

# On fronts in a vanishing viscosity limit

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Swansea

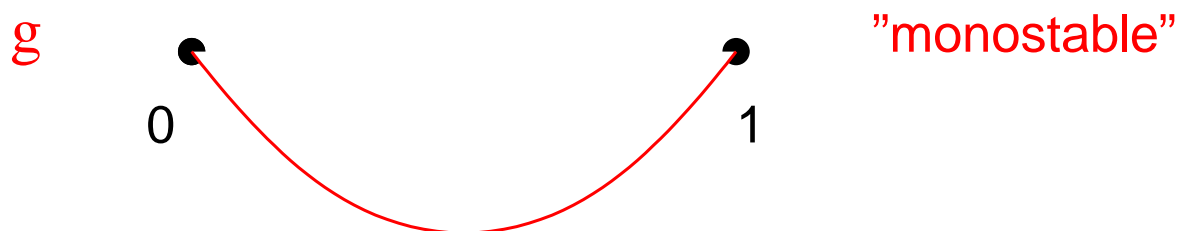
Joint work with Corrado Mascia, Rome.

Consider **hyperbolic** and **parabolic** equations

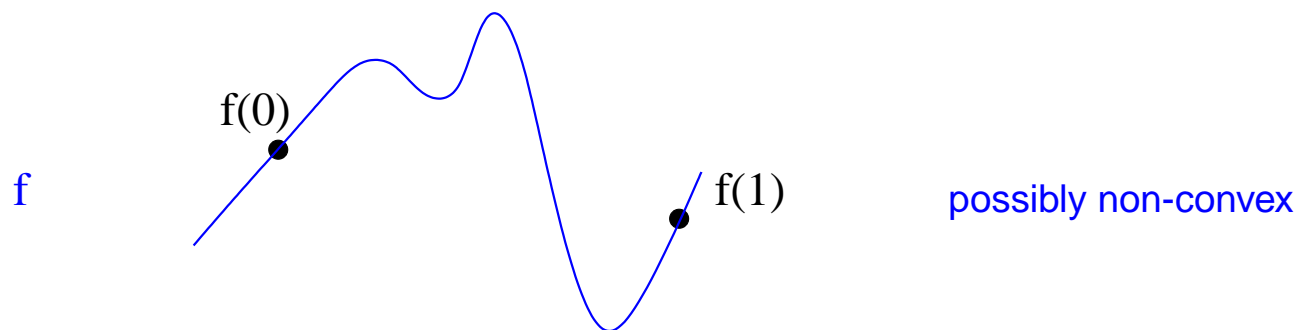
$$\left. \begin{array}{l} (H) \quad u_t + f(u)_x = g(u) \\ (P) \quad u_t + f(u)_x = \epsilon u_{xx} + g(u) \end{array} \right\} (x, t) \in \mathbb{R} \times [0, \infty), u(x, t) \in \mathbb{R};$$

where

- the **reaction** term **g** is smooth,  $g(0) = g(1) = 0$  and  $g(s) < 0$  for  $s \in (0, 1)$ ;



- the **flux** term **f** is smooth and has a finite number of points of inflection in  $(0, 1)$ ;



Interested in **monotone travelling-wave solutions** (“fronts”)

$$u(x, t) = \phi(x - ct)$$

- $\phi$  is increasing, and  $\phi(x) \rightarrow 0, 1$  (**equilibria of  $g$** ) as  $x \rightarrow -\infty, +\infty$
- possibly weak/entropy solutions

## Question

Given a travelling-front  $\phi$  of the **hyperbolic** equation of speed  $c$ , does there exist a family of travelling fronts  $\phi_\epsilon$  of the **parabolic** equation with speeds  $c_\epsilon$  such that as  $\epsilon \rightarrow 0$ ,

$$c_\epsilon \rightarrow c$$

and the profiles  $\phi_\epsilon$  converge in some sense?

# Background

- For the **hyperbolic** equation  $u_t + f(u)_x = g(u)$ , study is easier when

$f$  is convex

$$f'' > 0 \Rightarrow f'(u) \text{ is increasing in } u$$

$\Rightarrow$  ordering property on propagation speeds of characteristics

$$\frac{dx}{dt} = f'(u(x, t)), \quad \frac{du}{dt} = g(u).$$

- Existing work on the relation between **travelling fronts** for the hyperbolic and parabolic equations when  $f$  is convex

**J. Härterich (2000, 2003)** geometrical singular perturbation theory

$$c_\epsilon \rightarrow c, \quad \|\phi_\epsilon - \phi\|_{L^1} \rightarrow 0$$

- If flux  $f$  is not convex, then

- new ideas are needed to analyse the hyperbolic equation
- qualitatively different behaviour can arise

*e.g.* discontinuities may disappear in finite time

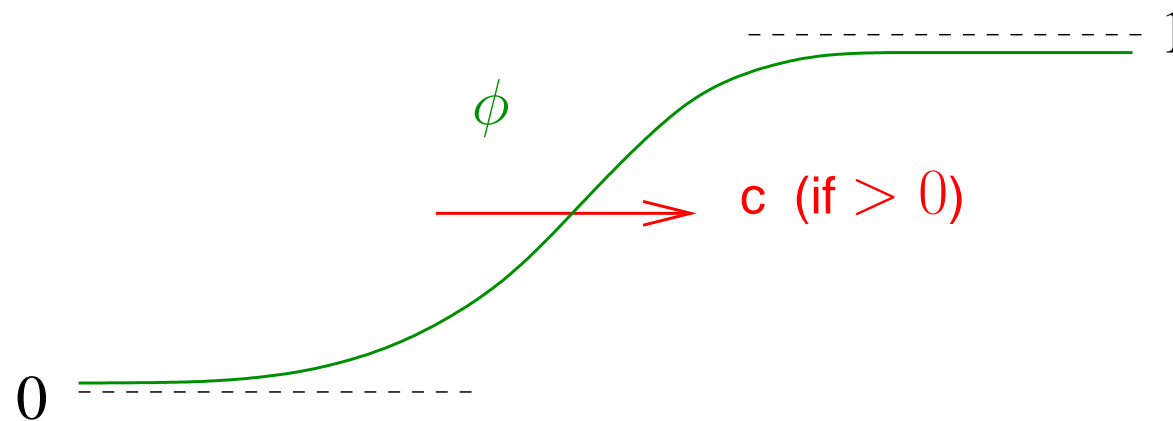
Sinestrari SIAM J. Math. Anal 1997, Mascia Comm. PDE 1998

- The parabolic equation  $u_t + f(u)_x = \epsilon u_{xx} + g(u)$  “does not care” whether or not  $f$  is convex

# Travelling Fronts

$$u(x, t) = \phi(x - ct)$$

- the profile  $\phi$  is non-decreasing and  $\phi(x) \rightarrow 0, 1$  as  $x \rightarrow -\infty, +\infty$
- for the **parabolic** problem  $u_t + f(u)_x = \epsilon u_{xx} + g(u)$ 
  - $\phi \in C^2(\mathbb{R})$
  - $(f'(\phi) - c)\phi' = \epsilon\phi'' + g(\phi)$



- in fact,  $\phi' > 0$  and  $\phi$  is strictly increasing

- for the **hyperbolic** problem  $u_t + f(u)_x = g(u)$

$u(x, t) = \phi(x - ct)$  is an entropy solution, in the sense that

- $u \in L^\infty(\mathbb{R} \times [0, \infty))$
- for all non-negative  $\psi \in C_0^\infty(\mathbb{R} \times [0, \infty))$  and all  $k \in \mathbb{R}$ ,

$$\int_{\mathbb{R} \times [0, \infty)} \left[ |u - k| \frac{\partial \psi}{\partial t} + \operatorname{sgn}(u - k)(f(u) - f(k)) \frac{\partial \psi}{\partial x} + \operatorname{sgn}(u - k)g(u)\psi \right] dxdt \geq 0.$$

