

Sharp error estimates for discretisations of the 1D convection/diffusion equation with Dirac initial data

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This paper derives sharp estimates of the error arising from explicit and implicit approximations of the constant coefficient 1D convection/diffusion equation with Dirac initial data. The error analysis is based on Fourier analysis and asymptotic approximation of the integrals resulting from the inverse Fourier transform. This research is motivated by applications in computational finance and the desire to prove convergence of approximations to adjoint partial differential equations.

Key words and phrases: convection/diffusion equation, Crank-Nicolson time-marching, Rannacher startup, Dirac initial data

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1 Introduction

This paper is concerned with a detailed error analysis of two different discretisations of the one-dimensional constant coefficient convection/diffusion equation on an infinite domain. Both are based on a second order central space discretisation; one uses the Forward Euler time discretisation and the other uses Crank-Nicolson, with or without a Rannacher startup in which one or more Crank-Nicolson timesteps is replaced by two half-timesteps of Backward Euler discretisation to improve the convergence.

The novelty in this paper is in the focus on Dirac initial data. One reason for this focus is concern with the convergence of adjoint discretisations. Adjoint methods are being used heavily for optimal design [10, 11], error analysis and correction for integral outputs [1, 7, 12], and optimal grid adaptation [2, 4]. In applications in which the original p.d.e. is nonlinear, the adjoint discretisation is usually obtained in one of two ways, either as a discretisation of the adjoint p.d.e. corresponding to the linearisation of the original p.d.e., or as the transposed equation corresponding to the linearised discretisation of the original p.d.e. In either case, if the original nonlinear solution is smooth, then the coefficients of the adjoint discretisation will be smooth, and it is possible to prove convergence in both steady and unsteady applications as the mesh spacing and timestep approach zero [19, 20]. However, when the underlying nonlinear solution is discontinuous, as in the case of shocks in compressible flow, then there is numerical evidence [5] showing that one must be careful in the treatment of the discontinuity to obtain convergence for the adjoint discretisation.

To understand the connection between Dirac initial data and adjoint equations, consider the following system of linear equations,

$$U^{n+1} = A^n U^n,$$

arising from the discretisation of an unsteady linear one-dimensional p.d.e. Here U^n represents the approximation to a scalar variable $u(x, t)$ on a one-dimensional grid with uniform spacing h at time $t^n = nk$. If one is interested in the value of an integral output

$$J = \int_{-\infty}^{\infty} g(x) u(x, T) dx,$$

this may be approximated as

$$J_h = h \sum_j g(x_j) U_j^N,$$

where $T = Nk$. Alternatively, but equivalently, it can be evaluated as

$$J_h = h \sum_j V_j^0 U_j^0,$$

where the adjoint solution V_j^n satisfies the adjoint discrete equations

$$V^n = (A^n)^T V^{n+1},$$

subject to the final data

$$V_j^N = g(x_j).$$

The equivalence follows immediately from the identity

$$(V^0)^T U^0 = (V^N)^T A^{N-1} A^{N-2} \dots A^1 A^0 U^0 = (V^N)^T U^N.$$

This adjoint approach to evaluating the output functional is advantageous when there is a single output functional of interest, but many different sets of initial data. Under these circumstances, the standard approach would require a separate forward analysis for each set of initial data, whereas the adjoint approach requires just one adjoint calculation, plus an inexpensive inner product evaluation for each set of initial data.

In the particular case of Dirac initial data with

$$U_j^0 = h^{-1} \delta_{j,0} \equiv \begin{cases} h^{-1}, & j = 0 \\ 0, & \text{otherwise} \end{cases}$$

one obtains

$$V_0^0 = h \sum_j g(x_j) U_j^N.$$

Thus, convergence of the integral output for Dirac initial data is equivalent to pointwise convergence of the adjoint discretisation. The results for the explicit Forward Euler discretisation in this paper will be used in a future paper [8] to prove the pointwise convergence of adjoint discretisations when there are discontinuities in the solution of the underlying nonlinear p.d.e..

A second motivation for the analysis in this paper is applications in mathematical finance which require the numerical solution of variants of the Black-Scholes equation [21]

$$\frac{\partial V}{\partial t} = rV - rS \frac{\partial V}{\partial S} - \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2}.$$

This is an equation which is solved backwards in time, from a terminal time $t=T$, to an initial time $t=0$. The value for σ is sufficiently large that the diffusion plays a significant role in the evolution of the solution; it is not a convection-dominated problem. Hence, second-order central space differencing and Crank-Nicolson time integration is widely used to approximate this equation. On a uniform grid with spacing h and timestep k this results in the discrete equations

$$(I + \frac{1}{2} D_j) V_j^{n+1} = (I - \frac{1}{2} D_j) V_j^n$$

where

$$D_j = -\frac{k}{2h^2} \sigma^2 (S_j)^2 \delta_s^2 - \frac{k}{2h} r S_j \delta_{2s} + r k$$

with δ_s^2 and δ_{2s} being the standard second difference and central first difference operators, respectively, and $t^{n+1} = t^n - k$ where n is the time level index which increases from $n=0$ at time $t=T$ to $n=N$ at time $t=0$.

For European call options, the “initial” data at the terminal time is

$$V(S, T) = \max(S - K, 0).$$

The top-left plot in Figure 1 shows the numerical solution $V(S, 0)$ at time $t=0$ obtained on a uniform grid $0 \leq S \leq S_{max} = 5$, using parameter values $r=0.05$, $\sigma=0.2$, $K = 1$, $T=2$. The boundary conditions which were used are $V_j=0$ at $S=0$, and $\delta^2 V_j=0$ at $S=S_{max}$. The agreement between the numerical solution and the analytic solution [21] appears quite good, but in the financial application the first derivative, $\Delta \equiv \partial V / \partial S$, and the second derivative, $\Gamma \equiv \partial^2 V / \partial S^2$, are both important quantities. Their numerical values obtained by central differencing are in much poorer agreement with the analytic solution, as shown in the other two left-hand plots in Figure 1. In particular, note that the maximum error in the computed value for Γ occurs at $S=1$, which is the location of the discontinuity in the first derivative of the initial data.

