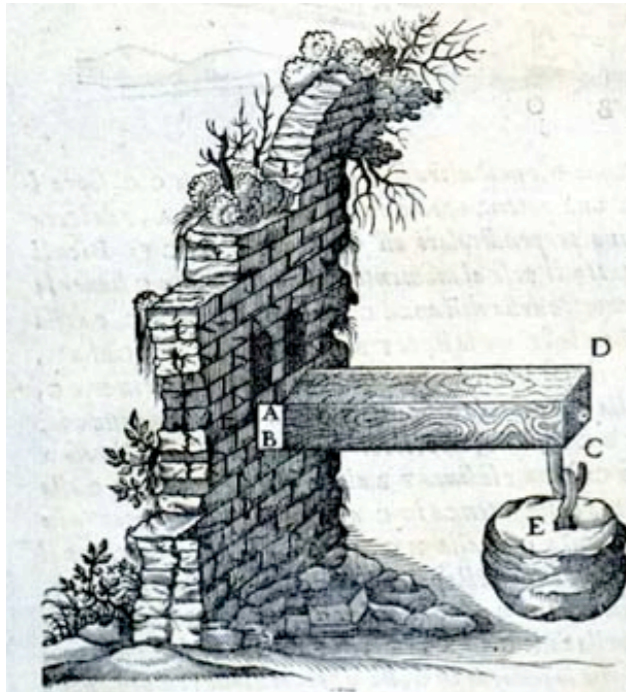
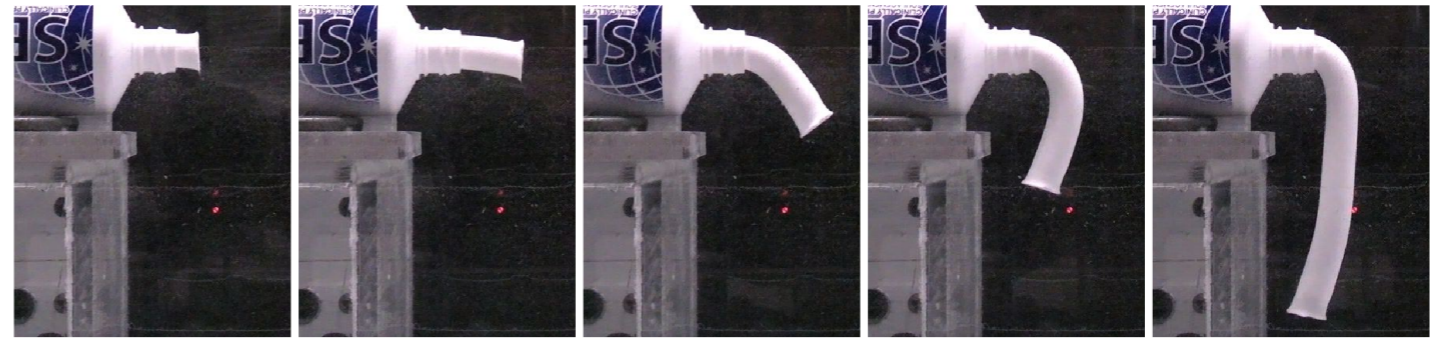


# Visco-elasto-plastica

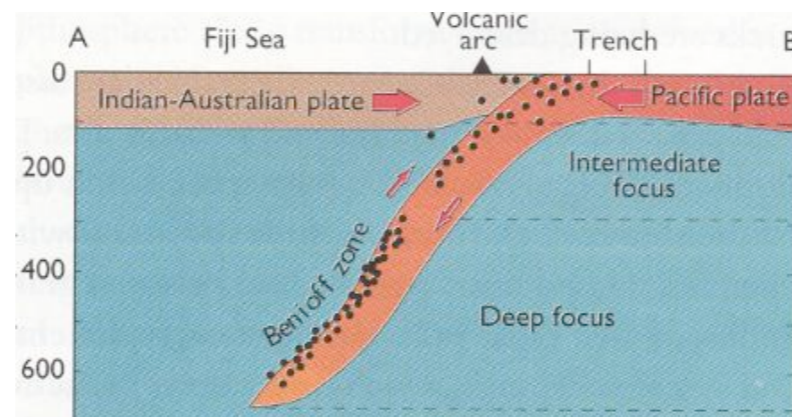
Ian Hewitt (+ Neil Balmforth, University of British Columbia)



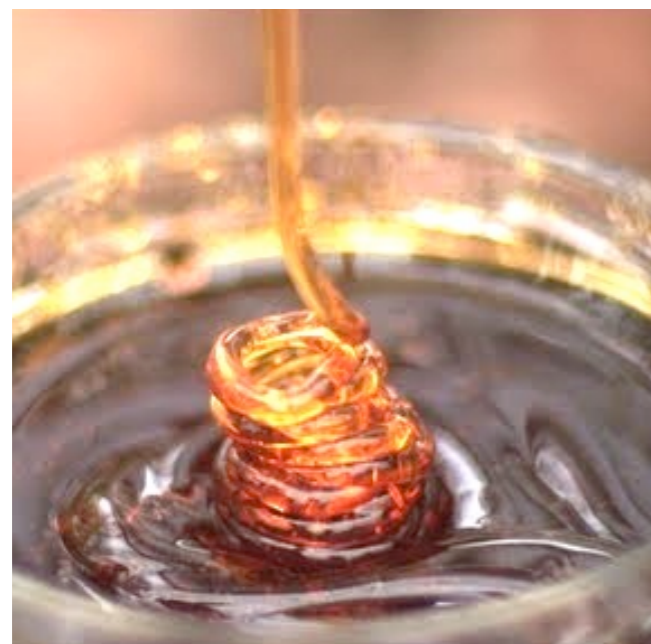
Galileo 1638, Euler, Bernoulli



Balmforth & Hewitt 2013



Ribe 2010

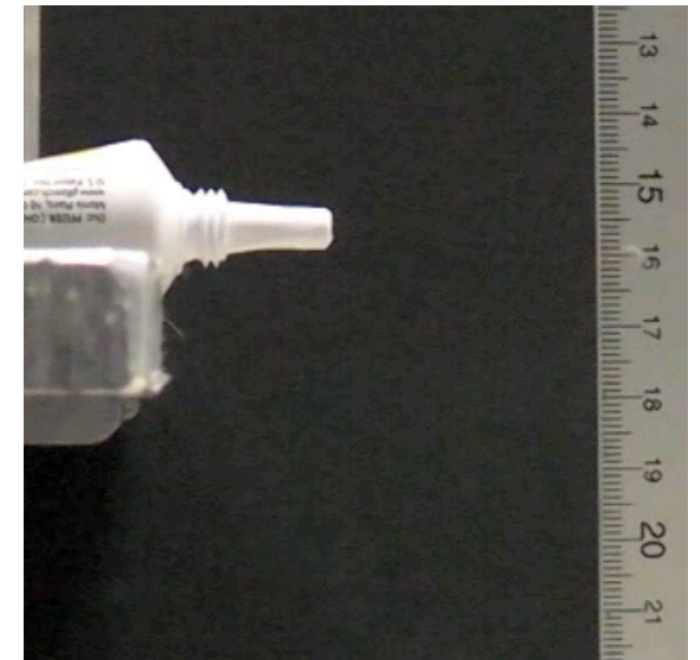
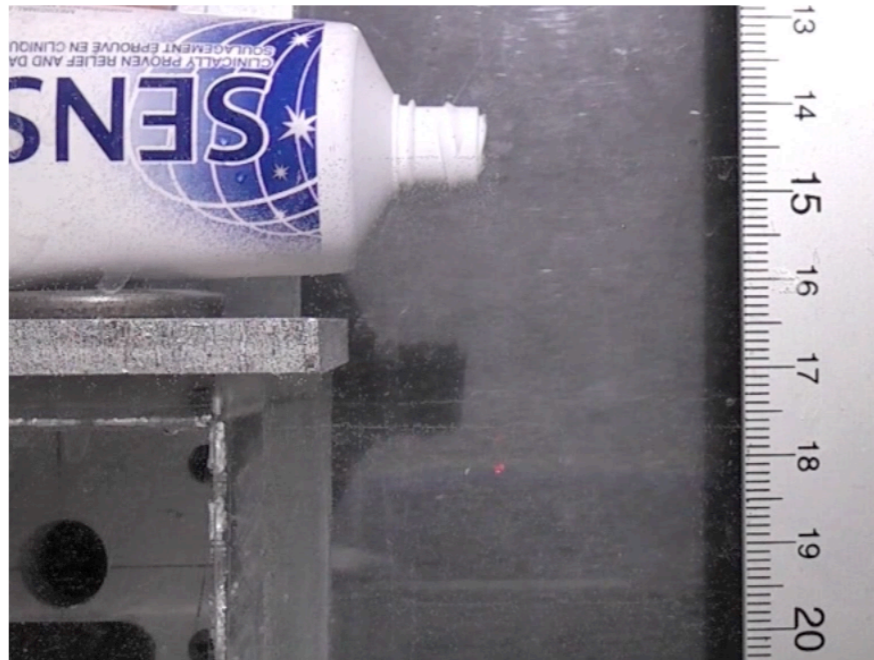


