also require the following result.

Lemma 2.3. *Let m_K be the barycenter of K ; then, there exists a constant $C = C(y)$ such that*

$$\left| \sum_{K \in \mathcal{T}} \left[\int_K g(\nabla y(x)) dx - |K| g(\nabla y(m_K)) \right] \frac{1}{2} \left\{ \bar{D}_{e_1} v_\ell + \bar{D}_{e_1} v_{\ell+e_2} \right\} \right| \leq C(y) \varepsilon^2 |v|_{W^{1,p}(\Omega)}.$$

Proof. We denote by ζ the functional

$$(2.5) \quad \zeta(w) := \frac{1}{|K|} \int_K \{w(x) - w(m_K)\} dx,$$

and observe that

$$\zeta(\varphi) = 0 \quad \text{for all } \varphi \in \mathbb{Q}_1(K).$$

Obviously $|\zeta(w)| \leq 2\|w\|_{L^\infty(K)}$ for every $w \in C(\overline{K})$, and thus by Lemma 2.1 and (2.1) we have that

$$(2.6) \quad |\zeta(w)| \leq C \varepsilon^2 \sum_{\alpha=1}^d \|\partial_\alpha^2 w\|_{L^\infty(K)}.$$

Therefore, using the fact that $v \in \mathbf{V}_\varepsilon$ we deduce with $w(\cdot) = g(\nabla y(\cdot))$ that

$$\begin{aligned} & \left| \sum_{K \in \mathcal{T}} \left[\int_K g(\nabla y(x)) dx - |K| g(\nabla y(m_K)) \right] \frac{1}{2} \left\{ \overline{D}_{e_1} v_\ell + \overline{D}_{e_1} v_{\ell+e_2} \right\} \right| \\ & \leq C \varepsilon^2 \sum_{K \in \mathcal{T}} |K| \left[\sum_{\alpha=1}^d \|\partial_\alpha^2 g(\nabla y(x))\|_{L^\infty(K)} \right] \|\partial_1 v\|_{L^\infty(K)}. \end{aligned}$$

The proof is thus complete in view of (2.3). \square

We summarize what we have shown so far in the following proposition.

Proposition 2.1. *Suppose that y is a smooth function, and let m_K be the barycenter of K ; then, for any $v \in \mathbf{V}_\varepsilon$, the quantity*

$$(2.7) \quad \begin{aligned} \langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon & := \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{S_{i1}(\nabla y(m_K))\} \left[\frac{1}{2} \left\{ \overline{D}_{e_1} v_\ell + \overline{D}_{e_1} v_{\ell+e_2} \right\} \right]_i \\ & + \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{S_{i2}(\nabla y(m_K))\} \left[\frac{1}{2} \left\{ \overline{D}_{e_2} v_\ell + \overline{D}_{e_2} v_{\ell+e_1} \right\} \right]_i \\ & = \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{\nabla_\zeta \phi_\eta(\nabla y(m_K) \eta) \eta_1\} \frac{1}{2} \left\{ \overline{D}_{e_1} v_\ell + \overline{D}_{e_1} v_{\ell+e_2} \right\} \\ & + \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{\nabla_\zeta \phi_\eta(\nabla y(m_K) \eta) \eta_2\} \frac{1}{2} \left\{ \overline{D}_{e_2} v_\ell + \overline{D}_{e_2} v_{\ell+e_1} \right\}, \end{aligned}$$

is a second order approximation to $\langle D\Phi^{CB}(y), v \rangle$ in the sense that there exists a constant $M = M(y, p)$, $1 \leq p \leq \infty$, independent of v , such that

$$\left| \langle D\Phi^{CB}(y), v \rangle - \langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon \right| \leq M \varepsilon^2 |v|_{W^{1,p}(\Omega)}.$$

2.3. The atomistic Cauchy–Born model. We define the average difference quotient (discrete derivative) as follows:

$$\begin{aligned} \overline{\overline{D}}_{e_1} v_\ell & := \frac{1}{2} \left\{ \overline{D}_{e_1} v_\ell + \overline{D}_{e_1} v_{\ell+e_2} \right\}, \\ \overline{\overline{D}}_{e_2} v_\ell & := \frac{1}{2} \left\{ \overline{D}_{e_2} v_\ell + \overline{D}_{e_2} v_{\ell+e_1} \right\}. \end{aligned}$$

Thus we can define the discrete gradient matrix as

$$\left\{ \overline{\nabla} v_\ell \right\}_{i\alpha} = \overline{\overline{D}}_{e_\alpha} v_\ell^i.$$

We introduce the atomistic potential

$$\begin{aligned}\Phi^{a,CB}(y) &:= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \phi_\eta(\bar{\nabla} y_\ell \eta) \\ &= \varepsilon^d \sum_{\ell \in \mathcal{L}} W_{CB}(\bar{\nabla} y_\ell).\end{aligned}$$

Notice that due to the definitions of $\bar{D}_{e_\alpha} v_\ell$, $\alpha = 1, 2$, as averages of discrete gradients, $\Phi^{a,CB}$ is not the standard atomistic potential that one gets by replacing in the atomistic model long-range interactions by short-range ones. In fact, in that case the corresponding atomistic potential would be

$$\begin{aligned}\tilde{\Phi}^{a,CB}(y) &:= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \phi_\eta(\tilde{\nabla} y_\ell \eta) \\ &= \varepsilon^d \sum_{\ell \in \mathcal{L}} W_{CB}(\tilde{\nabla} y_\ell), \quad \text{where } \{\tilde{\nabla} y_\ell\}_{i\alpha} = \bar{D}_{e_\alpha} y_\ell^i.\end{aligned}$$

Now, for a given field of external forces $f : \mathcal{L} \rightarrow \mathbb{R}^d$ the *atomistic Cauchy–Born* problem reads:

find a local minimizer $y^{a,CB}$ in \mathcal{X} of :

$$\Phi^{a,CB}(y) - \langle f, y \rangle_\varepsilon.$$

If such a minimizer exists, then

$$\langle D\Phi^{a,CB}(y^{a,CB}), v \rangle_\varepsilon = \langle f, v \rangle_\varepsilon, \quad \text{for all } v \in \mathcal{V}.$$

The next lemma provides the link between $\mathcal{A}^{a,CB}$ introduced earlier in Proposition 2.1 and $D\Phi^{a,CB}$.

Lemma 2.4. *Let $y \in \mathbf{V}_\varepsilon$; then for, any $v \in \mathbf{V}_\varepsilon$,*

$$(2.8) \quad \langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon = \langle D\Phi^{a,CB}(y), v \rangle_\varepsilon.$$

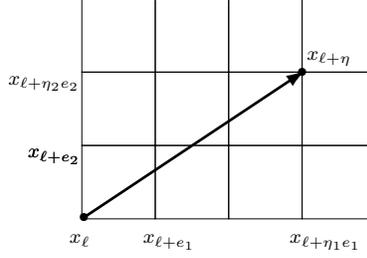
Proof. Obviously,

$$(2.9) \quad \begin{aligned}\langle D\Phi^{a,CB}(y), v \rangle_\varepsilon &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \{S_{i1}(\bar{\nabla} y_\ell)\} \left[\frac{1}{2} \left\{ \bar{D}_{e_1} v_\ell + \bar{D}_{e_1} v_{\ell+e_2} \right\} \right]_i \\ &\quad + \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \{S_{i2}(\bar{\nabla} y_\ell)\} \left[\frac{1}{2} \left\{ \bar{D}_{e_2} v_\ell + \bar{D}_{e_2} v_{\ell+e_1} \right\} \right]_i.\end{aligned}$$