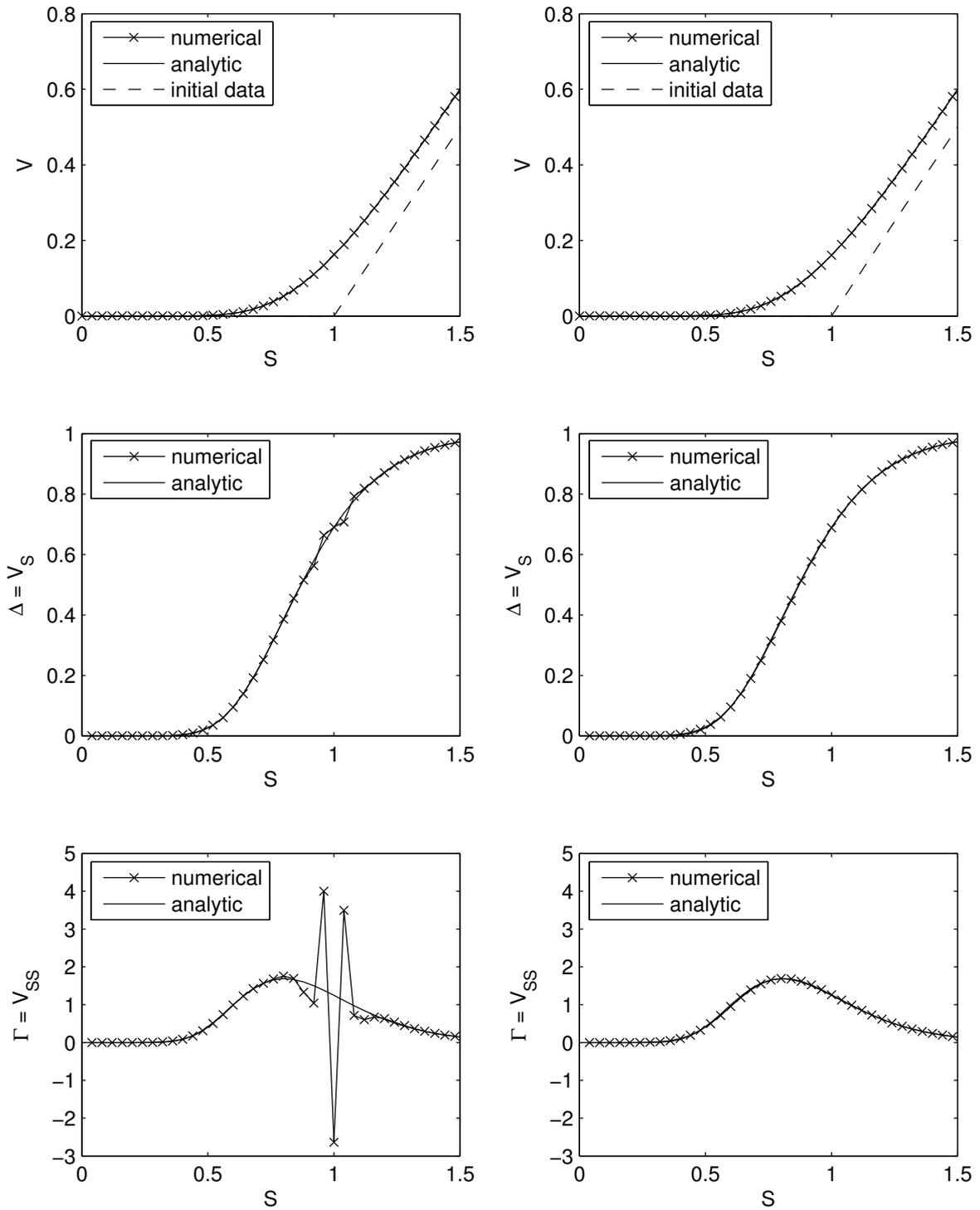
The left-hand plots in Figure 2 show the behaviour of the maximum error as the computational grid is refined, keeping fixed the ratio $\lambda \equiv k/h$. It can be seen that the numerical solution V_j exhibits first order convergence, while the discrete approximation to Δ does not converge, and the approximation to Γ diverges.

At first sight, this may appear surprising as the Crank-Nicolson method is well-known to be consistent and unconditionally stable, and hence one expects convergence. However, it is unconditionally stable only in the L_2 norm, and this, together with consistency, ensures convergence in L_2 only for initial data which lies in L_2 [17], and the order of convergence may be less than the second order achieved for smooth initial data. For example, the L_2 order of convergence for discontinuous initial data is $\frac{1}{2}$. With the European call, the initial data for V lies in L_2 , as does its first derivative, but the second derivative does not. This then is the root cause of the observed failure to converge as the grid is refined. Furthermore, it is the maximum error, the L_∞ error, which is most relevant in financial applications.

In [16], Rannacher analysed this problem from the perspective of L_2 convergence of convection-diffusion approximations with discontinuous initial data. His objective was to recover second order convergence in the context of Crank-Nicolson time-marching (he also considered higher order time integration schemes), and using energy methods he proved that this could be achieved by replacing the Crank-Nicolson approximation for the very first timestep by two half-timesteps using Backward Euler time integration. This solution, often referred to as Rannacher time-stepping, has been used with success in approximations of the Black-Scholes equations [9, 13, 14, 15]. The right-hand plots in Figures 1 and 2 show that replacing the first two Crank-Nicolson timesteps by four half-timesteps of Backward Euler, for which

$$(I + \frac{1}{2}D) V_j^{n+1/2} = V_j^n.$$

results in second order convergence for V , Δ and Γ . The purpose of the analysis in this paper is to explain this behaviour by analysing the implicit discretisation of the convection-diffusion equation subject to Dirac initial data, corresponding to the initial data for Γ . This will prove that four half-timesteps of Backward Euler time-marching is

Figure 1: V , Δ and Γ for European call option

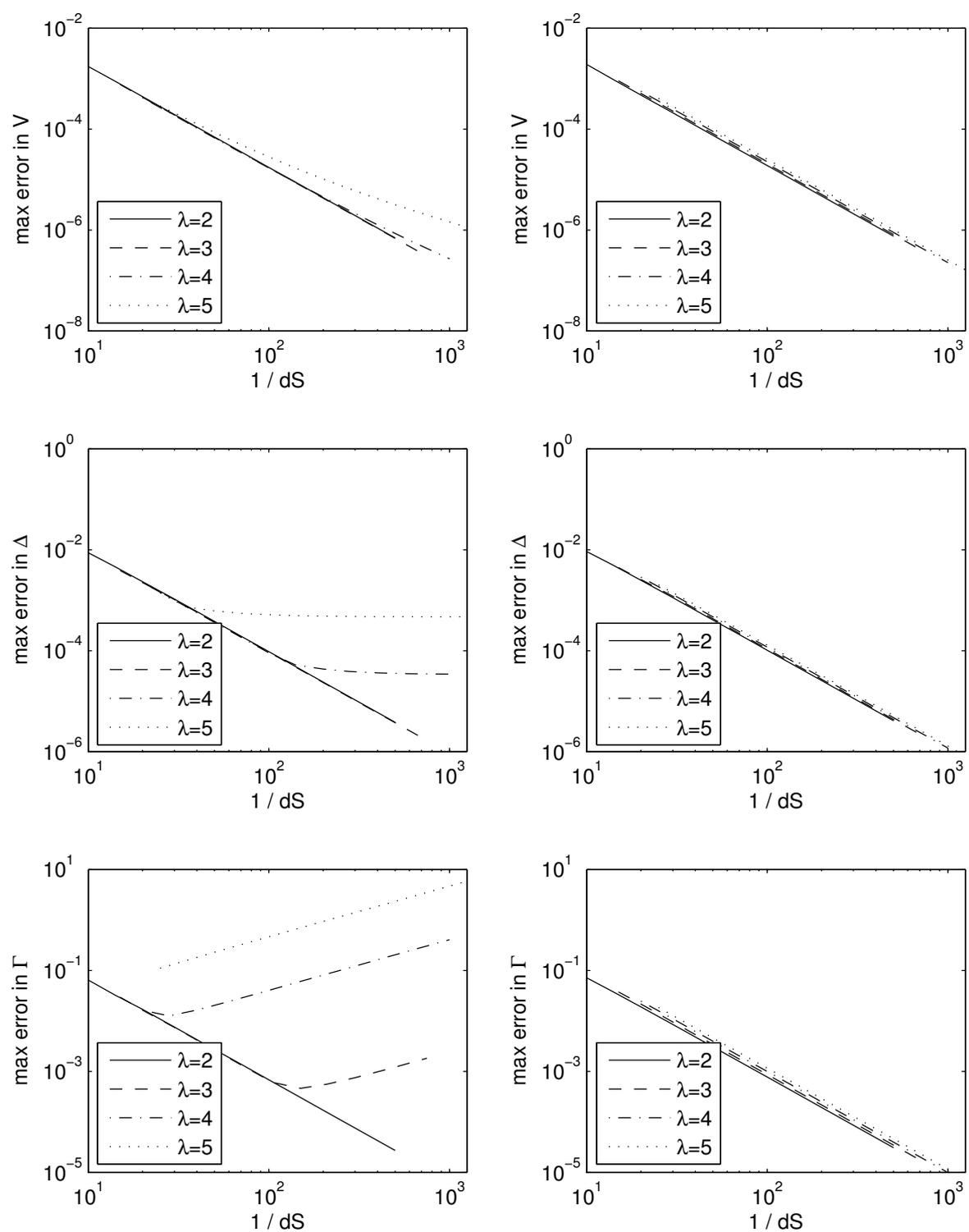


Figure 2: Grid convergence for European call option

the minimum required to recover second order convergence; the use of more than four half-timesteps will probably lead to an increase in the overall error, and therefore four half-timesteps can be regarded as optimal.