Buckmaster et al 1975, Ribe 2001

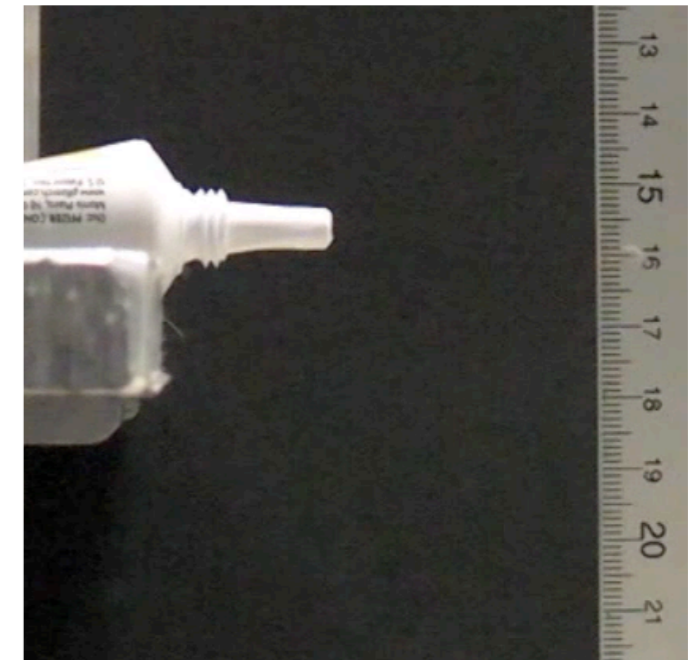
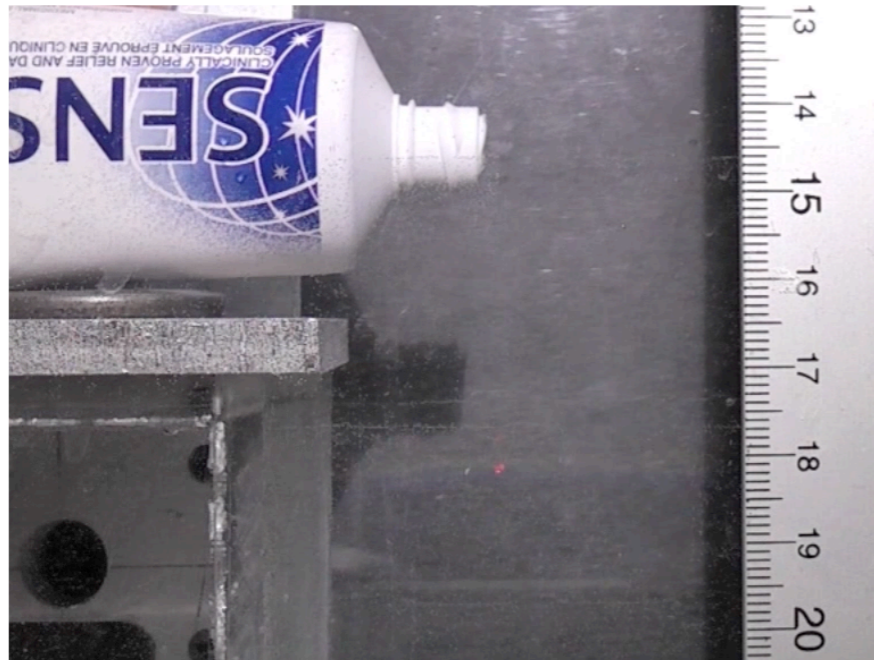


Prior et al 2010

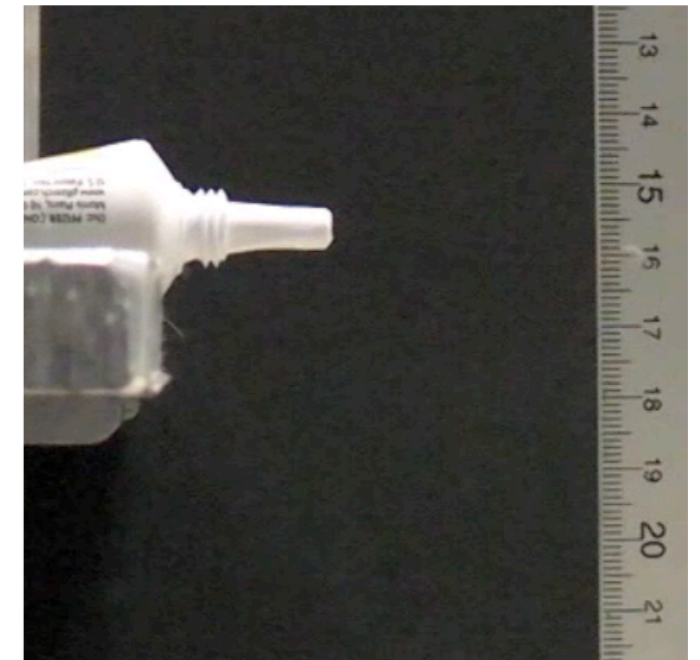
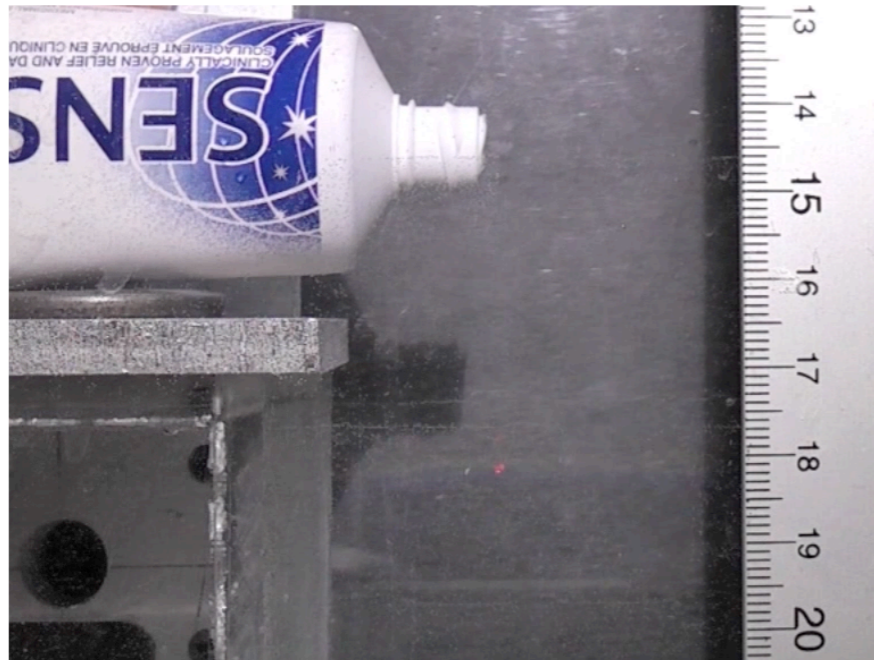
# Extrusion of a viscoplastic fluid