Hence, it suffices to observe that for $y \in \mathbf{V}_\varepsilon$ and for K being the element with vertices $x_\ell, x_{\ell+e_1}, x_{\ell+e_1+e_2}, x_{\ell+e_2}$, see Fig. 1, we have that

$$\nabla y(m_K) = \bar{\nabla} y_\ell, \quad \text{for } y \in \mathbf{V}_\varepsilon,$$

and thus $S_{i\alpha}(\nabla y(m_K)) = S_{i\alpha}(\bar{\nabla} y_\ell)$. □

FIGURE 1. Typical interaction vector η and the corresponding lattice points.3. COMPARISON OF ATOMISTIC CAUCHY–BORN AND ATOMISTIC MODELS: $d = 2$

To compare the atomistic and atomistic Cauchy–Born models we start from (1.4) and note that:

$$\begin{aligned} \langle D\Phi^a(y), v \rangle_\varepsilon &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \bar{D}_\eta v_\ell \\ &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} v_\ell + \frac{1}{2} \bar{D}_{\eta_1 e_1} v_{\ell + \eta_2 e_2} \right\} \\ &\quad + \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} v_\ell + \frac{1}{2} \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1} \right\}. \end{aligned}$$

Due to the assumed periodicity of the lattice, we have that

$$\begin{aligned} \langle D\Phi^a(y), v \rangle_\varepsilon &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \bar{D}_\eta v_\ell \\ (3.1) \quad &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \left\{ \frac{1}{2} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) + \frac{1}{2} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_2 e_2}) \right\} \cdot \bar{D}_{\eta_1 e_1} v_\ell \\ &\quad + \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \left\{ \frac{1}{2} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) + \frac{1}{2} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_1 e_1}) \right\} \cdot \bar{D}_{\eta_2 e_2} v_\ell. \end{aligned}$$

Notice that when η_1, η_2 are positive,

$$\begin{aligned} \bar{D}_{\eta_1 e_1} v_\ell &= \bar{D}_{e_1} v_\ell + \cdots + \bar{D}_{e_1} v_{\ell + (\eta_1 - 1)e_1}, \\ \bar{D}_{\eta_2 e_2} v_\ell &= \bar{D}_{e_2} v_\ell + \cdots + \bar{D}_{e_2} v_{\ell + (\eta_2 - 1)e_2}, \end{aligned}$$

while when, e.g., $\eta_1 = -\sigma_1 < 0$,

$$(3.2) \quad \bar{D}_{\eta_1 e_1} v_\ell = -\bar{D}_{e_1} v_{\ell - \sigma_1 e_1} - \cdots - \bar{D}_{e_1} v_{\ell - e_1}.$$

Therefore, we deduce that

$$\langle D\Phi^a(y), v \rangle_\varepsilon = \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \bar{\Phi}_{\eta, \ell, 1} \cdot \bar{D}_{e_1} v_\ell + \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \bar{\Phi}_{\eta, \ell, 2} \cdot \bar{D}_{e_2} v_\ell,$$

where

$$(3.3) \quad \bar{\Phi}_{\eta,\ell,2} := \begin{cases} \sum_{k=0}^{\eta_2-1} \left\{ \frac{1}{2} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k e_2}) + \frac{1}{2} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k e_2 - \eta_1 e_1}) \right\}, & \text{for } \eta_2 > 0 \\ \sum_{k=1}^{\sigma_2} - \left\{ \frac{1}{2} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell+k e_2}) + \frac{1}{2} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell+k e_2 - \eta_1 e_1}) \right\}, & \text{for } \eta_2 = -\sigma_2 < 0, \end{cases}$$

and $\bar{\Phi}_{\eta,\ell,1}$ is defined analogously.

In the sequel, we focus on the term $\bar{\Phi}_{\eta,\ell,2}$ when $\eta_2 > 0$. The other terms are treated in a similar manner. As a first step we will compare $\bar{\Phi}_{\eta,\ell,2}$ with

$$\Phi_{\eta,\ell,2} := \sum_{k=0}^{\eta_2-1} \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{k,\eta_2,\ell}) \eta), \quad \eta_2 > 0,$$

where

$$(3.4) \quad \begin{array}{ll} m_{k,\eta_2,\ell} & \text{is the midpoint of the side with endpoints } x_{\ell-k e_2}, x_{\ell-k e_2 + \eta_2 e_2}, \\ m_{2,\ell} & \text{is the midpoint of the side with endpoints } x_{\ell}, x_{\ell+e_2}, \text{ and} \\ m_{1,\ell} & \text{is the midpoint of the side with endpoints } x_{\ell}, x_{\ell+e_1}. \end{array}$$

We have the following result.

Lemma 3.1. *Let y be a smooth function; then, assuming that $\eta_2 > 0$, we have that*

$$|\bar{\Phi}_{\eta,\ell,2} - \Phi_{\eta,\ell,2}| \leq C(y) \varepsilon^2.$$

Proof. We begin by noting that (in the case of $k = 0$):

$$\begin{aligned} & \frac{1}{2} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell}) + \frac{1}{2} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell - \eta_1 e_1}) \\ &= \frac{1}{2} \nabla_{\zeta} \phi_{\eta} \left(\left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell + \eta_2 e_2} \right\} + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell + \eta_1 e_1} \right\} \right) \\ & \quad + \frac{1}{2} \nabla_{\zeta} \phi_{\eta} \left(\left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - \eta_1 e_1} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - \eta_1 e_1 + \eta_2 e_2} \right\} + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1 + \eta_1 e_1} \right\} \right). \end{aligned}$$

We shall use the following elementary bound: there exists a constant $c_1 = c_1(\psi'')$ such that, for any smooth function ψ and real numbers a, b ,

$$(3.5) \quad \left| \frac{1}{2} \psi(a) + \frac{1}{2} \psi(b) - \psi \left(\frac{a+b}{2} \right) \right| \leq c_1 |a-b|^2.$$

We notice that

$$\begin{aligned} & \left| \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell + \eta_2 e_2} \right\} + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell + \eta_1 e_1} \right\} \right. \\ & \quad \left. - \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - \eta_1 e_1} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - \eta_1 e_1 + \eta_2 e_2} \right\} - \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1 + \eta_1 e_1} \right\} \right| \leq C \varepsilon. \end{aligned}$$

In view of (3.5) it suffices to consider

$$\begin{aligned} & \nabla_{\zeta} \phi_{\eta} \left(\left\{ \frac{1}{4} \bar{D}_{\eta_1 e_1} y_{\ell} + \frac{1}{4} \bar{D}_{\eta_1 e_1} y_{\ell + \eta_2 e_2} \right\} + \left\{ \frac{1}{4} \bar{D}_{\eta_2 e_2} y_{\ell} + \frac{1}{4} \bar{D}_{\eta_2 e_2} y_{\ell + \eta_1 e_1} \right\} \right. \\ & \quad \left. + \left\{ \frac{1}{4} \bar{D}_{\eta_1 e_1} y_{\ell - \eta_1 e_1} + \frac{1}{4} \bar{D}_{\eta_1 e_1} y_{\ell - \eta_1 e_1 + \eta_2 e_2} \right\} + \left\{ \frac{1}{4} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1} + \frac{1}{4} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1 + \eta_1 e_1} \right\} \right) \\ &= \nabla_{\zeta} \phi_{\eta} \left(\left\{ \frac{1}{4} \bar{D}_{2\eta_1 e_1} y_{\ell - \eta_1 e_1} + \frac{1}{4} \bar{D}_{2\eta_1 e_1} y_{\ell - \eta_1 e_1 + \eta_2 e_2} \right\} \right. \\ & \quad \left. + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell} + \frac{1}{4} \bar{D}_{\eta_2 e_2} y_{\ell + \eta_1 e_1} + \frac{1}{4} \bar{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1} \right\} \right). \end{aligned}$$

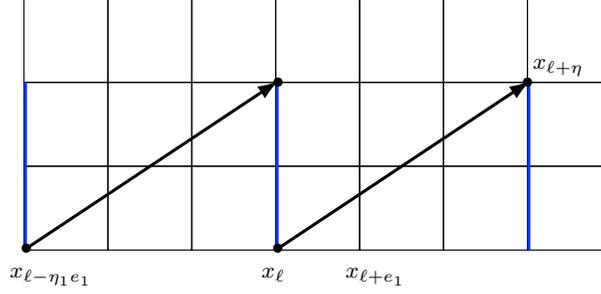


FIGURE 2. Symmetry as a result of combining $\overline{D}_{\eta}y_{\ell}$ and $\overline{D}_{\eta}y_{\ell - \eta_1 e_1}$.

