

Limiting small strain problems with cracks

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MOTIVATION

- In contrast to the linearized model, even when the strains are "small", e.g. metallic alloys **response nonlinearly** [Rajagopal (2014)]
- The boundedness, respectively smallness, of strains is required a-priori, within **limiting strain model** ensured by suitable **nonlinear response function**
- Since strains are constrained, they are complained by **singular stresses** within measure spaces [Beck, Bulíček, Málek, Süli (2017), Bulíček, Málek, Rajagopal, Süli (2014)]
- For cracks, **contact conditions** are reasoned physically and mathematically [Khludnev, Kovtunenکو (2000)]
- While boundary tractions are problematic, **contact conditions** formulated in displacements are suitable for limiting strain within nonlinear elastic model [Itou, Kovtunenکو, Rajagopal (2017a, 2017b)]

OUTLINE

- ① Nonlinear response function
 - General mathematical properties
 - Generic response functions
- ② Governing equations and inequalities
 - Domain with crack
 - Non-penetration condition
 - Hierarchy of formulations
- ③ Well-posedness theorems
 - Elliptic regularization and penalization
 - Generalized variational formulation
 - Weak variational formulation
 - Anti-plane problem with non-penetration
- ④ Conclusion

NONLINEAR RESPONSE FUNCTION

For an **abstract response function** given by a nonlinear map:

$$\mathcal{F} : \text{Sym}(\mathbb{R}^{d \times d}) \mapsto \text{Sym}(\mathbb{R}^{d \times d}), \quad \mathcal{F}(0) = 0 \quad (1)$$

let constant $M_1, M_2, M_4 > 0$ and $M_3 \geq 0$ exist such that \mathcal{F} is

uniform bounded: $\|\mathcal{F}(\sigma)\| \leq M_1 \quad (2)$

monotone: $(\mathcal{F}(\sigma) - \mathcal{F}(\bar{\sigma})) : (\sigma - \bar{\sigma}) \geq 0 \quad (3)$

Lipschitz-continuous: $(\mathcal{F}(\sigma) - \mathcal{F}(\bar{\sigma})) : (\sigma - \bar{\sigma}) \leq M_2 \|\sigma - \bar{\sigma}\|^2 \quad (4)$

semi-coercive: $-M_3 + M_4 \sum_{i,j=1}^d |\sigma_{ij}| \leq \mathcal{F}(\sigma) : \sigma \quad (5)$

Response function-1

Let $\Psi_1 : \mathbb{R} \mapsto \mathbb{R}$, $\Psi_1(0) = 0$ and $\Psi_2 : \mathbb{R}_+ \mapsto \mathbb{R}$ be **continuous a.e. differentiable functions**, constants $a_1, a_2, b_1, b_2, b_4 > 0$ and $a_3, b_3 \geq 0$ exist such that

$$|\Psi_1(y)| \leq a_1, \quad 0 \leq \Psi_1'(y) \leq a_2, \quad -a_3 \leq y\Psi_1(y) \text{ a.e. } y \in \mathbb{R} \quad (6)$$

$$y|\Psi_2(y)| \leq b_1, \quad y|\Psi_2'(y)| + \Psi_2(y) \leq b_2, \quad -b_3 + b_4y \leq y^2\Psi_2(y) \text{ a.e. } y \in \mathbb{R}_+ \quad (7)$$

and the two cases allowing switching hold in subintervals of \mathbb{R}_+ :

$$\text{either } \Psi_2'(y) \geq 0, \Psi_2(y) \geq 0 \quad \text{or } \Psi_2'(y) < 0, (y\Psi_2(y))' \geq 0 \quad (8)$$

