# Computing f(A) and in particular $e^{A}$

### **1. Why do we want** f(A)?

For all sorts of reasons. That said, it's rare to need exotic functions like  $\Gamma(A)$  or  $\zeta(A)$  or Ai(A). More often we want  $e^A$ , log(A),  $A^{1/2}$ . Also sign(A) and other projectors.

One reason f tends to be simple is that it often comes from differential equations or operators.

- Most fundamental example:  $\frac{du}{dt} = Au$  has solution  $u(t) = e^{tA}u(0)$ . Exponential integrators: high-order solns via "phi functions," e.g.  $\varphi_2(A) = A^{-2}(e^A I A)$ .
- Anomalous diffusion example:  $\partial_t u = \Delta^{1/2} u$  can be approximated via  $A^{1/2}$  with  $A \approx \Delta$ .
- More anomalous diffusion:  $(\partial_t)^{1/2} u = \Delta u$  leads to the Mittag-Leffler function of a matrix A.

# 2. How do we define f(A)?

I. Diagonalization / Jordan decomposition

If A is diagonal, f(A) has the obvious elementwise definition.

If A is diagonalizable with  $A = SDS^{-1}$ , we define  $f(A) = Sf(D)S^{-1}$ .

If A is nondiagonalizable with  $k \times k$  Jordan block at eigenvalue  $\lambda$ , this definition generalizes using  $f(\lambda), f'(\lambda), \dots, f^{(k-1)}(\lambda)$ .

# II. Polynomial interpolation

If A is diagonalizable, f(A) = p(A), where p interpolates f at the eigenvalues.

If A is nondiagonalizable, p becomes Hermite interpolant involving  $f(\lambda), f'(\lambda), \dots, f^{(k-1)}(\lambda)$ .

#### III. Contour integral

The Cauchy integral for scalar analytic functions is  $f(a) = \frac{1}{2\pi i} \int_{\Gamma} \frac{f(z)}{z-a} dz$ . For matrices,  $f(A) = \frac{1}{2\pi i} \int_{\Gamma} (zI - A)^{-1} f(z) dz$ .

 $\Gamma$  must lie in the region of analyticity of f and enclose the spectrum of A. For projectors such as (sign(A) + I)/2,  $\Gamma$  may enclose just certain parts of the spectrum.

#### 3. How do we compute f(A)?

I. Schur-Parlett algorithm

Compute Schur form,  $A = UT U^*$  with U unitary and T triangular.

With considerable clever engineering, one can then compute

 $f(A) = Uf(T)U^*$ . Worst case  $O(n^4)$  work.  $\rightarrow$  MATLAB funm(A).

II. Polynomial and rational approximation

Approximate f(z) by p(z) or r(z) = p(z)/q(z) for z in nbhd of spectrum of A.

Often r is a composite of simpler rational functions. Then use  $f(A) \approx p(A)$  or r(A).  $\rightarrow$  MATLAB expm(A), based on type (13,13) Padé approx  $e^z \approx r(z)$ .

III. Discretized contour integrals

Discretize  $f(A) = \frac{1}{2\pi i} \int_{\Gamma} (zI - A)^{-1} f(z) dz$  by e.g. *m*-point trapezoidal rule over a circle.

Geometric convergence as  $m \to \infty$ , independent of dimension of A.

This reduces f(A)b to m linear systems  $(z_iI - A)w_i = b$ .

Transformation by a conformal map may speed this up dramatically.

#### 4. What's special for $e^A$ ?

One can use ODE methods to compute  $e^{tA}$ . But more often it's the other way around. Moler & Van Loan, SIREV 2003 expm(A) uses "scaling-and-squaring":  $e^{A} = (e^{A/2^{s}})^{2^{s}}$ . So it's a composite of Padé approximations. Contour integrals:  $e^A = \frac{1}{2\pi i} \int_{\Gamma} (zI - A)^{-1} e^z dz$  is the inverse Laplace transform. Expert: J. A. C. Weideman

Quadrature formulas all implicitly involve rational approximations.

So contour integral and rational approximation methods for f(A) are very close.

For  $f(A) = e^A$  this is particularly well studied.





Davies & Higham, SIMAX 2003

Hale-Higham-T., SINUM 2008

Higham, SIREV 2009