The numerical analysis is based on the Fourier transform of the discrete equations [18] and asymptotic approximation of the inverse Fourier transform to bound the resulting discretisation error. It is similar to the approach used by Brenner, Thomée and Wahlbin [3], however, their interest was in studying convergence for L_p initial data, as opposed to the Dirac initial data of interest in this paper. Numerical results confirm the sharpness of the error bounds which are derived.

2 Model problem and discretisations

The model problem to be analysed is the convection-diffusion equation

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = \frac{\partial^2 u}{\partial x^2}, \quad (2.1)$$

on $-\infty < x < \infty$ and $0 < t < 1$, subject to the Dirac initial data

$$u(x, 0) = \delta(x).$$

The generalisation to non-unit diffusivity and terminal times other than $t = 1$ will be discussed later.

Defining the Fourier transform pair

$$\begin{aligned} \widehat{u}(\kappa, t) &= \int_{-\infty}^{\infty} u(x, t) e^{-i\kappa x} dx, \\ u(x, t) &= \frac{1}{2\pi} \int_{-\infty}^{\infty} \widehat{u}(\kappa, t) e^{i\kappa x} d\kappa, \end{aligned}$$

then the Fourier transform of Equation (2.1) yields

$$\frac{d\widehat{u}}{dt} = -(ia\kappa + \kappa^2) \widehat{u},$$

subject to initial data $\widehat{u}(\kappa, 0) = 1$. The solution to this is

$$\widehat{u}(\kappa, t) = \exp(-(ia\kappa + \kappa^2)t),$$

and hence

$$u(x, t) = \frac{1}{\sqrt{4\pi t}} \exp\left(-\frac{(x-at)^2}{4t}\right) = \frac{1}{\sqrt{2t}} N\left(\frac{x-at}{\sqrt{2t}}\right),$$

where

$$N(x) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{x^2}{2}\right),$$

is the standard Normal distribution with zero mean and unit variance.

The forward Euler central space discretisation on a uniform grid with spacing h and timestep k is

$$U_j^{n+1} = (I - D) U_j^n, \quad (2.2)$$

where

$$D = -d \delta_x^2 + \frac{r}{2} \delta_{2x}, \quad d = \frac{k}{h^2}, \quad r = \frac{ak}{h},$$

with δ_x^2 and δ_{2x} being the usual second difference and central first difference operators, respectively.

The Crank-Nicolson discretisation is

$$(I + \frac{1}{2}D) U_j^{n+1} = (I - \frac{1}{2}D) U_j^n, \quad (2.3)$$

and the half-timestep Backward Euler discretisation used in the Rannacher startup is

$$(I + \frac{1}{2}D) U_j^{n+1/2} = U_j^n. \quad (2.4)$$

The discrete approximation to the Dirac initial data in both cases is

$$U_j^0 = h^{-1} \delta_{j,0} \equiv \begin{cases} h^{-1}, & j = 0 \\ 0, & \text{otherwise.} \end{cases}$$

The objective of the error analysis will be to quantify the error $U_j^N - u(x_j, 1)$ for $N = 1/k$. First however, there is an important point to clarify, which is that Equations (2.3) and (2.4) do not have unique solutions because the homogeneous equation

$$(I + \frac{1}{2}D) V_j = 0,$$

has non-trivial solutions of the form $V_j = w^j$ where w satisfies the quadratic equation

$$w - \frac{1}{2}d(w^2 - 2w + 1) + \frac{1}{2}r(w^2 - 1) = 0.$$

It can be shown that one root has magnitude greater than unity, leading to exponential growth as $j \rightarrow \infty$, while the other has magnitude less than unity, leading to exponential growth as $j \rightarrow -\infty$. Hence, there is at most one solution of Equation (2.3) or (2.4) which remains bounded. We will now show that such a bounded solution does exist, and thus by requiring boundedness we obtain a unique solution.

To construct this bounded solution we consider the use of periodic boundary conditions $U_{j+J}^n = U_j^n$ for $j = -J/2, -J/2 + 1$, (with J even) and all n . Using the discrete Fourier transform pair

$$U_j^n = \frac{1}{hJ} \sum_{m=-J/2+1}^{J/2} \widehat{U}_m^n \exp(ij\theta_m)$$

$$\widehat{U}_m^n = h \sum_{j=-J/2+1}^{J/2} U_j^n \exp(-ij\theta_m).$$

where $\theta_m = m \Delta\theta = 2\pi m/J$, the Fourier transform of Equation (2.3) gives

$$\widehat{U}_m^{n+1} = \frac{1 - \frac{1}{2}ir \sin \theta - 2d \sin^2 \frac{\theta}{2}}{1 + \frac{1}{2}ir \sin \theta + 2d \sin^2 \frac{\theta}{2}} \widehat{U}_m^n,$$

for $n \geq R$, where R is the number of initial Crank-Nicolson timesteps replaced by $2R$ half-timesteps of Backward Euler time integration, while for $n < R$ the Fourier transform of Equation (2.4) gives

$$\widehat{U}_m^{n+1} = \frac{1}{(1 + \frac{1}{2}ir \sin \theta + 2d \sin^2 \frac{\theta}{2})^2} \widehat{U}_m^n.$$

These can be combined to give

$$\widehat{U}_m^n = z_1^n(\theta) z_2^{\min(n,R)}(\theta) \widehat{U}_m^0,$$

where

$$\begin{aligned} z_1(\theta) &= \left(1 - \frac{1}{2}ir \sin \theta - 2d \sin^2 \frac{\theta}{2}\right) \left(1 + \frac{1}{2}ir \sin \theta + 2d \sin^2 \frac{\theta}{2}\right)^{-1}, \\ z_2(\theta) &= \left(1 - \frac{1}{2}ir \sin \theta - 2d \sin^2 \frac{\theta}{2}\right)^{-1} \left(1 + \frac{1}{2}ir \sin \theta + 2d \sin^2 \frac{\theta}{2}\right)^{-1}. \end{aligned}$$

For the Dirac initial data, $\widehat{U}_m^0 = 1$ and hence

$$\begin{aligned} U_j^n &= \frac{1}{2\pi h} \sum_{m=-J/2+1}^{J/2} z_1^n(\theta_m) z_2^R(\theta_m) e^{ij\theta_m} \Delta\theta \\ &\longrightarrow \frac{1}{2\pi h} \int_{-\pi}^{\pi} z_1^n(\theta) z_2^{\min(n,R)}(\theta) e^{ij\theta} d\theta \end{aligned}$$

as $J \rightarrow \infty$ with h held fixed; the limit clearly exists because of the continuity of $z_1(\theta)$ and $z_2(\theta)$. By making the substitutions $\theta = \kappa h$, $x_j = jh$ the integral can also be expressed as

$$U_j^n = \frac{1}{2\pi} \int_{-\pi/h}^{\pi/h} z_1^n(\kappa h) z_2^{\min(n,R)}(\kappa h) e^{i\kappa x_j} d\kappa.$$