Now,

$$\begin{aligned} & \left| \left\{ \frac{1}{4} \overline{D}_{2\eta_1 e_1} y_{\ell - \eta_1 e_1} + \frac{1}{4} \overline{D}_{2\eta_1 e_1} y_{\ell - \eta_1 e_1 + \eta_2 e_2} \right\} - \eta_1 \partial_1 y(m_{0, \eta_2, \ell}) \right| \\ & \leq \left| \frac{1}{2} \eta_1 \partial_1 y(x_{\ell}) + \frac{1}{2} \eta_1 \partial_1 y(x_{\ell + \eta_2 e_2}) - \eta_1 \partial_1 y(m_{0, \eta_2, \ell}) \right| \\ & \quad + \left| \frac{1}{4} \overline{D}_{2\eta_1 e_1} y_{\ell - \eta_1 e_1} - \frac{1}{2} \eta_1 \partial_1 y(x_{\ell}) \right| + \left| \frac{1}{4} \overline{D}_{2\eta_1 e_1} y_{\ell - \eta_1 e_1 + \eta_2 e_2} - \frac{1}{2} \eta_1 \partial_1 y(x_{\ell + \eta_2 e_2}) \right| \\ & \leq C \varepsilon^2. \end{aligned}$$

Similarly,

$$\left| \left\{ \frac{1}{2} \overline{D}_{\eta_2 e_2} y_{\ell} + \frac{1}{4} \overline{D}_{\eta_2 e_2} y_{\ell + \eta_1 e_1} + \frac{1}{4} \overline{D}_{\eta_2 e_2} y_{\ell - \eta_1 e_1} \right\} - \eta_2 \partial_2 y(m_{0, \eta_2, \ell}) \right| \leq C \varepsilon^2.$$

Proceeding as above for any k , $k \leq \eta_2 - 1$, we complete the proof. \square

Next we establish the following result, which is valid for all positive or negative η_2 .

Lemma 3.2. *Let y be a smooth function, and let $m_{2, \ell}$ denote the midpoint of the side with endpoints $x_{\ell}, x_{\ell + e_2}$ (cf. (3.4) above); then,*

$$\left| \eta_2 \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{2, \ell}) \eta) - \overline{\Phi}_{\eta, \ell, 2} \right| \leq C(y) \varepsilon^2.$$

Proof. Assume first that $\eta_2 > 0$. It is a simple matter to observe that $\overline{\Phi}_{\eta, \ell, 2}$ is a sum of η_2 terms involving function evaluations at points that are symmetrically placed with respect to $m_{2, \ell}$ (if η_2 is odd, one of these points is $m_{2, \ell}$). Thus,

$$\left| \frac{1}{\eta_2} \overline{\Phi}_{\eta, \ell, 2} - \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{2, \ell}) \eta) \right| \leq C(y) \varepsilon^2.$$

In the case where $\eta_2 = -\sigma_2 < 0$ one can show that

$$\left| - \sum_{k=1}^{\sigma_2} \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{-k, \eta_2, \ell}) \eta) - \overline{\Phi}_{\eta, \ell, 2} \right| \leq C(y) \varepsilon^2.$$

As before, the points $m_{-k,\eta_2,\ell}$ are symmetrically placed with respect to $m_{2,\ell}$. Hence

$$\left| \frac{1}{\sigma_2} \sum_{k=1}^{\sigma_2} \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{-k,\eta_2,\ell}) \eta) - \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{2,\ell}) \eta) \right| \leq C(y) \varepsilon^2,$$

and the proof is complete. \square

We have therefore completed the proof of the following result.

Proposition 3.1. *Let y be a smooth function, and let $m_{1,\ell}, m_{2,\ell}$ be as in (3.4); then, for any $v \in \mathbf{V}_{\varepsilon}$, the quantity*

$$(3.6) \quad \begin{aligned} \langle \mathcal{A}, v \rangle_{\varepsilon} := & \varepsilon^d \sum_{\ell \in \mathfrak{L}} \sum_{\eta \in R} \{ \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{1,\ell}) \eta) \eta_1 \} \cdot \bar{D}_{e_1} v_{\ell} \\ & + \varepsilon^d \sum_{\ell \in \mathfrak{L}} \sum_{\eta \in R} \{ \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{2,\ell}) \eta) \eta_2 \} \cdot \bar{D}_{e_2} v_{\ell} \end{aligned}$$

is a second order approximation to $\langle D\Phi^a(y), v \rangle_{\varepsilon}$ in the sense that there exists a constant $M = M(y, p)$, independent of v , such that

$$\left| \langle D\Phi^a(y), v \rangle_{\varepsilon} - \langle \mathcal{A}, v \rangle_{\varepsilon} \right| \leq M \varepsilon^2 |v|_{W^{1,p}(\Omega)}, \quad 1 \leq p \leq \infty.$$

4. ENERGY AND VARIATIONAL CONSISTENCY: $d = 2$

In this section we present our basic results in two space dimensions. Similar results for the comparison of atomistic and atomistic Cauchy–Born models, or atomistic Cauchy–Born and continuum Cauchy–Born models are proved in a similar fashion, however we omit their (entirely similar) statements.

Theorem 4.1. (VARIATIONAL CONSISTENCY) *Let y be a smooth function; then, for any $v \in \mathbf{V}_{\varepsilon}$, the continuum Cauchy–Born variation $\langle D\Phi^{CB}(y), v \rangle$ is a second order approximation to the atomistic variation $\langle D\Phi^a(y), v \rangle_{\varepsilon}$ in the sense that there exists a constant $M_V = M_V(y, p)$, $1 \leq p \leq \infty$, independent of v , such that*

$$\left| \langle D\Phi^{CB}(y) - \langle D\Phi^a(y), v \rangle_{\varepsilon}, v \rangle \right| \leq M_V \varepsilon^2 |v|_{W^{1,p}(\Omega)}.$$

Proof. If x_{ℓ} is the bottom-left vertex of K , we denote by K_{e_1} the element that shares the edge $[x_{\ell}, x_{\ell+e_1}]$ with K . Similarly, we denote by K_{e_2} the element that shares the edge $[x_{\ell}, x_{\ell+e_2}]$ with K . Then, one can rewrite (2.7) as

$$(4.1) \quad \begin{aligned} \langle \mathcal{A}^{a,CB}, v \rangle_{\varepsilon} := & \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \frac{1}{2} \{ \nabla_{\zeta} \phi_{\eta} (\nabla y(m_K) \eta) \eta_1 + \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{K_{e_1}}) \eta) \eta_1 \} \cdot \bar{D}_{e_1} v_{\ell} \\ & + \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \frac{1}{2} \{ \nabla_{\zeta} \phi_{\eta} (\nabla y(m_K) \eta) \eta_2 + \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{K_{e_2}}) \eta) \eta_2 \} \cdot \bar{D}_{e_2} v_{\ell}. \end{aligned}$$