# Extrusion of a viscoplastic fluid



# Extrusion of a viscoplastic fluid

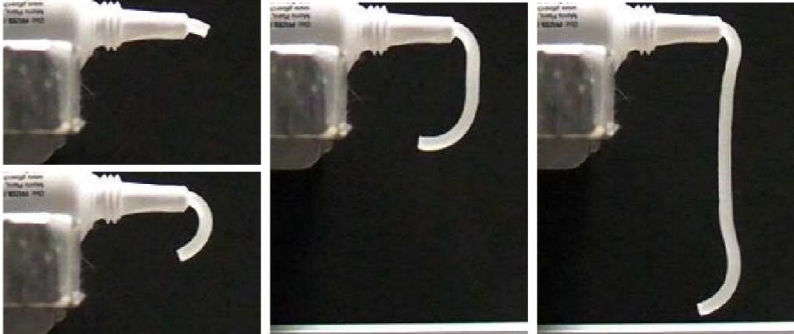


# Extruding a viscoplastic beam

Newtonian fluid



Bingham fluid

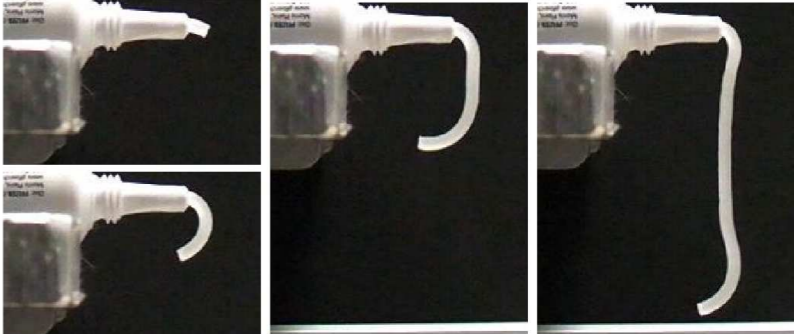


# Extruding a viscoplastic beam

Newtonian fluid



Bingham fluid

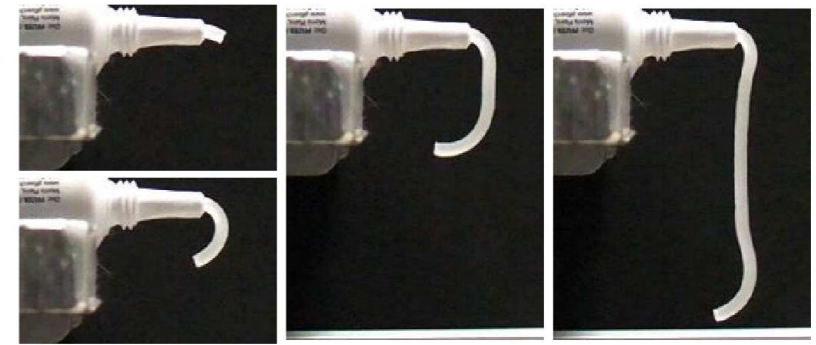


# Extruding a viscoplastic beam

Newtonian fluid



Bingham fluid

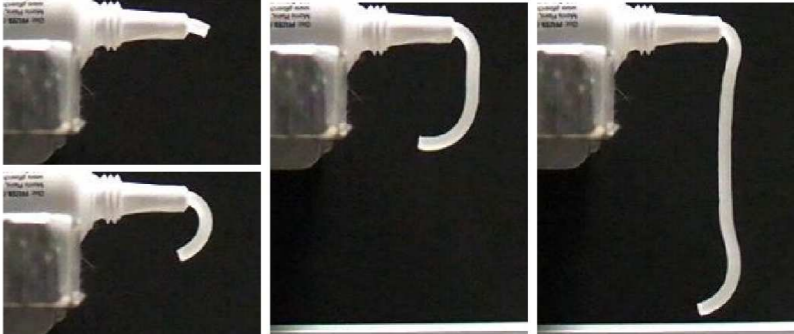


# Extruding a viscoplastic beam

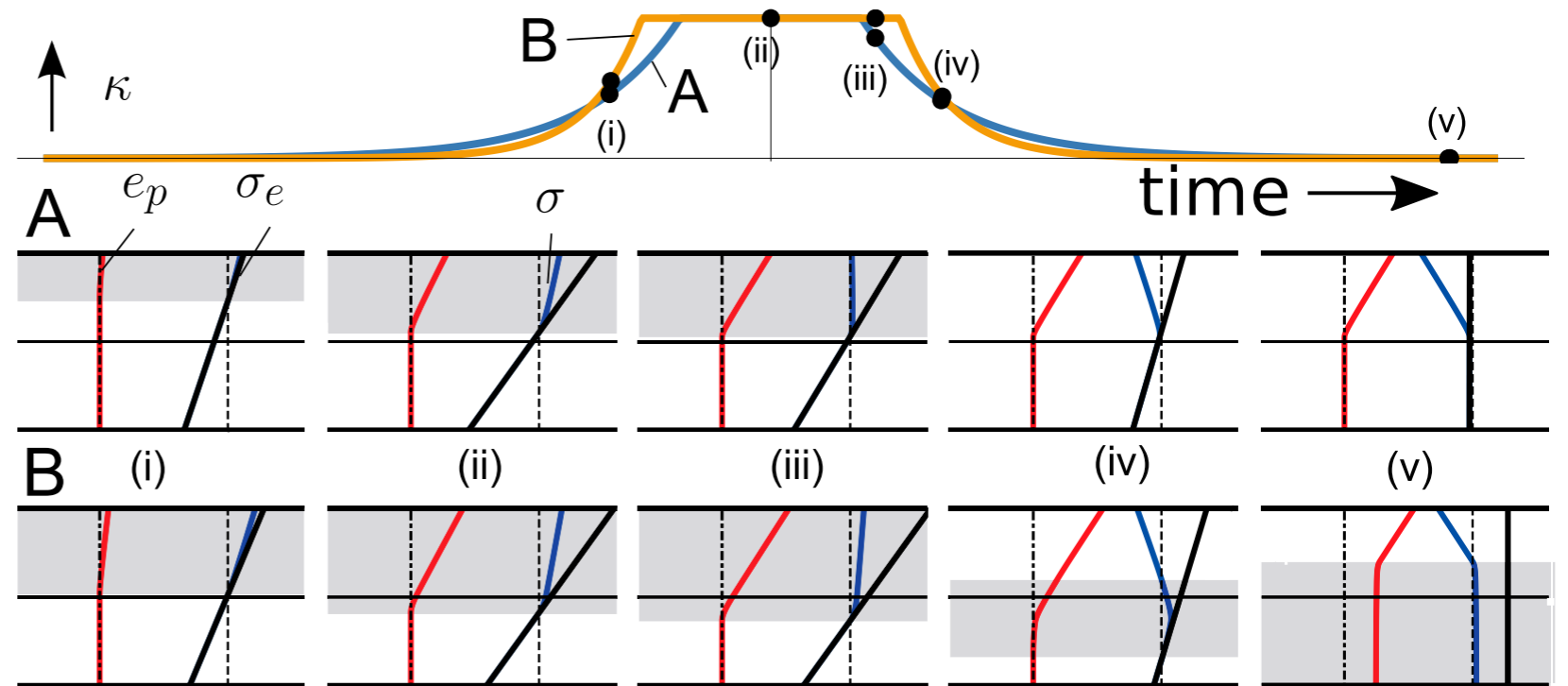
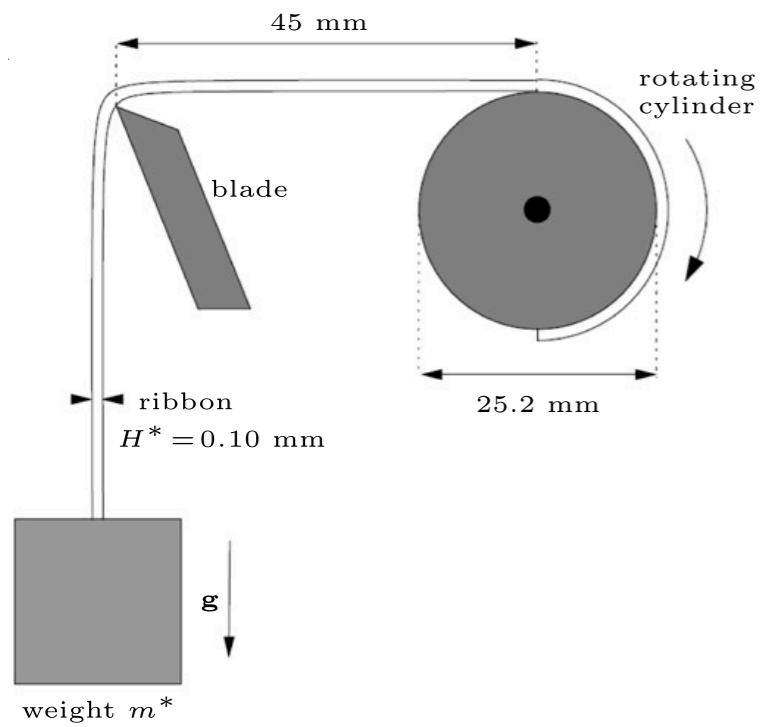
Newtonian fluid



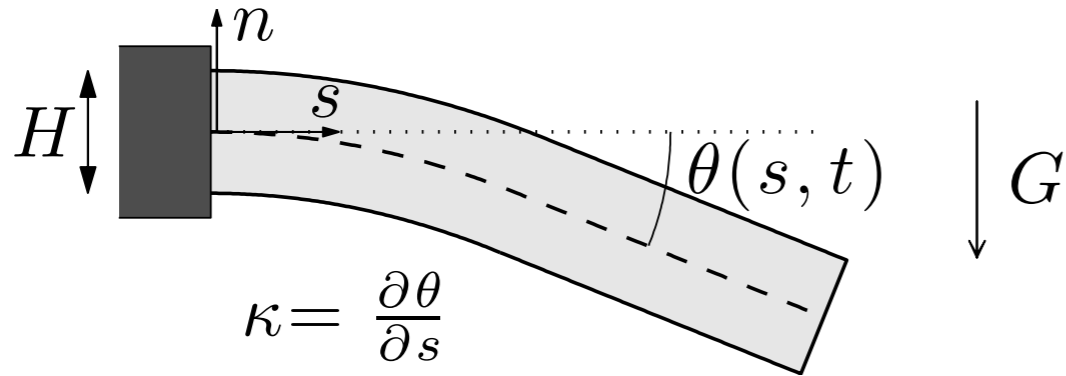
Bingham fluid



# Ribbon curling



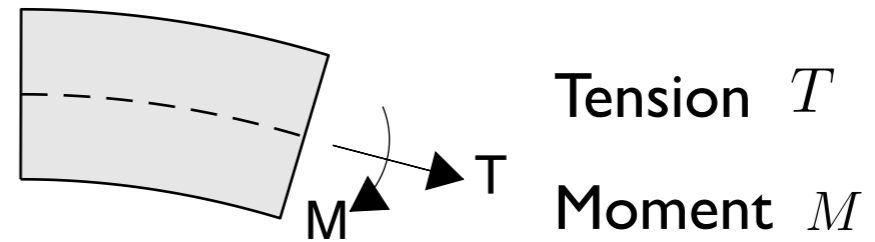
# Beam/ribbon models



Force balance

$$\frac{\partial T}{\partial s} - \kappa M = GH \sin \theta$$

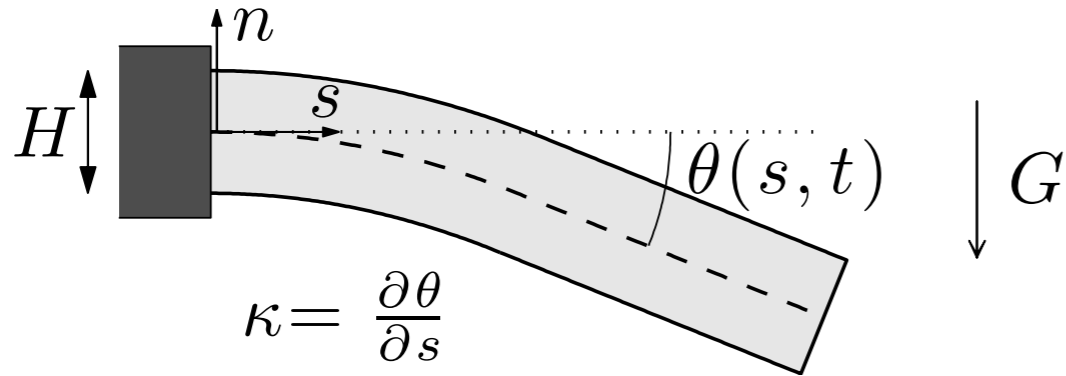
$$\frac{\partial^2 M}{\partial s^2} + \kappa T = GH \cos \theta$$



