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On the predictions and limitations of the Becker–Döring model for reaction kinetics in micellar surfactant solutions

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ABSTRACT

We investigate the breakdown of a system of micellar aggregates in a surfactant solution following an order-one dilution. We derive a mathematical model based on the Becker–Döring system of equations, using realistic expressions for the reaction constants fit to results from Molecular Dynamics simulations. We exploit the largeness of typical aggregation numbers to derive a continuum model, substituting a large system of ordinary differential equations for a partial differential equation in two independent variables: time and aggregate size. Numerical solutions demonstrate that re-equilibration occurs in two distinct stages over well-separated timescales, in agreement with experiment and with previous theories. We conclude by exposing a limitation in the Becker–Döring theory for re-equilibration of surfactant solutions.

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1. Introduction

When surfactant exceeds a particular bulk concentration in solution, termed the *critical micelle concentration* (CMC), it becomes favourable for aggregates or *micelles* to form. The micelles can have various sizes and shapes but for many simple surfactants with a single hydrocarbon chain the aggregates are approximately spherical and contain of the order of 100 monomers [1]. The distribution of aggregate sizes is localized around this optimum value with a half-width of the order of the square root of the aggregation number. Aggregates that are much smaller than the mean aggregation number are energetically highly unfavourable and consequently appear in much lower concentrations [2–5].

The re-equilibration and subsequent restructuring of a micellar surfactant solution upon a disturbance from equilibrium is of great importance for the adsorption kinetics of micellar solutions. Such a process is generally assumed to occur via stepwise monomer loss or gain [2–4], which leads to the Becker–Döring description [6], a special case of Smoluchowski coagulation theory which, more generally, allows all aggregates sizes to combine and dissociate [7]. Coagulation theory has been used to model aggregation in numerous situations (for a review see [8] and references therein). The original Becker–Döring formulation describes a system in which the monomer concentration is held constant. This can be interpreted as a phase transition in which a supersaturated gas condenses to form liquid drops at constant pressure. Penrose and Lebowitz [9]

extend this theory to account for systems which conserve mass. Billingham and Coveney [10] consider the formation of micelles in a system out of thermodynamic equilibrium, and a reduced description of this system which preserves all the properties of the infinite-dimensional Becker–Döring equations is presented by Coveney and Wattis [11]. Coagulation theory has also been analysed in more complex situations, such as within a flowing fluid, with particular application to biological systems. For example, Band et al. [12] combine the Becker–Döring theory with an advection-diffusion model to describe crystal aggregation in the lower urinary tract, while Guy et al. [13] model the formation of a blood clot in a shearing flow.

Aniansson and Wall [2] consider the small dilution of a surfactant with a realistic aggregation distribution, comprised predominantly of either monomers or aggregates localized around the large optimum aggregation number, with aggregates in between occurring at much lower concentrations, and demonstrate re-equilibration on two distinct timescales, termed the τ_1 and τ_2 processes [14]. The first, more rapid, timescale corresponds to the replenishment of monomer via release of individual monomers from aggregates. However, to return the monomer to its equilibrium value requires some aggregates to break down entirely. Some of the monomers released replenish the monomer concentration to its critical value, while the remainder join those aggregates which have not broken down. The associated relaxation times differ by at least three orders of magnitude, with monomer loss occurring on the μs – ms timescale and complete micelle breakdown on the ms – min timescale [1]. Recently, Rusanov et al. [15–19] provided a mathematical analysis of the micellization process, based on

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the Aniansson and Wall kinetic model, that outlines nine characteristic kinetic times of micellization in non-ionic surfactant solutions, although they propose no method of probing these experimentally.

While some temperature-jump and pressure-jump experiments do indeed satisfy the limit of small dilutions examined in [2], there are many physically important situations for which this is not the case. While large-deviation re-equilibration has been well studied in scenarios where there are a finite number of aggregates, all of which occur in equal concentrations at equilibrium (for example [8,12]), the re-equilibration of a surfactant with a realistic aggregate distribution following an order-one dilution has not been analysed in detail. As a consequence, the Aniansson and Wall model has been applied to many situations where the deviations from equilibrium are much too large for the linearized theory to be applicable.

In this paper we use the full Becker–Döring model to investigate the relaxation upon an order-one dilution (which leaves the system above the CMC) of a micellar surfactant solution with a realistic equilibrium aggregate distribution. In this case, the monomer concentration must be replenished to its equilibrium value via the breakdown of some of the aggregates, while a proportion of surfactant will still reside in aggregate form. We describe the mechanism by which this is achieved and the restructuring process of aggregates that ensues, demonstrating that the two-timescale behaviour predicted by Aniansson and Wall for small deviations from equilibrium is still a prominent feature.

Richardson et al. [20] exploit the large number of monomers that typically comprise an aggregate to derive a continuum model for the formation of lipid/protein microdomain structures within plasma membranes which interact via Smoluchowski coagulation theory. Tracking the evolution of a continuous function rather than the concentration of all individual species vastly simplifies the problem, and we employ a similar strategy in this paper.

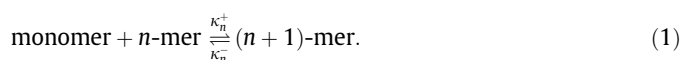
We first validate our continuum model by comparing its predictions with simulations of the discrete Becker–Döring system. We then use this representation to elucidate the two-timescale behaviour and to analyse the two stages of re-equilibration. We show that the relative concentration of smaller aggregates to the micelle concentration is a key parameter, setting the relative timescales at which the two processes occur. The predictions of our models are compared with experimental data obtained from stopped-flow experiments [1].

We conclude by discussing surfactant systems for which our description fails. In such circumstances the assumptions made by the Becker–Döring theory must be relaxed, and a new mechanism for micelle breakdown must exist, which we analyse in a follow-up to this paper.

2. A discrete model

2.1. The Becker–Döring equations

As discussed in Section 1, the self-assembly and dissociation of aggregates is assumed to occur via stepwise monomer loss and gain [2–4], in the following reaction scheme:



Here, we use the term n -mer to denote an aggregate containing n monomers, and κ_n^\pm are the association and dissociation rate coefficients. The reaction kinetics for this system are described by the Becker–Döring equations [6]

$$\frac{d\mathcal{X}_n}{dT} = \kappa_{n-1}^+ \mathcal{X}_1 \mathcal{X}_{n-1} - \kappa_{n-1}^- \mathcal{X}_n - \kappa_n^+ \mathcal{X}_1 \mathcal{X}_n + \kappa_n^- \mathcal{X}_{n+1}, \quad (2)$$

for $n \geq 2$, where $\mathcal{X}_n = \mathcal{X}_n(T)$ denotes the (molar) concentration of an aggregate containing n monomers at time T .

The net bulk concentration of monomer contained in all aggregates is given by

$$C_b = \sum_{n=1}^{\infty} n \mathcal{X}_n. \quad (3)$$

Under the assumption that C_b is conserved for all time, the free monomer concentration is determined by

$$\mathcal{X}_1(t) = C_b - \sum_{n=2}^{\infty} n \mathcal{X}_n(t) = \mathcal{X}_1(0) - \sum_{n=2}^{\infty} n (\mathcal{X}_n(t) - \mathcal{X}_n(0)). \quad (4)$$

Along with (2), this gives us an infinite-dimensional system of ODEs for $\mathcal{X}_2(t), \mathcal{X}_3(t), \dots$. The solution of this system requires us to specify all the initial concentrations $\mathcal{X}_1(0), \mathcal{X}_2(0), \dots$.