This has the correct initial data and satisfies the discrete equations on an infinite domain since for each j the periodic solution satisfies the discrete equations for all $J > j$. It is also bounded because of the discrete Parseval identity

$$h \sum_{j=-J/2+1}^{J/2} |U_j^n|^2 = \frac{1}{2\pi h} \sum_{m=-J/2+1}^{J/2} \left| \widehat{U}_m^n \right|^2 \Delta\theta$$

which in the limit $J \rightarrow \infty$ becomes

$$h \sum_j |U_j^n|^2 = \frac{1}{2\pi} \int_{-\pi/h}^{\pi/h} \left| \widehat{U}^n(\kappa) \right|^2 d\kappa.$$

3 Forward Euler error analysis

3.1 Analysis of Fourier transform error

The Fourier transform of Equation (2.2)) yields

$$\widehat{U}^N(\kappa) = z^N(\kappa).$$

where

$$z(\kappa) = 1 - i a d h \sin \kappa h - 4d \sin^2 \frac{\kappa h}{2}.$$

We now compare this to the analytic solution $u(x, 1)$ whose Fourier transform is

$$\widehat{u}(\kappa, 1) = \exp(-ia\kappa - \kappa^2).$$

The comparison is split over two wavenumber regions, a low wavenumber region in which $|\kappa| < h^{-m}$ for some constant m satisfying the constraints $0 < m < \frac{1}{2}$, and the high wavenumber region $|\kappa| > h^{-m}$.

Proposition 1 (Low wavenumber region)

For $|\kappa| < h^{-m}$, as $h \rightarrow 0$ with $Nk = 1$ and $d = k/h^2$ held fixed,

$$\widehat{U}^N(\kappa) - \widehat{u}(\kappa, 1) = h^2 \exp(-ia\kappa - \kappa^2) \left\{ p(a, d; \kappa) + O(h^2(\kappa^2 + \kappa^8)) \right\},$$

where

$$p(a, d; \kappa) = \frac{1}{2} d a^2 \kappa^2 + \left(\frac{1}{6} - d\right) i a \kappa^3 + \left(\frac{1}{12} - \frac{1}{2}d\right) \kappa^4. \quad (3.1)$$

Proof Performing a Taylor series expansion,

$$\log \widehat{U}^N = N \log z = -ia\kappa - \kappa^2 + h^2 p(a, d; \kappa) + O(h^4(\kappa^2 + \kappa^8)).$$

The restriction $m < \frac{1}{2}$ ensures that both the leading order error term and the remainder term tend to zero as $h \rightarrow 0$, and hence

$$\begin{aligned} \widehat{U}^N &= \exp(-ia\kappa - \kappa^2) \left\{ 1 + h^2 p(a, d; \kappa) + O(h^4(\kappa^2 + \kappa^8)) \right\} \\ &= \widehat{u}(\kappa, 1) + h^2 \exp(-ia\kappa - \kappa^2) \left\{ p(a, d; \kappa) + O(h^2(\kappa^2 + \kappa^8)) \right\}. \end{aligned}$$

A more detailed proof [6] gives precise bounds on the remainder term. ■

Proposition 2 (High wavenumber region)

For $h^{-m} < |\kappa| < \pi/h$, as $h \rightarrow 0$ with $Nk = 1$ and $d = k/h^2$ held fixed with $d < \frac{1}{2}$, $\widehat{U}^N = o(h^q)$, for any $q > 0$.

Proof For h sufficiently small so that $|a|h < 1$, then

$$\begin{aligned} |z|^2 &= 1 - 8d \sin^2 \frac{\kappa h}{2} \left(1 - 2d \sin^2 \frac{\kappa h}{2} - \frac{1}{2}(ah)^2 d \cos^2 \frac{\kappa h}{2} \right) \\ &\leq 1 - 8d(1-2d) \sin^2 \frac{\kappa h}{2}. \end{aligned}$$

Since $\sin^2(\theta/2) \geq (\theta/\pi)^2$ for $\theta \in [0, \pi]$, it follows that for $|\kappa| \leq \pi/h$,

$$|z|^2 \leq 1 - \frac{8d(1-2d)\kappa^2 h^2}{\pi^2} \leq \exp\left(-\frac{8d(1-2d)\kappa^2 h^2}{\pi^2}\right),$$

and hence for fixed $Nk = Ndh^2 = 1$ we obtain

$$|\widehat{U}^N(\kappa)| \leq \exp\left(-\frac{4(1-2d)\kappa^2}{\pi^2}\right) \leq \exp\left(-\frac{4(1-2d)h^{-2m}}{\pi^2}\right).$$

■

3.2 l_∞ and l_1 error estimates

The inverse Fourier transform of $\exp(-ia\kappa - \kappa^2) p(a, d; \kappa)$ is

$$\begin{aligned} e(x) = & -\frac{d}{4\sqrt{2}} a^2 N^{(2)}\left(\frac{x-a}{\sqrt{2}}\right) - \left(\frac{1}{24} - \frac{d}{4}\right) a N^{(3)}\left(\frac{x-a}{\sqrt{2}}\right) \\ & + \left(\frac{1}{48\sqrt{2}} - \frac{d}{8\sqrt{2}}\right) N^{(4)}\left(\frac{x-a}{\sqrt{2}}\right), \end{aligned} \quad (3.2)$$

where $N^{(m)}$ denotes the m^{th} derivative of the Normal distribution $N(x)$. Using the notation $q(h) \simeq r(h)$ to denote that

$$\frac{q(h)}{r(h)} - 1 = o(h), \text{ as } h \rightarrow 0,$$

then we obtain the following bounds for the error $U_j^N - u(x_j, 1)$:

Proposition 3 *For the discretisation (2.2), with fixed $d = k/h^2 < \frac{1}{2}$ as $h \rightarrow 0$,*

$$\|U^n - u(\cdot, 1)\|_{l_\infty} \simeq h^2 \|e\|_{L_\infty}$$

and

$$\|U^n - u(\cdot, 1)\|_{l_1} \simeq h^2 \|e\|_{L_1},$$

except for the specific case $a=0, d=\frac{1}{6}$ for which $e(x)$ is identically zero.

Proof We outline the proof; for additional details see [6]. The inverse Fourier transform gives

$$\begin{aligned} U^N(x) - u(x, 1) = & \frac{1}{2\pi} \int_{|\kappa| < h^{-m}} \left(\widehat{U}^N(\kappa) - \widehat{u}(\kappa, 1)\right) e^{i\kappa x} d\kappa \\ & + \frac{1}{2\pi} \int_{h^{-m} < |\kappa| < \pi/h} \left(\widehat{U}^N(\kappa) - \widehat{u}(\kappa, 1)\right) e^{i\kappa x} d\kappa - \frac{1}{2\pi} \int_{\pi/h < |\kappa|} \widehat{u}(\kappa, 1) e^{i\kappa x} d\kappa. \end{aligned}$$

The last two integrals both gives contributions which are $o(h^q)$ for any $q > 0$, and hence

$$\begin{aligned} U^N(x) - u(x, 1) = & \frac{1}{2\pi} \int_{|\kappa| < h^{-m}} h^2 \exp(-ia\kappa - \kappa^2) p(a, d; \kappa) e^{i\kappa x} d\kappa + O(h^4) \\ = & \frac{1}{2\pi} \int_{-\infty}^{\infty} h^2 \exp(-ia\kappa - \kappa^2) p(a, d; \kappa) e^{i\kappa x} d\kappa + O(h^4) \\ = & h^2 e(x) + O(h^4). \end{aligned}$$