- for the **hyperbolic** problem  $u_t + f(u)_x = g(u)$

$u(x, t) = \phi(x - ct)$  is an entropy solution, in the sense that

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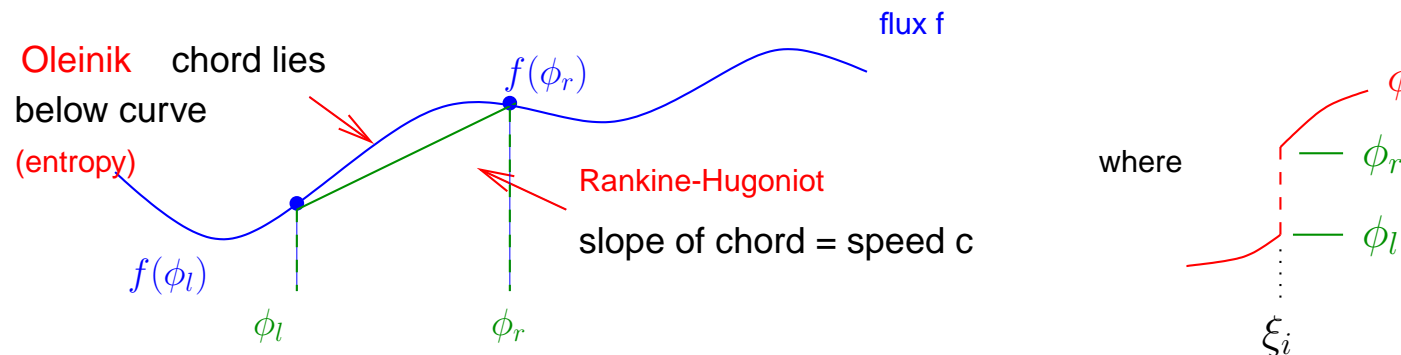
$$\int_{\mathbb{R} \times [0, \infty)} \left[ |u - k| \frac{\partial \psi}{\partial t} + \text{sgn}(u - k)(f(u) - f(k)) \frac{\partial \psi}{\partial x} + \text{sgn}(u - k)g(u)\psi \right] dxdt \geq 0.$$

- here, this is equivalent to

- $\phi \in C^1(\mathbb{R} \setminus \{\xi_1, \dots, \xi_N\})$  satisfies

$$(f'(\phi) - c)\phi = g(\phi) \quad \text{for } \xi \neq \xi_i$$

- **Oleinik** and **Rankine-Hugoniot** jump conditions hold at each  $\xi = \xi_i$



# Existence Theorems for Travelling Fronts

Hyperbolic Case (Mascia 1999)  $u_t + f(u)_x = g(u)$

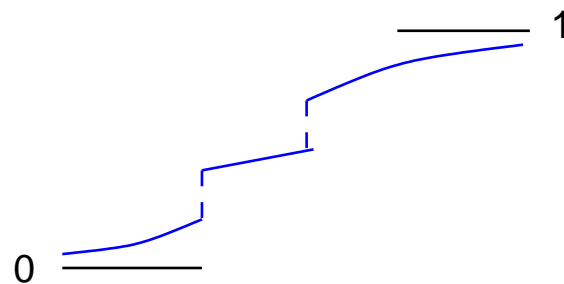
- There exists an entropy travelling-front solution of the **hyperbolic** equation of speed  $c$  if and only if

$$c \geq \sup_{s \in (0,1)} \frac{f(1) - f(s)}{1 - s} =: c^*$$

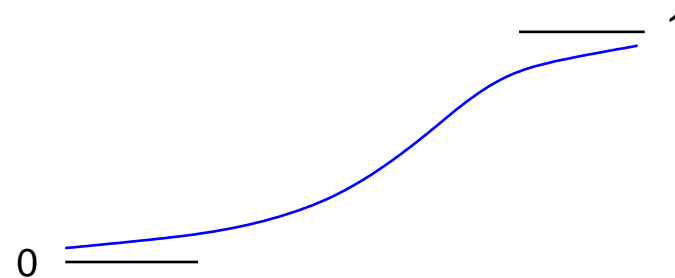
- Fronts of speed

$$c > \sup_{s \in (0,1)} f'(s) \quad (\geq c^*)$$

are smooth.



General Fronts



Fronts for  $c$  sufficiently large

- Given  $c \geq c^*$ , there is a **unique** (up to translation) front of speed  $c$

# Idea of Proof

- $c > \sup_{s \in (0,1)} f'(s)$  (smooth fronts)

– choose  $\phi(0) \in (0, 1)$  - there exists a smooth increasing solution of

$$\phi'(\xi) = \frac{g(\phi(\xi))}{f'(\phi(\xi)) - c}$$

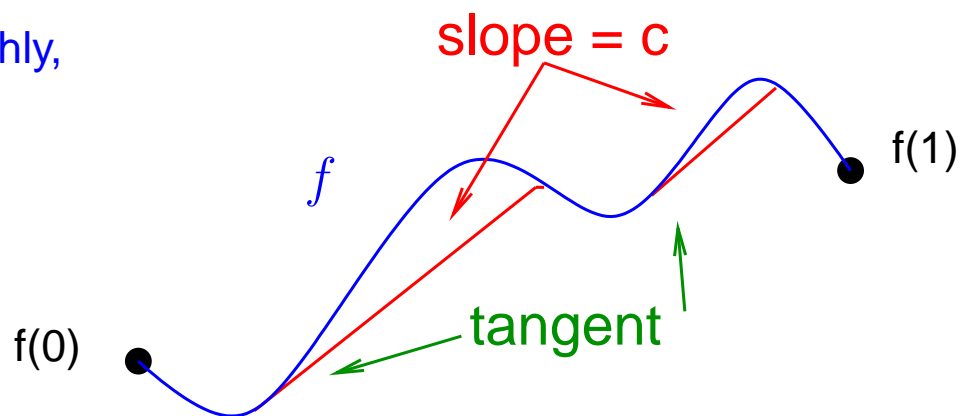
negative  
negative and bounded above

locally *ie* for  $\xi \in (-\delta, \delta)$

– can continue to  $(-\infty, \infty)$

- $c^* = \sup_{s \in [0,1)} \frac{f(1) - f(s)}{1 - s} \leq c \leq \sup_{s \in (0,1)} f'(s)$

Very roughly,



jump below flux curve  
with slope  $c$

Parabolic Case (KPP37, Hadeler and Rothe 75, Volperts 90s, C 03, etc .....

$$u_t + f(u)_x = \epsilon u_{xx} + g(u)$$

- For each  $\epsilon > 0$ , there exists a travelling front solution of the **parabolic** equation of speed  $c$  if and only if

$$c \geq c_\epsilon^*$$

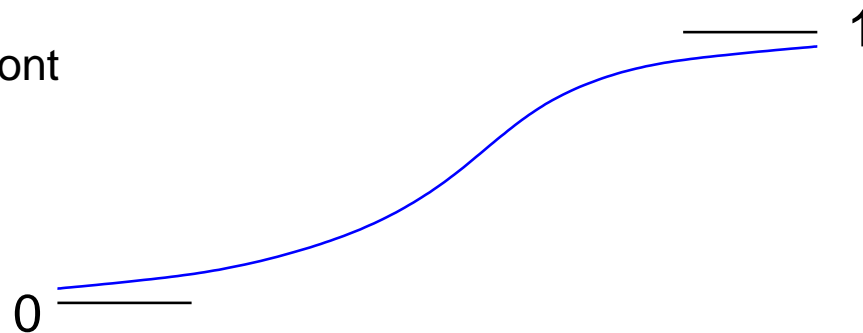
- where

$$c_\epsilon^* = \inf_{\rho \in \mathcal{K}} \sup_{\xi \in \mathbb{R}} \frac{\epsilon \rho''(\xi) + g(\rho(\xi))}{-\rho'(\xi)} + f'(\rho(\xi))$$

and

$$\mathcal{K} = \{\rho \in C^2(\mathbb{R}) : \rho' > 0 \text{ and } \rho(\xi) \rightarrow 0, 1 \text{ as } \xi \rightarrow -, +\infty\}.$$