For mathematical simplicity, it is customary to truncate the system at some large finite value $n = N$ and to assume that all the reaction rates are equal (see, for example, [21]). This is equivalent to setting

$$\kappa_n^\pm = \begin{cases} \kappa^\pm & 1 \leq n \leq N-1, \\ 0 & n \geq N. \end{cases} \quad (5)$$

As we will see below, this approximation fails to capture the correct physics for many real-life systems, and we will focus on analysing the system (2) with reaction rates consistent with real surfactants.

2.2. The equilibrium distribution

Determination of the aggregate size distribution for different surfactants and different micelle shapes is a subject of extensive debate. Since concentrations in the intermediate aggregate region are orders of magnitude smaller than those close to the optimum aggregation number, there are no direct experimental methods available for their measurement. It is, however, possible to calculate an equilibrium aggregate size distribution from knowledge of the chemical potential differences between monomers in different sized aggregates. This may be done via Molecular Dynamics (MD) simulations [22–24] or by Molecular Thermodynamics (MT) [5,25,26]. Either method predicts a distribution characterized by the following key features. Almost all surfactant material is contained within either a region of *pre-micellar aggregates* (monomer, dimers, trimers etc.) or a region of *proper micelles* close to the peak aggregation number. These are connected by an *intermediate region* containing a very low concentration of aggregates; see Fig. 1. (The change in slope at $n = 90$ arises from a change in the model from a sphere to a rod with spherical end-caps. In reality, micelles will pass through an ellipsoidal shape between spheres and rods that smooths out the distribution.) These predictions are in agreement with experimental techniques such as light-scattering methods or small-angle neutron scattering (SANS) experiments which may be used to determine the optimum aggregation number, and stopped-flow experiments to determine the CMC [1].

In modelling terms, an equilibrium distribution corresponds to a steady solution of the Becker–Döring system. Substitution of $\mathcal{X}_n = \mathcal{X}_n^* = \text{constant}$ into (2) yields a system of algebraic equations to determine \mathcal{X}_n^* , in terms of the reaction coefficients κ_n^\pm and the net surfactant concentration C_b . At equilibrium, the principle of microscopic reversibility requires that each mechanistic step in a reversible reaction must itself be in equilibrium, and so Eq. (2) implies that

$$\kappa_n^+ \mathcal{X}_1^* \mathcal{X}_n^* - \kappa_n^- \mathcal{X}_{n+1}^* \equiv \kappa_i^+ \mathcal{X}_1^* \mathcal{X}_i^* - \kappa_i^- \mathcal{X}_{i+1}^*, \quad (6)$$

for all $n, i \geq 1$. To ensure that the system contains a finite amount of surfactant, we must have $\mathcal{X}_i^* \rightarrow 0$ as $i \rightarrow \infty$, and hence

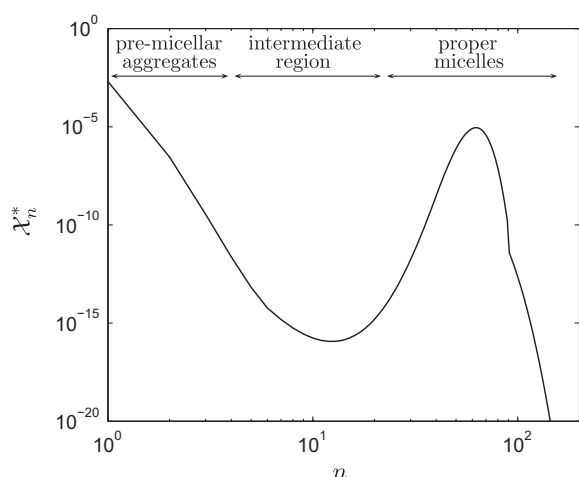


Fig. 1. An equilibrium aggregate size distribution predicted by MD simulation for the polyoxyethylene glycol alkyl ether surfactant C₁₀E₈ at a bulk concentration C_b = 10 mM [1].

$$\kappa_n^+ \chi_1^* \chi_n^* \equiv \kappa_n^- \chi_{n+1}^* \quad (7)$$

for all n . Given the reaction coefficients, (7) determines the equilibrium distribution

$$\chi_n^* = \chi_1^{*n} \prod_{i=1}^{n-1} \left(\frac{\kappa_i^+}{\kappa_i^-} \right), \quad (8)$$

in terms of the monomer concentration χ_1^* , which is related to the net concentration C_b by

$$C_b = \sum_{n=1}^{\infty} n \chi_1^{*n} \prod_{i=1}^{n-1} \left(\frac{\kappa_i^+}{\kappa_i^-} \right). \quad (9)$$

In practice, the reaction rates are not well characterized. Instead, we suppose that the equilibrium distribution itself is known, for some particular bulk concentration C_b , either from MD or from MT, and takes a form similar to that shown in Fig. 1. We can then use (7) to relate the reaction rates:

$$\kappa_n^- = \left(\frac{\chi_1^* \chi_n^*}{\chi_{n+1}^*} \right) \kappa_n^+ \quad (10)$$

for $n \geq 1$, which enforces the principle of microscopic reversibility.

For the association rates, ultrasonic adsorption studies [27,28] suggest that reactions proceed at a diffusion-controlled rate, so that

$$\kappa_n^+ \propto N_A \sigma_n (D_1 + D_n), \quad (11)$$

where N_A is the Avogadro number, D_n represents the diffusion coefficient of an aggregate of size n , and σ_n is the collision radius. We may take σ_n to be the sum of the aggregate radii, $r_1 + r_n$ (with r_n proportional to $n^{1/3}$), and the Stokes–Einstein equation provides a relation between the diffusion coefficient of an aggregate and its size, namely

$$D_n = \frac{k_B T}{6\pi\mu r_n}, \quad (12)$$

where k_B is the Boltzmann constant, and T and μ are the temperature and viscosity of the solution. This provides the estimate

$$\kappa_n^+ \sim \left(\frac{k_B N_A T}{6\pi\mu} \right) \frac{(1 + n^{1/3})^2}{n^{1/3}}, \quad (13)$$

which gives $\kappa_1^+ \sim 6 \times 10^5 \text{ m}^3 \text{ mol}^{-1} \text{ s}^{-1}$ for a surfactant in water at 300 K. For the polyoxyethylene glycol alkyl ether surfactants C₆E₃ and C₈E₆, with CMCs of order 100 mM and 12 mM [29,30], Eq.

(13) predicts reaction timescales of order 10^{-5} s and 10^{-4} s respectively. These are in line with spectroscopic stopped-flow experiments on the C_nE_m series, where rapid re-equilibration is observed to occur before data acquisition begins, that is, on a time-scale less than 10 ms [1].

We note that the estimate (13) predicts rather weak dependence of the association rates upon aggregate size; for example κ_{200}^+ is roughly twice κ_1^+ . In contrast, we will see that the dissociation rates κ_n^- vary significantly with n . As a first approximation, we will therefore suppose henceforth in this paper that the association rates are all equal. Given an equilibrium distribution χ_n^* , we may thus use (10) to determine all the reaction rates

$$\kappa_n^+ = \kappa_1^+, \quad \kappa_n^- = \left(\frac{\chi_1^* \chi_n^*}{\chi_{n+1}^*} \right) \kappa_1^+, \quad (14)$$

for $n = 2, 3, 4, \dots$, in terms of a single rate constant κ_1^+ .