Viscida  $M = -\frac{\eta H^3}{3} \frac{\partial \kappa}{\partial t}$

Elastica  $M = -\frac{EH^3}{3} \kappa$

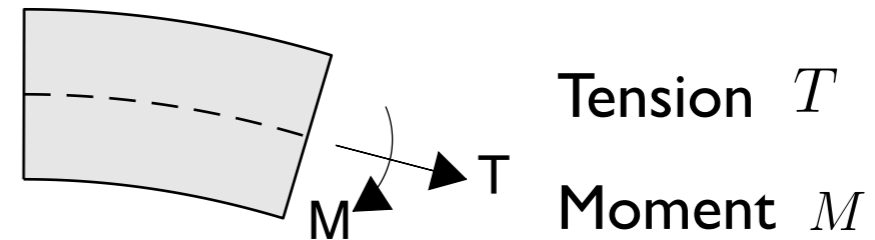
# Beam/ribbon models



Force balance

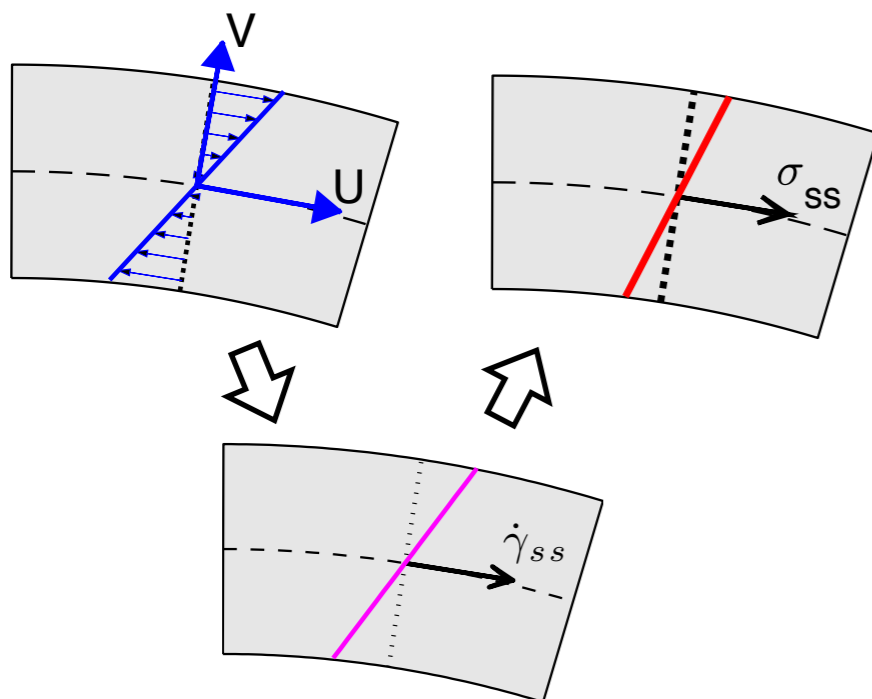
$$\frac{\partial T}{\partial s} - \kappa M = GH \sin \theta$$

$$\frac{\partial^2 M}{\partial s^2} + \kappa T = GH \cos \theta$$



Viscida  $M = -\frac{\eta H^3}{3} \frac{\partial \kappa}{\partial t}$

Elastica  $M = -\frac{EH^3}{3} \kappa$



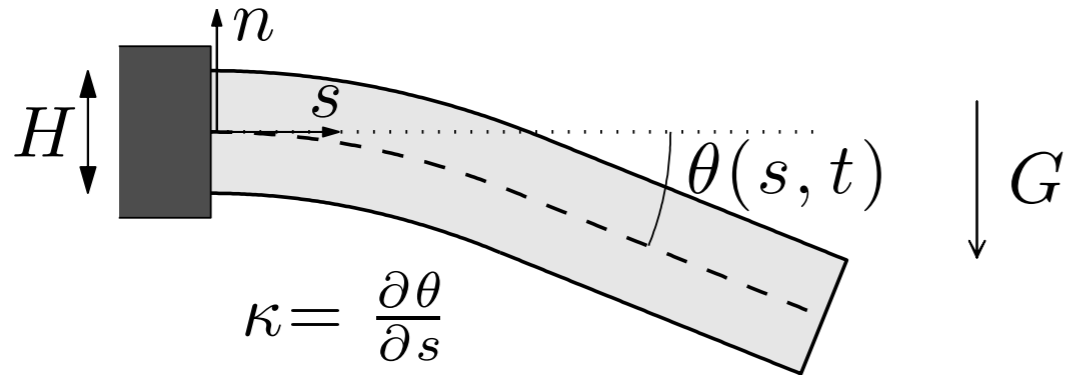
$$M = \int_{-\frac{1}{2}H}^{\frac{1}{2}H} n \sigma_{ss} \, dn$$

$$\sigma_{ss} = 2\tau_{ss} + O(\varepsilon)$$

$$\tau_{ss} = \eta \dot{\gamma}_{ss} \quad \dot{\gamma}_{ss} = 2 \left( \frac{\partial U}{\partial s} - \frac{\partial \kappa}{\partial t} n \right) + O(\varepsilon)$$

$$u(s, n, t) = U(s, t) - \frac{\partial \theta}{\partial t}(s, t) n + O(\varepsilon)$$

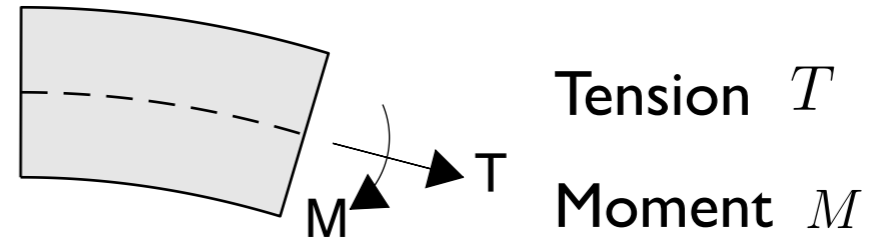
# Viscoplastic beams



Force balance

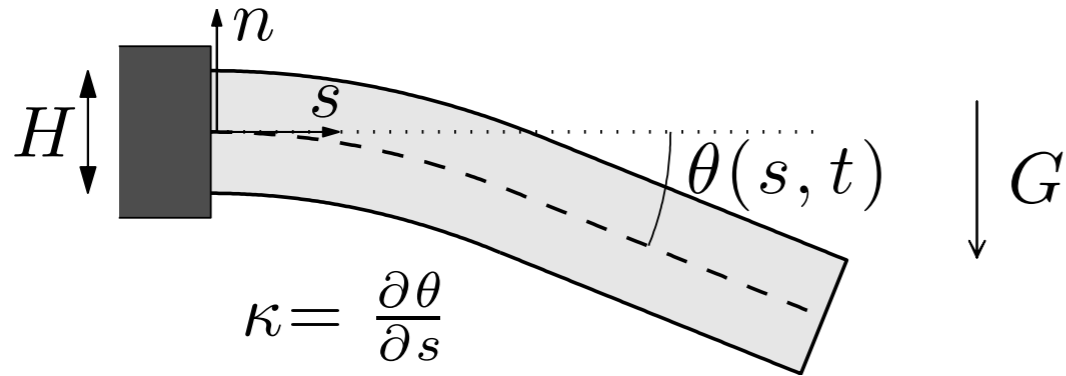
$$\frac{\partial T}{\partial s} - \kappa M = GH \sin \theta$$

$$\frac{\partial^2 M}{\partial s^2} + \kappa T = GH \cos \theta$$



Bingham model	{	$\dot{\gamma}_{ss} = 0$	$ \tau_{ss}  < B$
		$\tau_{ss} = \eta \dot{\gamma}_{ss} + B \text{sgn}(\dot{\gamma}_{ss})$	$ \tau_{ss}  > B$

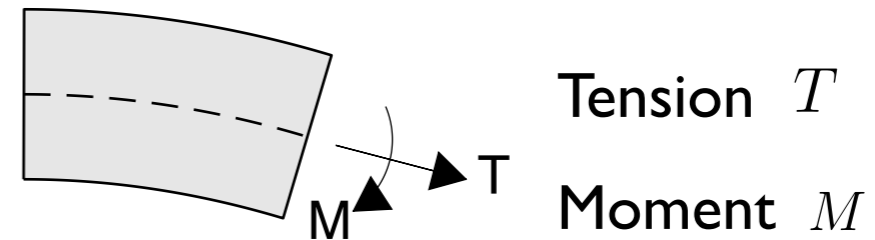
# Viscoplastic beams



Force balance

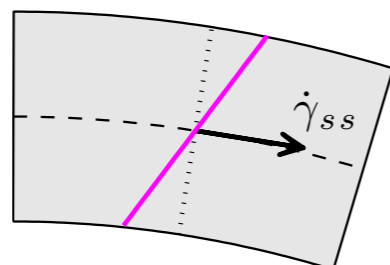
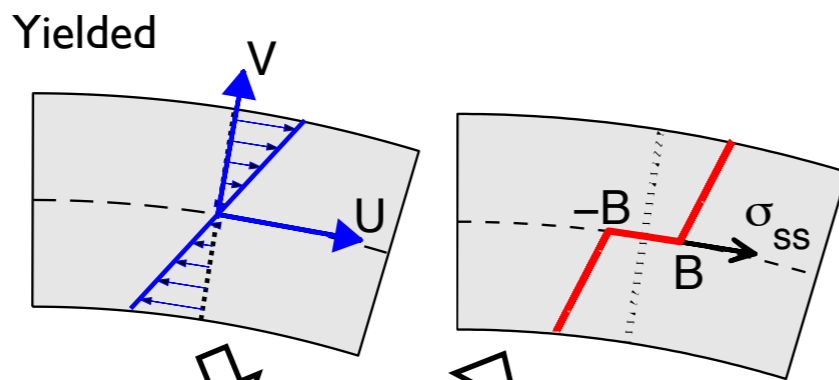
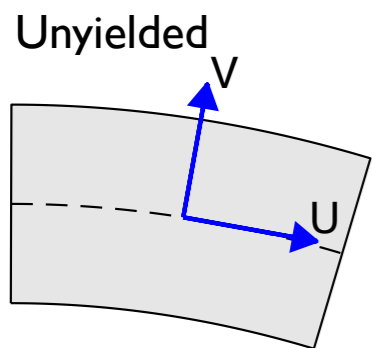
$$\frac{\partial T}{\partial s} - \kappa M = GH \sin \theta$$