For the **nonlinear response function** \mathcal{F} defined by

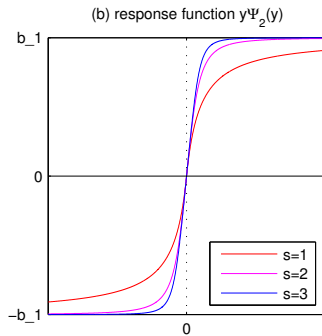
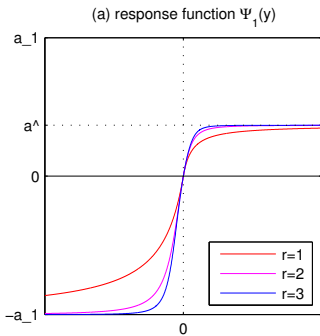
$$\mathcal{F}(\sigma) = \Psi_1(\text{tr}(\sigma))I + \Psi_2(\|\sigma\|)\sigma, \quad (9)$$

the **properties** (2) are true with

$$M_1 = a_1\sqrt{d} + b_1, \quad M_2 = a_2d + b_2, \quad M_3 = a_3 + b_3, \quad M_4 = \frac{b_4}{d} \quad (10)$$

Example response functions

$$\Psi_1(y) = \alpha \left\{ 1 - \exp\left(\frac{-\lambda y}{(1 + \gamma|y|^r)^{1/r}}\right) \right\}, \quad \Psi_2(y) = \frac{\beta}{(1 + \kappa y^s)^{1/s}} \quad (11)$$



$$a_1 = \alpha(e^{\frac{\lambda}{c_s \kappa^{1/r}} - 1}), \quad a_2 = \alpha \lambda e^{\frac{\lambda}{c_s \kappa^{1/r}}}, \quad a_3 = 0, \quad b_1 = \frac{\beta}{\kappa^{1/s}}, \quad b_2 = 2\beta, \quad b_3 = \frac{b_4}{\kappa^{1/s}},$$

$$b_4 = \frac{\beta}{c_s \kappa^{1/s}} \text{ where } c_s = 2^{1/s-1} \text{ for } s \in (0, 1) \text{ and } c_s = 1 \text{ for } s \geq 1$$

Response function-2

Let $\tilde{\Psi}_1$ and Ψ_2 satisfy (6)–(8), and constant $a_4 > 0$ exist such that

$$-a_3 + a_4|y| \leq y\tilde{\Psi}_1(y) \quad \text{a.e. } y \in \mathbb{R} \quad (12)$$

For the deviatoric stress tensor $\sigma^{\text{dev}} := \sigma - \frac{\text{tr}(\sigma)}{d}I$ such that $\text{tr}(\sigma^{\text{dev}}) = 0$ and the nonlinear response function $\tilde{\mathcal{F}}$ defined by

$$\tilde{\mathcal{F}}(\sigma) = \tilde{\Psi}_1(\text{tr}(\sigma))I + \Psi_2(\|\sigma^{\text{dev}}\|)\sigma^{\text{dev}} \quad (13)$$

- the properties (2) hold with M_1, M_2, M_3 given in (10) and $M_4 = \min\{a_4, \frac{b_4}{d}\}$

$$\text{For example, } \tilde{\Psi}_1(y) = \frac{\alpha y}{(1 + \gamma|y|^r)^{1/r}}, \quad \alpha, \gamma, r > 0 \quad (14)$$

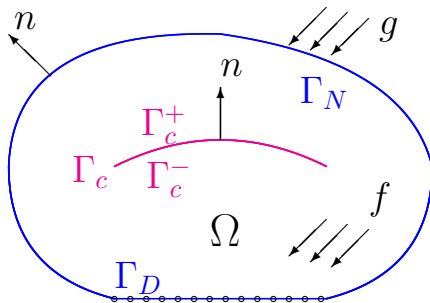
satisfies (6) and (12) with $a_1 = \frac{\alpha}{\gamma^{1/r}}$, $a_2 = \alpha$, $a_3 = \frac{a_4}{\gamma^{1/r}}$, $a_4 = \frac{\alpha}{c_r \gamma^{1/r}}$

- In the limit $\kappa \searrow 0^+$ in (11) and $\gamma \searrow 0^+$ in (14), from (13) we arrive at

$$\tilde{\mathcal{F}}(\sigma) = \alpha \text{tr}(\sigma)I + \beta \sigma^* = \left(\alpha - \frac{\beta}{d}\right) \text{tr}(\sigma)I + \beta \sigma,$$

which turns into the linearized elasticity in 3d when $\alpha = \frac{1-2\nu}{3E}$ and $\beta = \frac{1+\nu}{E}$

