

Reflected Backward SPDEs and Optimal Stopping Problems

Jinniao Qiu

Fudan University

July 2, 2012

American Option Problem

Dividend paying stock:

$$X_t^{s,x} = x + \int_s^t (r - d) X_\theta^{s,x} d\theta + \int_s^t \sigma X_\theta^{s,x} dW_\theta, \quad t \in [s, T];$$

Arbitrage-free value of American option:

$$V(s, x) = \sup_{s \leq \tau \leq T} E e^{-r(\tau-s)} g(X_\tau^{s,x}), \quad (g(x) = (x - K)^+).$$

Reflected BSDE (El Karoui-Kapoudjian-Pardoux-Peng-Quenes, 1997, Ann. Prob.):

$$\left\{ \begin{array}{l} Y_t^{s,x} = g(X_T^{s,x}) - \int_t^T r Y_\theta^{s,x} d\theta + K_T^{s,x} - K_t^{s,x} - \int_t^T Z_\theta^{s,x} dW_\theta, \quad t \in [s, T], \\ Y_t^{s,x} \geq g(X_t^{s,x}), \quad t \in [s, T], \\ K^{s,x} \text{ is continuously increasing, } K_s^{s,x} = 0, \int_s^T (Y_t^{s,x} - g(X_t^{s,x})) dK_t^{s,x} = 0. \end{array} \right.$$

Benth-Karlsen-Reikvam (2003), Klimsiak-Rozkosz (2010)

$$V(s, x) = Y_s^{s,x}, \quad K_t^{s,x} = \int_s^t (dX_\theta^{s,x} - rK)^+ 1_{Y_\theta^{s,x} = g(X_\theta^{s,x})} d\theta$$

quasi-variational inequality:

$$\left\{ \begin{array}{l} \min\{u(s, x) - g(x), -\mathcal{L}_{BS}u(s, x) + ru(s, x)\} = 0, \\ u(T, x) = g(x). \\ \mathcal{L}_{BS} = \partial_s u + (r - d)x\partial_x u + \frac{1}{2}\sigma^2 x^2 \partial_{xx}^2 u. \end{array} \right.$$

$$\Leftrightarrow \left\{ \begin{array}{l} \mathcal{L}_{BS}u(s, x) = ru(s, x) - \mu, \\ u(T) = g, \quad u \geq g, \quad \int_{[0, T] \times \mathbb{R}} (u - g) \varrho^2 d\mu = 0. \end{array} \right.$$

$$(Y_t^{s,x}, Z_t^{s,x}) = (u(s, X_t^{s,x}), \sigma x \partial_x u(t, X_t^{s,x})),$$

$$\mu(dt, dx) = q(x, u(t, x)) dt dx, \quad q(x, y) = (dx - rK)^+ 1_{(-\infty, g(x)]}(y).$$

- How about Non-Markovian case ?

Starting point: quasi-linear Backward SPDE (BSPDE):

$$\left\{ \begin{array}{l} -du(t, x) = \left[\frac{1}{2} \Delta u(t, x) + (f + \operatorname{div} g)(t, x, u(t, x), \nabla u(t, x), v(t, x)) \right] dt \\ \sum_{r=1}^m v^r(t, x) dW_t^r, \quad (t, x) \in [0, T] \times \mathbb{R}^d; \\ u(T, x) = G(x), \quad x \in \mathbb{R}^d. \end{array} \right.$$

- $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, \mathbb{P})$ complete probability space with filtration;
- W : m -dimensional BM;
- $G \in L^2(\Omega, \mathcal{F}_T; L^2(\mathbb{R}^d))$;
- f and g satisfy Lipschitz conditions.

Known results:

- Existence and uniqueness of the weak solution;
- The solution satisfies Itô's formula;
- Comparison Theorem;
- Maximum principles for Backward SPDEs on bounded domains;
- ...

The obstacle problem for BSPDEs leads to reflected BSPDE (RBSPDE)

$$\left\{ \begin{array}{l} -du(t, x) = \left[\frac{1}{2} \Delta u(t, x) + (f + \operatorname{div} g)(t, x, u, \nabla u, v) \right] dt \\ \quad + \mu(dt, dx) - v^r(t, x) dW_t^r, \quad (t, x) \in [0, T] \times \mathbb{R}^d; \\ u(t, x) \geq \xi(t, x), \quad \mathbb{P} \otimes dt dx\text{-a.e.}; \\ u(T, x) = G(x); \int_0^T \int_{\mathbb{R}^d} (\bar{u}(s, x) - \xi(s, x)) \mu(dx, ds) = 0, \quad a.s.. \end{array} \right. \quad (1)$$

- Unique solvability of RBSPDE (1), unknown is the triple (u, v, μ) ;
- Its connections with optimal stopping problems.