One should compare directly the above expression with (3.6). Since, obviously,

$$(4.2) \quad \left| \frac{1}{2} \{ \nabla_{\zeta} \phi_{\eta} (\nabla y(m_K) \eta) \eta_1 + \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{K_{e_1}}) \eta) \eta_1 \} - \{ \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{1,\ell}) \eta) \eta_1 \} \right| \leq C(y) \varepsilon^2,$$

the proof is complete in view of Propositions 2.1 and 3.1. \square

Theorem 4.2. (ENERGY CONSISTENCY) *Let y be a smooth function; then, the continuum Cauchy–Born energy $\Phi^{CB}(y)$ is a second order approximation to the atomistic energy $\Phi^a(y)$ in the sense that there exists a constant $M_E = M_E(y)$, such that*

$$\left| \Phi^{CB}(y) - \Phi^a(y) \right| \leq M_E \varepsilon^2.$$

Proof. The proof is similar to, though considerably simpler than, the proof of the variational consistency. We start from the continuum Cauchy–Born energy

$$\begin{aligned}\Phi^{CB}(y) &= \int_{\Omega} W_{CB}(\nabla y(x)) \, dx = \sum_{K \in \mathcal{T}} \int_K W_{CB}(\nabla y(x)) \, dx \\ &= \sum_{K \in \mathcal{T}} |K| W_{CB}(\nabla y(m_K)) + \sum_{K \in \mathcal{T}} \int_K \left[W_{CB}(\nabla y(x)) - W_{CB}(\nabla y(m_K)) \right] \, dx =: I_1 + I_2,\end{aligned}$$

where as before m_K is the barycenter of K . Using similar arguments as in the proof of Lemma 2.3 we get

$$|I_2| \leq C(y) \varepsilon^2.$$

As before we will compare I_1 with the atomistic energy $\Phi^a(y)$. Since m_K is the barycenter of K the key point here is to rearrange the terms in $\Phi^a(y)$ in order to create symmetries around the cell K . In fact, using the assumed periodicity of the lattice, we have that

$$\begin{aligned}\Phi^a(y) &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \phi_{\eta}(\bar{D}_{\eta} y_{\ell}) \\ &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \frac{1}{4} \left[\phi_{\eta}(\bar{D}_{\eta} y_{\ell}) + \phi_{\eta}(\bar{D}_{\eta} y_{\ell - (\eta_1 - 1)e_1}) \right. \\ &\quad \left. + \phi_{\eta}(\bar{D}_{\eta} y_{\ell - (\eta_2 - 1)e_2}) + \phi_{\eta}(\bar{D}_{\eta} y_{\ell - (\eta_1 - 1)e_1 - (\eta_2 - 1)e_2}) \right].\end{aligned}$$

Next we use similar splittings as in Lemma 3.1:

$$\begin{aligned}\bar{D}_{\eta} y_{\ell} &= \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell + \eta_2 e_2} \right\} + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell + \eta_1 e_1} \right\}, \\ \bar{D}_{\eta} y_{\ell - (\eta_1 - 1)e_1} &= \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_1 - 1)e_1} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_1 - 1)e_1 + \eta_2 e_2} \right\} \\ &\quad + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - (\eta_1 - 1)e_1} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - (\eta_1 - 1)e_1 + \eta_1 e_1} \right\}, \\ \bar{D}_{\eta} y_{\ell - (\eta_2 - 1)e_2} &= \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_2 - 1)e_2} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_2 - 1)e_2 + \eta_2 e_2} \right\} \\ &\quad + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - (\eta_2 - 1)e_2} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - (\eta_2 - 1)e_2 + \eta_1 e_1} \right\}, \\ \bar{D}_{\eta} y_{\ell - (\eta_1 - 1)e_1 - (\eta_2 - 1)e_2} &= \left\{ \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_1 - 1)e_1 - (\eta_2 - 1)e_2} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_1 - 1)e_1 - (\eta_2 - 1)e_2 + \eta_2 e_2} \right\} \\ &\quad + \left\{ \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - (\eta_1 - 1)e_1 - (\eta_2 - 1)e_2} + \frac{1}{2} \bar{D}_{\eta_2 e_2} y_{\ell - (\eta_1 - 1)e_1 - (\eta_2 - 1)e_2 + \eta_1 e_1} \right\}.\end{aligned}$$

Observe now that, for example,

$$\begin{aligned}\frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell} + \frac{1}{2} \bar{D}_{\eta_1 e_1} y_{\ell - (\eta_1 - 1)e_1} &= \frac{y_{\ell + \eta_1 e_1} - y_{\ell - (\eta_1 - 1)e_1}}{2\varepsilon} + \frac{y_{\ell + e_1} - y_{\ell}}{2\varepsilon} \\ &= \frac{2\eta_1 - 1}{2} \partial_1 y(m_{1,\ell}) + \frac{1}{2} \partial_1 y(m_{1,\ell}) + \mathcal{O}(\varepsilon^2) = \eta_1 \partial_1 y(m_{1,\ell}) + \mathcal{O}(\varepsilon^2),\end{aligned}$$

where $m_{1,\ell}$ is the midpoint of the edge $[x_{\ell}, x_{\ell + e_1}]$. Notice that the above relations do not depend on the signs of η_1, η_2 . Using similar groupings and the fact that

$$\eta_1 \frac{1}{4} \left[\partial_1 y(m_{1,\ell}) + \partial_1 y(m_{1,\ell + e_2}) + \partial_1 y(m_{1,\ell + \eta_2 e_2}) + \partial_1 y(m_{1,\ell - (\eta_2 - 1)e_2}) \right] = \eta_1 \partial_1 y(m_K) + \mathcal{O}(\varepsilon^2),$$

one can deduce, by adopting the arguments of Lemma 3.1 to our case, that

$$\Phi^a(y) = \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \phi_{\eta}(\nabla y(m_K) \eta) + \mathcal{O}(\varepsilon^2).$$

The proof is thus complete. \square

5. ANALYSIS OF CAUCHY–BORN APPROXIMATIONS: $d = 3$

The analysis presented in the previous sections can be extended to three space dimensions. The arguments are similar, but there are certain steps that differ, so we shall focus our attention on these, and we shall only present the key points here. In particular, we shall omit arguments that are similar to those in two dimensions, unless this is necessary. Linking the continuum model to the atomistic model is based on a three-dimensional *atomistic Cauchy–Born model (A-CB)*. As before, to derive this model we start from the continuum model and perform appropriate approximation steps. The final model has consistency error of the order $\mathcal{O}(\varepsilon^2)$ compared to the continuum Cauchy–Born model and the original atomistic model.

Trilinear finite elements on the lattice. Let \mathbf{V}_ε be the linear space of all periodic functions on the lattice \mathfrak{L} that are continuous and piecewise trilinear on $\bar{\Omega}$. More precisely, let

$$\begin{aligned} \mathcal{T} &:= \{K \subset \Omega : K = (x_{\ell_1}, x_{\ell_1+1}) \times (x_{\ell_2}, x_{\ell_2+1}) \times (x_{\ell_3}, x_{\ell_3+1}), \quad x_\ell = (x_{\ell_1}, x_{\ell_2}, x_{\ell_3}) \in \Omega_{\text{discr}}\}, \\ \mathbf{V}_\varepsilon &:= \{v : \Omega \rightarrow \mathbb{R}^d, \quad v \in C(\Omega), \quad v|_K \in \mathbb{Q}_1(K) \text{ and } v_\ell = v(x_\ell) \quad \text{periodic with respect to } \mathfrak{L}\}, \end{aligned}$$

where $\mathbb{Q}_1(K)$ denotes the set of all trilinear functions on K . As before the elements of \mathbf{V}_ε can be expressed in terms of the nodal basis functions $\Psi_\ell = \Psi_\ell(x)$ as

$$v(x) = \sum_{\ell \in \mathfrak{L}} v_\ell \Psi_{\ell_1}(x_1) \Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3), \quad v_\ell = v(x_\ell),$$

where we have used the fact that $\Psi_\ell(x)$ can be written as the tensor product of the standard one-dimensional piecewise linear hat functions $\Psi_{\ell_i}(x_i)$. Here $\Psi_{\ell_i}(x_{\bar{\ell}_i}) = \delta_{\ell_i \bar{\ell}_i}$.