$$\frac{\partial^2 M}{\partial s^2} + \kappa T = GH \cos \theta$$



Bingham model

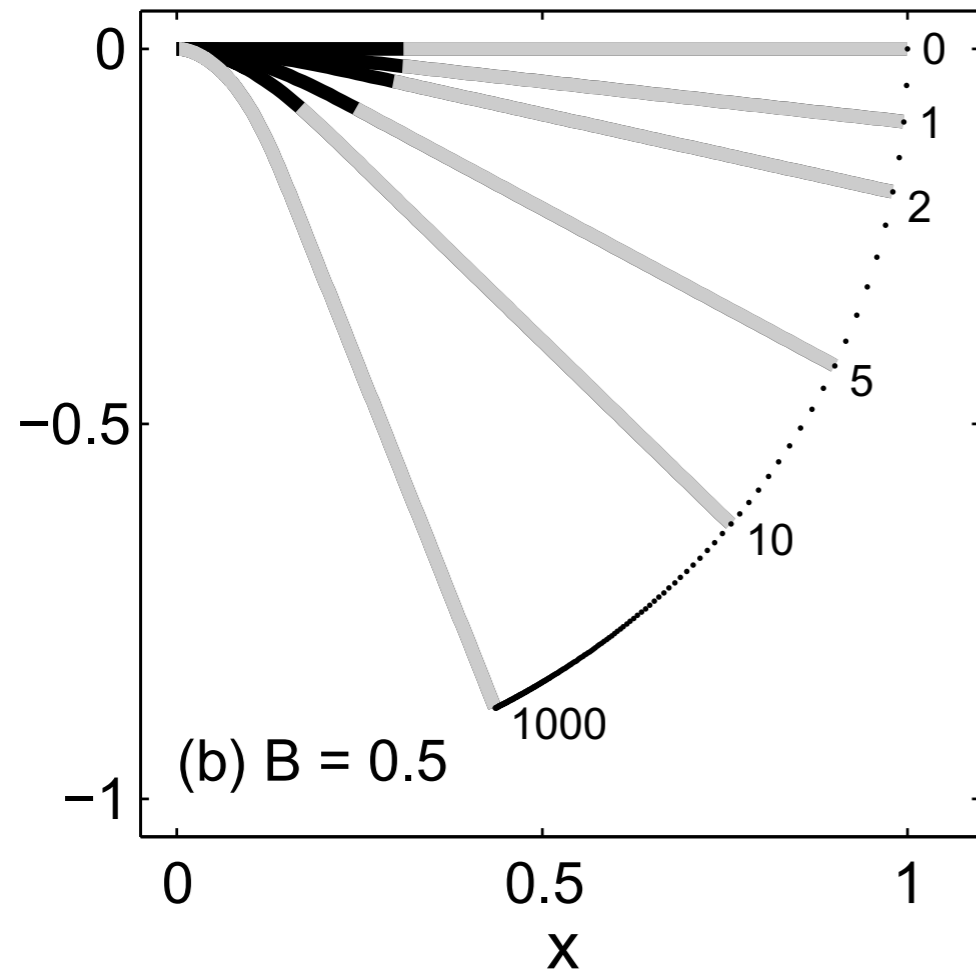
$$\begin{cases} \dot{\gamma}_{ss} = 0 & |\tau_{ss}| < B \\ \tau_{ss} = \eta \dot{\gamma}_{ss} + B \operatorname{sgn}(\dot{\gamma}_{ss}) & |\tau_{ss}| > B \end{cases}$$



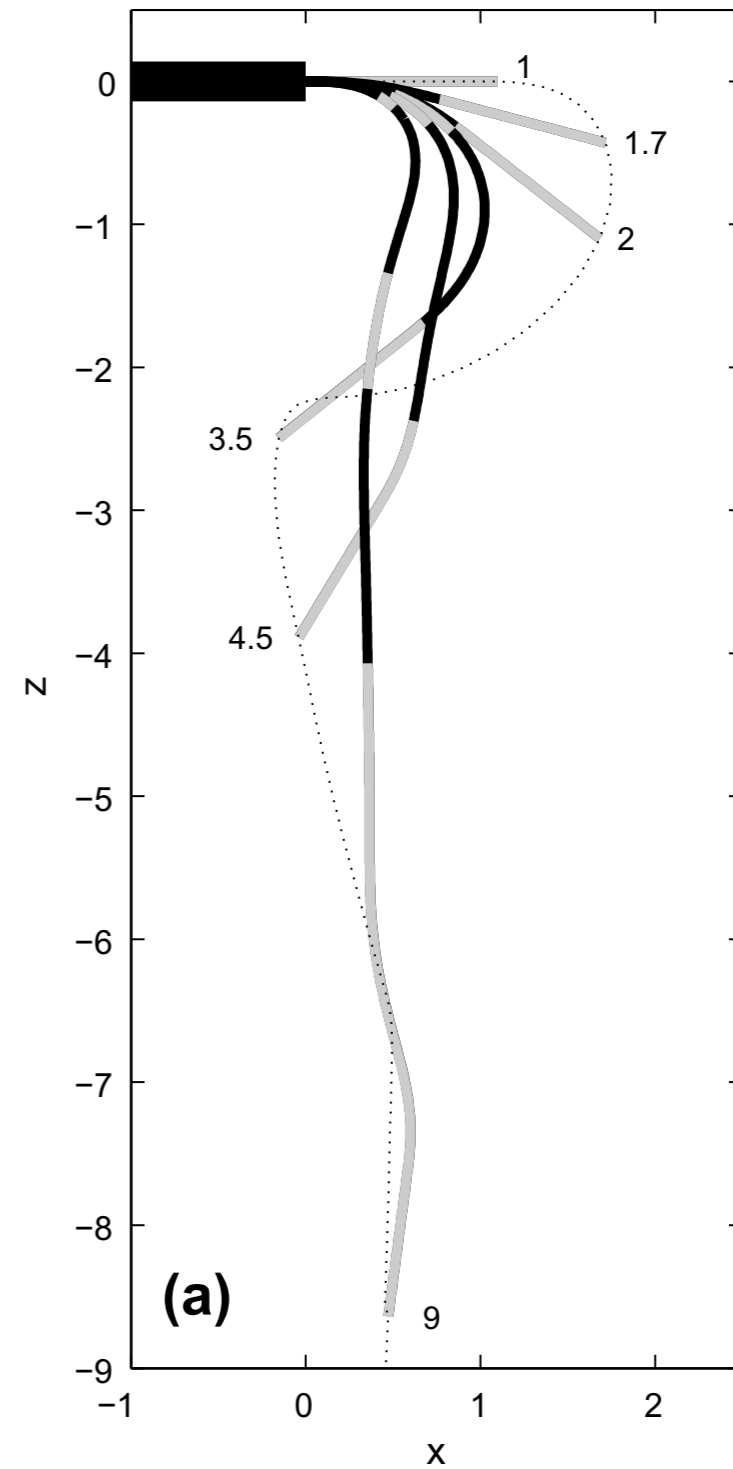
$$\begin{cases} \frac{\partial \kappa}{\partial t} = 0 & |M| \leq \frac{1}{2} BH^2 \\ M = -\frac{\eta H^3}{3} \frac{\partial \kappa}{\partial t} - \frac{1}{2} BH^2 \operatorname{sgn} \left( \frac{\partial \kappa}{\partial t} \right) & |M| > \frac{1}{2} BH^2 \end{cases}$$

# Viscoplastic beams

## Sagging beam

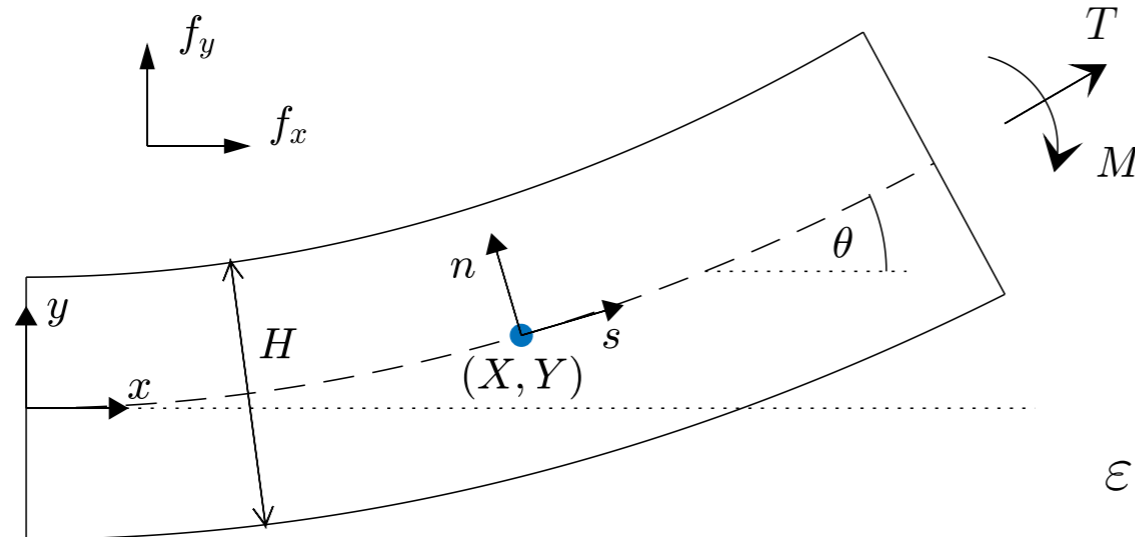


## Extruded thread



# Visco-elastica

**Aim:** consider the equivalent model for a viscoelastic fluid



$$\frac{\partial X}{\partial s} = \cos \theta \quad \frac{\partial Y}{\partial s} = \sin \theta$$

Curvature  $\kappa = \frac{\partial \theta}{\partial s}$

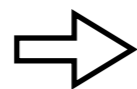
$$\epsilon = \frac{\mathcal{H}}{\mathcal{L}}$$

Force balance equations  
in curvilinear coordinates  
(ignore inertia)

$$\frac{\partial \sigma_{ss}}{\partial s} + \frac{1}{\epsilon}(1 - \epsilon \kappa n) \frac{\partial \sigma_{sn}}{\partial n} - 2\kappa \sigma_{sn} = -\epsilon(1 - \epsilon \kappa n) f_s$$

$$\frac{\partial \sigma_{sn}}{\partial s} + \frac{1}{\epsilon}(1 - \epsilon \kappa n) \frac{\partial \sigma_{nn}}{\partial n} + \kappa(\sigma_{ss} - \sigma_{nn}) = -\epsilon(1 - \epsilon \kappa n) f_n$$

Integrate over width  
(with stress-free sides)



$$\frac{\partial T}{\partial s} - \kappa \frac{\partial M}{\partial s} = -f_s$$

$$\frac{\partial^2 M}{\partial s^2} + \kappa T = -f_n$$

(independent of rheology)