GOVERNING EQUATIONS

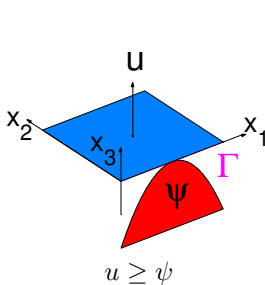


A reference domain $\Omega \subset \mathbb{R}^d$ with Lipschitz boundary $\partial\Omega$, consisted of the Dirichlet Γ_D and the Neumann Γ_N parts with the normal vector n , which contains crack $\Gamma_c \subset \Omega$ with opposite crack faces Γ_c^\pm

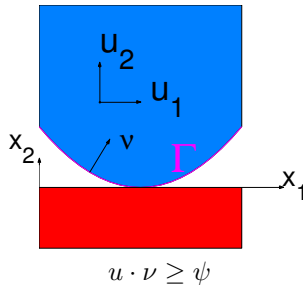
The domain with crack $\Omega_c := \Omega \setminus \bar{\Gamma}_c$ with boundary $\partial\Omega \cup \Gamma_c^+ \cup \Gamma_c^-$

Non-penetration condition

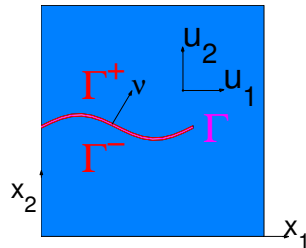
contacting obstacle:



Signorini's contact:



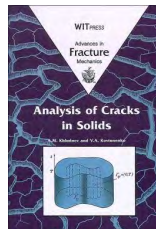
contacting crack faces:



Non-penetration condition for the jump:

$$[[u \cdot \nu]] := u|_{\Gamma^+} \cdot \nu - u|_{\Gamma^-} \cdot \nu \geq 0$$

[Khludnev, Kovtunenکو (2000)]



Boundary-value problem

Find:

vector of the displacement	$u(t, x) = (u_1, \dots, u_d)$
tensor of the Cauchy–Green strain	$\varepsilon(t, x) \in \text{Sym}(\mathbb{R}^{d \times d})$
tensor of the Cauchy stress	$\sigma(t, x) \in \text{Sym}(\mathbb{R}^{d \times d})$

satisfying the **boundary-value problem** in Ω_c :

$$\text{equilibrium equation:} \quad -\text{div} \sigma = f \quad (15)$$

$$\text{constitutive equation:} \quad \varepsilon(u) = \mathcal{F}(\sigma) \quad (16)$$

$$\text{linearized strain:} \quad \varepsilon_{ij}(u) := \frac{1}{2} \left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \quad (17)$$

for $i, j = 1, \dots, d$

Boundary and non-penetration conditions

under **boundary and non-penetration conditions**:

$$\text{Dirichlet boundary condition on } \Gamma_D: \quad u = 0 \quad (18)$$

$$\text{Neumann boundary condition on } \Gamma_N: \quad \sigma \cdot n = g \quad (19)$$

non-penetration conditions on the crack Γ_c :

$$\begin{aligned} \sigma \cdot n - ((\sigma \cdot n) \cdot n)n &= 0, \quad \llbracket (\sigma \cdot n) \cdot n \rrbracket = 0 \\ \llbracket u \cdot n \rrbracket \geq 0, \quad (\sigma \cdot n) \cdot n \leq 0, \quad ((\sigma \cdot n) \cdot n) \llbracket u \cdot n \rrbracket &= 0 \end{aligned} \quad (20a)$$