5.1. Consistency analysis of the Cauchy–Born model: $d = 3$. Let, as before, $v \in \mathbf{V}_\varepsilon$ and let y be a sufficiently smooth function. Our aim is to approximate

$$\langle D\Phi^{CB}(y), v \rangle = \int_{\Omega} S_{i\alpha}(\nabla y(x)) \partial_\alpha v^i(x) dx, \quad v \in \mathbf{V}_\varepsilon.$$

As before, we consider a generic term of the above sum of the form:

$$\int_{\Omega} g(\nabla y(x)) \partial_1 v(x) dx, \quad v \in \mathbf{V}_\varepsilon.$$

Recall that, since $v \in \mathbf{V}_\varepsilon$,

$$\begin{aligned} \partial_1 v(x) &= \sum_{\ell \in \mathfrak{L}} v_{(\ell_1, \ell_2, \ell_3)} \frac{1}{\varepsilon} \left(\mathbf{1}_{[x_{\ell_1-1}, x_{\ell_1}]}(x_1) - \mathbf{1}_{[x_{\ell_1}, x_{\ell_1+1}]}(x_1) \right) \Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3) \\ &= \sum_{\ell \in \mathfrak{L}} \frac{1}{\varepsilon} \left(v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right) \mathbf{1}_{[x_{\ell_1}, x_{\ell_1+1}]}(x_1) \Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3). \end{aligned}$$

Let us now consider

$$G(x) := G(x_1, x_2, x_3) = \int_{x_{-N_1-1}}^{x_1} g(\nabla y(x'_1, x_2, x_3)) dx'_1.$$

Then,

$$\begin{aligned}
& \int_{\Omega} g(\nabla y(x)) \partial_1 v(x) \, dx \\
&= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{\Omega} g(\nabla y(x)) \left(v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right) \mathbf{1}_{[x_{\ell_1}, x_{\ell_1+1}]}(x_1) \Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3) \, dx \\
&= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \int_{x_{\ell_3-1}}^{x_{\ell_3+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) \, dx_1 \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3) \right\} \, dx_2 \, dx_3 \\
&= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \int_{x_{\ell_3-1}}^{x_{\ell_3+1}} \left[G(x_{\ell_1+1}, x_2, x_3) - G(x_{\ell_1}, x_2, x_3) \right] \Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3) \, dx_2 \, dx_3 \\
&\quad \times \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \\
&= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \int_{x_{\ell_3-1}}^{x_{\ell_3+1}} \left[G(x_{\ell_1+1}, x_2, x_3) - G(x_{\ell_1}, x_2, x_3) \right] \left(\Psi_{\ell_2}(x_2) \Psi_{\ell_3}(x_3) - \frac{1}{4} \right) \, dx_2 \, dx_3 \\
&\quad \times \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \\
&\quad + \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \int_{x_{\ell_3-1}}^{x_{\ell_3+1}} \left[G(x_{\ell_1+1}, x_2, x_3) - G(x_{\ell_1}, x_2, x_3) \right] \frac{1}{4} \, dx_2 \, dx_3 \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \\
&=: A_1 + A_2.
\end{aligned}$$

As in two space dimensions (cf. Lemma 2.2) one can show that A_1 is second order accurate with respect to ε . The term A_2 , on the other hand, requires further simplification. To this end, notice that

$$\begin{aligned}
A_2 &= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \int_{x_{\ell_3-1}}^{x_{\ell_3+1}} \left[G(x_{\ell_1+1}, x_2, x_3) - G(x_{\ell_1}, x_2, x_3) \right] \frac{1}{4} \, dx_2 \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \\
&= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \frac{1}{4} \int_{x_{\ell_2-1}}^{x_{\ell_2+1}} \int_{x_{\ell_3-1}}^{x_{\ell_3+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) \, dx_1 \right\} \, dx_2 \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \\
&= \frac{1}{\varepsilon} \sum_{\ell \in \mathcal{L}} \frac{1}{4} \int_{x_{\ell_2}}^{x_{\ell_2+1}} \int_{x_{\ell_3}}^{x_{\ell_3+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) \, dx_1 \right\} \, dx_2 \left[v_{(\ell_1+1, \ell_2, \ell_3)} - v_{(\ell_1, \ell_2, \ell_3)} \right] \\
&\quad + \frac{1}{\varepsilon} \sum_{\tilde{\ell} \in \mathcal{L}} \frac{1}{4} \int_{x_{\ell_2}}^{x_{\ell_2+1}} \int_{x_{\tilde{\ell}_3}}^{x_{\tilde{\ell}_3+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) \, dx_1 \right\} \, dx_2 \left[v_{(\ell_1+1, \ell_2, \tilde{\ell}_3+1)} - v_{(\ell_1, \ell_2, \tilde{\ell}_3+1)} \right] \\
&\quad + \frac{1}{\varepsilon} \sum_{\ell' \in \mathcal{L}} \frac{1}{4} \int_{x_{\ell'_2}}^{x_{\ell'_2+1}} \int_{x_{\ell_3}}^{x_{\ell_3+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) \, dx_1 \right\} \, dx_2 \left[v_{(\ell_1+1, \ell'_2+1, \ell_3)} - v_{(\ell_1, \ell'_2+1, \ell_3)} \right] \\
&\quad + \frac{1}{\varepsilon} \sum_{\tilde{\ell} \in \mathcal{L}} \frac{1}{4} \int_{x_{\ell'_2}}^{x_{\ell'_2+1}} \int_{x_{\tilde{\ell}_3}}^{x_{\tilde{\ell}_3+1}} \left\{ \int_{x_{\ell_1}}^{x_{\ell_1+1}} g(\nabla y(x)) \, dx_1 \right\} \, dx_2 \left[v_{(\ell_1+1, \ell'_2+1, \tilde{\ell}_3+1)} - v_{(\ell_1, \ell'_2+1, \tilde{\ell}_3+1)} \right] \\
&= \sum_{K \in \mathcal{T}} \int_K g(\nabla y(x)) \, dx \frac{1}{4} \left\{ \bar{D}_{e_1} v_{\ell} + \bar{D}_{e_1} v_{\ell+e_2} + \bar{D}_{e_1} v_{\ell+e_3} + \bar{D}_{e_1} v_{\ell+e_2+e_3} \right\},
\end{aligned}$$

where $\tilde{\ell} = (\ell_1, \ell_2, \tilde{\ell}_3)$, $\ell' = (\ell_1, \ell'_2, \ell_3)$, and $\hat{\ell} = (\ell_1, \ell'_2, \tilde{\ell}_3)$. We define the average discrete derivatives as follows:

$$(5.1) \quad \overline{\overline{D}}_{e_1} v_\ell = \frac{1}{4} \left\{ \overline{D}_{e_1} v_\ell + \overline{D}_{e_1} v_{\ell+e_2} + \overline{D}_{e_1} v_{\ell+e_3} + \overline{D}_{e_1} v_{\ell+e_2+e_3} \right\}.$$