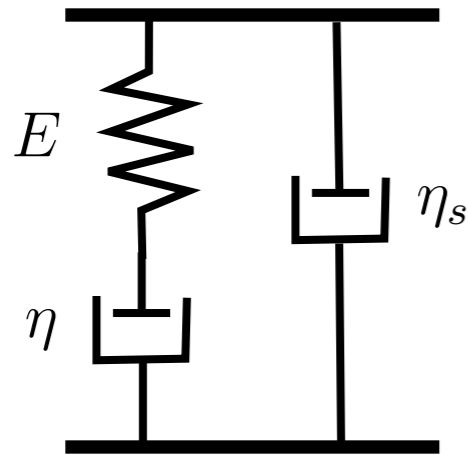
Tension  $T = \frac{1}{\epsilon} \int_{-\frac{1}{2}H}^{\frac{1}{2}H} \sigma_{ss} \, dn$

Moment  $M = \int_{-\frac{1}{2}H}^{\frac{1}{2}H} n \sigma_{ss} \, dn$

Also note  $\sigma_{sn} = O(\epsilon)$   
 $\sigma_{nn} = O(\epsilon)$

# Oldroyd B constitutive model

A common rheological model for viscoelastic fluids



solvent viscosity

$$\sigma_{ij} = -p\delta_{ij} + \eta_s \dot{\gamma}_{ij} + \tau_{ij} \qquad \dot{\gamma}_{ij} = \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}$$

'polymer' stress

$$\frac{1}{E} \overset{\nabla}{\tau}_{ij} + \frac{1}{\eta} \tau_{ij} = \dot{\gamma}_{ij}$$

creep viscosity  
elastic shear modulus

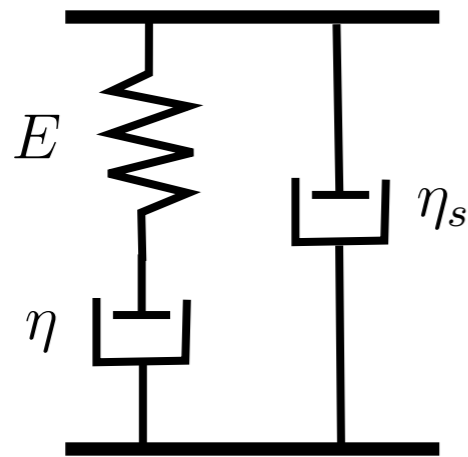
$\eta_s \rightarrow 0$  Maxwell fluid

$\eta \rightarrow \infty$  Kelvin fluid

In our case the important quantity is the stress component  $\sigma_{ss} = \tau_{ss} - \tau_{nn} + 2\eta_s \dot{\gamma}_{ss} + O(\varepsilon)$

# Oldroyd B constitutive model

A common rheological model for viscoelastic fluids



solvent viscosity

$$\sigma_{ij} = -p\delta_{ij} + \eta_s \dot{\gamma}_{ij} + \tau_{ij} \quad \dot{\gamma}_{ij} = \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}$$

'polymer' stress

$$\frac{1}{E} \overset{\nabla}{\tau}_{ij} + \frac{1}{\eta} \tau_{ij} = \dot{\gamma}_{ij}$$

creep viscosity  
elastic shear modulus

$\eta_s \rightarrow 0$  Maxwell fluid

$\eta \rightarrow \infty$  Kelvin fluid

In our case the important quantity is the stress component  $\sigma_{ss} = \tau_{ss} - \tau_{nn} + 2\eta_s \dot{\gamma}_{ss} + O(\varepsilon)$

$$\frac{1}{E} \left[ \frac{D\tau_{ss}}{Dt} - \frac{2\varepsilon}{1 - \varepsilon\kappa\eta} \tau_{ss} \left( \frac{\partial u}{\partial s} - \kappa v \right) - 2\tau_{sn} \frac{\partial u}{\partial n} \right] + \frac{1}{\eta} \tau_{ss} = \dot{\gamma}_{ss}$$

$$\frac{1}{E} \left[ \frac{D\tau_{sn}}{Dt} - \frac{\varepsilon}{1 - \varepsilon\kappa\eta} \tau_{ss} \left( \frac{\partial v}{\partial s} + \kappa u + \frac{1}{\varepsilon} \frac{\partial \theta}{\partial t} \right) - \tau_{nn} \frac{\partial u}{\partial n} \right] + \frac{1}{\eta} \tau_{sn} = \dot{\gamma}_{sn}$$

$$\frac{1}{E} \left[ \frac{D\tau_{nn}}{Dt} - \frac{2\varepsilon}{1 - \varepsilon\kappa\eta} \tau_{sn} \left( \frac{\partial v}{\partial s} + \kappa u + \frac{1}{\varepsilon} \frac{\partial \theta}{\partial t} \right) - 2\tau_{nn} \frac{\partial v}{\partial n} \right] + \frac{1}{\eta} \tau_{nn} = \dot{\gamma}_{nn}$$

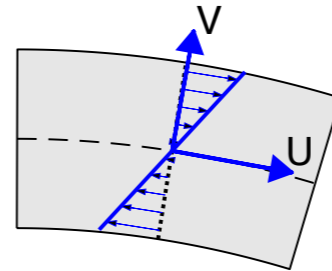
# Asymptotic derivation

## Strain-rate components

$$\dot{\gamma}_{ss} = \frac{2}{1 - \varepsilon \kappa n} \left( \frac{\partial u}{\partial s} - \kappa v \right) \quad \dot{\gamma}_{sn} = \frac{1}{1 - \varepsilon \kappa n} \left( \frac{\partial v}{\partial s} + \kappa u + \frac{1}{\varepsilon} \frac{\partial \theta}{\partial t} \right) + \frac{1}{\varepsilon} \frac{\partial u}{\partial n} \quad \dot{\gamma}_{nn} = \frac{2}{\varepsilon} \frac{\partial v}{\partial n}$$

**Deduce**  $v(s, n, t) = O(\varepsilon)$

$$u(s, n, t) = U(s, t) - \frac{\partial \theta}{\partial t}(s, t) n + O(\varepsilon)$$



$$\Rightarrow \dot{\gamma}_{ss} = 2 \left( \frac{\partial U}{\partial s} - \frac{\partial \kappa}{\partial t} n \right)$$

$$\tau_{nn} = -\tau_{ss}$$

$$\frac{1}{E} \frac{\partial \tau_{ss}}{\partial t} + \frac{1}{\eta} \tau_{ss} = 2 \left( \frac{\partial U}{\partial s} - \frac{\partial \kappa}{\partial t} n \right)$$

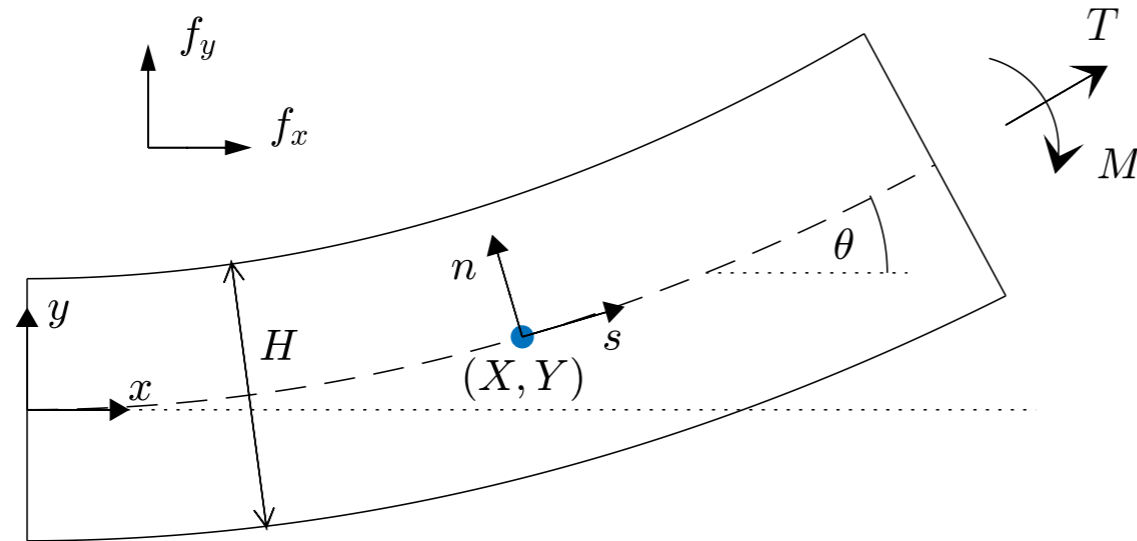
$$\Rightarrow \sigma_{ss} = 2\tau_{ss} + 4\eta_s \left( \frac{\partial U}{\partial s} - \frac{\partial \kappa}{\partial t} n \right)$$

**Width-integrating gives expressions for tension/moment**

$$\varepsilon \left( \frac{1}{E} \frac{\partial}{\partial t} + \frac{1}{\eta} \right) T = 4H \frac{\partial U}{\partial s} + \left( \frac{1}{E} \frac{\partial}{\partial t} + \frac{1}{\eta} \right) 4H\eta_s \frac{\partial U}{\partial s}$$

$$\left( \frac{1}{E} \frac{\partial}{\partial t} + \frac{1}{\eta} \right) M = -\frac{1}{3} H^3 \frac{\partial \kappa}{\partial t} - \left( \frac{1}{E} \frac{\partial}{\partial t} + \frac{1}{\eta} \right) \frac{1}{3} H^3 \eta_s \frac{\partial \kappa}{\partial t}$$

# Visco-elastica



$$\frac{\partial X}{\partial s} = \cos \theta \quad \frac{\partial Y}{\partial s} = \sin \theta$$

Curvature  $\kappa = \frac{\partial \theta}{\partial s}$

$$\frac{\partial T}{\partial s} - \kappa \frac{\partial M}{\partial s} = -f_s$$

$$\frac{\partial^2 M}{\partial s^2} + \kappa T = -f_n$$

$$\left( \frac{1}{E} \frac{\partial}{\partial t} + \frac{1}{\eta} \right) M = -\frac{1}{3} H^3 \frac{\partial \kappa}{\partial t} - \left( \frac{1}{E} \frac{\partial}{\partial t} + \frac{1}{\eta} \right) \frac{1}{3} H^3 \eta_s \frac{\partial \kappa}{\partial t}$$

