

Morse homology-

M : smooth compact n -manifold

$f: M \rightarrow \mathbb{R}$ Morse function (= critical points are non-degenerated)

\Rightarrow (Morse lemma) near a critical point x , in a chart:

$$f(x_1, \dots, x_n) = f(x) - x_1^2 - \dots - x_k^2 + x_{k+1}^2 + \dots + x_n^2$$

\uparrow $k =: i(x)$: Morse index

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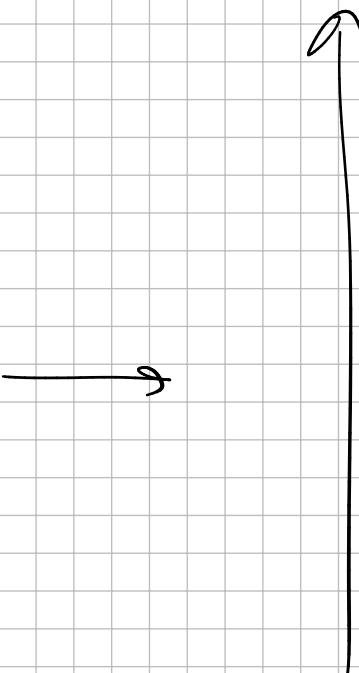
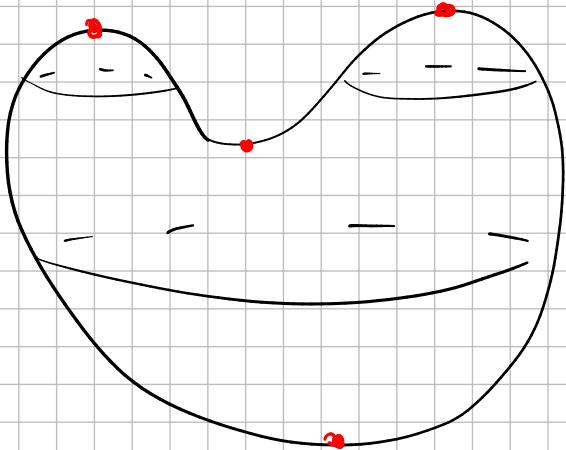
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ex:



g : Riemannian metric / M

$\rightsquigarrow X = -\nabla f$ negative gradient.

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$x \in \text{crit}(f)$: $U_x = \left\{ y \mid \lim_{t \rightarrow -\infty} \phi_t(y) = x \right\}$ "Unstable manifold" $\dim U_x = i(x)$

$S_x = \left\{ y \mid \lim_{t \rightarrow +\infty} \phi_t(y) = x \right\}$ "Stable manifold" $\dim S_x = m - i(x)$