As in Lemma 2.3, one can show, with m_K signifying the barycenter of K , that there exists a constant $C = C(y)$ such that

$$\left| \sum_{K \in \mathcal{T}} \left[\int_K g(\nabla y(x)) \, dx - |K| g(\nabla y(m_K)) \right] \overline{\overline{D}}_{e_1} v_\ell \right| \leq C(y) \varepsilon^2 |v|_{W^{1,p}(\Omega)}.$$

As in two space dimensions, one can define, for any $v \in \mathbf{V}_\varepsilon$, the quantity

$$(5.2) \quad \begin{aligned} \langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon : &= \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{ \nabla_\zeta \phi_\eta(\nabla y(m_K)) \eta_1 \} \cdot \overline{\overline{D}}_{e_1} v_\ell \\ &+ \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{ \nabla_\zeta \phi_\eta(\nabla y(m_K)) \eta_2 \} \cdot \overline{\overline{D}}_{e_2} v_\ell \\ &+ \varepsilon^d \sum_{K \in \mathcal{T}} \sum_{\eta \in R} \{ \nabla_\zeta \phi_\eta(\nabla y(m_K)) \eta_3 \} \cdot \overline{\overline{D}}_{e_3} v_\ell. \end{aligned}$$

We thus deduce that $\langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon$ is a second order approximation to $\langle D\Phi^{CB}(y), v \rangle$ in the sense that

$$\left| \langle D\Phi^{CB}(y), v \rangle - \langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon \right| \leq M \varepsilon^2 |v|_{W^{1,p}(\Omega)}.$$

5.2. The atomistic Cauchy–Born model: $d = 3$. Using the above definition of the average discrete derivatives we define the discrete gradient matrix as

$$\left\{ \overline{\nabla} v_\ell \right\}_{i\alpha} := \overline{\overline{D}}_{e_\alpha} v_\ell^i,$$

and the atomistic potential

$$\Phi^{a,CB}(y) := \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \phi_\eta(\overline{\nabla} y_\ell \eta) = \varepsilon^d \sum_{\ell \in \mathcal{L}} W_{CB}(\overline{\nabla} y_\ell).$$

Now, for a given field of external forces $f : \mathcal{L} \rightarrow \mathbb{R}^d$ the *atomistic Cauchy–Born* problem reads as follows:

$$\begin{aligned} &\text{find a local minimizer } y^{a,CB} \text{ in } \mathcal{X} \text{ of :} \\ &\Phi^{a,CB}(y^{a,CB}) - \langle f, y^a \rangle_\varepsilon. \end{aligned}$$

If such a minimizer exists, then

$$\langle D\Phi^{a,CB}(y^{a,CB}), v \rangle_\varepsilon = \langle f, v \rangle_\varepsilon, \quad \text{for all } v \in \mathcal{V}.$$

As in two space dimensions, one can link $\mathcal{A}^{a,CB}$ to $D\Phi^{a,CB}$ as follows: let $y \in \mathbf{V}_\varepsilon$; then, for any $v \in \mathbf{V}_\varepsilon$,

$$(5.3) \quad \langle \mathcal{A}^{a,CB}, v \rangle_\varepsilon = \langle D\Phi^{a,CB}(y), v \rangle_\varepsilon.$$

5.3. Comparison of atomistic Cauchy–Born and atomistic models: $d = 3$. To compare the atomistic and atomistic Cauchy–Born models we start from (1.4):

$$\langle D\Phi^a(y), v \rangle_\varepsilon = \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \bar{D}_\eta v_\ell.$$

Then, one can split $\bar{D}_\eta v_\ell$ and $\bar{D}_\eta v_\ell$ as follows:

$$\bar{D}_\eta v_\ell = \bar{D}_{\eta_1 e_1} v_\ell + \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1} + \bar{D}_{\eta_3 e_3} v_{\ell + \eta_1 e_1 + \eta_2 e_2}$$

and

$$\bar{D}_\eta v_\ell = \bar{D}_{\eta_1 e_1} v_\ell + \bar{D}_{\eta_3 e_3} v_{\ell + \eta_1 e_1} + \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1 + \eta_3 e_3}.$$

Using similar splittings but starting with $\bar{D}_{\eta_2 e_2} v_\ell$ and $\bar{D}_{\eta_3 e_3} v_\ell$, we end up with six alternative expressions for $\bar{D}_\eta v_\ell$. Thus, by replacing $\bar{D}_\eta v_\ell$ with its average and grouping terms of the same type of discrete derivative we deduce that

$$\begin{aligned} & \langle D\Phi^a(y), v \rangle_\varepsilon \\ &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \left\{ \frac{1}{3} \bar{D}_{\eta_1 e_1} v_\ell + \frac{1}{6} \bar{D}_{\eta_1 e_1} v_{\ell + \eta_2 e_2} + \frac{1}{6} \bar{D}_{\eta_1 e_1} v_{\ell + \eta_3 e_3} + \frac{1}{3} \bar{D}_{\eta_1 e_1} v_{\ell + \eta_2 e_2 + \eta_3 e_3} \right\} \\ &+ \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \left\{ \frac{1}{3} \bar{D}_{\eta_2 e_2} v_\ell + \frac{1}{6} \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1} + \frac{1}{6} \bar{D}_{\eta_2 e_2} v_{\ell + \eta_3 e_3} + \frac{1}{3} \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1 + \eta_3 e_3} \right\} \\ &+ \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) \cdot \left\{ \frac{1}{3} \bar{D}_{\eta_3 e_3} v_\ell + \frac{1}{6} \bar{D}_{\eta_3 e_3} v_{\ell + \eta_1 e_1} + \frac{1}{6} \bar{D}_{\eta_3 e_3} v_{\ell + \eta_2 e_2} + \frac{1}{3} \bar{D}_{\eta_3 e_3} v_{\ell + \eta_1 e_1 + \eta_2 e_2} \right\}. \end{aligned}$$

Hence, since the lattice is periodic, we deduce that

(5.4)

$$\begin{aligned} & \langle D\Phi^a(y), v \rangle_\varepsilon \\ &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \left\{ \frac{1}{3} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) + \frac{1}{6} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_2 e_2}) + \frac{1}{6} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_3 e_3}) + \frac{1}{3} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_2 e_2 - \eta_3 e_3}) \right\} \\ & \quad \cdot \bar{D}_{\eta_1 e_1} v_\ell \\ &+ \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \left\{ \frac{1}{3} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) + \frac{1}{6} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_1 e_1}) + \frac{1}{6} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_3 e_3}) + \frac{1}{3} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_1 e_1 - \eta_3 e_3}) \right\} \\ & \quad \cdot \bar{D}_{\eta_2 e_2} v_\ell \\ &+ \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \left\{ \frac{1}{3} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_\ell) + \frac{1}{6} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_1 e_1}) + \frac{1}{6} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_2 e_2}) + \frac{1}{3} \nabla_\zeta \phi_\eta(\bar{D}_\eta y_{\ell - \eta_1 e_1 - \eta_2 e_2}) \right\} \\ & \quad \cdot \bar{D}_{\eta_3 e_3} v_\ell. \end{aligned}$$

As before we split, for $\eta_1, \eta_2, \eta_3 > 0$,

$$\begin{aligned} \bar{D}_{\eta_1 e_1} v_\ell &= \bar{D}_{e_1} v_\ell + \cdots + \bar{D}_{e_1} v_{\ell + (\eta_1 - 1)e_1}, \\ \bar{D}_{\eta_2 e_2} v_\ell &= \bar{D}_{e_2} v_\ell + \cdots + \bar{D}_{e_2} v_{\ell + (\eta_2 - 1)e_2}, \\ \bar{D}_{\eta_3 e_3} v_\ell &= \bar{D}_{e_3} v_\ell + \cdots + \bar{D}_{e_3} v_{\ell + (\eta_3 - 1)e_3}. \end{aligned}$$