for the given **body force** $f(x) = (f_1, \dots, f_d)$

and the **boundary traction** $g(x) = (g_1, \dots, g_d)$

Hierarchy of formulations

Weak variational formulation

$$\llbracket u \cdot n \rrbracket \geq 0, \quad \int_{\Omega_c} \sigma : \varepsilon(\bar{u} - u) dx \geq \int_{\Omega_c} f \cdot (\bar{u} - u) dx + \int_{\Gamma_N} g \cdot (\bar{u} - u) dS_x$$

$$\mathcal{F}(\sigma) = \varepsilon(u)$$

Generalized variational formulation

$$\llbracket u \cdot n \rrbracket \geq 0, \quad \int_{\Omega_c} \sigma : \varepsilon(\bar{u}) dx \geq \int_{\Omega_c} f \cdot \bar{u} dx + \int_{\Gamma_N} g \cdot \bar{u} dS_x$$

$$\int_{\Omega} (\sigma - \bar{\sigma}) : \mathcal{F}(\bar{\sigma}) dx + \int_{\Omega_c} \varepsilon(u) : \bar{\sigma} dx \leq \int_{\Omega_c} f \cdot u dx + \int_{\Gamma_N} g \cdot u dS_x$$

Elliptic regularization and penalization

$$\int_{\Omega_c} (\delta \varepsilon(u^\delta) + \sigma^\delta) : \varepsilon(\bar{u}) dx + \frac{1}{\delta} \int_{\Gamma_c} \llbracket u^\delta \cdot n \rrbracket^- \llbracket \bar{u} \cdot n \rrbracket dS_x = \int_{\Omega_c} f \cdot \bar{u} dx + \int_{\Gamma_N} g \cdot \bar{u} dS_x$$

$$\delta \sigma^\delta + \mathcal{F}(\sigma^\delta) = \varepsilon(u^\delta)$$

WELL-POSEDNESS THEOREMS

In order to express the **right-hand side** $f \in L^2(\Omega_c; \mathbb{R}^d)$ and $g \in L^2(\Gamma_N; \mathbb{R}^d)$, an **auxiliary linearized elasticity problem**: Find

the **displacement** $u^E \in H^1(\Omega_c; \mathbb{R}^d)$ such that $u^E = 0$ on Γ_D ,
 the **strain** $\varepsilon(u^E) \in L^2(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$,
 and the **stress** $\sigma^E \in L^2(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$ such that

$$\int_{\Omega_c} \sigma^E : \varepsilon(\bar{u}) \, dx = \int_{\Omega_c} f \cdot \bar{u} \, dx + \int_{\Gamma_N} g \cdot \bar{u} \, dS_x \quad (21a)$$

$$\sigma^E = \varepsilon(u^E) \quad (21b)$$

for all test functions $\bar{u} \in H^1(\Omega_c; \mathbb{R}^d)$ such that $\bar{u} = 0$ on Γ_D

Elliptic regularization and penalization

For a small parameter $\delta > 0$, the **regularized and penalized problem**: Find the **displacement** $u^\delta \in H^1(\Omega_c; \mathbb{R}^d)$ such that $u^\delta = 0$ on Γ_D , the **strain** $\varepsilon(u^\delta) \in L^2(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$, and the **stress** $\sigma^\delta \in L^2(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$ such that

$$\int_{\Omega_c} (\delta \varepsilon(u^\delta) + \sigma^\delta - \sigma^E) : \varepsilon(\bar{u}) \, dx + \frac{1}{\delta} \int_{\Gamma_c} \llbracket u^\delta \cdot n \rrbracket^- \llbracket \bar{u} \cdot n \rrbracket \, dS_x = 0 \quad (22a)$$

$$\delta \sigma^\delta + \mathcal{F}(\sigma^\delta) = \varepsilon(u^\delta) \quad (22b)$$

for all test functions $\bar{u} \in H^1(\Omega_c; \mathbb{R}^d)$ such that $\bar{u} = 0$ at Γ_D

Well-posedness of regularized and penalized problem

Theorem (well-posedness of regularized and penalized problem)

