

# **A tree projection algorithm for wavelet-based sparse approximation**

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# Wavelet trees

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- Discontinuities propagate down branches of the tree
- $\Rightarrow$  **Why the DWT is so effective:** it provides sparse representations for piecewise smooth signals
- ...also, we expect it to be **tree-sparse:** the coefficients form a rooted subtree.

# Tree projection

- $z$  is  $k$ -**tree sparse** if it is supported on a rooted tree of cardinality  $k$ :

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- Let  $x \in \mathbb{R}^N$  and let  $\{x_i : i = 1, \dots, N\}$  correspond to nodes of a tree of order  $d$ .
- **Tree projection:** Find the  $k$ -tree sparse  $z$  which is closest in Euclidean distance to  $x$ :

$$\mathcal{P}_k(x) := \arg \min_{z \in \mathcal{T}_k} \|z - x\|_2.$$



# Applications of tree projections

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- Tree-based Compressed Sensing for wavelets.  
(Baraniuk et al.,2010)

# Existing algorithms for wavelets

- **Greedy tree approximation (GTA)**

Choose  $l < k$ , take the largest  $l$  coefficients, fill out to a rooted tree, repeat until the rooted tree is of size  $k$ .

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- **Condensing sort and select algorithm (CSSA)**

(Baraniuk/Jones,1994)

# Optimization formulation

- $\mathcal{P}_k$  preserves the value of selected coefficients.

$$\{\mathcal{P}_k(x)\}_i := \begin{cases} x_i & i \in \Gamma \\ 0 & i \notin \Gamma \end{cases} \quad \text{where } \Gamma := \text{supp} \{\mathcal{P}_k(x)\}.$$



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- $\Rightarrow$  equivalent to finding the rooted tree of size  $k$  whose coefficients have maximum energy.
- $\Rightarrow$  we can formulate as an Integer Program (IP).

# Optimization formulation/relaxations

$$\begin{aligned} \max_{\tau \in \mathbb{Z}^N} \sum_{i=1}^N x_i^2 \tau_i \quad \text{subject to} \quad & \tau \geq 0 \\ & \{\tau_i\} \text{ tree-nonincreasing} \\ & \sum \tau_i = k \\ & \tau_1 = 1. \end{aligned} \quad (\text{IP})$$

- $\{\mathcal{P}_k(x)\}_i = x_i \tau_i^*$ , where  $\tau^*$  solves (IP).

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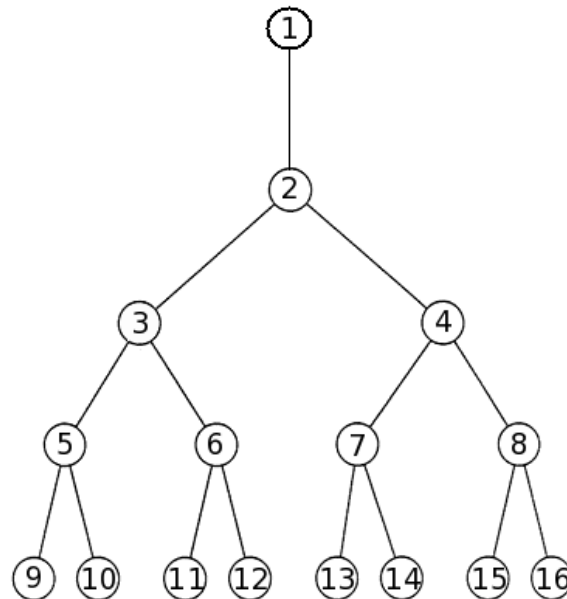
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- $\Rightarrow$  neither guaranteed to exactly find  $\mathcal{P}_k$ .

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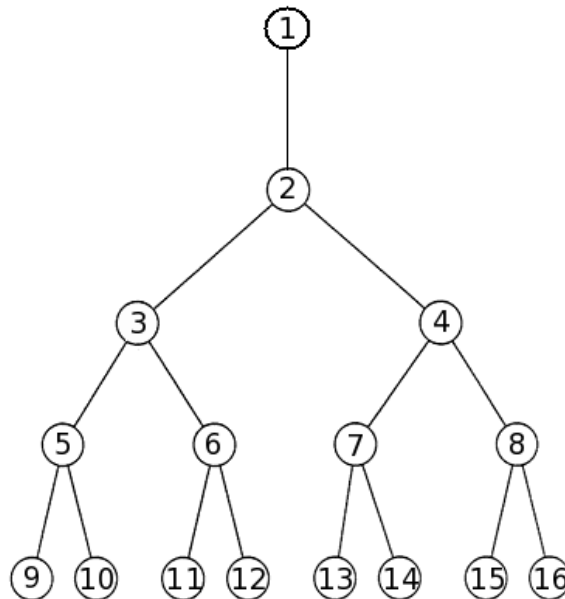
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- A similar algorithm was used for CART (Bohanec/Bratko, 1994).

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- ...and finally for the root node
- Trace back precedences to identify solution.

# Complexity of ETP

- **Theorem:** ETP requires at most  $(3d^2 Nk + N)$  additions/comparisons to calculate  $\mathcal{P}_k$ .  
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- **Comparison with approximate algorithms:** both CPSS and CSSA are  $\mathcal{O}(N \log N)$
- $\Rightarrow$  if  $\log N \ll k$ , ETP guarantees exact optimality at the expense of a worse order of complexity.

# An application of ETP

- **Compressed sensing:** Recover  $x \in \mathbb{R}^n$  from  $b = Ax \in \mathbb{R}^m$  where  $m < n$

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- **Gradient projection algorithm:**  
(Blumensath/Davies,2009;Baraniuk et al.,2010)

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**Recovery guarantee for  $A$  Gaussian:** (CC/AT,2013)

**Theorem:** Let

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$\Rightarrow \mathcal{P}_k$  must be exact for result to hold.

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- **Paper:** *An exact tree projection algorithm for wavelets*
- **Code:** both available at  
`www.math.duke.edu/~thompson`

# References

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