Two existing results

- Optimal stopping problems with random coefficients :
Chang-Pang-Yong, SCION, (2008);
- Singular control problems of SPDEs:
Øksendal-Sulem-Zhang, INRIA, (2011).
- Results with $\mu(dt, dx) = k(t, x)dt$.

Notations

- Continuous Hunt process $(\Omega', B_t, \theta_t, \mathcal{F}^0, \mathcal{F}_t^0, \mathbb{P}^x)$:
 $\Omega' := C([0, \infty); \mathbb{R}^d)$;
 $(B_t)_{t \geq 0}$: d -dim Brownian motion starting from distribution dx ;
 $\mathbb{P}^{dx} := (B.)^{-1}(dx \otimes \mathbb{P}^0)$;
- $(L^2(\mathbb{R}^d), \langle \cdot, \cdot \rangle, \|\cdot\|_2)$, $(H^1(\mathbb{R}^d), \langle \cdot, \cdot \rangle_1, \|\cdot\|_{H^1})$;
For each Banach space $(V, \|\cdot\|_V)$,
- $\mathcal{S}^2(V)$: V -valued, (\mathcal{F}_t) -adapted and continuous processes $(X_t)_{t \in [0, T]}$, s.t.

$$\|X\|_{\mathcal{S}^2(V)} := \left(E \left[\sup_{t \in [0, T]} \|X_t\|_V^2 \right] \right)^{1/2} < \infty;$$

- $\mathcal{L}^2(V)$: $\|X\|_{\mathcal{L}^2(V)} := \left(E \left[\int_0^T \|X_t\|_V^2 dt \right] \right)^{1/2} < \infty$;
- $\mathcal{H} := \mathcal{S}^2(L^2(\mathbb{R}^d)) \cap \mathcal{L}^2(H^1(\mathbb{R}^d))$ equipped with norm

$$\|\phi\|_{\mathcal{H}} := \left(\|\phi\|_{\mathcal{S}^2(L^2(\mathbb{R}^d))}^2 + \|\nabla \phi\|_{\mathcal{L}^2(L^2(\mathbb{R}^d))}^2 \right)^{1/2}, \quad \phi \in \mathcal{H}.$$

Assumptions

(A1) *The pair of random functions*

$f(\cdot, \cdot, \cdot, \vartheta, y, z) : \Omega \times [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$ and $g(\cdot, \cdot, \cdot, \vartheta, y, z) : \Omega \times [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d$

are $\mathcal{P} \otimes \mathcal{B}(\mathbb{R}^d)$ -measurable for any $(\vartheta, y, z) \in \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^m$. There exist positive constants $\kappa < 1/2$ and L such that for all

$(\vartheta_1, y_1, z_1), (\vartheta_2, y_2, z_2) \in \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^{n \times m}$, $\varphi_1, \varphi_2 \in L^2(\mathbb{R}^d)$, $\phi_1, \phi_2 \in (L^2(\mathbb{R}^d))^m$ and $(\omega, t, x) \in \Omega \times [0, T] \times \mathbb{R}^d$

$$\begin{aligned} |f(\omega, t, x, \vartheta_1, y_1, z_1) - f(\omega, t, x, \vartheta_2, y_2, z_2)| &\leq L|\vartheta_1 - \vartheta_2| + |y_1 - y_2| + |z_1 - z_2|; \\ |g(\omega, t, x, \vartheta_1, y_1, z_1) - g(\omega, t, x, \vartheta_2, y_2, z_2)| &\leq L(|\vartheta_1 - \vartheta_2| + |y_1 - y_2| + |z_1 - z_2|); \\ &\quad - \langle \nabla(\varphi_1 - \varphi_2), g(t, \varphi_1, \nabla\varphi_1, \phi_1) - g(t, \varphi_2, \nabla\varphi_2, \phi_2) \rangle \\ &\leq \kappa (\|\nabla(\varphi_1 - \varphi_2)\|_2^2 + \|\phi_1 - \phi_2\|_2^2) + L\|\varphi_1 - \varphi_2\|_2^2. \end{aligned}$$

Assumptions continued

(A2) $G \in L^2(\Omega, \mathcal{F}_T; L^2(\mathbb{R}^d))$.