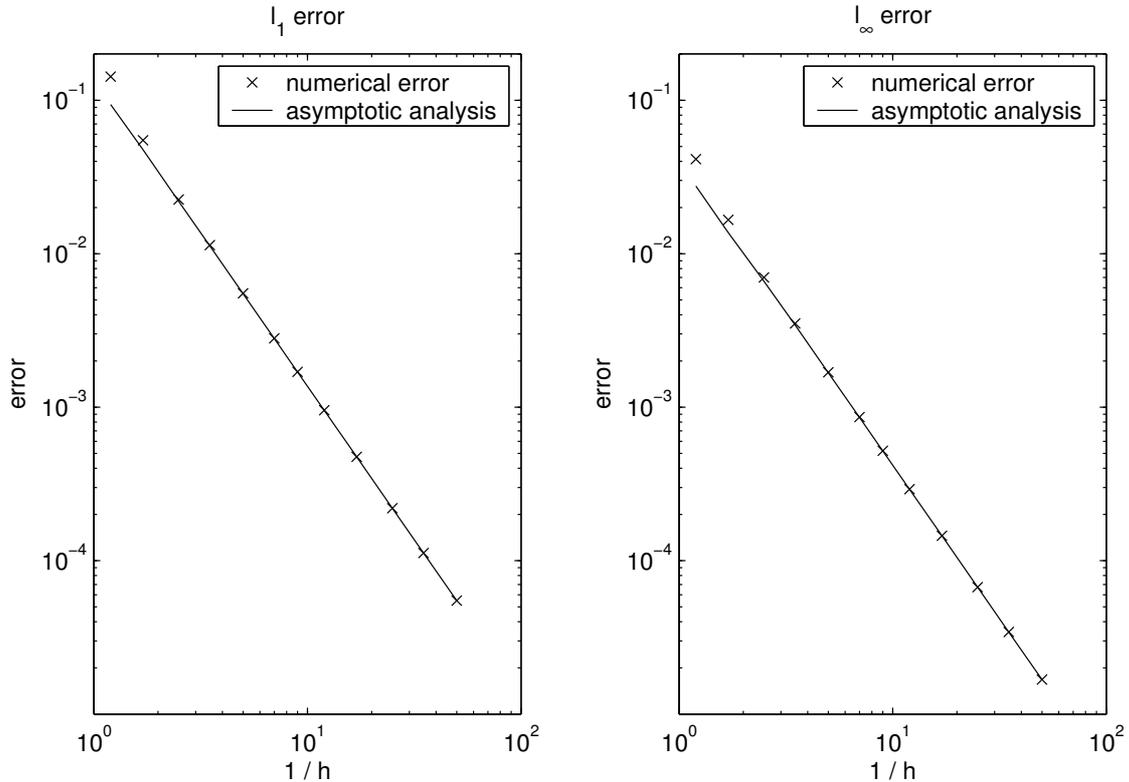


Figure 3: Convergence results for the explicit discretisation

The l_∞ error bound follows immediately; the l_1 error bound requires the additional observation that due to the explicit nature of the discretisation U^N has compact support in a region of width $2Nh = O(h^{-1})$, and $u(x, 1)$ is negligibly small outside this region. ■

Figure 3 presents convergence results obtained on the truncated domain $-10 < x < 10$ and the time interval $0 < t < 1$ using $a = 2$. As the grid spacing h is reduced, the timestep is related to the grid spacing h through $k = dh^2$ with $d = 1/8$. For all but the very largest values of h , there is very good agreement between the numerical errors and the asymptotic analysis of Proposition 3.

4 Crank-Nicolson and Rannacher error analysis

The Fourier analysis in Section 2 gives the solution at the final iteration level $N = 1/k$ (assumed to be greater than R , the number of Crank-Nicolson timesteps replaced by two half-timesteps of Backward Euler time-marching) as

$$U_j^N = \frac{1}{2\pi} \int_{-\pi/h}^{\pi/h} \widehat{U}^N(\kappa h) e^{i\kappa x_j} d\kappa,$$

where

$$\widehat{U}^N(\theta) = z_1^N(\theta) z_2^R(\theta).$$

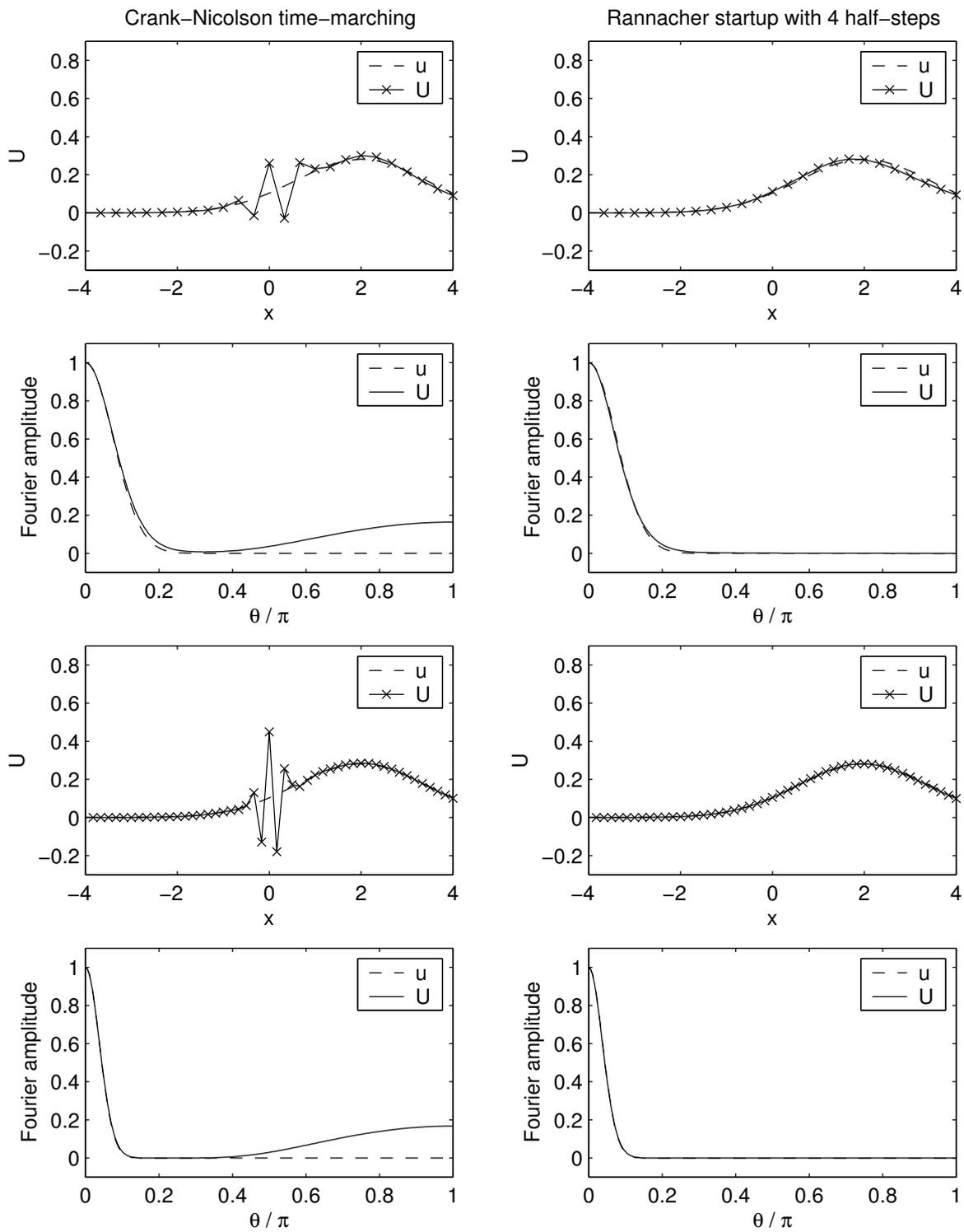


Figure 4: Numerical results for the implicit discretisations

Figure 4 plots comparisons between the numerical and analytic solutions to the convection-diffusion problem with $a=2$ at the final time $t=1$ for two grid resolutions, $h=1/3$ for the upper half of the figure, and $h=1/6$ for the lower half. The timestep is chosen so that $\lambda = k/h = 3/4$ in each case. The plots on the left are for Crank-Nicolson without any Rannacher startup, whereas the plots on the right are for $R=2$, replacing the first two Crank-Nicolson timesteps by four half-timesteps of Backward Euler integration.