Illustration of front



- Given  $c \geq c_\epsilon^*$ , there is a **unique** (up to translation) front of speed  $c$

# Theorem 1

## (i) Properties of minimal speed

- $c_\epsilon^* \geq c^*$  for each  $\epsilon \geq 0$

( $\Rightarrow$  viscous approximation overestimates front speeds)

- $c_{\epsilon_1}^* \leq c_{\epsilon_2}^*$  if  $\epsilon_1 \leq \epsilon_2$

- $c_\epsilon^* \downarrow c^*$  as  $\epsilon \downarrow 0$

## (ii) Convergence of minimal-speed front profiles

let  $\phi_\epsilon, \phi$  denote the profiles of front solutions of  $(P)$ ,  $(H)$  with speeds  $c_\epsilon^*, c^*$  and  $\phi_\epsilon(0) = \phi(0) = 1/2$ . Then as  $\epsilon \rightarrow 0$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } L^1(\mathbb{R})$$

## Theorem 2 (proved by similar methods)

- General convergence of profiles

-suppose  $c \geq c^*$  and  $c_\epsilon \rightarrow c$

-let  $\phi_\epsilon, \phi$  denote the profiles of front solutions of  $(P), (H)$  with speeds  $c_\epsilon, c$  and  $\phi_\epsilon(0) = \phi(0) = 1/2$ . Then as  $\epsilon \rightarrow 0$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } L^1(\mathbb{R})$$

- Convergence of front profiles of a fixed speed  $c$

- suppose

(i)  $c > c^*$

(ii)  $\epsilon_0 > 0$  be such that  $c_\epsilon < c$  for  $\epsilon \in (0, \epsilon_0)$

- let  $\phi_\epsilon, \phi$  denote the profiles of the front solutions of  $(P), (H)$  with speed  $c$  and  $\phi_\epsilon(0) = \phi(0) = 1/2$ . Then as  $\epsilon \rightarrow 0$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } L^1(\mathbb{R})$$

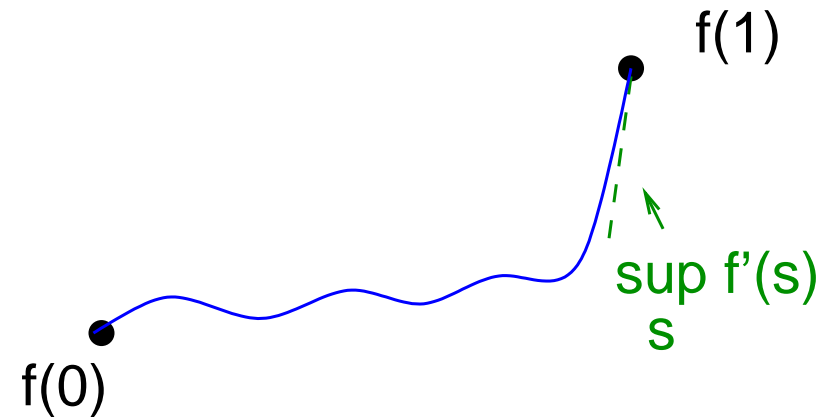
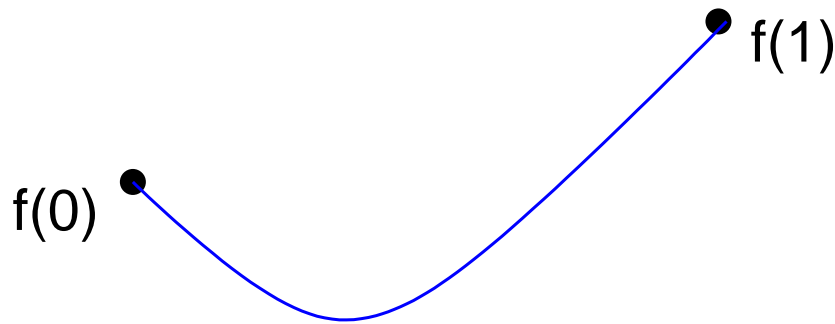
# Ideas in proof of convergence of minimal speed

## 1. Easy Case

$$\sup_{s \in [0,1]} f'(s) = f'(1)$$

e.g.  $f$  is convex

or



● **Note:** in general

$$f'(1) = \lim_{s \rightarrow 1} \frac{f(s) - f(0)}{s - 0} \leq c^* = \sup_{s \in [0,1)} \frac{f(s) - f(1)}{s - 1} \leq \sup_{s \in [0,1]} f'(s)$$

● in **easy case**, have = throughout

● so  $c^* = \sup_{s \in (0,1)} f'(s) \Rightarrow$  **hyperbolic** fronts are **smooth** for  $c > c^*$

## Easy Case

**Step 1:**  $\limsup_{\epsilon \rightarrow 0} c_\epsilon^* \leq c^*$

- use **variational formula** for  $c_\epsilon^*$  with a suitable test function  $\rho \in \mathcal{K}$  (smooth, increasing from 0 to 1)
- because  $c^* = \sup_{s \in (0,1)} f'(s)$  here, can use **hyperbolic** fronts of speed  $c > c^*$  as test functions  $\rho$
- for  $\delta > 0$ , let  $\phi$  be a **hyperbolic** front of speed  $c^* + \delta$ . Then

$$\begin{aligned} c_\epsilon^* &= \inf_{\rho \in \mathcal{K}} \sup_{\xi \in \mathbb{R}} \frac{\epsilon \rho'' + g(\rho)}{-\rho'} + f'(\rho) \\ &\leq \sup_{\xi \in \mathbb{R}} \frac{\epsilon \phi'' + g(\phi)}{-\phi'} + f'(\phi) \\ &= \sup_{\xi \in \mathbb{R}} -\epsilon \frac{\phi''(\xi)}{\phi'(\xi)} + c^* + \delta \quad \text{since } (f'(\phi) - (c^* + \delta))\phi' = g(\phi) \\ &\rightarrow c^* + \delta \text{ as } \epsilon \rightarrow 0. \end{aligned}$$

## Step 2: $c_\epsilon^* \geq c^*$ for each $\epsilon > 0$

- a **necessary (but not sufficient)** condition for the existence of a **parabolic** front converging **monotonically** to 1 as  $\xi \rightarrow \infty$  is the existence of a **real, negative eigenvalue** of the linearisation of the **parabolic** equation at 1
- **linearisation**  $-cy' + f'(1)y' = \epsilon y'' + g'(1)y$ ,  $y = \phi - 1$ , which gives

$$\begin{pmatrix} y' \\ z' \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -\epsilon^{-1}g'(1) & \epsilon^{-1}(f'(1) - c) \end{pmatrix} \begin{pmatrix} y \\ z \end{pmatrix}$$

