# CAT L4: Quantum Non-Locality and Contextuality 

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We give linear algebraic methods for computing these obstructions.
Direct path from sheaf theory to computing global sections using Mathematica ${ }^{T M}$ !

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Think e.g. of making observations at different nodes of a network.

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Can we tell from this observational history if there is interference/dependence between different parts of the system?

## The Quantum Case: Spin Measurements

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Note the appearance of quantization here: there are not a continuum of possible outcomes for each measurement, but only two!

## The Stern-Gerlach Experiment



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EPR state:


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Bell's theorem: QM is essentially non-local.

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This is exactly a form of conditional independence assumption.
Is is, famously, not satisfied by QM (Bell's theorem).

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Quantum mechanics denies this.
Moreover, as we shall see, there are probability tables for which, as a mathematical fact, there is no consistent extension to a joint distribution on outcomes; so we must consider certain combinations of measurements as not jointly performable in principle, under any physical theory whatever.

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Each row of the table specifies a probability distribution on events $O^{C}$ for a given choice of measurements $C$.

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(ii) We could vary $R$.

## Empirical Models: Reconstructing Probability Tables

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Thus each $e_{C}$ is a probability distribution on the row indexed by $C$; it specifies a probability for the events corresponding to the observation of an outcome for each measurement in $C$.

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We shall consider models $\left\{e_{C} \mid C \in \mathcal{M}\right\}$ which are compatible in the sense of agreeing on overlaps: for all $C, C^{\prime} \in \mathcal{M}$,

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E.g. in the bipartite case, consider $C=\left\{m_{a}, m_{b}\right\}, C^{\prime}=\left\{m_{a}, m_{b}^{\prime}\right\}$. Fix $s_{0} \in \mathcal{E}\left(\left\{m_{a}\right\}\right)$. Compatibility implies

$$
\sum_{s \in \mathcal{E}(C), s \mid m_{\mathrm{a}}=s_{0}} e_{C}(s)=\sum_{s^{\prime} \in \mathcal{E}\left(C^{\prime}\right), s^{\prime} \mid m_{\mathrm{a}}=s_{0}} e_{C^{\prime}}\left(s^{\prime}\right) .
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E.g. in the bipartite case, consider $C=\left\{m_{a}, m_{b}\right\}, C^{\prime}=\left\{m_{a}, m_{b}^{\prime}\right\}$. Fix $s_{0} \in \mathcal{E}\left(\left\{m_{a}\right\}\right)$. Compatibility implies

$$
\sum_{s \in \mathcal{E}(C), s \mid m_{\mathrm{a}}=s_{0}} e_{C}(s)=\sum_{s^{\prime} \in \mathcal{E}\left(C^{\prime}\right), s^{\prime} \mid m_{\mathrm{a}}=s_{0}} e_{C^{\prime}}\left(s^{\prime}\right) .
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This says that the probability for Alice to get the outcome $s_{0}\left(m_{a}\right)$ is the same, whether we marginalize over the possible outcomes for Bob with measurement $m_{b}$, or with $m_{b}^{\prime}$.

## Compatibility And No-Signalling

We shall consider models $\left\{e_{C} \mid C \in \mathcal{M}\right\}$ which are compatible in the sense of agreeing on overlaps: for all $C, C^{\prime} \in \mathcal{M}$,

$$
e_{C}\left|C \cap C^{\prime}=e_{C^{\prime}}\right| C \cap C^{\prime} .
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This says that the probability for Alice to get the outcome $s_{0}\left(m_{a}\right)$ is the same, whether we marginalize over the possible outcomes for Bob with measurement $m_{b}$, or with $m_{b}^{\prime}$.

In other words, Bob's choice of measurement cannot influence Alice's outcome.

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Thus it can be seen as a deterministic hidden variable.
If $d$ is a global section for the model $\left\{e_{C}\right\}$, we recover the predictions of the model by averaging over the values of these hidden variables:

$$
e_{C}(s)=d \mid C(s)=\sum_{s^{\prime} \in \mathcal{E}(X), s^{\prime} \mid C=s} d\left(s^{\prime}\right)=\sum_{s^{\prime} \in \mathcal{E}(X)} \delta_{s^{\prime} \mid C(s)} \cdot d\left(s^{\prime}\right) .
$$

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The general result is as follows:

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Any factorizable (i.e. local) hidden-variable model defines a global section.