The continuum model we derive in Section 3 is valid for any equilibrium distribution χ_n^* resembling that shown in Fig. 1, with surfactant concentrated in narrow neighbourhoods of $n = 1$ and $n = m$ (the peak aggregation number), separated by an intermediate region of very low concentration. However, we will find it helpful to fix ideas by focusing on a particular fit to the equilibrium distribution, namely

$$\begin{aligned} \frac{\chi_n^*}{\chi_1^*} &= A \exp(b - bn) + \frac{B}{m^{3/2}} \exp(-\beta m(n/m - 1)^2) \\ &+ \frac{C}{m^2} \exp(-dn/m), \end{aligned} \quad (15)$$

where A, B, C, b, β, d and m are fitting parameters. The first term represents the spike at $n = 1$ and the small number of pre-micellar aggregates. The second term captures the distribution of proper micelles with a width determined by β . The third term is a slowly decaying exponential to represent the concentration of intermediate aggregates: the value of C can be used to control the ratio of maximum to minimum aggregate concentrations. The scaling of the second and third terms by $m^{-3/2}$ and m^{-2} , respectively, ensures that the importance of these terms relative to each other and to the monomer concentration depends on the coefficients A, B and C and not on the most probable aggregation number, m . The distribution (15) captures the key features predicted by MT illustrated in Fig. 1. In particular, the largeness of m ensures the high relative concentration of monomer to aggregates, as well as a narrow Gaussian spread around $n = m$.

We can fix two parameters, for example A and B , by requiring the right-hand side of (15) to be equal to 1 when $n = 1$ and by specifying the net concentration:

$$1 = A + \frac{B}{m^{3/2}} e^{-\beta(m-1)^2/m} + \frac{C}{m^2} e^{-d/m}, \quad (16)$$

$$C_b = \frac{C_b}{\chi_1^*} = \frac{A}{(1 - e^{-b})^2} + \frac{B}{m^{3/2}} \sum_{n=1}^{\infty} n e^{-\beta m(n/m-1)^2} + \frac{C e^{-d/m}}{m^2 (1 - e^{-d/m})^2}. \quad (17)$$

Here we have introduced for convenience the dimensionless bulk concentration C_b , scaled with the equilibrium monomer concentration χ_1^* . In Fig. 2, we show a typical MD prediction for the surfactant C₆E₃ alongside our ansatz (15), with chosen parameter values $b = 4.7, \beta = 0.765, C = 3.47 \times 10^{-4}, d = 2.72, C_b = 10$ and $m = 34$ from which we infer that $A \approx 1$ and $B \approx 2.26$.

For many realistic surfactants, the concentration of aggregates in the intermediate region is extremely low, which corresponds to very small values of C . As we will find, this leads to extreme separation of timescales in the re-equilibration process: rapid dissociation via stepwise monomer release followed by excruciatingly slow micelle reassembly to reach the equilibrium. To begin with, we shall consider systems for which C is not too small, which

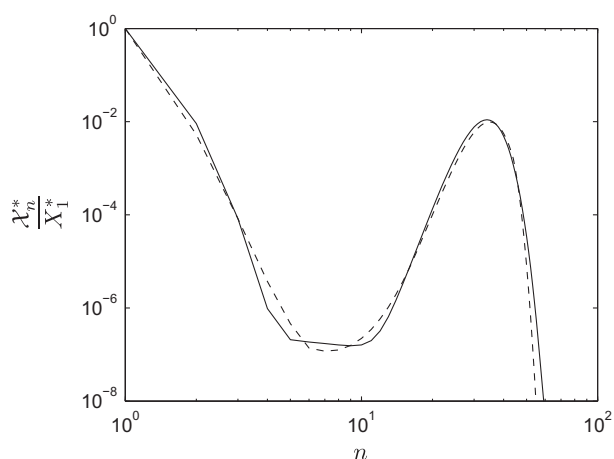


Fig. 2. Comparison between discrete equilibrium distribution for the surfactant C_6E_3 at a bulk concentration $C_b = 10$, predicted by MT (dashed) and the ansatz (15) (solid) with $A = 1$, $b = 4.7$, $B = 2.26$, $\beta = 0.765$, $m = 34$, $C = 3.47 \times 10^{-4}$, $d = 2.72$ [31].

serves to illustrate the behaviour without compromising computational expediency.

2.3. The post-dilution distribution

We now consider a surfactant system that starts in equilibrium with a known distribution, $\mathcal{X}_n = \mathcal{X}_n^*$, before being instantaneously diluted. Upon dilution of the system by a factor $D > 1$, the initial distribution $\mathcal{X}_n(0)$ becomes \mathcal{X}_n^*/D , and the new equilibrium distribution, say $\bar{\mathcal{X}}_n$, satisfies

$$\frac{\bar{\mathcal{X}}_1 \bar{\mathcal{X}}_n}{\bar{\mathcal{X}}_{n+1}} = \frac{\mathcal{X}_1^* \mathcal{X}_n^*}{\mathcal{X}_{n+1}^*}, \quad (18)$$

for $n \geq 1$, from (2) and (10), assuming that the rate constants κ_n^\pm are unaffected by a dilution. Eq. (18) may be used recursively to give

$$\bar{\mathcal{X}}_n = \nu^n \mathcal{X}_n^*, \quad (19)$$

for $n \geq 1$, where ν is determined implicitly by

$$\sum_{n=1}^{\infty} n \mathcal{X}_n^* (1 - D\nu^n) = 0, \quad (20)$$

which enforces conservation in the total amount of surfactant before and after dilution. From (19) we note that the parameter ν represents the ratio of the equilibrium monomer concentration following dilution to the concentration before dilution.

In Fig. 3 we plot the dependence of ν on the dilution factor D for the equilibrium distribution (15) with illustrative parameter values $b = 10$, $C = 0.5$, $d = 1$, $\beta = 0.2$, $m = 100$ and $C_b = 10$, from which we deduce that $A \approx 1$ and $B \approx 2.27$. Provided we dilute by a factor $D < C_b$ so that there remains sufficient surfactant to replenish the depleted monomer to its critical value, then ν remains close to 1. In this case, the equilibrium monomer concentration $\bar{\mathcal{X}}_1$ after dilution is only slightly smaller than the pre-dilution equilibrium concentration \mathcal{X}_1^* . On the other hand, when the solution is diluted so that the total bulk concentration is below \mathcal{X}_1^* , there is insufficient surfactant in the form of aggregates to replenish the monomer to the CMC, and ν then decreases significantly. In Fig. 3 this is clearly evident upon dilution by a factor $D > C_b = 10$ in this case. These observations reinforce the fact that, as surfactant is added to solution, it exists only in monomer form until the bulk concentration reaches a well-defined critical concentration (the CMC), while further increases in bulk concentration increase the monomer concentration only marginally, so that the majority of the excess surfactant exists in aggregate form.

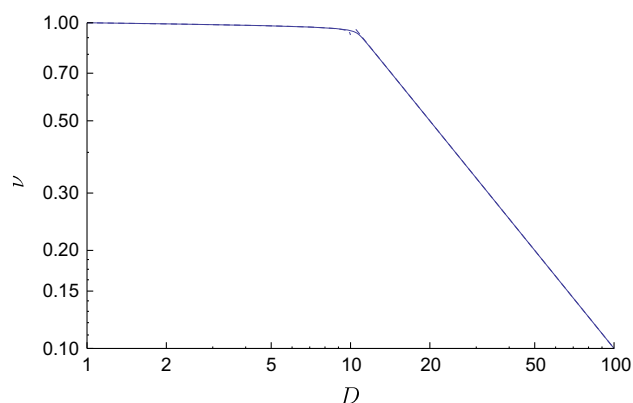


Fig. 3. The dependence of the parameter ν on the dilution ratio D for the equilibrium distribution (15) with parameter values $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$ and $C_b = 10$. The dashed curves show the asymptotic prediction (21).