- **eigenvalues satisfy**  $\epsilon\lambda^2 + (c - f'(1))\lambda + g'(1) = 0$ , so

$$(c_\epsilon^* - f'(1))^2 \geq 4\epsilon g'(1)$$

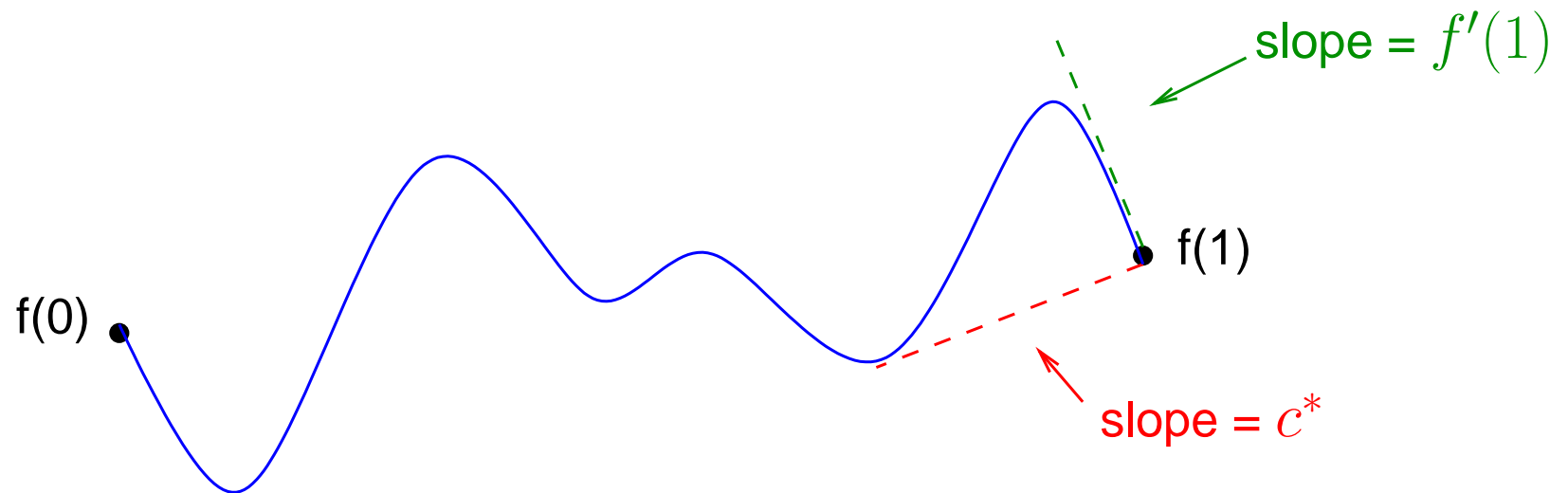
$$\begin{aligned} \Rightarrow c_\epsilon^* &\geq f'(1) + 2\sqrt{\epsilon g'(1)} =: c_{L,\epsilon} \text{ (minimal } c \text{ for } \lambda < 0 \text{ to exist)} \\ &= c^* + 2\sqrt{\epsilon g'(1)} \end{aligned}$$

because  $c^* = f'(1)$  in **easy case**

## 2. General “non-convex” flux

$$c^* = \sup_{s \in [0, \infty)} \frac{f(s) - f(1)}{s - 1} < \sup_{s \in [0, 1]} f'(s)$$

⇒ **hyperbolic** fronts of speed close to  $c^*$  discontinuous



$$f'(1) < c^* = \sup_{s \in [0, 1]} \frac{f(s) - f(1)}{s - 1} < \sup_{s \in [0, 1]} f'(s)$$

## General Case

$$\text{Step 1: } \limsup_{\epsilon \rightarrow 0} c_\epsilon^* \leq c^*$$

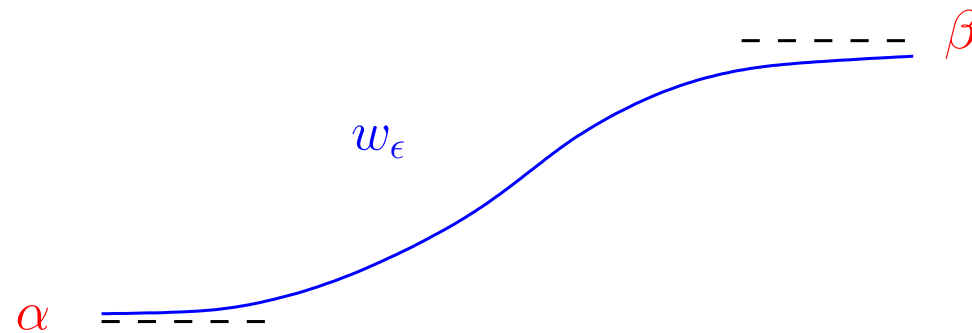
- again use **variational formula** for  $c_\epsilon^*$  with suitable  $\rho \in \mathcal{K}$
- can't use **hyperbolic** fronts for  $c$  close to  $c^*$  because not continuous
- instead use suitable solutions of a **reactionless** equation

# Technical background: Existence of Viscous Shock Profiles

There exists a solution  $u(x, t) = w(x - ct)$  of the reactionless equation

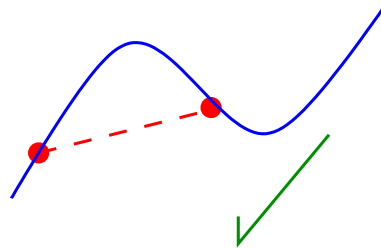
$$u_t + f(u)_x = \epsilon u_{xx}$$

with  $c \in \mathbb{R}$  and  $w_\epsilon$

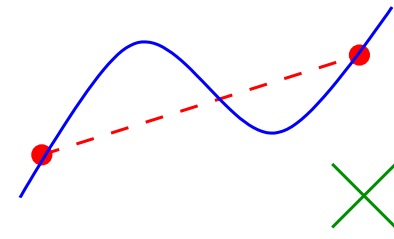


if and only if the straight line connecting  $(\alpha, f(\alpha))$  to  $(\beta, f(\beta))$  lies strictly below the graph of  $f$  between  $\alpha$  and  $\beta$

e.g.



but



Also 1. speed  $c = \text{slope} \frac{f(\beta) - f(\alpha)}{\beta - \alpha}$  2. scaling  $w_\epsilon(\xi) = w_1(\xi/\epsilon)$

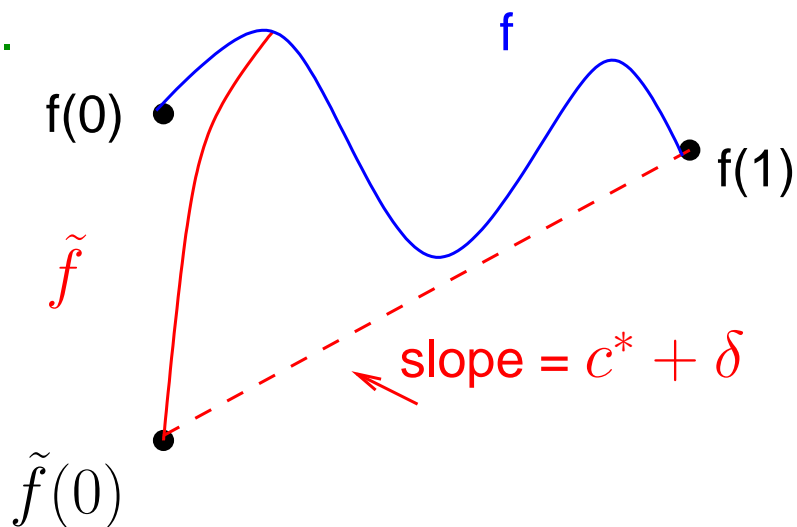
For  $\delta > 0$ , let  $\psi_\epsilon$  be a **viscous shock profile** connecting 0 to 1 and solving the **reactionless** equation

$$-(c^* + \delta)\psi'_\epsilon + \tilde{f}'(\psi_\epsilon)\psi'_\epsilon = \epsilon\psi''_\epsilon$$