$f_0 := f(\cdot, \cdot, \cdot, 0, 0, 0) \in \mathcal{L}^2(L^2(\mathbb{R}^d))$, $g_0 := g(\cdot, \cdot, \cdot, 0, 0, 0) \in \mathcal{L}^2(L^2(\mathbb{R}^d)^m)$.

(A3) *The obstacle process $\xi(\omega, t, x)$ is a predictable random function with respect to filtration $(\mathcal{F}_t)_{t \in [0, T]}$ and $t \mapsto \xi(\omega, t, B_t)$ is $\mathbb{P} \otimes \mathbb{P}^{dx}$ -a.s. continuous on $[0, T]$ and satisfies*

$$EE^{dx} \left[\sup_{t \in [0, T]} |\xi^+(t, B_t)|^2 \right] < \infty \text{ and } \xi(T, \omega) \leq G, \mathbb{P} \otimes dx\text{-a.e..}$$

Definition

Random function $u : \Omega \times [0, T] \times \mathbb{R}^d \rightarrow \bar{\mathbb{R}}$ is said to be stochastic quasi-continuous provided that for each $\varepsilon > 0$, there exists a predictable random set $D^\varepsilon \subset \Omega \times [0, T] \times \mathbb{R}^d$ such that \mathbb{P} -a.s. the section D_ω^ε is open and $u(\omega, \cdot, \cdot)$ is continuous on its complement $(D_\omega^\varepsilon)^c$ and

$$\mathbb{P} \otimes \mathbb{P}^{dx} ((\omega, \omega') | \exists t \in [0, T] \text{ s.t. } (\omega, t, B_t(\omega')) \in D^\varepsilon) \leq \varepsilon.$$

Remark

If u is stochastic quasi-continuous, we can check that the process $u(t, B_t)_{t \in [0, T]}$ has continuous trajectories, $\mathbb{P} \otimes \mathbb{P}^{dx}$ -a.s..

Quasi-continuity of the weak solutions for BSPDEs

Consider BSPDE

$$\left\{ \begin{array}{l} -du(t, x) = \left[\frac{1}{2} \Delta u(t, x) + (f + \operatorname{div} g)(t, x, u(t, x), \nabla u(t, x), v(t, x)) \right] dt \\ \quad - \sum_{r=1}^m v^r(t, x) dW_t^r, \quad (t, x) \in [0, T] \times \mathbb{R}^d; \\ u(T, x) = G(x), \quad x \in \mathbb{R}^d. \end{array} \right.$$

Theorem

Let (A1) and (A2) hold. Then the BSPDE above admits a unique weak solution pair

$$(u, v) \in \mathcal{H} \times \mathcal{L}^2((L^2(\mathbb{R}^6))^m)$$

Moreover, u admits a stochastic quasi-continuous version.

Definition

$u \in \mathcal{H}$ is called a stochastic potential, provided that u is stochastic quasi-continuous, $\lim_{t \rightarrow T} u(t, \cdot) = 0$ in $L^2(\mathbb{R}^d)$, a.s.,

$$EE^{dx} \left[\sup_{t \in [0, T]} |u(t, B_t)|^2 \right] < \infty, \quad (2)$$

and

$$E \left[(\tilde{P}_s u)(t) | \mathcal{F}_t \right] \leq u(t), \quad \forall s > 0, \forall t \in [0, T], \text{ a.s.} \quad (3)$$

where the conditional expectation is defined in the Hilbertian sense and

$$\tilde{P}_s u(t, x) := \begin{cases} \int_{\mathbb{R}^d} \rho_s(x - y) u(t + s, y) dy, & \text{if } s + t \leq T; \\ 0, & \text{otherwise,} \end{cases}$$

with $\rho_s(x) = (2\pi s)^{-d/2} \exp(-|x|^2/2s)$.

Theorem

Let $u \in \mathcal{H}$. Then u admits a version which is a stochastic potential if and only if there exist stochastic field $v \in \mathcal{L}^2((L^2(\mathbb{R}^d))^m)$ and a continuous increasing process $A = (A_t)_{t \in [0, T]}$ which is $\mathcal{F}_t \vee \mathcal{F}_t^0$ -adapted and such that $A_0 = 0$,

$EE^{dx} [A_T^2] < \infty$, and

(i)

$$u(t, B_t) = A_T - A_t - \sum_{i=1}^d \int_t^T \partial_{x^i} u(s, B_s) dB_s^i - \sum_{r=1}^m \int_t^T v^r(s, B_s) dW_s^r, \mathbb{P} \otimes \mathbb{P}^{dx} - a.s.$$

for each $t \in [0, T]$. The processes A and v are uniquely determined by those properties. Moreover, there hold the following relations:

(ii)

$$\begin{aligned} & E \left[\|u(t)\|_2^2 + \int_t^T (\|\nabla u(s)\|_2^2 + \|v(s)\|_2^2) ds \right] \\ &= EE^{dx} [(A_T - A_t)^2], \quad \forall t \in [0, T]; \end{aligned}$$

Theorem (continued)

(iii) for any $\varphi \in \mathcal{D}_T$,

$$\begin{aligned} & \langle u(0), \varphi(0) \rangle + \int_0^T \left(\frac{1}{2} \langle \nabla u(s), \nabla \varphi(s) \rangle \right) + \langle u(s), \partial_s \varphi(s) \rangle ds + \sum_{r=1}^m \int_0^T \langle \varphi(s), v^r(s, B_s) \rangle ds \\ &= \mu(\varphi) = \int_0^T \int_{\mathbb{R}^d} \varphi(s, x) \mu(dx, ds), \end{aligned}$$

where μ is the random measure $\mu : \Omega \rightarrow \mathcal{M}([0, T] \times \mathbb{R}^d)$

$$(iv) \quad \mu(\varphi) = E^{dx} \int_0^T \varphi(t, B_t) dA_t, \quad \varphi \in \mathcal{D}_T, \text{ a.s.},$$

with $\mathcal{M}([0, T] \times \mathbb{R}^d)$ denoting the set of all the Radon measures on $[0, T] \times \mathbb{R}^d$.

Lemma

Let u be a stochastic potential and $\mu : \Omega \rightarrow \mathcal{M}([0, T] \times \mathbb{R}^d)$ a random Radon measure such that relations (iii) holds. Then one has

$$\langle \phi, u(t) \rangle = E \left[\int_t^T \int_{\mathbb{R}^d} \left(\int_{\mathbb{R}^d} \phi(x) \rho_{s-t}(x, y) dx \right) \mu(dy, ds) \middle| \mathcal{F}_t \right], \quad (4)$$

for each $\phi \in L^2(\mathbb{R}^d)$ and $t \in [0, T]$.

Definition

A nonnegative random Radon measure $\mu : \Omega \rightarrow \mathcal{M}([0, T] \times \mathbb{R}^d)$ is called regular stochastic measure provided that there exists a stochastic potential u such that the relation (iii) from the above theorem is satisfied.

Remark

As $EE^{dx} [A_T^2] < \infty$, for any random field $\phi \in \mathcal{L}^2(L^2(\mathbb{R}^d))$ satisfying

$$\phi(t, B_t) \text{ is continuous } \mathbb{P} \otimes \mathbb{P}^{dx}\text{-a.s., and } EE^{dx} \left[\sup_{t \in [0, T]} |\phi(t, B_t)|^2 \right] < \infty,$$

$\mu(\phi)$ makes sense by relation (iv).

Proposition A

Let $\{u^n; n \in \mathbb{N}\}$ be a sequence of stochastic potentials associated with $\{(v^n, \mu^n); n \in \mathbb{N}\}$ such that $u^n \rightarrow u$ in \mathcal{H} and $v^n \rightarrow v$ in $\mathcal{L}^2((L^2(\mathbb{R}^d))^m)$ respectively. Then for some regular stochastic measure μ , u is a stochastic potential associated with (v, μ) .

Proposition B

Let $\{u^n; n \in \mathbb{N}\}$ be a sequence of stochastic potential which converges up to some $u \in \mathcal{H}$. Assume moreover that u is quasi-continuous and $EE^{dx} \left[\sup_{t \in [0, T]} |u(t, B_t)|^2 \right] < \infty$. Then u is a stochastic potential.