The distinctive form of the graph shown in Fig. 3 may be understood by analysing the implicit relation (20) asymptotically in the limit $m \rightarrow \infty$. The analysis outlined in Section 3.2 shows that ν and D are related approximately by

$$\nu \sim \begin{cases} \left(\frac{C_b - D}{(C_b - 1)D} \right)^{1/m} & D < C_b, \\ \frac{C_b}{D} & D > C_b. \end{cases} \quad (21)$$

These are shown in Fig. 3 as dashed curves, which are virtually indistinguishable from the exact relation (20).

Using the formula (15) to fit the pre-dilution equilibrium distribution \mathcal{X}_n^* , we find that the initial and equilibrium states following dilution have exactly the same form, namely

$$\frac{\mathcal{X}_n(0)}{\bar{\mathcal{X}}_1} = A_0 \exp(b - bn) + \frac{B_0}{m^{3/2}} \exp(-\beta m(n/m - 1)^2) + \frac{C_0}{m^2} \exp(-dn/m), \quad (22)$$

$$\frac{\bar{\mathcal{X}}_n}{\bar{\mathcal{X}}_1} = A \exp(\bar{b} - \bar{b}n) + \frac{\bar{B}}{m^{3/2}} \exp(-\bar{\beta} \bar{m}(n/\bar{m} - 1)^2) + \frac{\bar{C}}{m^2} \exp(-\bar{d}n/m), \quad (23)$$

where

$$A_0 = \frac{A}{\nu D}, \quad B_0 = \frac{B}{\nu D}, \quad C_0 = \frac{C}{\nu D}, \quad \bar{b} = b - \log \nu, \quad \bar{B} = B \nu^{m-1} \exp\left(\frac{m \log^2 \nu}{4\beta}\right), \quad \bar{C} = \frac{C}{\nu}, \quad (24a-j)$$

$$\bar{\beta} = \bar{\omega} \beta, \quad \bar{m} = \bar{\omega} m, \quad \bar{d} = d - m \log \nu,$$

and

$$\bar{\omega} = 1 + \frac{\log \nu}{2\beta}. \quad (25)$$

Eq. (23) implies that the dilution has the effect of shifting the optimum aggregation number from m to \bar{m} , given by (24f). We illustrate the dependence of the ratio $\bar{\omega} = \bar{m}/m$ on the dilution ratio D in Fig. 4, for the equilibrium distribution (15). The dashed curves show the leading-order approximations corresponding to (21) in the limit $m \rightarrow \infty$, namely

$$\bar{\omega} \sim \begin{cases} 1 - \frac{1}{2m\beta} \log\left(\frac{(C_b - 1)D}{C_b - D}\right) & D < C_b, \\ 1 - \frac{1}{2\beta} \log\left(\frac{D}{C_b}\right) & D > C_b. \end{cases} \quad (26)$$

So long as $D < C_b$, we observe that $1 - \bar{\omega} = O(1/m)$, where m is chosen to be large. The peak in the distribution is thus shifted only very slightly to the left by the dilution. This result validates the common assumption that the optimum aggregation number in a micellar

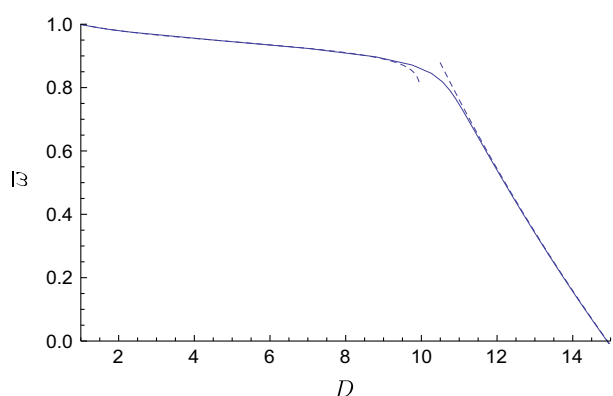


Fig. 4. The dependence of the post-dilution peak aggregation number $\bar{\omega}$ on the dilution ratio D for the equilibrium distribution (15) with parameter values $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$ and $C_b = 10$. The dashed curves show the asymptotic prediction (26).

solution is constant for a given surfactant. However, when the dilution is increased above the value C_b , the optimum aggregate size falls rapidly, with surfactant predominantly residing in monomer form for finite dilution ratios $D \gtrsim e^{2\beta}C_b$. This models the break-up of aggregates into monomers as the net bulk concentration falls below the CMC.

2.4. Non-dimensionalization and scaling

We scale the concentrations following dilution with the equilibrium monomer post-dilution concentration $\bar{\mathcal{X}}_1 = \nu\mathcal{X}_1^*$, while an

appropriate timescale is set by the monomer association rate. We therefore define the dimensionless quantities X_n, \bar{X}_n and τ as follows:

$$X_n = \bar{\mathcal{X}}_1 X_n, \quad \bar{X}_n = \bar{\mathcal{X}}_1 \bar{\mathcal{X}}_n, \quad \mathcal{T} = \frac{\tau}{\kappa_1^+ \bar{\mathcal{X}}_1}. \quad (27a-c)$$

The non-dimensional initial and final distributions are then given by

$$X_n(0) = \frac{1}{\nu D} \frac{\mathcal{X}_n^*}{\mathcal{X}_1^*}, \quad \bar{X}_n = \nu^{n-1} \frac{\mathcal{X}_n^*}{\mathcal{X}_1^*}, \quad (28a, b)$$

for $n \geq 1$. As described above, the parameter ν is determined from (20) for a given initial distribution \mathcal{X}_n^* and dilution factor D .

The non-dimensional Becker–Döring Eqs. (2), (4) may be written as

$$\frac{dX_n}{d\tau} = X_1 X_{n-1} - \frac{\bar{X}_{n-1}}{\bar{X}_n} X_n - X_1 X_n + \frac{\bar{X}_n}{\bar{X}_{n+1}} X_{n+1}, \quad (29a)$$

$$X_1 = 1 - \sum_{n=2}^{\infty} n(X_n - \bar{X}_n), \quad (29b)$$

where we have used (14) to eliminate the rate constants κ_n^{\pm} . Given the initial post-dilution distribution (28a), the system of Eq. (29) is used to determine the evolution towards the equilibrium (28b).