For δ fixed, there exists the unique solution $(u^\delta, \varepsilon(u^\delta), \sigma^\delta)$ to the **regularized and penalized problem** (22) which satisfies *a-priori estimates* uniformly in $\delta \in (0, \delta_0)$:

$$\begin{aligned} & \delta c_{\text{KP}} \|u^\delta\|_{H^1(\Omega_c)}^2 + \frac{\delta}{2} \|\sigma^\delta\|_{L^2(\Omega_c)}^2 + M_4 \|\sigma^\delta\|_{L^1(\Omega_c)} + \frac{1}{\delta} \|[[u^\delta \cdot n]]^-\|_{L^2(\Gamma_c)}^2 \\ & \leq M_3 |\Omega_c| + \frac{\delta_0}{2} \|\sigma^E\|_{L^2(\Omega_c)}^2 + M_1 \|\sigma^E\|_{L^1(\Omega_c)} =: c_{\text{RHS}} \end{aligned} \quad (23a)$$

$$c_{\text{KP}} \|u^\delta\|_{H^1(\Omega_c)}^2 \leq \|\varepsilon(u^\delta)\|_{L^2(\Omega_c)}^2 \leq 2M_1^2 |\Omega_c| + 4\delta_0 c_{\text{RHS}} \quad (23b)$$

where the linearized elastic stress tensor σ^E is from (21), and constant $c_{\text{KP}} > 0$ from the **Korn–Poincaré inequality**:

$$c_{\text{KP}} \|u\|_{H^1(\Omega_c)}^2 \leq \int_{\Omega_c} \|\varepsilon(u)\|^2 dx \quad \text{for } u \in H^1(\Omega_c; \mathbb{R}^d) \text{ such that } u = 0 \text{ on } \Gamma_D$$

Generalized variational formulation

For the space of **bounded measures** $\mathcal{M}^1(\Omega_c)$ which is **dual** to the space $C_c(\Omega_c)$ of continuous functions with compact support in Ω_c , the **generalized variational formulation** of the problem:

Find the **displacement** $u \in H^1(\Omega_c; \mathbb{R}^d)$ such that $u = 0$ on Γ_D , the **strain** $\varepsilon(u) \in L^2(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$, and the **stress** $\sigma \in \mathcal{M}^1(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$ such that

$$\llbracket u \cdot n \rrbracket \geq 0 \quad \text{on } \Gamma_c \quad (24a)$$

$$\langle \sigma : \varepsilon(\bar{u}) \rangle_{\Omega_c} \geq \int_{\Omega_c} \sigma^E : \varepsilon(\bar{u}) \, dx \quad (24b)$$

$$\langle (\sigma - \bar{\sigma}) : \mathcal{F}(\bar{\sigma}) \rangle_{\Omega_c} + \int_{\Omega_c} \varepsilon(u) : \bar{\sigma} \, dx \leq \int_{\Omega_c} \sigma^E : \varepsilon(\bar{u}) \, dx \quad (24c)$$

for all test functions $\bar{u} \in H^1(\Omega_c; \mathbb{R}^d)$ such that $\llbracket \bar{u} \cdot n \rrbracket \geq 0$ on Γ_c , $\bar{u} = 0$ at Γ_D , and $\varepsilon(\bar{u}), \bar{\sigma} \in C_c(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$

Well-posedness of generalized formulation

Theorem (well-posedness of generalized formulation)

(i) As $\delta \searrow 0^+$, there exists an *accumulation point* $(u, \varepsilon(u), \sigma)$ of the solutions $(u^\delta, \varepsilon(u^\delta), \sigma^\delta)$ of the regularized and penalized problem (22) which solves the *generalized variational problem* (24).