The main feature of the results in physical space (i.e. the plots of U and u versus x) is the high-wavenumber error near $x=0$ for the Crank-Nicolson time-marching. Asymptotic analysis will show its width is proportional to h , and its magnitude is proportional to h^{-1} . Looking at the comparison in Fourier space (i.e. the plots of $|\widehat{U}|$ and $|\widehat{u}|$ versus θ) in the Crank-Nicolson results there appear to be three regions: an $O(h)$ region on the left in which $\widehat{u} \approx \widehat{U}$, an $O(1)$ region on the right in which $\widehat{u} \ll 1$ but $\widehat{U} = O(1)$, and a central region in which both $\widehat{u} \ll 1$ and $\widehat{U} \ll 1$. This is the basis for the asymptotic analysis, which considers a low wavenumber range defined by $|\kappa| < h^{-m}$, a high wavenumber range defined by $h^{-q} < |\kappa|$, and the intermediate range $h^{-m} < |\kappa| < h^{-q}$, with m and p satisfying the constraints $0 < m < \frac{1}{3}$ and $\frac{1}{2} < q < 1$ for reasons to be explained later.

The convergence analysis considers the limit $h, k \rightarrow 0$ with $\lambda = k/h$ held fixed. The reason for this choice of limit is that the truncation error due to the spatial central differencing and the Crank-Nicolson time integration is $O(k^2 + h^2)$, and so $k = \lambda h$ keeps the spatial and temporal approximation errors of the same order. We now analyse the Fourier error $\widehat{U} - \widehat{u}$ in each of the three regions.

Proposition 4 (Low wavenumber region)

For $|\kappa| < h^{-m}$, as $h \rightarrow 0$ with $\lambda = k/h$ held fixed,

$$\widehat{U}^N(\kappa) - \widehat{u}(\kappa, 1) = h^2 \exp(-ia\kappa - \kappa^2) \left\{ p(a, \lambda, R; \kappa) + O(h(\kappa^3 + \kappa^9)) \right\},$$

where

$$p(a, \lambda, R; \kappa) = \frac{1}{6}ia\kappa^3 + \frac{1}{12}\kappa^4 - \frac{1}{12}\lambda^2\kappa^3(ia + \kappa)^3 + \frac{1}{4}R\lambda^2\kappa^2(ia + \kappa)^2.$$

Proof Setting $\theta = \kappa h$, $N = \frac{1}{k} = \frac{1}{\lambda h}$, $r = a\lambda$, $d = \frac{\lambda}{h}$, a Taylor series expansion in h gives

$$\log \widehat{U}^N = N \log z_1 + R \log z_2 = -ia\kappa - \kappa^2 + h^2 p(a, \lambda, R; \kappa) + O(h^3(\kappa^3 + \kappa^9)).$$

The restriction that $m < \frac{1}{3}$ ensures that the $h^2\kappa^6$ term and the $h^3\kappa^9$ remainder both tend to zero as $h \rightarrow 0$, and hence

$$\widehat{U}^N = \exp(-ia\kappa - \kappa^2) \left\{ 1 + h^2 p(a, \lambda, R; \kappa) + O(h^3(\kappa^3 + \kappa^9)) \right\}.$$

■

Proposition 5 (High wavenumber region)

For $h^{-q} < |\kappa|$, as $h \rightarrow 0$ with $\lambda = k/h$ held fixed,

$$\widehat{U}^N = (-1)^{N-R} \frac{h^{2R}}{(2\lambda \sin^2 \frac{\theta}{2})^{2R}} \exp\left(-\frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}}\right) \left(1 + O(h\theta^{-2})\right).$$

Proof

$$\begin{aligned} z_1(\theta) &= \left(1 - \frac{1}{2}ir \sin \theta - 2d \sin^2 \frac{\theta}{2}\right) \left(1 + \frac{1}{2}ir \sin \theta + 2d \sin^2 \frac{\theta}{2}\right)^{-1} \\ &= \left(\frac{1}{2d \sin^2 \frac{\theta}{2}} - \frac{ir}{2d} \cot \frac{\theta}{2} - 1\right) \left(\frac{1}{2d \sin^2 \frac{\theta}{2}} + \frac{ir}{2d} \cot \frac{\theta}{2} + 1\right)^{-1} \\ &\longrightarrow -1 \quad \text{as } d \rightarrow \infty, \end{aligned}$$

and similarly

$$\begin{aligned} z_2(\theta) &= \left(2d \sin^2 \frac{\theta}{2}\right)^{-2} \left(\frac{1}{2d \sin^2 \frac{\theta}{2}} - \frac{ir}{2d} \cot \frac{\theta}{2} - 1\right)^{-1} \left(\frac{1}{2d \sin^2 \frac{\theta}{2}} + \frac{ir}{2d} \cot \frac{\theta}{2} + 1\right)^{-1} \\ &\longrightarrow -\left(2d \sin^2 \frac{\theta}{2}\right)^{-2} \quad \text{as } d \rightarrow \infty, \end{aligned}$$

Hence, expressing d and N as functions of h as in the proof of Proposition 4, Taylor series analysis gives

$$\log \left\{ (-1)^{N-R} \widehat{U}^N \right\} = 2R \log \frac{h}{2\lambda \sin^2 \frac{\theta}{2}} - \frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}} + O\left(\frac{h}{\sin^2 \frac{\theta}{2}}\right).$$

The restriction that $q > \frac{1}{2}$ ensures that the remainder term tends to zero as $h \rightarrow 0$, and therefore we obtain the result in the Proposition. ■

Proposition 6 (Intermediate region)

For $h^{-m} < |\kappa| < h^{-q}$, as $h \rightarrow 0$ with $\lambda = k/h$ held fixed, $\widehat{U}^N(\kappa) = o(h^r)$, for any $r > 0$.