2.5. Numerical solutions

In Fig. 5 we show the evolution of a typical distribution of aggregates, given by (15), with $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$,

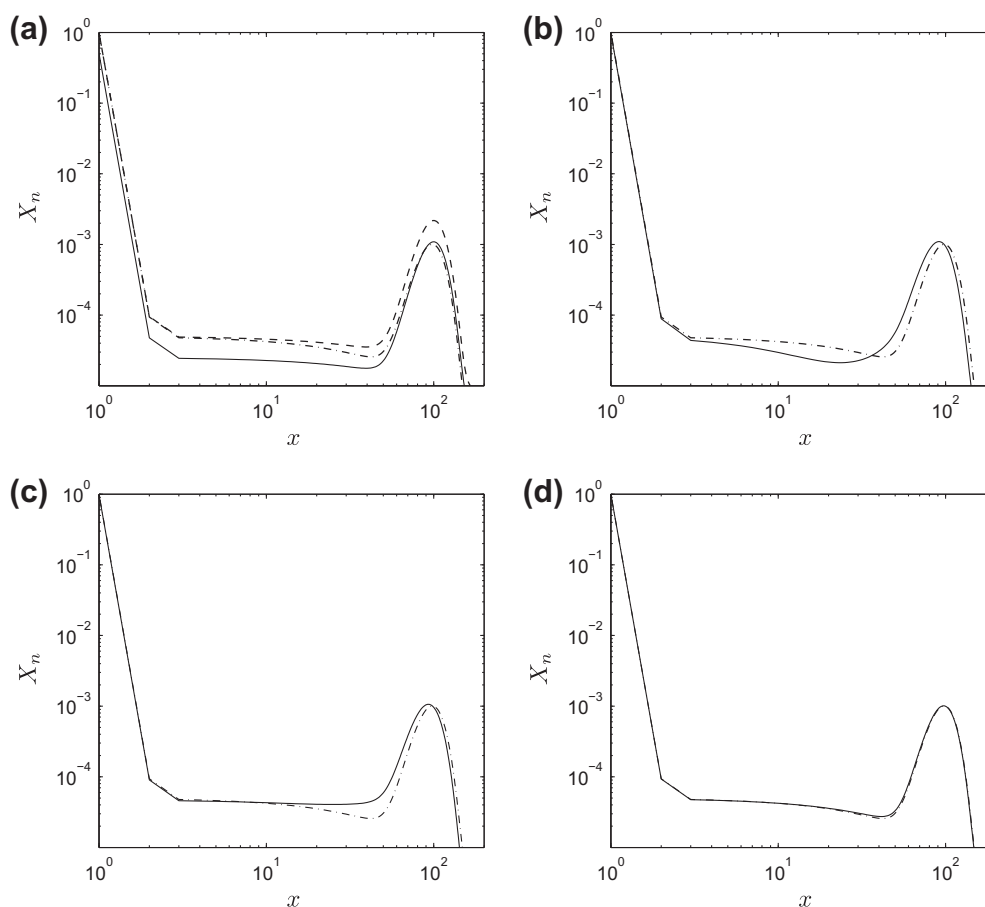


Fig. 5. The solid curve shows the evolution of an initial pre-dilution distribution given by (15) with $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$, $C_b = 10$ and $D = 2$, at (a) $\tau = 0$, (b) $\tau = 100$, (c) $\tau = 500$, (d) $\tau = 5000$. The dot-dash line shows the equilibrium distribution. The pre-dilution distribution is shown as a dashed line in (a).

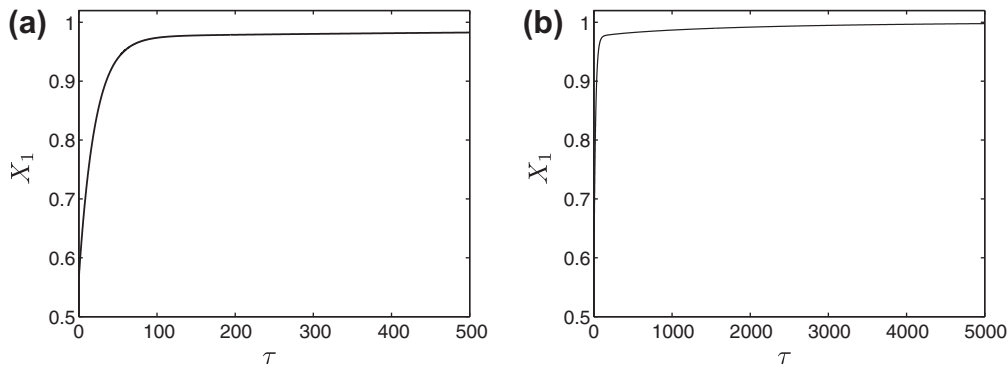


Fig. 6. Monomer concentration $X_1(\tau)$ versus time for the pre-dilution distribution (15) with $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$, $C_b = 10$ and $D = 2$ on (a) the τ_1 timescale, (b) the τ_2 timescale.

$m = 100$ and $C_b = 10$, upon a two-fold dilution. We solve (20) to give $v \approx 0.992$ in this case, highlighting again the weak dependence of the equilibrium monomer concentration on the dilution factor provided the bulk concentration exceeds the CMC. We then solve the system (29) numerically.

As predicted for re-equilibration following a weak dilution [2–4], the generic behaviour of the system is via a two-stage process. Firstly, the position of the micelle peak shifts to the left while retaining its magnitude, as aggregates shed individual monomers to replenish the concentration of monomers. This is called the τ_1 process [2–4]. However, since the energetic stability of aggregates falls rapidly with decreasing aggregation number, this process becomes unfeasible before it has supplied enough material to replenish the monomer to its new equilibrium value. As a result, some of the aggregates have to break down completely to replenish the monomer fully to the new equilibrium. The remaining monomers associate with those aggregates which have not broken down to increase their typical aggregation number and hence their energetic stability. Thus the position of the peak in the aggregate distribution moves to the right and reduces in magnitude. This second process is called the τ_2 process [2–4]. The τ_2 process is governed by the rate at which micelles are able to break down entirely, which is set by the concentration of aggregates in the intermediate region: the lower the concentration of aggregates, the longer the time taken to re-equilibrate. These two distinct mechanisms are clearly illustrated in the graph of monomer concentration X_1 versus time in Fig. 6. The monomer concentration initially rises rapidly, over a timescale of $0 \leq \tau \lesssim 100$ before the rate of replenishment slows, finally reaching equilibrium when $\tau \approx 5000$.

3. A continuum model

3.1. Introduction

In Figs. 2 and 5 we exploited the largeness of the optimum aggregation number m by joining the discrete set of values for each species concentration to form a smooth curve. Tracking the evolution of a single continuous function rather than the concentration of many aggregates provides a welcome simplification and invites us to seek a continuum limit to the Becker–Döring Eq. (29) in the limit $1/m \rightarrow 0$. This approach both reduces the numerical complexity of the problem and uncovers analytical simplifications which provide deeper insight into the re-equilibration process. Richardson et al. [20] utilize a similar approach to model the formation of lipid/protein microdomain structures within plasma membranes.

To implement our continuum model, we first exploit the fact that, in our distribution representation (15), the first exponential is solely responsible for the spike behaviour near $n = 1$. We may therefore approximate the pre-dilution equilibrium distribution (15) as

$$\frac{\mathcal{X}_n^*}{\mathcal{X}_1^*} = \begin{cases} 1 & n = 1 \\ \frac{B}{m^{3/2}} \exp(-\beta m(n/m - 1)^2) + \frac{C}{m^2} \exp(-dn/m) & n \geq 2. \end{cases} \quad (30)$$

Outside a narrow neighbourhood of the optimal aggregation number $n = m$, the ansatz (15) indicates that the concentration scales with m^2 . We therefore choose to describe the pre-dilution equilibrium distribution of aggregates by the continuous order-one function $Y(n/m) = m^2 \mathcal{X}_n^* / \mathcal{X}_1^*$ for $n \geq 2$, that is,

$$Y(x) = B\sqrt{m} \exp(-\beta m(x - 1)^2) + C \exp(-dx). \quad (31)$$

The post-dilution concentration is similarly scaled with m^2 by defining

$$y(n/m, t) = m^2 X_n(t) \quad (32)$$

for $n \geq 2$. The initial and equilibrium post-dilution concentrations are then given by the continuous functions

$$y_0(x) = y(x, 0) = \frac{Y(x)}{vD} = B_0\sqrt{m} \exp(-\beta m(x - 1)^2) + C_0 \exp(-dx), \quad (33a)$$

$$\dagger(x) = \lim_{t \rightarrow \infty} y(x, t) = Y(x)v^{mx-1} = \bar{B}\sqrt{m} \exp(-\beta m(x - \bar{\omega})^2) + \bar{C} \exp(-\bar{d}x), \quad (33b)$$

which replace (22) and (23) respectively, while the corresponding monomer concentrations are

$$X_1(0) = \frac{1}{vD}, \quad \lim_{t \rightarrow \infty} X_1(t) = \bar{X}_1 = 1. \quad (34)$$

The parameters in (33) are still related to the pre-dilution distribution by (24).