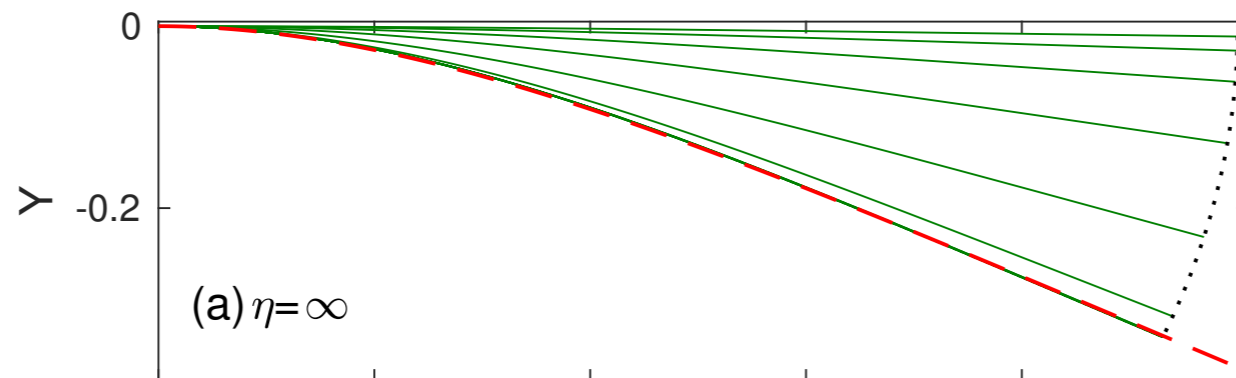
At free end  $T = M = \frac{\partial M}{\partial s} = 0$

The moment can alternatively be expressed in **integral** form

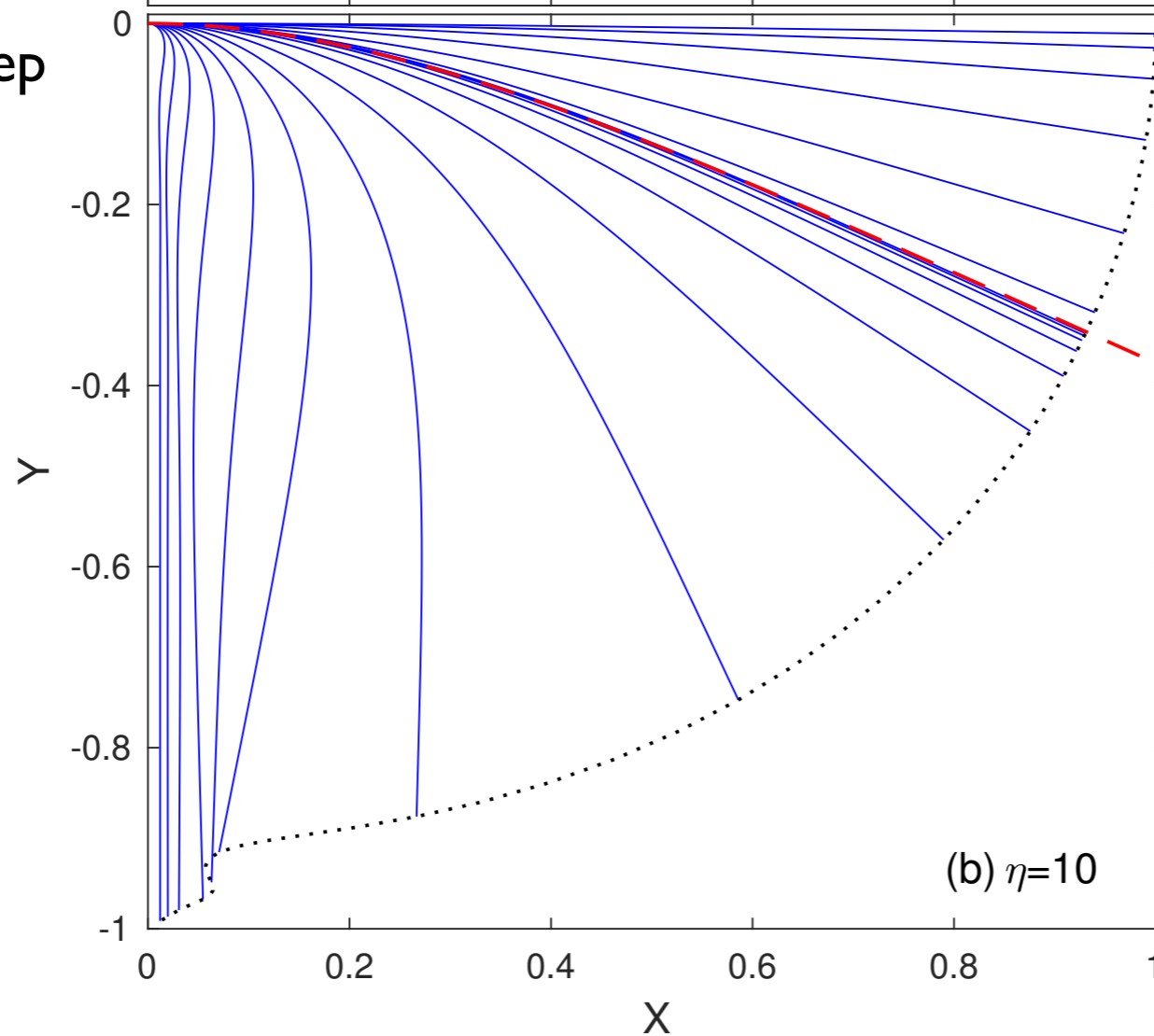
$$M + \frac{1}{3} E \kappa + \frac{1}{3} \eta_s \frac{\partial \kappa}{\partial t} = \left( M + \frac{1}{3} E \kappa + \frac{1}{3} \eta_s \frac{\partial \kappa}{\partial t} \right) \Big|_{t=0} e^{-Et/\eta} + \frac{E^2}{3\eta} \int_0^t \kappa(t') e^{-E(t-t')/\eta} dt'$$

# Sagging viscoelastic beam

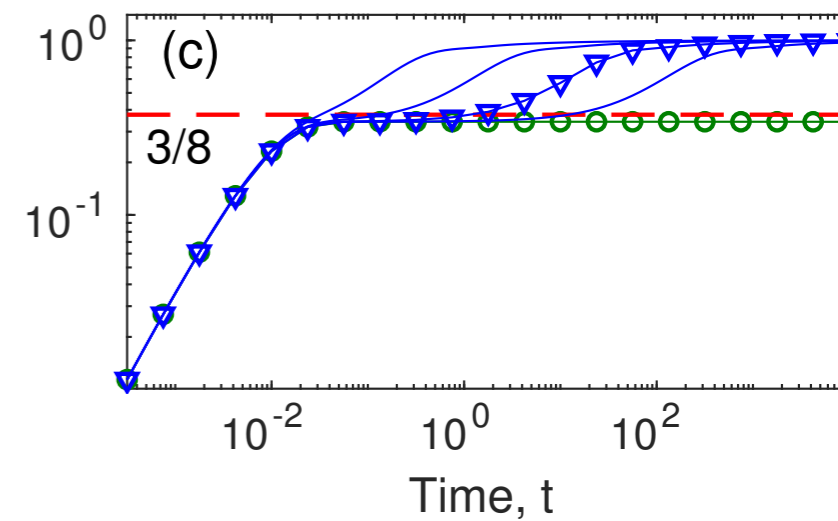
**Kelvin** limit -  
relaxes to elastic  
solution