Proof Defining $s = \sin^2 \frac{\theta}{2}$,

$$|z_1|^2 = \frac{(1-ds)^2 + r^2s(1-s)}{(1+ds)^2 + r^2s(1-s)}.$$

Differentiating, one finds that $d|z_1|^2/ds = 0$ when $s^2 = (d^2 - r^2)^{-1}$. Substituting $r = a\lambda$, $d = \frac{\lambda}{h}$, this shows that as $h \rightarrow 0$, $|z_1|$ has a maximum at $s = 0, 1$, and a minimum at $s \approx d^{-1}$, corresponding to $\kappa = O(h^{-1/2})$ which lies within the intermediate region. Noting that for any $r > 0$, the Proposition 4 and 5 prove that $|z_1|^N = o(h^r)$ at both $\kappa = h^{-m}$ and $\kappa = h^{-q}$, it follows that $|z_1|^N = o(h^r)$ within the entire intermediate region. Since $|z_1^N z_2^R| < |z_1|^{N-R}$, it follows that $\widehat{U}^N = o(h^r)$ for any $r > 0$. ■

Defining

$$\widehat{E}^{low} = h^2 \exp(-ia\kappa - \kappa^2) p(a, \lambda, R; \kappa),$$

and

$$\widehat{E}^{high} = (-1)^{N-R} \frac{h^{2R}}{(2\lambda \sin^2 \frac{\theta}{2})^{2R}} \exp\left(\frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}}\right),$$

then since $\widehat{E}^{low} \ll \widehat{E}^{high}$ in the high wavenumber region, and $\widehat{E}^{high} \ll \widehat{E}^{low}$ in the low wavenumber region, the results above can be combined to give

$$\widehat{U}^N(\kappa) - \widehat{u}(\kappa, 1) \approx \widehat{E}^{low} + \widehat{E}^{high}, \quad |\kappa| < \pi/h.$$

The inverse Fourier transform then gives

$$U_j^N - u(x_j, 1) \approx E_j^{low} + E_j^{high},$$

where the low wavenumber error is

$$\begin{aligned} E_j^{low} = h^2 & \left\{ \frac{R a^2 \lambda^2}{8\sqrt{2}} N^{(2)}\left(\frac{x_j - a}{\sqrt{2}}\right) \right. \\ & - \frac{2a + a^3 \lambda^2 + 6R a \lambda^2}{48} N^{(3)}\left(\frac{x_j - a}{\sqrt{2}}\right) \\ & + \frac{1 + 3a^2 \lambda^2 + 3R \lambda^2}{48\sqrt{2}} N^{(4)}\left(\frac{x_j - a}{\sqrt{2}}\right) \\ & - \frac{a \lambda^2}{32} N^{(5)}\left(\frac{x_j - a}{\sqrt{2}}\right) \\ & \left. + \frac{\lambda^2}{96\sqrt{2}} N^{(6)}\left(\frac{x_j - a}{\sqrt{2}}\right) \right\}, \end{aligned}$$

and the high wavenumber error is

$$E_j^{high} = (-1)^{N-R} h^{2R-1} (2\lambda)^{-2R} f_j,$$

where

$$\begin{aligned} f_j &= \frac{h}{2\pi} \int_{-\pi/h}^{\pi/h} \frac{e^{-i\kappa x_j}}{\sin^{4R} \frac{\theta}{2}} \exp\left(-\frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}}\right) d\kappa \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{e^{-ij\theta}}{\sin^{4R} \frac{\theta}{2}} \exp\left(-\frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}}\right) d\theta \\ &= \frac{1}{\pi} \int_0^{\pi} \frac{\cos j\theta}{\sin^{4R} \frac{\theta}{2}} \exp\left(-\frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}}\right) d\theta. \end{aligned}$$

E_j^{high} clearly has a width which is $O(h)$, and has a maximum magnitude at $j=0$ where $x_j=0$, which explains the observed behaviour in Figure 4. The integral for $j=0$ can be evaluated analytically (see Appendix A) giving

$$\max_j |E_j^{high}| = |E_0^{high}| = h^{2R-1} (2\lambda)^{-2R} \frac{d^{2R}}{d\beta^{2R}} \operatorname{erfc}(\sqrt{\beta}),$$

where $\beta = \lambda^{-2}$ and $\operatorname{erfc}(x)$ is the complementary error function.

The fact that the low wavenumber is $O(h^2)$ and the high wavenumber error is $O(h^{2R-1})$ is confirmed by the results in the upper plots of Figure 5, which shows convergence results for the convection-diffusion case with $a = 2$. It can be seen that for the standard Crank-Nicolson time-marching, the results exhibit $O(h^2)$ convergence until

h reaches a sufficiently small value that the $O(h^{-1})$ high wavenumber error becomes dominant. The plots show the sensitive dependence of the high wavenumber error on the value of λ . For large values of λ , $\operatorname{erfc}(\lambda^{-1}) \approx 1$ and so E_j^{high} becomes significant for quite large values of h . On the other hand, for small values of λ , $\operatorname{erfc}(\lambda^{-1})$ is extremely small, and so E_j^{high} does not become dominant until h is extremely small. With the Rannacher startup with four half-timesteps of Backward Euler integration ($R=2$), the high wavenumber error is $O(h^3)$ and so the low wavenumber error remains dominant for all h . The sharpness of the error analysis is demonstrated by the lower plots in the figure, which compare the numerical error with the maximum magnitude of E_j^{low} and E_j^{high} .

5 Extensions

5.1 Diffusion coefficient and terminal time

The error analysis of the convection-diffusion equation

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = \epsilon \frac{\partial^2 u}{\partial x^2},$$

and the terminal time $t=T$ is handled through the non-dimensionalisation

$$\bar{t} = \frac{t}{T}, \quad \bar{x} = \frac{x}{\sqrt{\epsilon T}}, \quad \bar{k} = \frac{k}{T}, \quad \bar{h} = \frac{h}{\sqrt{\epsilon T}}, \quad \bar{a} = \sqrt{\frac{T}{\epsilon}} a, \quad \bar{U}_j^n = \sqrt{\epsilon T} U_j^n,$$

which reduces the more general problem to the one which has already been analysed.

5.2 Alternative initial data

The analysis so far has assumed that there is a grid point at $x=0$, so the grid is perfectly aligned with the discrete Dirac initial data. If the grid points x_j are still located at jh , but instead of j taking integer values it is $j+\alpha$ which takes integer values (with $0 < \alpha < 1$) then the appropriate discretisation of the Dirac initial data is

$$U_j^0 = \begin{cases} (1-\alpha) h^{-1}, & j = -\alpha, \\ \alpha h^{-1}, & j = 1 - \alpha, \\ 0, & \text{otherwise.} \end{cases}$$

This gives

$$\widehat{U}_m^0 = (1-\alpha) e^{-i\alpha\theta_m} + \alpha e^{i(1-\alpha)\theta_m}.$$

Putting $\theta_m = \kappa h$, an asymptotic expansion with respect to h gives

$$\widehat{U}_m^0 = 1 + O(\kappa^2 h^2),$$

which leads to the result that the low wavenumber error remains second order. Further analysis shows that the convergence order of the high wavenumber error in the implicit discretisations is also unaffected.