3.2. Integral relations

In the continuum limit, the non-dimensional pre-dilution bulk concentration C_b is now expressed as an integral, namely

$$C_b = 1 + \int_0^\infty xY(x) dx. \quad (35)$$

Using the fit (31) to $Y(x)$, we find that this integral may be evaluated to give

$$C_b - 1 = B\sqrt{\frac{\pi}{\beta}} G(\sqrt{\beta m}) + \frac{C}{d^2}, \quad (36)$$

where for convenience we introduce the function

$$G(s) = \frac{1}{2} \left(\frac{e^{-s^2}}{\sqrt{\pi} s} + \operatorname{erfc}(-s) \right). \quad (37)$$

We can use Eq. (36) to evaluate B in terms of all the other fitting parameters. Since $G(\sqrt{\beta m}) \sim 1$ with exponential accuracy as $m \rightarrow \infty$, no further asymptotic error is incurred by using the approximation

$$B \sim \sqrt{\frac{\beta}{\pi}} \left(C_b - 1 - \frac{C}{d^2} \right). \quad (38)$$

For example, with $\beta = 0.2$, $m = 100$, $C = 0.5$, $d = 1$, and $C_b = 10$, we obtain $B \approx 2.27$; the value differs from that obtained using the discrete model in Section 2.2 by a factor of less than 10^{-5} .

The value of v corresponding to a given dilution ratio D can now be determined from the continuum version of (20), namely

$$\frac{C_b}{vD} = 1 + \int_0^\infty x\bar{y}(x) dx, \quad (39)$$

with $\bar{y}(x)$ given by (33b). Again, this integral may be calculated explicitly to give

$$\frac{C_b}{D} - v = B\sqrt{\frac{\pi}{\beta}} \bar{\omega} e^{-\beta m(1-\bar{\omega})^2} G(\bar{\omega}\sqrt{\beta m}) + \frac{C}{(d - m \log v)^2}, \quad (40)$$

where $\bar{\omega}$ is still defined by (25). The right-hand side of (40) is exponentially small unless v and $\bar{\omega}$ are asymptotically close to 1. We therefore obtain the leading-order relation

$$v \sim \frac{C_b}{D}, \quad (41)$$

which is valid for $v < 1$, that is, for $D > C_b$.

The right-hand side of (40) comes into play when

$$\bar{\omega} = 1 - \frac{\kappa}{m\beta}, \quad (42)$$

so that $v = e^{-2\kappa/m}$, with $\kappa = O(1)$. In this case, Eq. (40) is approximated by

$$\frac{C_b}{D} - e^{-2\kappa/m} \sim (C_b - 1)e^{-2\kappa} \left(1 - \frac{\kappa}{\beta m} \right) e^{\kappa^2/\beta m} + \frac{C}{(d + 2\kappa)^2} \quad (43)$$

with exponential accuracy. For the parameter values used in Fig. 3, we note that C is relatively small, while C_b is relatively large. This allows us to simplify (43) further by neglecting the term proportional to C , corresponding to the contributions from the tail of the distribution. Finally, neglecting terms of order $1/m$, we obtain the leading-order approximation

$$\frac{C_b - D}{(C_b - 1)D} \sim e^{-2\kappa}, \quad (44)$$

and hence

$$v \sim \left(\frac{C_b - D}{(C_b - 1)D} \right)^{1/2}, \quad (45)$$

which is valid when $D < C_b$. Fig. 3 demonstrates that the simple approximations (41) and (45) are extremely accurate when $D > C_b$ and when $D < C_b$ respectively. We recall that realistic surfactants are likely to be modelled by even smaller values of C , in which case we can expect our approximations to be even better.

3.3. The governing equations

After using (32) to scale the aggregate concentrations, we find that it is necessary also to rescale the time variable τ via

$$\tau = mt \quad (46)$$

to obtain a dominant balance in the governing equations. This result is in keeping with Figs. 5 and 6, where the evolution to equilibrium was observed to occur over a large τ timescale. This longer timescale is a consequence of the large size of the typical aggregation number m , since larger aggregates will take longer to release all their monomers and break down entirely.

To obtain the continuum version of (29) we substitute (32) into (29a) and Taylor expand for small $\epsilon \equiv 1/m$ to obtain

$$\frac{\partial y}{\partial t} = (1 - X_1(t)) \frac{\partial y}{\partial x} + \frac{\epsilon}{2} (1 + X_1(t)) \frac{\partial^2 y}{\partial x^2} - \epsilon \frac{\partial}{\partial x} \left(\frac{y'}{y} y \right), \quad (47a)$$

where we neglect terms of order ϵ^2 , and prime denotes differentiation with respect to x . Similarly, substituting our continuum representation into (29b) and approximating the series as an integral provides

$$X_1(t) = \frac{C_b}{vD} - \int_0^\infty xy(x, t) dx, \quad (47b)$$

which enforces net conservation of surfactant and closes the system.

We note that X_1 tends towards 1 as the system approaches equilibrium, so that the first term on the right-hand side of (47a) will eventually become comparable with the remaining terms on the right-hand side. We therefore retain terms of order ϵ in (47a) to ensure that the system is balanced at leading order during the entire evolution to equilibrium.

The initial condition for the problem is given by (33a), that is

$$y(x, 0) = \frac{B_0}{\sqrt{\epsilon}} \exp\left(-\frac{\beta}{\epsilon}(x-1)^2\right) + C_0 \exp(-dx). \quad (48)$$

In addition, the system (47) requires two boundary conditions. The first of these is obtained by writing the Becker–Döring Eq. (29a) with $n = 2$ in terms of our continuous function y and scaled time t :

$$\epsilon^3 \frac{\partial y(2\epsilon, t)}{\partial t} = X_1^2 - \frac{y(\epsilon, t)}{y(\epsilon)} - \epsilon^2 X_1 y(2\epsilon, t) + \epsilon^2 \frac{\bar{y}(2\epsilon)y(2\epsilon, t)}{\bar{y}(3\epsilon)}. \quad (49)$$

Again neglecting terms of $O(\epsilon^2)$, we obtain the boundary condition

$$y(0, t) = X_1(t)^2 \bar{y}(0), \quad (50)$$

which implies that $y(0, t)$ instantaneously falls to $X_1(0)^2 \bar{y}(0)$ for $t = 0^+$. This indicates that dimers rapidly dissociate to replenish the depleted monomer, and is a consequence of the large difference between the concentrations of monomer and dimer in the solution. This rapid depletion occurs over a much shorter timescale on which $t = O(\epsilon^3)$ and all other aggregate concentrations remain fixed. The second boundary condition is provided by ensuring that we have a finite quantity of surfactant, which requires

$$y(x, t) \rightarrow 0 \quad \text{as } x \rightarrow \infty. \quad (51)$$

If we set $X_1 = 1$ and $\bar{y} = 1$ then (47a) reduces to the standard diffusion equation. As discussed in Section 1, there are many applications in which a ready supply of monomer ensures that X_1 remains effectively fixed at its equilibrium value. The assumption of constant monomer concentration may also be used to approximate the evolution of a system subject to very small dilutions, as in Aniansson and Wall [2–4].