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existence of a local hidden-variable model for a given empirical model IFF
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Any factorizable (i.e. local) hidden-variable model defines a global section.

Hence:
No such h.v. model exists (the empirical model is non-local/contextual) IFF there is an obstruction to the existence of a global section

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Incidence matrix for $(2,2,2)$ is $16 \times 16$.

## The $(2,2,2)$ Incidence Matrix

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$$
\left[\begin{array}{llllllllllllllll}
1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\
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0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & 0 & 1 & 0 & 1 & 0 \\
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This matrix has rank 9 .

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Hence solutions correspond exactly to global sections - which as we have seen, correspond exactly to local hidden-variable realizations!

## The Bell Model

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|  | $(0,0)$ | $(1,0)$ | $(0,1)$ | $(1,1)$ |
| :--- | :---: | :---: | :---: | :---: |
| $(a, b)$ | 0 | $1 / 2$ | $1 / 2$ | 0 |
| $\left(a^{\prime}, b\right)$ | $3 / 8$ | $1 / 8$ | $1 / 8$ | $3 / 8$ |
| $\left(a, b^{\prime}\right)$ | $3 / 8$ | $1 / 8$ | $1 / 8$ | $3 / 8$ |
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Solutions in the non-negative reals: this corresponds to solving the linear system over $\mathbb{R}$, subject to the constraint that $\mathbf{X} \geq \mathbf{0}$ (linear programming problem).

## Bell's Theorem

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Proof We focus on 4 out of the 16 equations, corresponding to rows 3, 7, 11 and 14 of the incidence matrix. We write $X_{i}$ rather than $\mathbf{X}[i]$.

$$
\begin{aligned}
& x_{9}+X_{10}+X_{11}+X_{12}=1 / 2 \\
& x_{9}+X_{11}+x_{13}+X_{15}=1 / 8 \\
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Since all these numbers must be non-negative, the left-hand side of this equation must be greater than or equal to the left-hand side of the first equation, yielding the required contradiction.

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We consider the possibilistic version of the Hardy model, specified by the following table.

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Now we are interested in solutions over the boolean semiring, i.e. a boolean satisfiability problem. E.g. the equation specified by the first row of the incidence matrix gives the clause

$$
X_{1} \vee X_{2} \vee X_{3} \vee X_{4}
$$

while the fifth yields the formula

$$
\neg X_{1} \wedge \neg X_{3} \wedge \neg X_{5} \wedge \neg X_{7} .
$$

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\neg X_{1} & \wedge & \neg X_{2} & \wedge & \neg X_{9} & \wedge & \neg X_{10} \\
\neg X_{4} & \wedge & \neg X_{8} & \wedge & \neg X_{12} & \wedge & \neg X_{16}
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\neg X_{1} & \wedge & \neg X_{3} & \wedge & \neg X_{5} & \wedge & \neg X_{7} \\
\neg X_{1} & \wedge & \neg X_{2} & \wedge & \neg X_{9} & \wedge & \neg X_{10} \\
\neg X_{4} & \wedge & \neg X_{8} & \wedge & \neg X_{12} & \wedge & \neg X_{16}
\end{array}
$$

Since every disjunct in the first formula appears as a negated conjunct in one of the other three formulas, there is no satisfying assignment.

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Conclusion: Bell < Hardy.

## Quantum Realizations of Probability Models

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To compute the tensor product of vectors:

$$
\sum_{i} a_{i}|i\rangle \otimes \sum_{j} b_{j}|j\rangle=\sum_{i, j} a_{i} b_{j}|i j\rangle .
$$

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The possibilistic collapse of this model is thus a Hardy model.

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Thus negative probabilities characterize the no-signalling rather than the quantum realm.