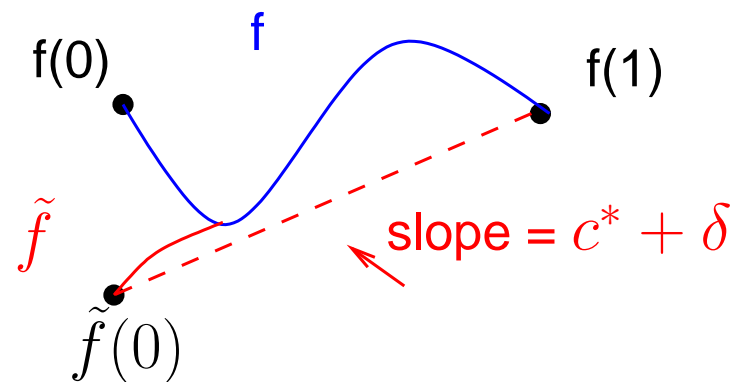
where the **modified flux**  $\tilde{f}$  satisfies

1.  $\tilde{f}(1) = \tilde{f}(0) = c^* + \delta$
2.  $\tilde{f}'(s) \geq f'(s)$  for all  $s \in (0, 1)$

e.g.



or



$\psi_\epsilon$  **exists** because **chord** between  $(0, \tilde{f}(0))$  and  $(1, \tilde{f}(1))$  lies below graph

## Step 1 contd.....

- by scaling,  $\psi_\epsilon(\xi) = \psi_1(\xi/\epsilon)$ , so

$$c_\epsilon^* = \inf_{\rho \in \mathcal{K}} \sup_{\xi \in \mathbb{R}} \frac{\epsilon \rho'' + g(\rho)}{-\rho'} + f'(\rho)$$

$$\leq \sup_{\xi \in \mathbb{R}} \frac{\epsilon \psi_\epsilon'' + g(\psi_\epsilon)}{-\psi_\epsilon'} + f'(\psi_\epsilon)$$

$$= \sup_{\xi \in \mathbb{R}} c^* + \delta - \frac{g(\psi_\epsilon)}{\psi_\epsilon'} - [\tilde{f}'(\psi_\epsilon) - f'(\psi_\epsilon)]$$

$$\text{because } (\tilde{f}'(\psi_\epsilon) - (c^* + \delta))\psi_\epsilon' = \epsilon \psi_\epsilon''$$

$$\leq c^* + \delta + \epsilon \sup_{x \in \mathbb{R}} \left( \frac{-g(\psi_1)}{\psi_1'} \right) \leftarrow \text{finite}$$

$$\rightarrow c^* + \delta$$

as  $\epsilon \rightarrow 0$ .

## Step 2: $c_\epsilon^* \geq c^*$ for each $\epsilon > 0$

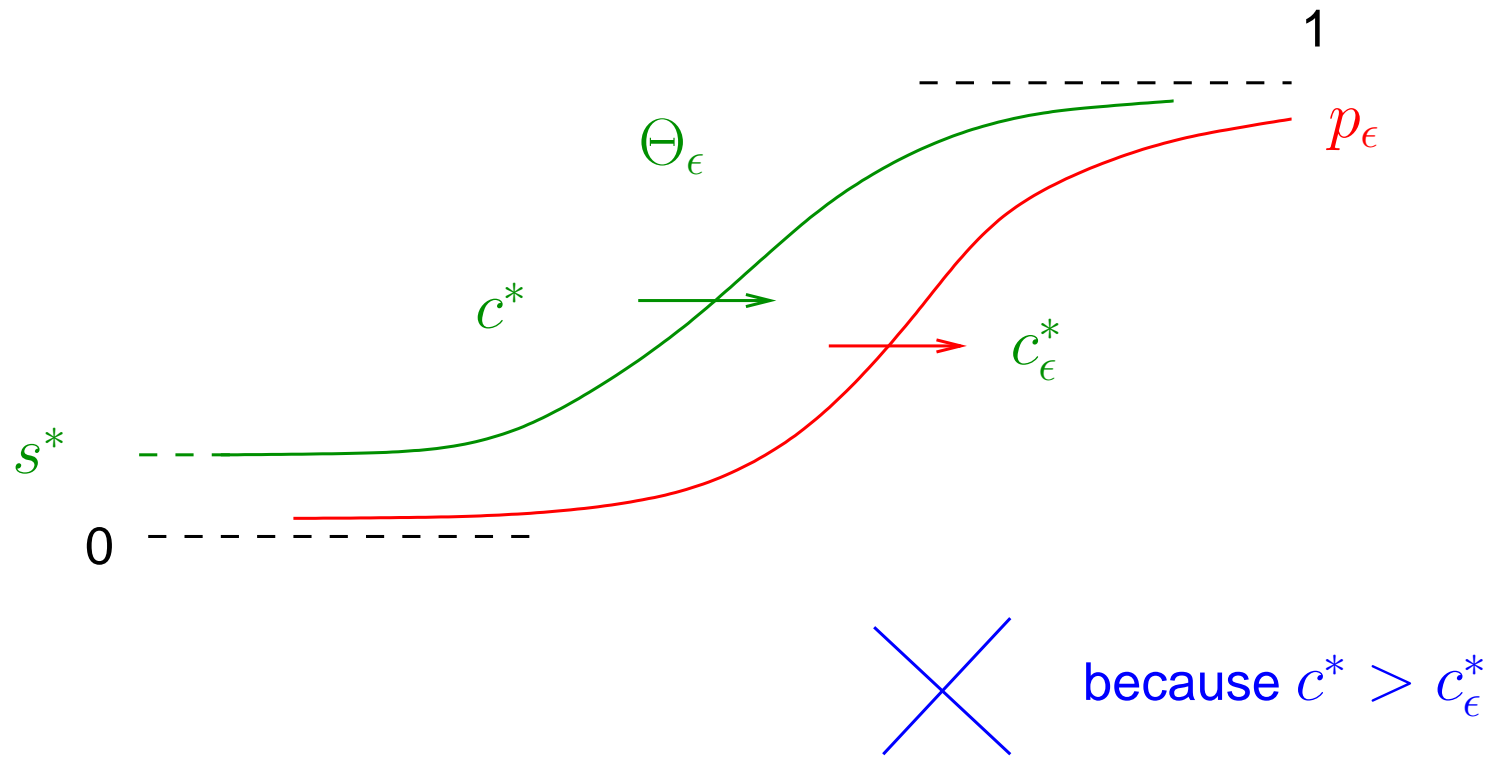
- suppose **not** - that  $c_\epsilon^* < c^*$  for some  $\epsilon > 0$
- seek  $\Theta_\epsilon(x - c^*t)$  such that
  1.  $c^* > c_\epsilon^*$
  2.  $\Theta_\epsilon \geq p_\epsilon$ , where  $p_\epsilon$  is a **parabolic** front of speed  $c_\epsilon^*$
  3.  $v(x, t) := \Theta_\epsilon(x - c^*t)$  is a **supersolution** for the **parabolic** equation:

$$v_t + f(v)_x - \epsilon v_{xx} - g(v) \geq 0$$

- **then** by the **comparison theorem** for the parabolic equations,

$$\Theta_\epsilon(x - c^*t) \geq p_\epsilon(x - c_\epsilon^*t) \text{ for all } x, t$$