In case where $\eta_\alpha < 0$ we use splittings of the form (3.2). In the sequel we will assume that $\eta_1, \eta_2, \eta_3 > 0$. The general case can be treated by adopting the arguments presented in two space dimensions (cf. (3.3) and

Lemma 3.2). Therefore, by using the notation

$$\begin{aligned}
\bar{\Phi}_{\eta,\ell,1} &:= \sum_{k=0}^{\eta_1-1} \left\{ \frac{1}{3} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_1) + \frac{1}{6} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_1 - \eta_2 e_2) \right. \\
&\quad \left. + \frac{1}{6} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_1 - \eta_3 e_3) + \frac{1}{3} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_1 - \eta_2 e_2 - \eta_3 e_3) \right\}, \\
\bar{\Phi}_{\eta,\ell,2} &:= \sum_{k=0}^{\eta_2-1} \left\{ \frac{1}{3} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_2) + \frac{1}{6} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_2 - \eta_1 e_1) \right. \\
&\quad \left. + \frac{1}{6} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_2 - \eta_3 e_3) + \frac{1}{3} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_2 - \eta_1 e_1 - \eta_3 e_3) \right\}, \\
\bar{\Phi}_{\eta,\ell,3} &:= \sum_{k=0}^{\eta_3-1} \left\{ \frac{1}{3} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_3) + \frac{1}{6} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_3 - \eta_1 e_1) \right. \\
&\quad \left. + \frac{1}{6} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_3 - \eta_2 e_2) + \frac{1}{3} \nabla_{\zeta} \phi_{\eta} (\bar{D}_{\eta} y_{\ell-k} e_3 - \eta_1 e_1 - \eta_2 e_2) \right\},
\end{aligned} \tag{5.5}$$

we finally deduce that

$$\begin{aligned}
\langle D\Phi^a(y), v \rangle_{\varepsilon} &= \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \bar{\Phi}_{\eta,\ell,1} \cdot \bar{D}_{e_1} v_{\ell} \\
&\quad + \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \bar{\Phi}_{\eta,\ell,2} \cdot \bar{D}_{e_2} v_{\ell} + \varepsilon^d \sum_{\ell \in \mathcal{L}} \sum_{\eta \in R} \bar{\Phi}_{\eta,\ell,3} \cdot \bar{D}_{e_3} v_{\ell}.
\end{aligned}$$

Next, we shall focus on the comparison of $\bar{\Phi}_{\eta,\ell,1}$ with the term

$$\Phi_{\eta,\ell,1} = \sum_{k=0}^{\eta_1-1} \nabla_{\zeta} \phi_{\eta} (\nabla y(m_{k,\eta_1,\ell}) \eta),$$

where

$m_{k,\eta_1,\ell}$ is the midpoint of the side with endpoints $x_{\ell-k} e_1, x_{\ell-k} e_1 + \eta_1 e_1$, and
 $m_{1,\ell}$ is the midpoint of the side with endpoints $x_{\ell}, x_{\ell} + e_1$.

Let $k = 0$. We group together the $\frac{1}{3}$ -terms in $\bar{\Phi}_{\eta,\ell,1}$. We use the splittings

$$\begin{aligned}
\bar{D}_{\eta} v_{\ell} &= \frac{1}{2} \left\{ \bar{D}_{\eta_2 e_2} v_{\ell} + \bar{D}_{\eta_3 e_3} v_{\ell + \eta_2 e_2} + \bar{D}_{\eta_1 e_1} v_{\ell + \eta_2 e_2 + \eta_3 e_3} \right. \\
&\quad \left. + \bar{D}_{\eta_1 e_1} v_{\ell} + \bar{D}_{\eta_3 e_3} v_{\ell + \eta_1 e_1} + \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1 + \eta_3 e_3} \right\},
\end{aligned}$$

and

$$\begin{aligned}
\bar{D}_{\eta} v_{\ell - \eta_2 e_2 - \eta_3 e_3} &= \frac{1}{2} \left\{ \bar{D}_{\eta_2 e_2} v_{\ell - \eta_2 e_2 - \eta_3 e_3} + \bar{D}_{\eta_3 e_3} v_{\ell - \eta_3 e_3} + \bar{D}_{\eta_1 e_1} v_{\ell} \right. \\
&\quad \left. + \bar{D}_{\eta_1 e_1} v_{\ell - \eta_2 e_2 - \eta_3 e_3} + \bar{D}_{\eta_3 e_3} v_{\ell - \eta_2 e_2 - \eta_3 e_3 + \eta_1 e_1} + \bar{D}_{\eta_2 e_2} v_{\ell - \eta_2 e_2 + \eta_1 e_1} \right\}.
\end{aligned}$$

These choices were made in order to create the required symmetries. In fact, by taking into account that $\bar{D}_{\eta} v_{\ell}$ and $\bar{D}_{\eta} v_{\ell - \eta_2 e_2 - \eta_3 e_3}$ are grouped together in (5.5) and observing that

$$\begin{aligned}
2\bar{D}_{\eta_1 e_1} v_{\ell} + \bar{D}_{\eta_1 e_1} v_{\ell + \eta_2 e_2 + \eta_3 e_3} + \bar{D}_{\eta_1 e_1} v_{\ell - \eta_2 e_2 - \eta_3 e_3} &= 4\eta_1 \partial_1 y(m_{0,\eta_1,\ell}) + \mathcal{O}(\varepsilon^2), \\
\bar{D}_{\eta_2 e_2} v_{\ell} + \bar{D}_{\eta_2 e_2} v_{\ell + \eta_1 e_1 + \eta_3 e_3} + \bar{D}_{\eta_2 e_2} v_{\ell - \eta_2 e_2 - \eta_3 e_3} + \bar{D}_{\eta_2 e_2} v_{\ell - \eta_2 e_2 + \eta_1 e_1} &= 4\eta_2 \partial_2 y(m_{0,\eta_1,\ell}) + \mathcal{O}(\varepsilon^2), \\
\bar{D}_{\eta_3 e_3} v_{\ell + \eta_2 e_2} + \bar{D}_{\eta_3 e_3} v_{\ell + \eta_1 e_1} + \bar{D}_{\eta_3 e_3} v_{\ell - \eta_3 e_3} + \bar{D}_{\eta_3 e_3} v_{\ell - \eta_2 e_2 - \eta_3 e_3 + \eta_1 e_1} &= 4\eta_3 \partial_3 y(m_{0,\eta_1,\ell}) + \mathcal{O}(\varepsilon^2),
\end{aligned}$$

yields a second order approximation to $\frac{4}{6}\nabla_\zeta\phi_\eta(\nabla y(m_{0,\eta_1,\ell})\eta)$, upon employing similar arguments as in Lemma 3.1. The remaining $\frac{2}{6}$ factor is due to the $\frac{1}{6}$ -terms in $\bar{\Phi}_{\eta,\ell,1}$. In fact, we use the splittings

$$\begin{aligned} \bar{D}_\eta v_{\ell-k e_1-\eta_2 e_2} &= \frac{1}{2} \left\{ \bar{D}_{\eta_2 e_2} v_{\ell-k e_1-\eta_2 e_2} + \bar{D}_{\eta_3 e_3} v_{\ell-k e_1} + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1+\eta_3 e_3} \right. \\ &\quad \left. + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1-\eta_2 e_2} + \bar{D}_{\eta_3 e_3} v_{\ell-\eta_2 e_2} + \bar{D}_{\eta_2 e_2} v_{\ell-\eta_2 e_2+\eta_3 e_3} \right\} \end{aligned}$$

and

$$\begin{aligned} \bar{D}_\eta v_{\ell-k e_1-\eta_3 e_3} &= \frac{1}{2} \left\{ \bar{D}_{\eta_2 e_2} v_{\ell-k e_1-\eta_3 e_3} + \bar{D}_{\eta_3 e_3} v_{\ell-k e_1-\eta_3 e_3+\eta_2 e_2} + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1+\eta_2 e_2} \right. \\ &\quad \left. + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1-\eta_3 e_3} + \bar{D}_{\eta_3 e_3} v_{\ell-\eta_3 e_3} + \bar{D}_{\eta_2 e_2} v_{\ell-\eta_3 e_3+\eta_3 e_3} \right\}. \end{aligned}$$