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D:=\sum_{U \in \mathcal{U}}(I-1)^{|U|}
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As a special case, we derive a formula for the dimension for Bell-type ( $n, k, l$ )-scenarios:

$$
D=(k \cdot(I-1)+1)^{n} .
$$

## Reasons

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In the case of ( $n, 2,2$, ) systems, this result can be visualized in terms of elegant self-similarity properties of the inductively defined incidence matrices $\mathbf{M}(n)$ :

$$
\mathbf{M}(1)=\left[\begin{array}{cccc}
1 & 1 & 0 & 0 \\
0 & 0 & 1 & 1 \\
1 & 0 & 1 & 0 \\
0 & 1 & 0 & 1
\end{array}\right] \quad \mathbf{M}(n+1)=\left[\begin{array}{cccc}
\mathbf{M}(n) & \mathbf{M}(n) & 0 & 0 \\
0 & 0 & \mathbf{M}(n) & \mathbf{M}(n) \\
\mathbf{M}(n) & 0 & \mathbf{M}(n) & 0 \\
0 & \mathbf{M}(n) & 0 & \mathbf{M}(n)
\end{array}\right]
$$

and of the probability vectors $\mathbf{V}$ corresponding to no-signalling models, from which it follows that

$$
\operatorname{rank}(\mathbf{M}(n))=\operatorname{rank}([\mathbf{M}(n) \mid \mathbf{V}])=3^{n} .
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 The 'Popescu-Rohrlich box':|  | $(0,0)$ | $(1,0)$ | $(0,1)$ | $(1,1)$ |
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| $(a, b)$ | $1 / 2$ | 0 | 0 | $1 / 2$ |
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Example solution:

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This vector can be taken as giving a local hidden-variable realization of the PR box using negative probabilities. Similar explicit realizations can be given for the other PR boxes.

## Strong Contextuality

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Note that this is a very weak requirement: just that some assignment is possible. The negative result is correspondingly very strong.

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We shall now show that the well-known GHZ models, of type $(n, 2,2)$ for all $n>2$, are strongly contextual. This will establish a strict hierarchy

$$
\text { Bell < Hardy }<\mathrm{GHZ}
$$

of increasing strengths of obstructions to non-contextual behaviour for these salient models.

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Note that $X$ and $Y$ do not commute; hence according to quantum mechanics, they are incompatible; they cannot be measured together.

## GHZ States

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If we measure each particle with a choice of $X$ or $Y$ observable, the probability for each outcome is given by the inner product

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This computation is controlled by the product of the $|\downarrow\rangle$-coefficients of the basis vectors: cyclic group generated by $i \cong \mathbb{Z}_{4}$.


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The GHZ model of type ( $n, 2,2$ ) can be specified as follows. We label the two measurements at each part as $X^{(i)}$ and $Y^{(i)}$, and the outcomes as 0 and 1 .

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NB: a model with these properties can be realized in quantum mechanics.

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Thus for any $Y^{(i)}, Y^{(j)}$ assigned the same value, if we substitute $X^{\prime}$ 's in those positions they must receive different values. Similarly, for any $Y^{(i)}, Y^{(j)}$ assigned different values, the corresponding $X^{(i)}, X^{(j)}$ must receive the same value.

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Suppose not all $Y^{(i)}$ are assigned the same value. Then for some $\mathrm{i}, \mathrm{j}, \mathrm{k}, Y^{(i)}$ is assigned the same value as $Y^{(j)}$, and $Y^{(j)}$ is assigned a different value to $Y^{(k)}$. Thus $Y^{(i)}$ is also assigned a different value to $Y^{(k)}$. Then $X^{(i)}$ is assigned the same value as $X^{(k)}$, and $X^{(j)}$ is assigned the same value as $X^{(k)}$. By transitivity, $X^{(i)}$ is assigned the same value as $X^{(j)}$, yielding a contradiction.

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The remaining cases are where all Y's receive the same value. Then any pair of X's must receive different values. But taking any 3 X's, this yields a contradiction, since there are only two values, so some pair must receive the same value.

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S. Abramsky and A. Brandenburger, The Sheaf-Theoretic Structure of Non-Locality and Contextuality. Available at arXiv:1102.0264.