- but this contradicts (1.): that  $c^* > c_\epsilon^*$



- take  $\Theta_\epsilon$  as the solution of the **reactionless** equation

$$(f'(\theta_\epsilon) - c^*)\theta'_\epsilon = \epsilon\theta''_\epsilon$$

- $\Theta_\epsilon(x - c^*t)$  is a **supersolution** for the parabolic equation because  $g(v) < 0$

## Ideas in proof of convergence of profiles

**Step 1** There exists a sequence  $\epsilon_n \downarrow 0$  and a non-decreasing function  $\phi : \mathbb{R} \rightarrow [0, 1]$  with  $\phi(0) = 1/2$  such that

$$\phi_{\epsilon_n}(\xi) \rightarrow \phi(\xi) \quad \text{for each } \xi \in \mathbb{R},$$

and

$$\phi_{\epsilon_n}(x - c_{\epsilon_n}^* t) \rightarrow \phi(x - c^* t) \quad \text{for a.e. } (x, t) \in \mathbb{R} \times [0, \infty)$$

## Ideas in proof of convergence of profiles

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and

$$\phi_{\epsilon_n}(x - c_{\epsilon_n}^* t) \rightarrow \phi(x - c^* t) \quad \text{for a.e. } (x, t) \in \mathbb{R} \times [0, \infty)$$

because

- $\phi_\epsilon(\xi)$  is increasing in  $\xi$  for each  $\epsilon$ , so Helly's Selection Principle applies
- $\phi$  is monotone, so  $\phi(x - c^* t)$  is continuous at a.e.  $(x, t) \in \mathbb{R} \times [0, \infty)$
- given  $\mu > 0$ , there exists  $\epsilon_0 > 0$  such that for  $\epsilon_n \in (0, \epsilon_0)$ ,

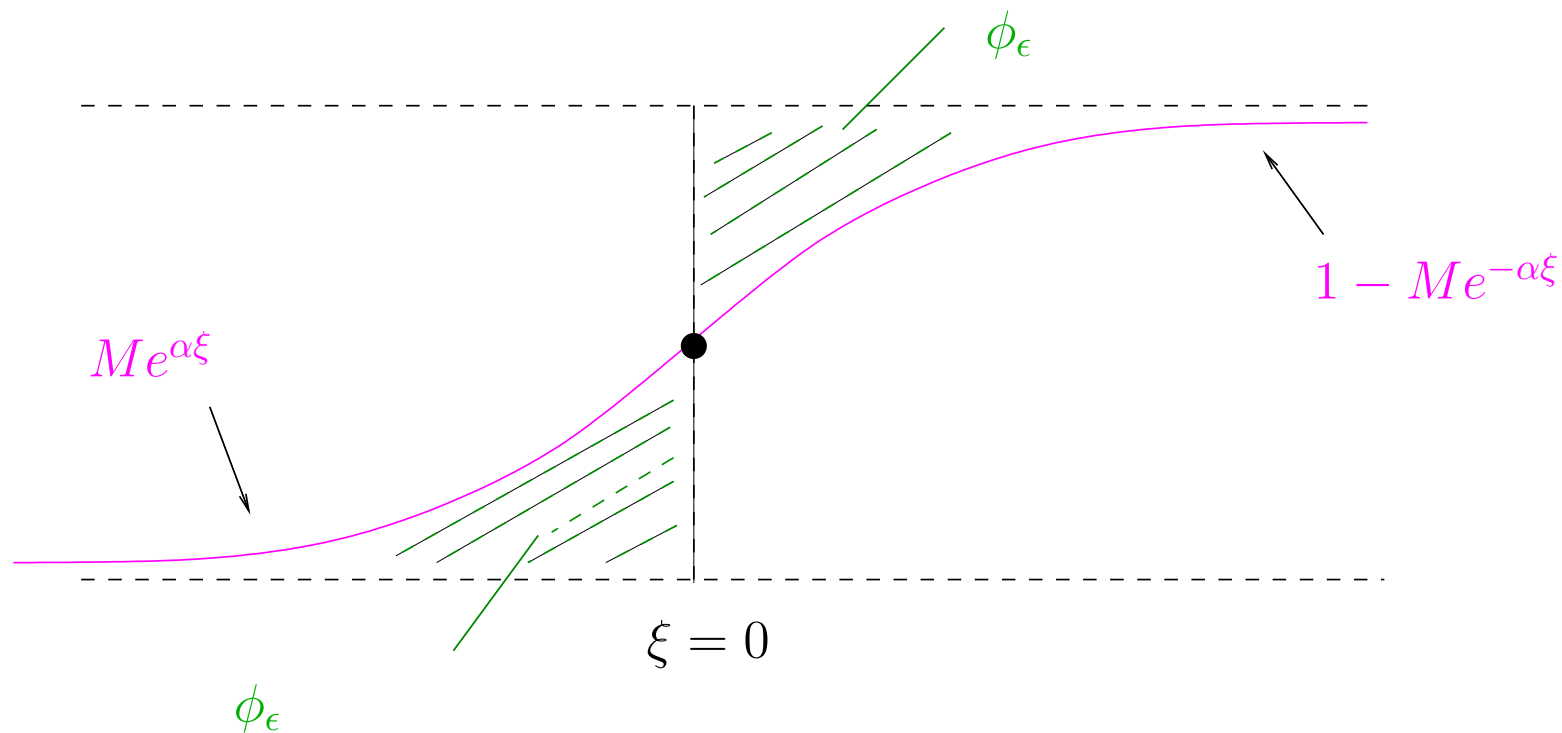
$$\begin{aligned} \phi_{\epsilon_n}(x - c^* t) - \phi(x - c^* t) &\geq \phi_{\epsilon_n}(x - c_{\epsilon_n}^* t) - \phi(x - c^* t) \\ &\geq \phi_{\epsilon_n}(x - (c^* + \mu)t) - \phi(x - c^* t) \end{aligned}$$

$$\Rightarrow \phi_{\epsilon_n}(x - c^* t) \rightarrow \phi(x - c^* t) \quad \text{if } \phi \text{ is continuous at } x - c^* t$$

**Step 2 (uniform bounds)** Given  $\epsilon_0 > 0$ , there exist  $\alpha > 0$  and  $M > 0$  such that for each  $\epsilon \in (0, \epsilon_0)$ ,

$$0 \leq \phi_\epsilon(\xi) \leq Me^{\alpha\xi} \quad \text{whenever } \xi \leq 0$$