3.4. Comparison between discrete and continuum models

In Fig. 7 we compare the evolution predicted by the Becker–Döring Eq. (29) with that predicted by our continuum model, using the distribution (15) with $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$, $C_b = 10$ and $m = 100$, upon a two-fold dilution. The parabolic Eq. (47a) is solved by the method of lines: a discretization in x produces a system of nonlinear ordinary differential equations in t which are solved using an implicit Euler scheme. The agreement between the evolu-

tions predicted by the two models is excellent, except, as expected, in a small region as x approaches zero where the discrete distribution rises to the monomer concentration (since y is a continuous representation of the aggregate distribution for $n \geq 2$). The monomer concentration is also accurately captured by the continuum model, as illustrated in Fig. 8.

In Fig. 9 we use (47a) to plot the evolution of the position of the maximum in the aggregate distribution. The distinct two-step behaviour of the re-equilibration is clearly apparent, with the

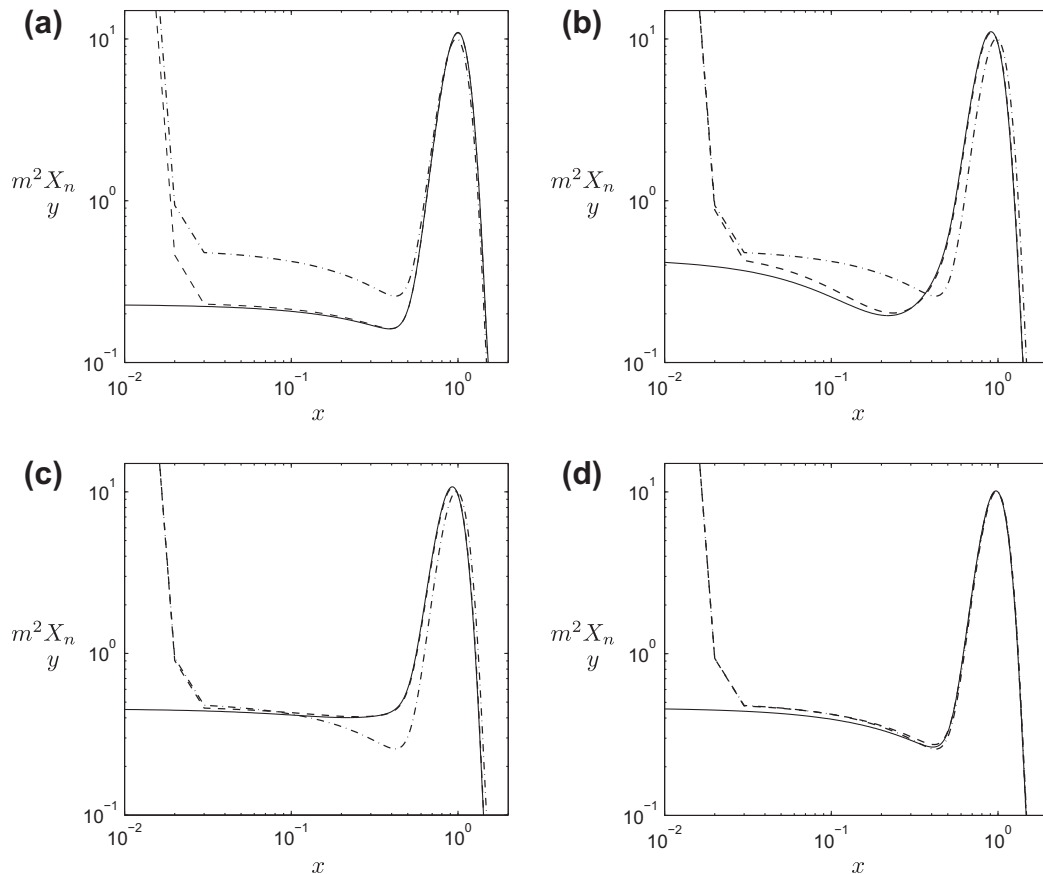


Fig. 7. Comparison between the concentration profile evolutions predicted by the Becker–Döring Eq. (29) (dashed) and by the continuum model (47a) (solid) at times at (a) $t = 0$, (b) $t = 1$, (c) $t = 5$, (d) $t = 50$. The pre-dilution distribution (15) and continuum version (31) are used, with parameter values $b = 10$, $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$, $C_b = 10$ and $D = 2$. The dot-dash line shows the equilibrium distribution.

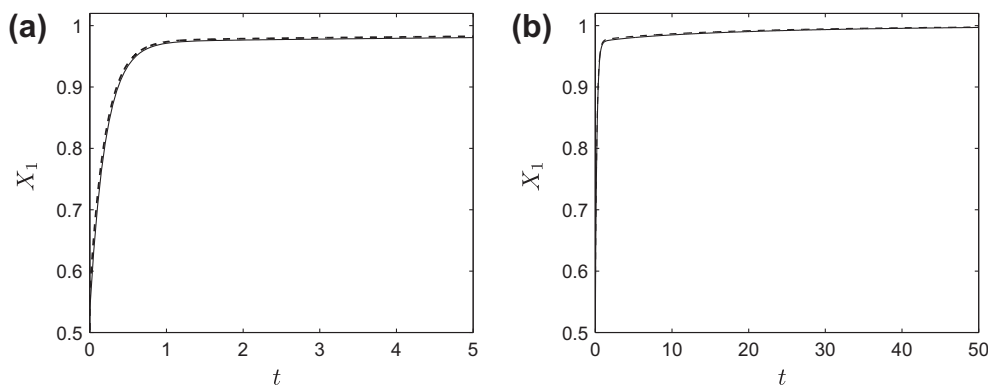


Fig. 8. Comparison between the evolutions in the monomer concentration $X_1(t)$ predicted by the Becker–Döring Eq. (29) (dashed) and by the continuum model (47a) (solid) on (a) the τ_1 timescale, (b) the τ_2 timescale. The pre-dilution distribution (15) and continuum version (31) are used, with parameter values $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$, $C_b = 10$ and $D = 2$.

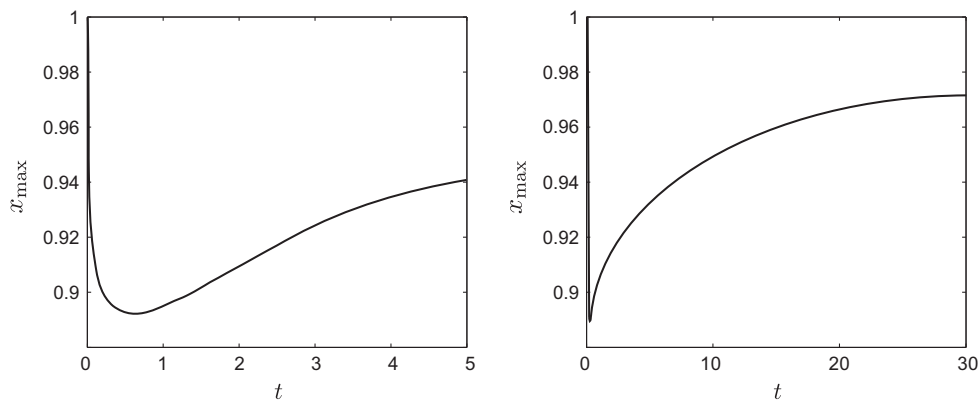


Fig. 9. Evolution of the position of the maximum for the pre-dilution distribution (31), with $\beta = 0.2$, $C = 0.5$, $d = 1$, $m = 100$, $C_b = 10$ and $D = 2$, on (a) the τ_1 timescale, (b) the τ_2 timescale.