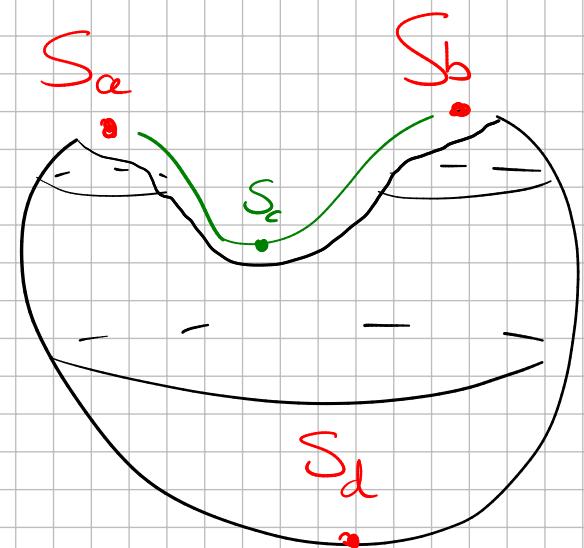
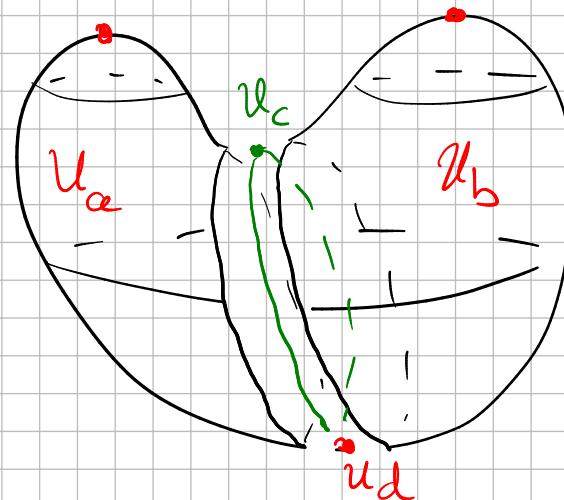
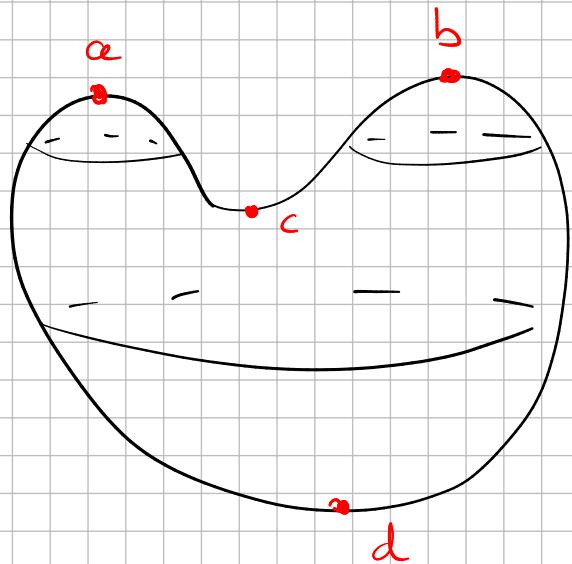
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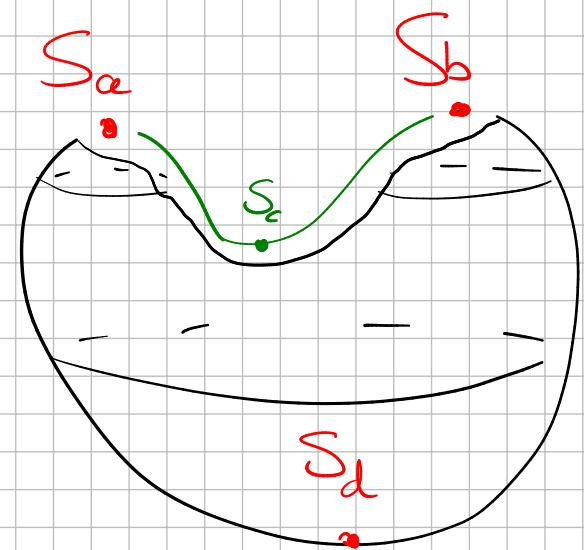
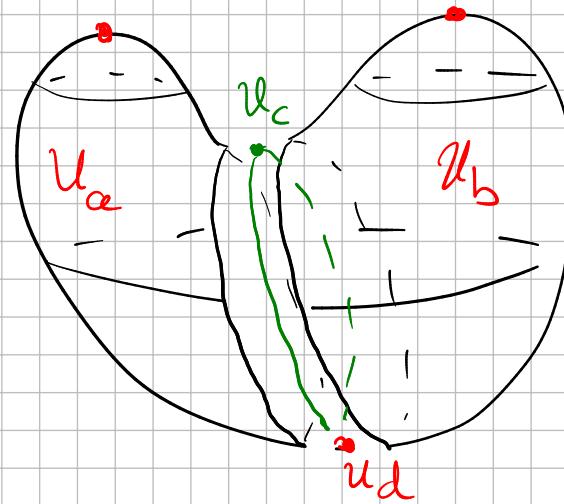
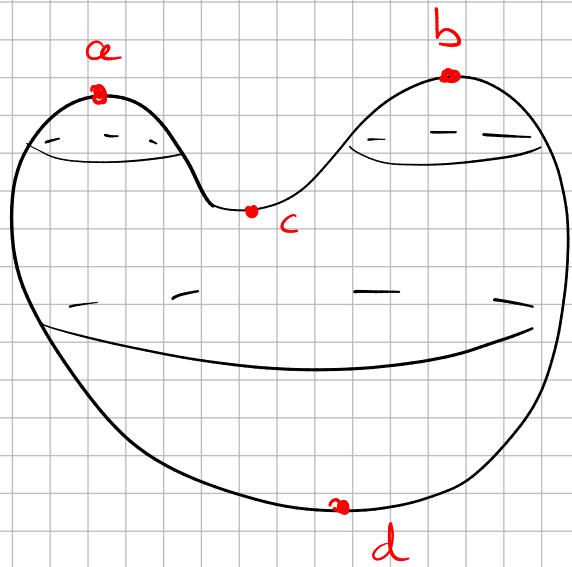
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f self-indexed \Rightarrow cellular decomposition