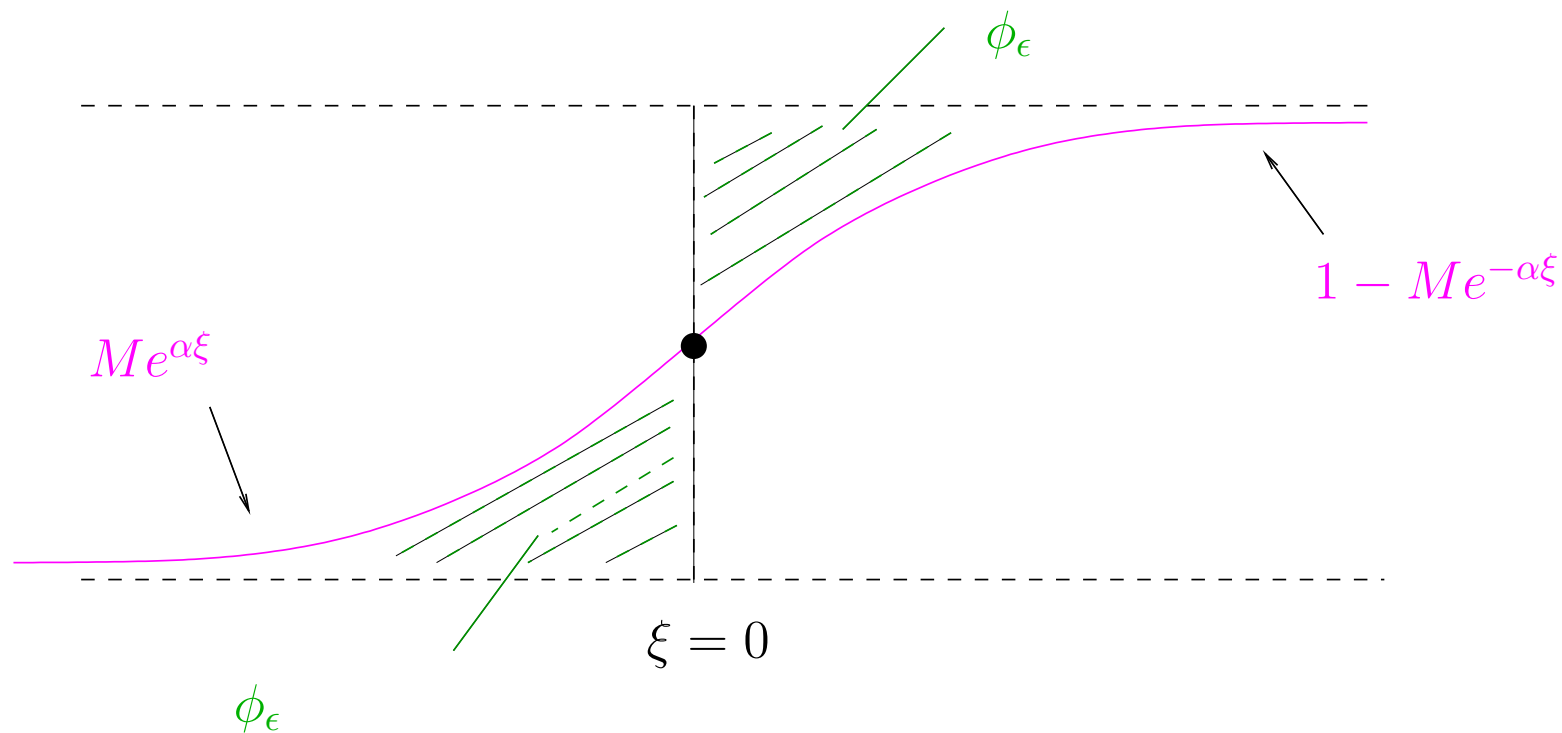
$$0 \leq 1 - \phi_\epsilon(\xi) \leq Me^{-\alpha\xi} \quad \text{whenever } \xi \geq 0$$



**Step 2 (uniform bounds)** Given  $\epsilon_0 > 0$ , there exist  $\alpha > 0$  and  $M > 0$  such that for each  $\epsilon \in (0, \epsilon_0)$ ,

$$0 \leq \phi_\epsilon(\xi) \leq Me^{\alpha\xi} \quad \text{whenever } \xi \leq 0$$

$$0 \leq 1 - \phi_\epsilon(\xi) \leq Me^{-\alpha\xi} \quad \text{whenever } \xi \geq 0$$



**Step 1 + Step 2**  $\Rightarrow \|\phi_{\epsilon_n} - \phi\|_{L^1(\mathbb{R})} \rightarrow 0$  as  $\epsilon_n \downarrow 0$

**Step 3**  $\phi(x - c^*t)$  is the unique up-to-translation entropy front solution of  $(H)$  of speed  $c^*$

- by standard vanishing-viscosity arguments (cf Kružkov, Dafermos)

**Step 3**  $\phi(x - c^*t)$  is the unique up-to-translation entropy front solution of  $(H)$  of speed  $c^*$

- by standard vanishing-viscosity arguments (cf Kruřkov, Dafermos)
- particularly elementary here since  $\phi_\epsilon$  is monotone
- for  $u_{\epsilon_n}(x, t) = \phi_{\epsilon_n}(x - c_{\epsilon_n}^* t)$ , non-negative  $\psi \in C_0^\infty(\mathbb{R} \times [0, \infty))$  and  $k \in \mathbb{R}$ ,

$$-\text{sgn}(u_{\epsilon_n} - k) \psi \left[ \frac{\partial u_{\epsilon_n}}{\partial t} + \frac{\partial f(u_{\epsilon_n})}{\partial x} - g(u_{\epsilon_n}) \right] = -\epsilon_n \text{sgn}(u_{\epsilon_n} - k) \psi \frac{\partial^2 u_{\epsilon_n}}{\partial x^2}$$

$\Rightarrow$

$$\begin{aligned} \int_{\mathbb{R} \times [0, \infty)} |u_{\epsilon_n} - k| \frac{\partial \psi}{\partial t} + [f(u_{\epsilon_n}) - f(k)] \frac{\partial \psi}{\partial x} + \text{sgn}(u_{\epsilon_n} - k) \psi g(u_{\epsilon_n}) \, dx dt \\ \geq -\epsilon_n \int_{\mathbb{R} \times [0, \infty)} |u_{\epsilon_n} - k| \frac{\partial^2 \psi}{\partial x^2} \, dx dt. \end{aligned}$$

$\Rightarrow$

$$\int_{\mathbb{R} \times [0, \infty)} \left[ |u - k| \frac{\partial \psi}{\partial t} + \text{sgn}(u - k) (f(u) - f(k)) \frac{\partial \psi}{\partial x} + \text{sgn}(u - k) g(u) \psi \right] \, dx dt \geq 0$$

where  $u(x, t) = \phi(x - c^*t)$

## Better convergence for fronts of speed $c > \sup_{s \in [0,1]} f'(s)$

**Lemma** let  $\phi_\epsilon, \phi$  denote the profiles of the front solutions of  $(P)$ ,  $(H)$  with speed  $c > \sup_{s \in [0,1]} f'(s)$  and  $\phi_\epsilon(0) = \phi(0) = 1/2$ . Then as  $\epsilon \rightarrow 0$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } W^{1,1}(\mathbb{R}),$$

and for each compact interval  $[-M, M] \subset \mathbb{R}$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } C^1([-M, M]).$$

## Better convergence for fronts of speed $c > \sup_{s \in [0,1]} f'(s)$

**Lemma** let  $\phi_\epsilon, \phi$  denote the profiles of the front solutions of  $(P)$ ,  $(H)$  with speed  $c > \sup_{s \in [0,1]} f'(s)$  and  $\phi_\epsilon(0) = \phi(0) = 1/2$ . Then as  $\epsilon \rightarrow 0$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } W^{1,1}(\mathbb{R}),$$

and for each compact interval  $[-M, M] \subset \mathbb{R}$ ,

$$\phi_\epsilon \rightarrow \phi \text{ in } C^1([-M, M]).$$

because

- uniform bounds on  $\phi'_\epsilon, \phi''_\epsilon$
- e.g. the maximum of  $\phi'_\epsilon$  is attained at a point  $\xi_0$  where  $\phi''_\epsilon(\xi_0) = 0$ , so

$$\begin{aligned} (f'(\phi_\epsilon(\xi_0)) - c)\phi'_\epsilon(\xi_0) &= g(\phi_\epsilon(\xi_0)) \\ \Rightarrow \phi'_\epsilon(\xi_0) &= \frac{g(\phi_\epsilon(\xi_0))}{f'(\phi_\epsilon(\xi_0)) - c} \leq A \end{aligned}$$