(ii) If the *stress is regular* such that $\sigma \in L^p(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$ with $p \in (1, \infty)$, then

- the triple $(u, \varepsilon(u), \sigma)$ satisfies the *weak variational formulation* (26)
- the *strain* $\varepsilon(u) \in L^\infty(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$ due to (16) and (26c)
- the *a-priori estimate* holds

$$M_4 \|\sigma\|_{L^1(\Omega_c)} \leq M_3 |\Omega_c| + M_1 \|\sigma^E\|_{L^1(\Omega_c)} \quad (25)$$

- If *monotony* (3) is strict, then the *stress is unique*

Weak variational formulation

The **weak variational formulation** of the problem:

Find the **displacement** $u \in H^1(\Omega_c; \mathbb{R}^d)$ such that $u = 0$ on Γ_D ,
the **strain** $\varepsilon(u) \in L^\infty(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$,
and the **stress** $\sigma \in L^p(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$, $p > 1$, such that

$$[[u \cdot n]] \geq 0 \quad \text{on } \Gamma_c \quad (26a)$$

$$\int_{\Omega_c} (\sigma - \sigma^E) : \varepsilon(\bar{u} - u) \, dx \geq 0 \quad (26b)$$

$$\mathcal{F}(\sigma) = \varepsilon(u) \quad (26c)$$

for all test functions $\bar{u} \in H^1(\Omega_c; \mathbb{R}^d)$ such that $[[\bar{u} \cdot n]] \geq 0$ on Γ_c , $\bar{u} = 0$ at Γ_D ,
and $\varepsilon(\bar{u}) \in L^\infty(\Omega_c; \text{Sym}(\mathbb{R}^{d \times d}))$

Anti-plane problem with non-penetration

Under the **anti-plane strain assumption**:

$$u(x_1, x_2) = (0, 0, u_3), \quad \varepsilon(u) = \begin{bmatrix} 0 & 0 & \frac{u_{3,1}}{2} \\ 0 & 0 & \frac{u_{3,2}}{2} \\ \frac{u_{3,1}}{2} & \frac{u_{3,2}}{2} & 0 \end{bmatrix} \quad \sigma = \begin{bmatrix} 0 & 0 & \sigma_{13} \\ 0 & 0 & \sigma_{23} \\ \sigma_{13} & \sigma_{23} & 0 \end{bmatrix}$$

for the **inclined normal vector** to crack Γ_c : $n = \frac{1}{\sqrt{n_1^2 + n_2^2 + 1}}(n_1, n_2, 1)$

Find the **vertical displacement** $u_3 \in H^1(\Omega_c; \mathbb{R})$ such that $u_3 = 0$ on Γ_D ,
the **gradient** $\nabla u_3 \in L^\infty(\Omega_c; \mathbb{R}^2)$,

and the **stress pair** $(\sigma_{13}, \sigma_{23}) \in L^p(\Omega_c; \mathbb{R}^2)$, $p > 1$, such that

$$[[u_3]] \geq 0 \quad \text{on } \Gamma_c \quad (27a)$$

$$\frac{1}{2} \int_{\Omega_c} (\sigma_{13}, \sigma_{23}) \cdot \nabla(\bar{u} - u_3) dx \geq \int_{\Omega_c} f_3(\bar{u} - u_3) dx + \int_{\Gamma_N} g_3(\bar{u} - u_3) dS_x \quad (27b)$$

$$\frac{\beta}{[1 + \kappa(2\sigma_{13}^2 + 2\sigma_{23}^2)^{s/2}]^{1/s}} (\sigma_{13}, \sigma_{23}) = \frac{1}{2} \nabla u_3 \quad (\mathcal{F}(\sigma) = \Psi_2(\|\sigma\|)\sigma) \quad (27c)$$

for $\bar{u} \in H^1(\Omega_c; \mathbb{R})$ such that $[[\bar{u}]] \geq 0$ on Γ_c , $\bar{u} = 0$ at Γ_D , and $\nabla \bar{u} \in L^\infty(\Omega_c; \mathbb{R}^2)$

CONCLUSION

- Limiting strain models provide **regularity, boundedness, smallness of strain**
- **Stress** is defined by bounded measures
- **Cracks** are admissible within the modeling
- **Contact conditions** are suitable on the boundary/crack
- Elliptic regularization and penalization provide existence of **generalized solution** as an accumulation point
- If stress is smooth, then the generalized solution turns into **weak solution**
- We extend to **nonlinear viscoelastic model** for crack with stress-free faces [Itou, Kovtunenکو, Rajagopal (2017c)]

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