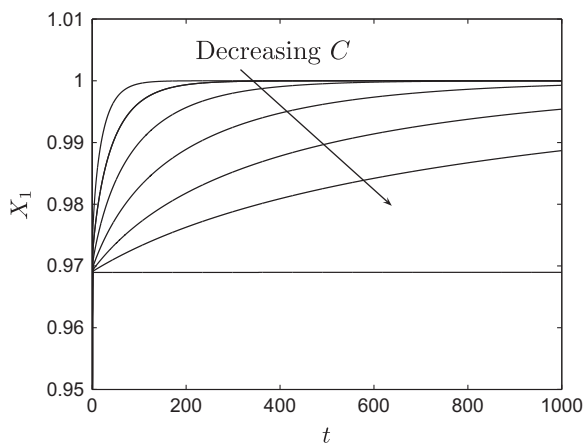


Fig. 10. τ_2 evolution of $X_1(t)$ with time predicted by the continuum model (47a). The pre-dilution distribution (15) and continuum version (31) are used, with parameter values $\beta = 0.2$, $d = 1$, $m = 100$, $C_b = 10$ and $D = 2$, and we vary $C = e^{-9}$, e^{-10} , e^{-11} , e^{-12} , e^{-13} , e^{-14} , 0.

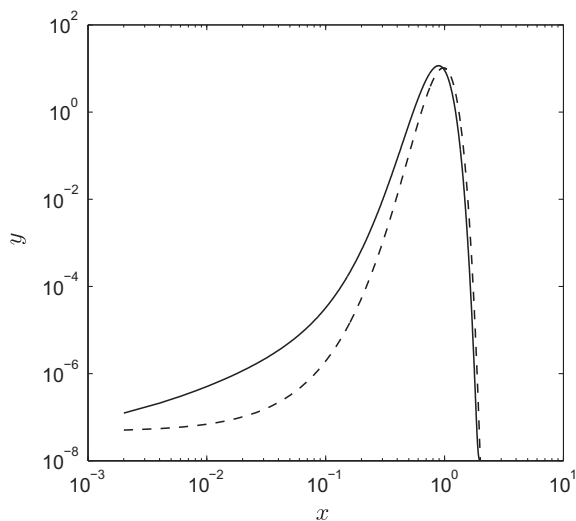


Fig. 11. Concentration profile distribution at $t = 10^5$ for a pre-dilution distribution (31) with parameter values $\beta = 0.2$, $C = 0$, $m = 100$, $C_b = 10$ and $D = 2$. The profile effectively assumes a pseudo-equilibrium, taking an exponentially longer time to attain the actual system equilibrium (shown as a dashed line).

position of the peak moving rapidly to the left to begin with, reaching a minimum at $t \approx 0.5$ before very slowly rising back to the new equilibrium value, at $x = \bar{\omega} \approx 0.980$ for this choice of parameters.

As discussed in Section 2.5, the rate at which the τ_2 process occurs is dependent upon the concentration of aggregates in the intermediate region, which implies a vast separation between the timescales of the τ_1 and τ_2 processes when the relative concentration of intermediate aggregates is very low. This is shown in Fig. 10: as C becomes very small, following the order-one τ_1 process, the monomer concentration plateaus at a pseudo-equilibrium, which takes an exponentially long time to evolve towards the actual equilibrium (Fig. 11).

As discussed in Section 1, many surfactants exhibit equilibrium distributions with extremely low concentrations of intermediate aggregates. However, it has been observed that such surfactant systems are able to re-equilibrate on a timescale much shorter than the Becker–Döring theory would suggest. For example, the surfactant $C_{12}E_8$ at a bulk concentration ten times the CMC has a typical concentration of intermediate aggregates 10^{-15} times lower than the concentration of proper micelles [1]. For such a system, the Becker–Döring theory predicts that the τ_1 and τ_2 processes will occur on timescales of the order of ms and hundreds of years respectively, while stopped-flow experiments suggest re-equilibration on the order of seconds [1]. It is thus evident that, while the Becker–Döring theory and our continuum model accurately describe the re-equilibration process for many surfactant systems, it fails to capture the physical mechanism of re-equilibration in all situations. This implies that there must be an alternative route that permits re-equilibration over sensible timescales for such surfactants and we will address this question in a follow-up paper.

4. Conclusions

In this paper, we examined the re-equilibration mechanism for a micellar surfactant solution following an order-one dilution. This extends the theory of Aniansson and Wall [2–4] who consider only small variations in concentration. During re-equilibration, aggregates must release material to replenish the concentration of monomers back to its critical value, and we adopted the usual assumption that the breakdown or assembly of surfactant aggregates occurs via stepwise monomer loss or gain respectively. This leads to the set of coupled nonlinear ordinary differential equations known as the Becker–Döring equations. We considered a typical realistic system, in which the surfactant exists predominantly either in monomer form or as large aggregates (micelles) centred around an optimum aggregation number, with an intermediate separating region of much lower concentration.

For the majority of surfactant systems, the number of monomers that comprise a micelle is large. This permits the derivation of a continuum model, comprising a partial differential equation governing the evolution of aggregate concentrations coupled to an integral equation for the monomer concentration. Validation of the continuum model against the discrete Becker–Döring system showed excellent agreement while removing the complexity of tracking each species individually, which vastly simplifies numerical computation. The re-equilibration process was shown still to be characterized by two distinct stages, which are referred to as the τ_1 and τ_2 processes, in agreement with the behaviour observed following small dilutions [2–4], and was validated against observations from stopped-flow experiments.

In the τ_1 process, following dilution, the depleted monomer is replenished by the shedding of individual monomers from aggregates near micellar size, leading to a decrease in the dominant aggregate size. This occurs on a timescale of the order of microseconds. The τ_2 process is characterized by the entire breakdown of some aggregates via stepwise monomer release. Here, some of the monomers released remain in this form to replenish the monomer to the equilibrium, while the remainder associate with some of the aggregates which have not dissociated. This has the simultaneous impact of increasing the dominant aggregate size while decreasing the total concentration of surfactant contained in aggregates.

The relative timescales of the τ_1 and τ_2 processes are related to the relative concentration of aggregates in the intermediate region compared with the concentration of aggregates in the micellar region. For typical surfactants, this is often many orders of magnitude lower than the concentration of proper micelles, leading to well-separated timescales. A key result of our analysis is that the separation between the timescales of the τ_1 and τ_2 processes is exponentially large when the relative concentration of intermediate aggregates is low. In such cases, experimental observations indicate that the systems are able to re-equilibrate on a timescale very much shorter than this would suggest. While the Becker–Döring theory would predict that the τ_1 and τ_2 processes will occur on timescales of the order of ms and hundreds of years respectively, stopped-flow experiments indicate re-equilibration on the order of seconds [1]. We conclude that the standard theory fails to predict the correct re-equilibration times for such surfactant systems. An alternative mechanism for re-equilibration that correctly explains the observed behaviour will be proposed in a follow-up to this paper.

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