## A consequence for **parabolic** fronts

- a **necessary** condition for existence of **parabolic** fronts is the existence of a real, negative eigenvalue at 1

$$\Rightarrow c_\epsilon^* \geq c_{L,\epsilon}$$

- $c_{L,\epsilon}$  is **minimal**  $c$  for which **linear** problem at 1

$$(f'(1) - c)y' = \epsilon y'' + g'(1)y$$

has an eigenvalue  $\lambda < 0$  satisfying

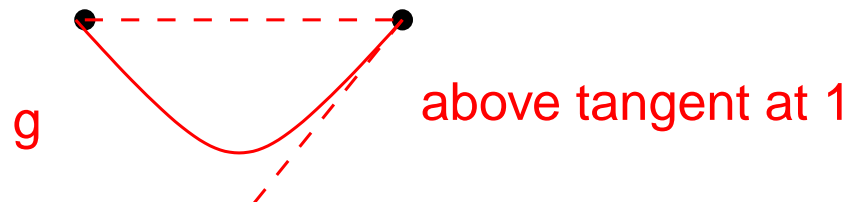
$$(f'(1) - c)\lambda = \epsilon\lambda^2 + g'(1)$$

- would like to know if

$$c_\epsilon^* > c_{L,\epsilon} \quad \text{or} \quad c_\epsilon^* = c_{L,\epsilon}$$

## Previous results

- Hadeler and Rothe (1975)  $f = 0 \Rightarrow c_\epsilon^* = c_{L,\epsilon}$



- Berestycki and Nirenberg (1992)

$$f = 0, \quad \sqrt{2} \int_0^1 \sqrt{-g} \geq 2\sqrt{g'(1)} \Rightarrow c_\epsilon^* > c_{L,\epsilon}$$

- Lucia, Muratov and Novaga (2004)

$$f = 0, \quad \text{various conditions on } g \Rightarrow \text{conditions for } c_\epsilon^* > c_{L,\epsilon} \text{ and } c_\epsilon^* = c_{L,\epsilon}$$

- Weinberger, Lewis and Li (2002, 2005)

$$f = 0, \quad \text{systems} \Rightarrow \text{conditions for } c_\epsilon^* = c_{L,\epsilon}$$

- Benguria, Depassier and Mendez (2004)

$$f \neq 0, \quad g''(u)/\sqrt{g'(1)} + f''(1) < 0 \text{ for } u \in (0, 1) \Rightarrow c_\epsilon^* = c_{L,\epsilon}$$

.....

Here

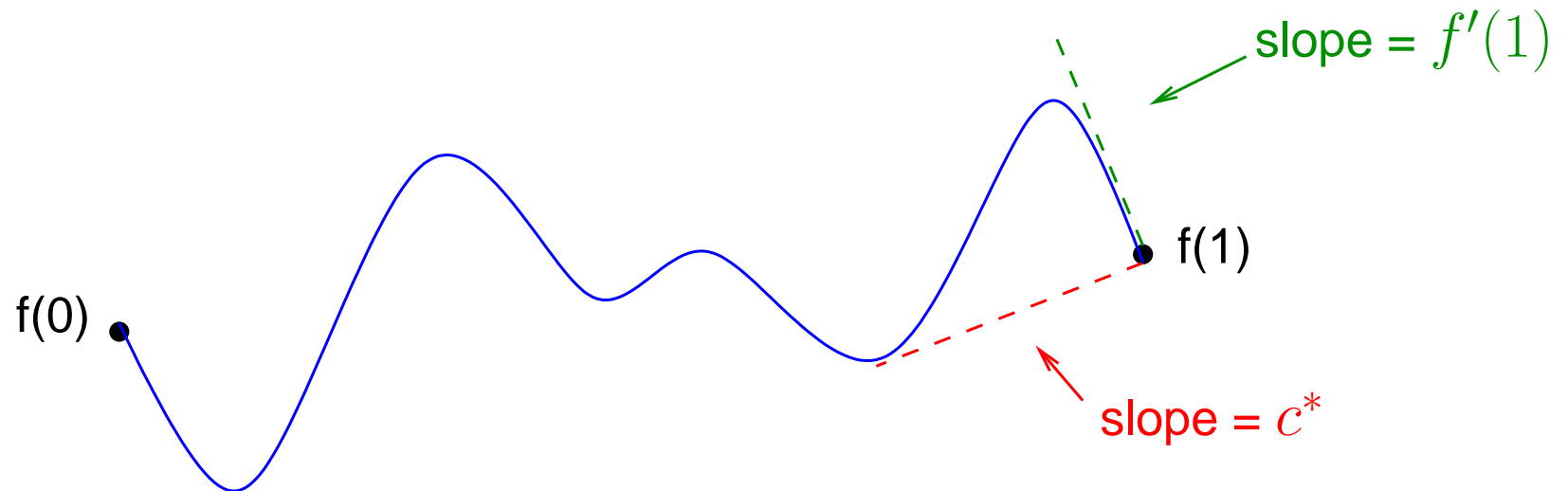
- $c_{L,\epsilon} = f'(1) + 2\sqrt{\epsilon g'(1)} \rightarrow f'(1)$  as  $\epsilon \rightarrow 0$

- $c_\epsilon^* \rightarrow c^* = \sup_{s \in (0,1)} \frac{f(1) - f(s)}{1 - s}$  as  $\epsilon \rightarrow 0$

- thus if

$$f'(1) < \sup_{s \in (0,1)} \frac{f(1) - f(s)}{1 - s},$$

e.g.



then  $c_\epsilon^* > c_{L,\epsilon}$  for  $\epsilon$  small

- no condition on reaction  $g$

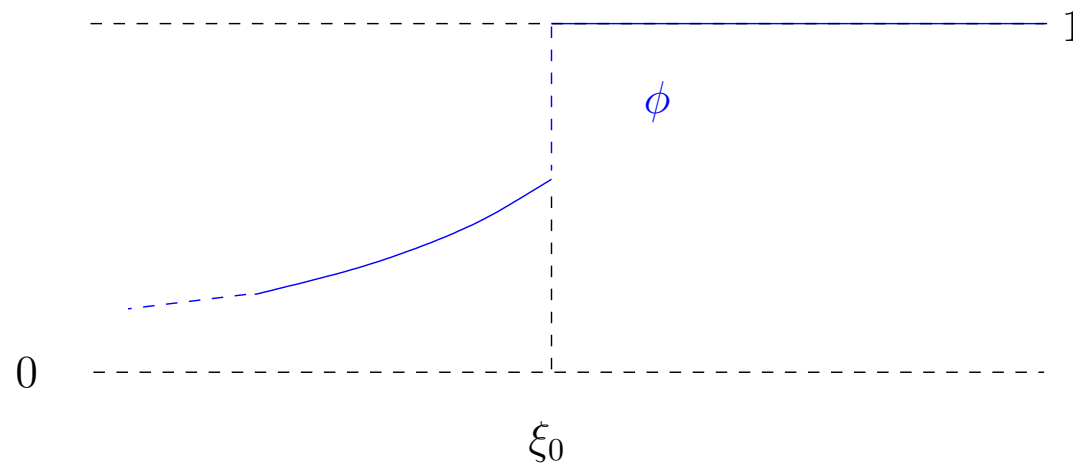
In fact, it can be shown that if

$$f'(1) < \sup_{s \in (0,1)} \frac{f(1) - f(s)}{1 - s},$$

then the minimal speed front solution of (H) is such that

$$\phi(\xi) = 1 \quad \text{for all } \xi \geq \xi_0, \quad \phi(\xi_0^-) < 1$$

for some  $\xi_0$



*i.e.* unstable state is followed by a shock propagating at the limiting speed  $c^*$ , so the pushing of the (P) front to a speed faster than  $c_{L,\epsilon}$  is because of a compression effect from the hyperbolic structure of the equation