Definition

We say that a triple (u, v, μ) is a weak solution of the RBSPDE (1) associated to (G, f, g, ξ) , if

- (1) $u \in \mathcal{H}$, $u(t, x) \geq \xi(t, x)$, $\mathbb{P} \otimes dt \otimes dx$ -a.e. and $u(T, x) = G$, $\mathbb{P} \otimes dx$ -a.e.
- (2) $\mu : \Omega \rightarrow \mathcal{M}([0, T] \times \mathbb{R}^d)$ is a regular stochastic measure;
- (3) for each $\varphi \in \mathcal{D}_T$ and $t \in [0, T]$

$$\begin{aligned} & \langle u(t), \varphi(t) \rangle + \int_t^T \left[\langle u(s), \partial_s \varphi(s) \rangle + \frac{1}{2} \langle \nabla u(s), \nabla \varphi(s) \rangle \right] ds \\ &= \langle G, \varphi(T) \rangle + \int_t^T [\langle f(s, u, \nabla u, v), \varphi(s) \rangle - \langle g(s, u, \nabla u, v), \nabla \varphi(s) \rangle] ds \\ &+ \int_t^T \int_{\mathbb{R}^d} \varphi(s, x) \mu(ds, dx) - \sum_{r=1}^m \int_t^T \langle \varphi(s), v^r(s) dW_s^r \rangle; \end{aligned}$$

- (4) u admits a stochastic quasi-continuous version \bar{u} such that

$$\int_0^T \int_{\mathbb{R}^d} (\bar{u}(s, x) - \xi(s, x)) \mu(dx, ds) = 0, \quad a.s..$$

Decomposition of the Solution

- Let (u, v, μ) be a weak solution of RBSPDE (1) and (u_μ, v_μ) corresponds to the regular stochastic measure μ with u_μ being the stochastic potential.
- Clearly, $(u_0, v_0) := (u - u_\mu, v - v_\mu)$ solves the following BSPDE without obstacle:

$$\begin{aligned} -du(t, x) = & \left[\frac{1}{2} \Delta u(t, x) + (f + \operatorname{div} g)(t, x, u(t, x), \nabla u(t, x), v(t, x)) \right] dt \\ & - \sum_{r=1}^m v^r(t, x) dW_t^r; \end{aligned}$$

- $u = u_0 + u_\mu$ must be stochastic quasi-continuous.

Existence and Uniqueness Theorem

Let assumptions $(\mathcal{A}1) - (\mathcal{A}3)$ hold. Then there exists a unique weak solution (u, v, μ) of RBSPDE (1) associated with (G, f, g, ξ) .

Comparison theorem

Let $\tilde{G}, \tilde{f}, \tilde{\xi}$ satisfy the same hypothesis as G, f, ξ . And let (u, v, μ) be the weak solution of RBSPDE (1) associated with (G, f, g, ξ) and $(\tilde{u}, \tilde{v}, \tilde{\mu})$ the weak solution associated with $(\tilde{G}, \tilde{f}, g, \tilde{\xi})$. Moreover, we assume that there hold the following conditions:

- (i) $G \leq \tilde{G}$, $\mathbb{P} \otimes dx$ -a.e.;
- (ii) $f(u, \nabla u, v) \leq \tilde{f}(u, \nabla u, v)$, $\mathbb{P} \otimes dt dx$ -a.e.;
- (iii) $\xi \leq \tilde{\xi}$, $\mathbb{P} \otimes dt dx$ -a.e..

Then one has $u \leq \tilde{u}$, $\mathbb{P} \otimes dt dx$ -a.e..

RBSPDEs and optimal stopping problems

Let (u, v, μ) be the weak solution of RBSPDE (1). Denote

$$(Y_t, Z_t, \tilde{Z}_t, \zeta_t) = (u, \nabla u, v, \xi)(t, B_t), \quad t \in [0, T].$$

$(K_t)_{t \in [0, T]}$ is the increasing process w.r.t. μ . Then (Y, Z, \tilde{Z}, K) solves RBSDE:

$$\left\{ \begin{array}{l} Y_t = G + \int_t^T f(s, B_s, Y_s, Z_s, \tilde{Z}_s) ds + \int_t^T g(s, B_s, Y_s, Z_s, \tilde{Z}_s) * dB_s \\ \quad - \int_t^T Z_s dB_s - \int_t^T \tilde{Z}_s dW_s, \quad t \in [0, T]; \\ Y_t \geq \zeta_s, \quad t \in [0, T]; \quad \int_0^T (Y_s - \zeta_s) dK_s = 0. \end{array} \right.$$

Hence,

$$u(t, B_t) = \operatorname{ess\,sup}_{\tau \in S_{t, T}} EE^{dx} \left[\int_t^\tau f_s ds + \int_t^\tau g_s * dB_s + \zeta_\tau 1_{\tau < T} + G(T, B_T) 1_{\tau = T} \middle| \mathcal{F}_t \right].$$

Future work

- Analytic approach to Reflected BSPDEs;
- Reflected BSPDE on domains;
- Degenerate case;
- regularity problems;
- Applications ...

Thank You !