As before,

$$\begin{aligned} \bar{D}_{\eta_1 e_1} v_{\ell-k e_1+\eta_3 e_3} + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1-\eta_2 e_2} + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1+\eta_2 e_2} + \bar{D}_{\eta_1 e_1} v_{\ell-k e_1-\eta_3 e_3} &= 4\eta_1 \partial_1 y(m_{0,\eta_1,\ell}) + \mathcal{O}(\varepsilon^2), \\ \bar{D}_{\eta_2 e_2} v_{\ell-k e_1-\eta_2 e_2} + \bar{D}_{\eta_2 e_2} v_{\ell-\eta_2 e_2+\eta_3 e_3} + \bar{D}_{\eta_2 e_2} v_{\ell-k e_1-\eta_3 e_3} + \bar{D}_{\eta_2 e_2} v_{\ell-\eta_3 e_3+\eta_3 e_3} &= 4\eta_2 \partial_2 y(m_{0,\eta_1,\ell}) + \mathcal{O}(\varepsilon^2), \\ \bar{D}_{\eta_3 e_3} v_{\ell-k e_1} + \bar{D}_{\eta_3 e_3} v_{\ell-\eta_2 e_2} + \bar{D}_{\eta_3 e_3} v_{\ell-k e_1-\eta_3 e_3+\eta_2 e_2} + \bar{D}_{\eta_3 e_3} v_{\ell-\eta_3 e_3} &= 4\eta_3 \partial_3 y(m_{0,\eta_1,\ell}) + \mathcal{O}(\varepsilon^2). \end{aligned}$$

We thus deduce that

$$|\bar{\Phi}_{\eta,\ell,1} - \Phi_{\eta,\ell,1}| \leq C(y) \varepsilon^2.$$

Finally, as in the case of two space dimensions, we have that

$$|\eta_1 \nabla_\zeta \phi_\eta(\nabla y(m_{1,\ell})\eta) - \Phi_{\eta,\ell,1}| \leq C(y) \varepsilon^2,$$

with $m_{1,\ell}$ signifying the midpoint of the side with endpoints $x_\ell, x_{\ell+e_1}$. By employing entirely similar arguments as in the case of two space dimensions, we then deduce that Theorem 4.1 holds in three space dimensions as well. Analogously, Theorem 4.2 is also valid in three dimensions.

6. REMARKS ON CONVERGENCE

We briefly discuss here how the consistency results presented in this paper, combined with appropriate *local stability* properties of the Cauchy–Born solution, can imply local convergence. In one space dimension these results are based on a simple application of the inverse function theorem, see [36], [31], [33], see also [24]. The stability in multiple space dimensions is very subtle (see, for example, [24]) and is beyond the scope of this paper. A key assumption in the inverse function theorem in the form presented in [12, Theorem 2.1] is that $G(w) = D\Phi^a(w)$ is differentiable with bounded inverse at a given point $w \in X$. Next, for the sake of simplicity of the presentation, we shall assume that in an appropriate discrete space X_ε , $D\Phi^a(y^{CB})$ evaluated on a sufficiently smooth solution y^{CB} of (1.6), whose existence is assumed, is differentiable with bounded inverse. Then, upon verifying two further assumptions on $D\Phi^a$ and y^{CB} one can apply the inverse function theorem to infer the local existence of a solution of the atomistic problem y^a in a ball with center y^{CB} . Hence, in addition, one obtains an estimate of the form

$$\|y^a - y^{CB}\|_{X_\varepsilon} \leq \gamma \|D\Phi^a(y^{CB}) - f\|_{Y_\varepsilon}.$$

Here γ depends on the norm of the inverse of the derivative of $D\Phi^a(y^{CB})$ and

$$\|D\Phi^a(y^{CB}) - f\|_{Y_\varepsilon} = \sup \left\{ \frac{|\langle D\Phi^a(y^{CB}) - f, v \rangle_\varepsilon|}{\|v\|_{X_\varepsilon}} : v \in X_\varepsilon \text{ with } \|v\|_{X_\varepsilon} \neq 0 \right\}.$$

Thus, to estimate the error we observe that

$$\begin{aligned} \langle D\Phi^a(y^{CB}), v \rangle_\varepsilon - \langle f, v \rangle_\varepsilon &= [\langle D\Phi^a(y^{CB}), v \rangle_\varepsilon - \langle D\Phi^{CB}(y^{CB}), v \rangle_\varepsilon] + [\langle f, v \rangle - \langle f, v \rangle_\varepsilon] \\ &=: I_1 + I_2. \end{aligned}$$

Let us also suppose that X_ε is a subspace of \mathbf{V}_ε equipped with $W^{1,p}(\Omega)$ norm. Then, the consistency result of Theorem 4.1 implies that

$$|I_1| \leq C(y^{CB}) \varepsilon^2 |v|_{W^{1,p}(\Omega)} \leq C(y^{CB}) \varepsilon^2 \|v\|_{X_\varepsilon}.$$

In addition,

$$\begin{aligned} I_2 &= \langle f, v \rangle - \langle f, v \rangle_\varepsilon = \int_\Omega (fv - Q_I(fv)) \, dx \\ &= \sum_{K \in \mathcal{T}} \int_K (fv - Q_I(fv)) \, dx, \end{aligned}$$

where Q_I denotes the standard nodal interpolation operator on \mathbf{V}_ε . Let us denote by ζ the functional

$$(6.1) \quad \zeta(w) = \frac{1}{|K|} \int_K \{w - Q_I(w)\} \, dx, \quad w \in C(\overline{K}),$$

and observe that $\zeta(\varphi) = 0$ for all $\varphi \in \mathbb{Q}_1(K)$. Lemma 2.1 and inequality (2.1) then yield that

$$(6.2) \quad |\zeta(w)| \leq C \varepsilon^2 \sum_{\alpha=1}^d \|\partial_\alpha^2 w\|_{L^\infty(K)}.$$

Further, since $v \in \mathbf{V}_\varepsilon$, we have that $\|\partial_\alpha^2(fv)\|_{L^\infty(K)} \leq 3\|f\|_{W^{2,\infty}(K)}\|v\|_{W^{1,\infty}(K)}$, and we deduce, using similar arguments as in the proof of Lemma 2.3, that

$$|I_2| \leq C\|f\|_{W^{2,\infty}(\Omega)} \varepsilon^2 |v|_{W^{1,p}(\Omega)} \leq C \varepsilon^2 \|v\|_{X_\varepsilon}.$$

We thus arrive at the error bound

$$\|y^a - y^{CB}\|_{X_\varepsilon} \leq C(y^{CB}, f) \varepsilon^2,$$

where $\|y^a - y^{CB}\|_{X_\varepsilon}$ is a discrete $W^{1,p}(\Omega)$ norm corresponding to $\|y^a - Q_I y^{CB}\|_{W^{1,p}(\Omega)}$.

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