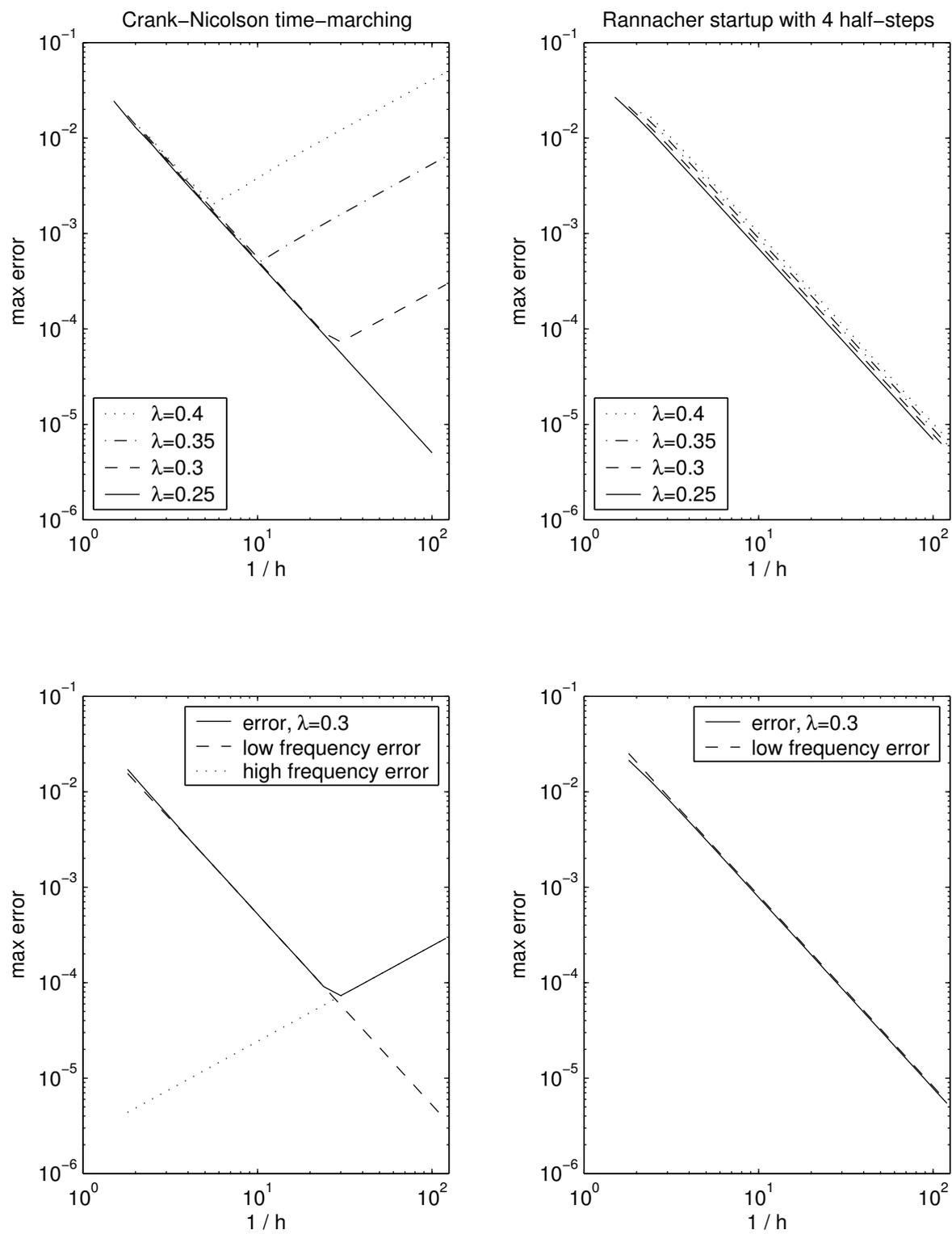


Figure 5: Convergence results for the implicit discretisations

Although the focus of our analysis so far has been on Dirac initial data, there are other sets of initial data which are also of interest. One is the first difference of the discrete Dirac initial data, defined at half-integer locations,

$$U_j^0 = h^{-2} (\delta_{j,-1/2} - \delta_{j,1/2}) \equiv \begin{cases} -h^{-2}, & j = 1/2, \\ h^{-2}, & j = -1/2, \\ 0, & \text{otherwise,} \end{cases}$$

for which

$$\widehat{U}_m^0 = \frac{2i \sin \frac{\theta_m}{2}}{h},$$

leading to

$$U_j^n = \frac{1}{2\pi h^2} \int_{-\pi}^{\pi} 2i \sin \frac{\theta}{2} z^n(\theta) \exp(ij\theta) d\theta.$$

Another is a discrete equivalent of $H(x) - \frac{1}{2}$, where $H(x)$ is the Heaviside step function, which is again defined at half-integer locations,

$$U_j^0 = \begin{cases} -\frac{1}{2}, & -J/2 < j < 0, \\ \frac{1}{2}, & 0 < j < J/2, \end{cases}$$

for which

$$\widehat{U}_m^0 = \frac{h(1 - (-1)^m)}{2i \sin \frac{\theta_m}{2}},$$

leading to

$$U_j^n = \frac{1}{2\pi} PV \int_{-\pi}^{\pi} \left(2i \sin \frac{\theta}{2}\right)^{-1} z^n(\theta) \exp(ij\theta) d\theta,$$

where PV denotes the Cauchy principal value about $\theta=0$ where the integrand is singular.

For both of these sets of alternative initial data, the low wavenumber error will still be $O(h^2)$. However, in the implicit discretisation error analysis, the high wavenumber error will be one order worse in the first case, $O(h^{-2+2R})$ where R is again the number of Crank-Nicolson timesteps replaced by two half-timesteps of Backward Euler integration, and one order better in the second case, $O(h^{2R})$.

6 Conclusions

In this paper we have derived sharp estimates for the error arising from explicit and implicit discretisations of the constant coefficient 1D convection/diffusion equation subject to Dirac initial data.

The extension of the Fourier analysis to multiple dimensions would pose no particular difficulties. To extend the analysis to varying coefficients would not be so easy, but could be performed using a matched inner and outer asymptotic analysis, with the inner analysis in the neighbourhood of the Dirac initial data being performed using the

analysis in this paper, treating the coefficients as being locally approximately constant. The inner solution would then have to be matched to an outer solution describing the subsequent evolution of the solution and the discretisation error in the outer region in which the solution is well resolved, at least asymptotically.

The results in this paper can also be used in circumstances where the viscosity ϵ depends on the mesh spacing h , provided $\bar{h} = h/\sqrt{\epsilon t} \rightarrow 0$. This is important in proving the pointwise convergence of adjoint Burgers equation solutions along characteristics leading into a discontinuity in the underlying nonlinear solution [8].

Regarding the use of Rannacher time-stepping, replacing each of the first R Crank-Nicolson timesteps by two half-timesteps of Backward Euler integration, the analysis proves, and numerical results confirm, that there is a low wavenumber error which is $O(h^2)$, and a high wavenumber error which is $O(h^{2R-1})$. Hence $R=2$ is the minimum to give $O(h^2)$ convergence, and it is likely to be the optimum in general since larger values will increase the low wavenumber error.

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Appendix A Evaluation of integral

Consider the integral

$$I_0 = \frac{1}{\pi} \int_0^\pi \exp\left(-\frac{1}{\lambda^2 \sin^2 \frac{\theta}{2}}\right) d\theta.$$

Making the substitutions $t = \cot \frac{\theta}{2}$ and $\alpha = \lambda^{-1}$, one obtains

$$I_0 = \frac{2}{\pi} \int_0^\infty \frac{1}{t^2+1} \exp(-\alpha^2(t^2+1)) dt,$$

and hence

$$\frac{dI_0}{d\alpha} = -\frac{4\alpha}{\pi} \int_0^\infty \exp(-\alpha^2(t^2+1)) dt = -\frac{2}{\sqrt{\pi}} \exp(-\alpha^2).$$

Since $I_0 \rightarrow 0$ as $\alpha \rightarrow \infty$, integration gives

$$I_0 = \frac{2}{\sqrt{\pi}} \int_{\lambda^{-1}}^\infty \exp(-s^2) ds \equiv \operatorname{erfc}(\lambda^{-1}),$$

where $\operatorname{erfc}(x)$ is the complementary error function.

Switching to a new variable $\beta = \lambda^{-2} = \alpha^2$, then $I_0(\beta) = \operatorname{erfc}(\sqrt{\beta})$, and

$$I_R(\beta) \equiv \frac{1}{2\pi} \int_{-\pi}^\pi \frac{1}{(\sin^2 \frac{\theta}{2})^{2R}} \exp\left(-\frac{\beta}{\sin^2 \frac{\theta}{2}}\right) d\theta = \frac{d^{2R} I_0}{d\beta^{2R}}.$$