$x, y \in \text{crit } f$

$$\widetilde{\mathcal{M}}(x, y) = \left\{ \gamma : \mathbb{R} \rightarrow M \text{ flow line, } \begin{array}{l} \lim_{-\infty} \gamma = x \\ \lim_{+\infty} \gamma = y \end{array} \right\} \simeq U_x \cap S_y$$

$\gamma \mapsto \gamma(0)$

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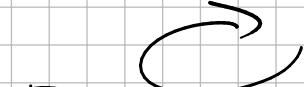


\mathbb{R}

$\gamma \mapsto \gamma(t_0 + \cdot)$

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$$M(x, y) = \tilde{\mathcal{M}}(x, y)/\mathbb{R}$$

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$$\mathcal{M}(x, y) = \mathcal{M}(x, y)/\mathbb{R} : \begin{aligned} & * \text{ generically smooth, of dim } i(x) - i(y) - 1 \\ & * \text{ can be oriented if } \mathcal{U}_x \text{ and } \mathcal{U}_y \text{ are given an orientation.} \end{aligned}$$

$x, y \in \text{Cut } f$

$$\tilde{\mathcal{M}}(x, y) = \left\{ \gamma : \mathbb{R} \rightarrow M \text{ flow line, } \lim_{-\infty} \gamma = x \right. \left. \begin{array}{l} \lim_{+\infty} \gamma = y \\ \gamma \mapsto \gamma(0) \end{array} \right\} \simeq U_x \cap S_y$$

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Def: $C\mathcal{M}_k(M, f) = \bigoplus_{\substack{x \in \text{Cut } f \\ i(x) = k}} \mathbb{Z} \cdot x$

$$\partial : C\mathcal{M}_k(M, f) \rightarrow C\mathcal{M}_{k-1}(M, f)$$

$$x \mapsto \sum_y \# \mathcal{M}(x, y) \cdot y$$

$x, y \in \text{Cut } f$

$$\widetilde{\mathcal{M}}(x, y) = \left\{ \gamma : \mathbb{R} \rightarrow M \text{ flow line, } \lim_{-\infty} \gamma = x \right. \left. \begin{array}{l} \simeq U_x \cap S_y \\ \lim_{+\infty} \gamma = y \end{array} \right\} \simeq U_x \cap S_y$$

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$$\gamma \mapsto \gamma(t_0 + \cdot)$$

$$M(x, y) = \widetilde{\mathcal{M}}(x, y)/\mathbb{R}$$

- * generically smooth, of dim $i(x) - i(y) - 1$
- * can be oriented if U_x and U_y are given an orientation.

Def: $C\mathcal{M}_k(M, f) = \bigoplus_{\substack{x \in \text{Cut } f \\ i(x) = k}} \mathbb{Z} \cdot x$

prop: $\partial^2 = 0$
 $\rightarrow HM_*(M, f) := \frac{\text{ker } \partial}{\text{Im } \partial}$

$$\partial : C\mathcal{M}_k(M, f) \rightarrow C\mathcal{M}_{k-1}(M, f)$$

$$x \mapsto \sum_y \# \mathcal{M}(x, y) \cdot y$$

$\simeq H_*^{\text{coll}}(M, \{U_x\})$
if f self-indexing
 $\simeq H_*(M; \mathbb{Z})$ in general.