with long-term creep



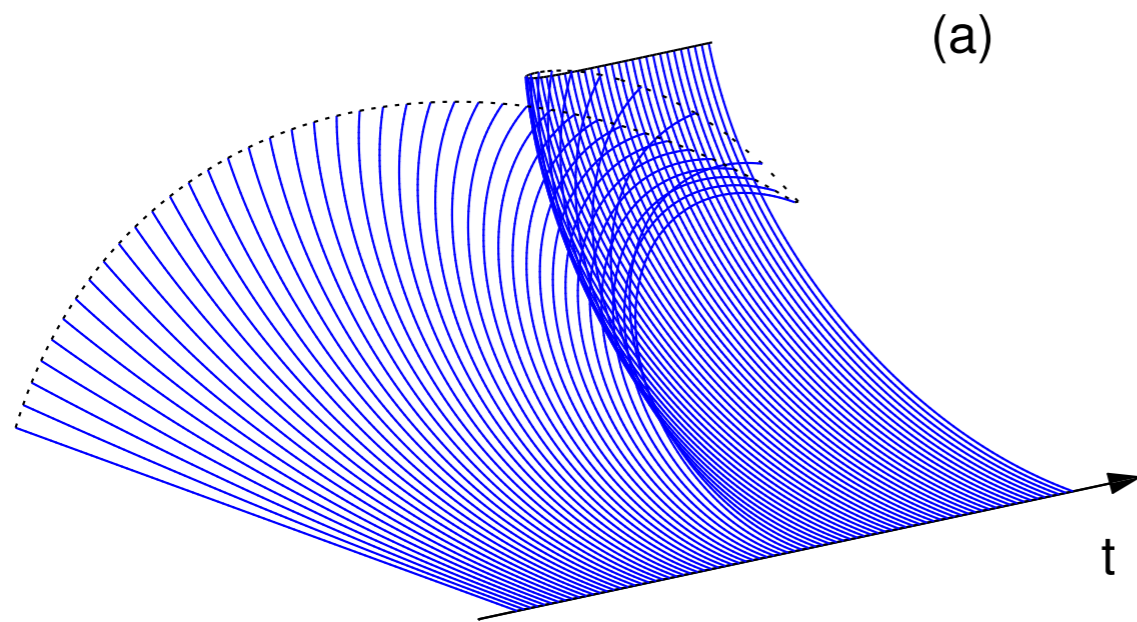
Vertical end displacement



# Viscoelastic curling

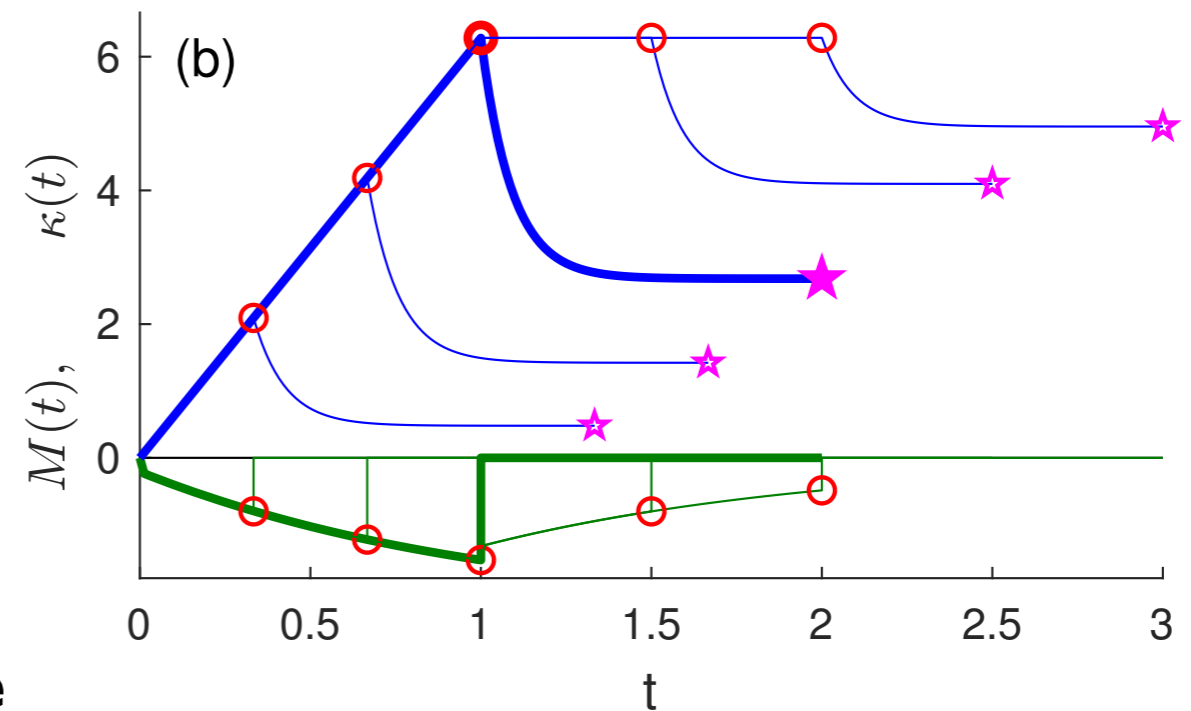
$$\kappa = \kappa(t) \quad M = M(t)$$

$$\frac{dM}{dt} + \frac{E}{\eta}M = -\frac{1}{3} \left[ E \left( 1 + \frac{\eta_s}{\eta} \right) \frac{d\kappa}{dt} + \eta_s \frac{d^2\kappa}{dt^2} \right]$$



**Curling phase**  
imposed curvature,  
moment relaxes

**Release phase**  
zero moment,  
curvature relaxes



# Visco-elasto-plastica

Reintroduce the **yield stress**  $B$

$$\frac{1}{E} \dot{\tau}_{ij} + \frac{1}{\eta} \max \left( 0, 1 - \frac{B}{\tau_I} \right) \tau_{ij} = \dot{\gamma}_{ij} \quad (\text{Saramito 2007})$$

$$\sigma_{ij} = -p\delta_{ij} + \eta_s \dot{\gamma}_{ij} + \tau_{ij} \quad \dot{\gamma}_{ij} = \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i}$$

---

Following similar analysis....

$$\frac{1}{E} \frac{\partial \tau_{ss}}{\partial t} + \frac{\tau_{ss}}{\eta} \max \left( 0, 1 - \frac{B}{|\tau_{ss}|} \right) = -2n \frac{\partial \kappa}{\partial t} \quad (\text{Prior 2016})$$

The non-linearity means a fully width-integrated model is not possible.

Instead, split the strain into **elastic** and **plastic** components  $-n\kappa = \frac{\tau_{ss}}{2E} + \gamma_p(s, n, t)$

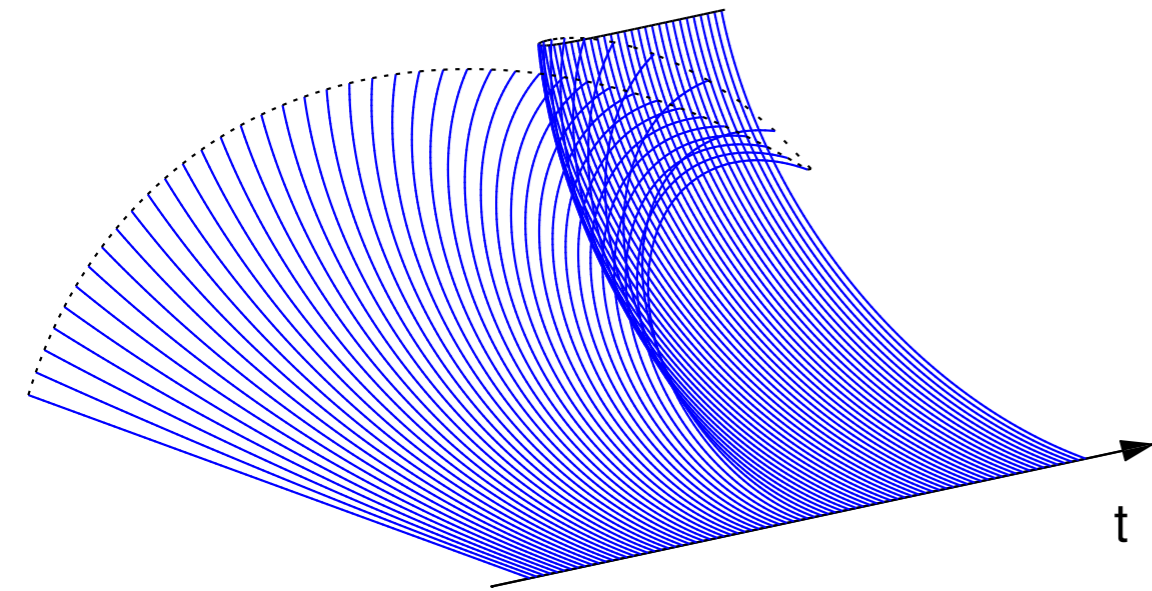
... the moment is given by

$$M = -\frac{1}{3} E H^3 \kappa - \frac{1}{3} \eta_s H^3 \frac{\partial \kappa}{\partial t} - 4E \int_{-\frac{1}{2}H}^{\frac{1}{2}H} n \gamma_p \, dn$$

where

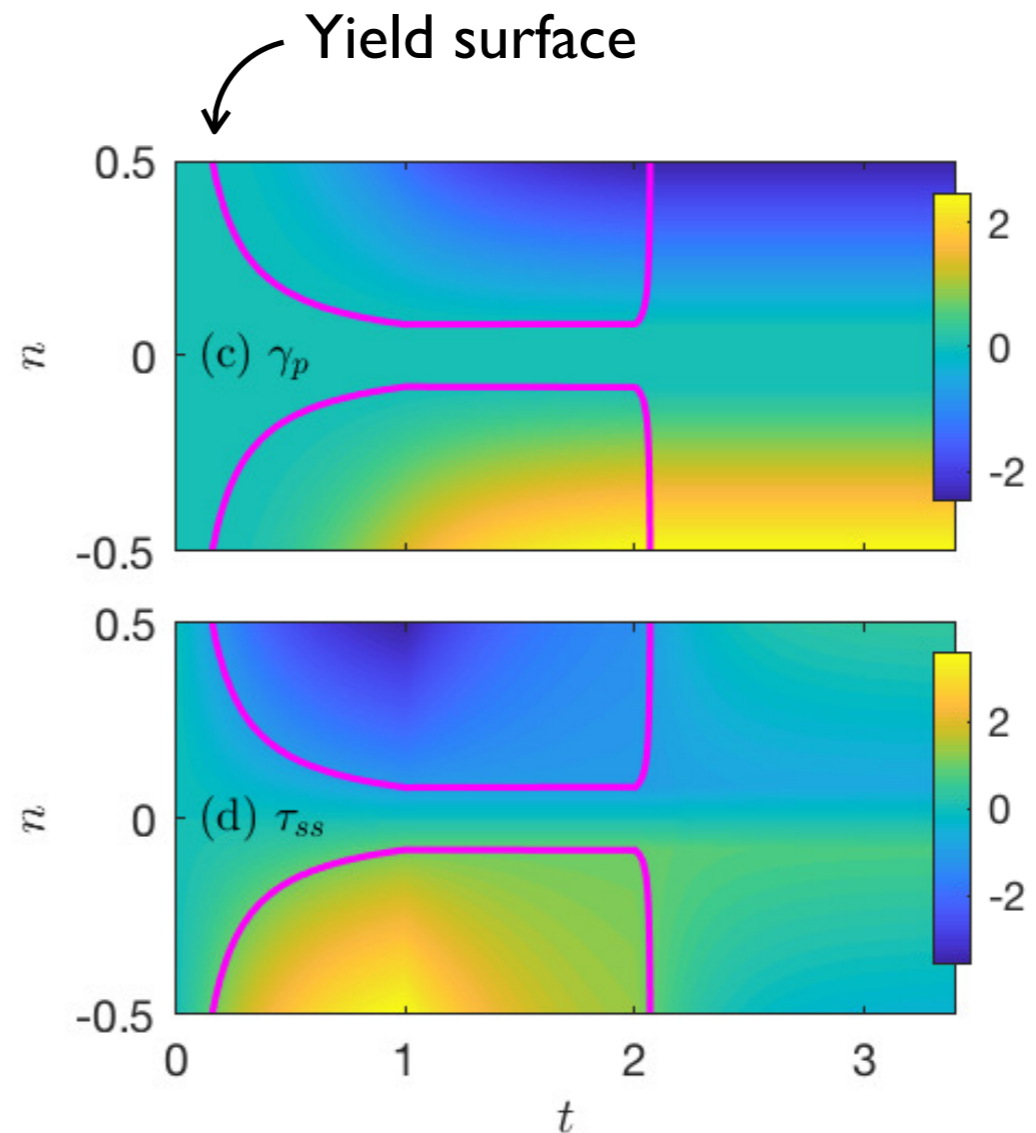
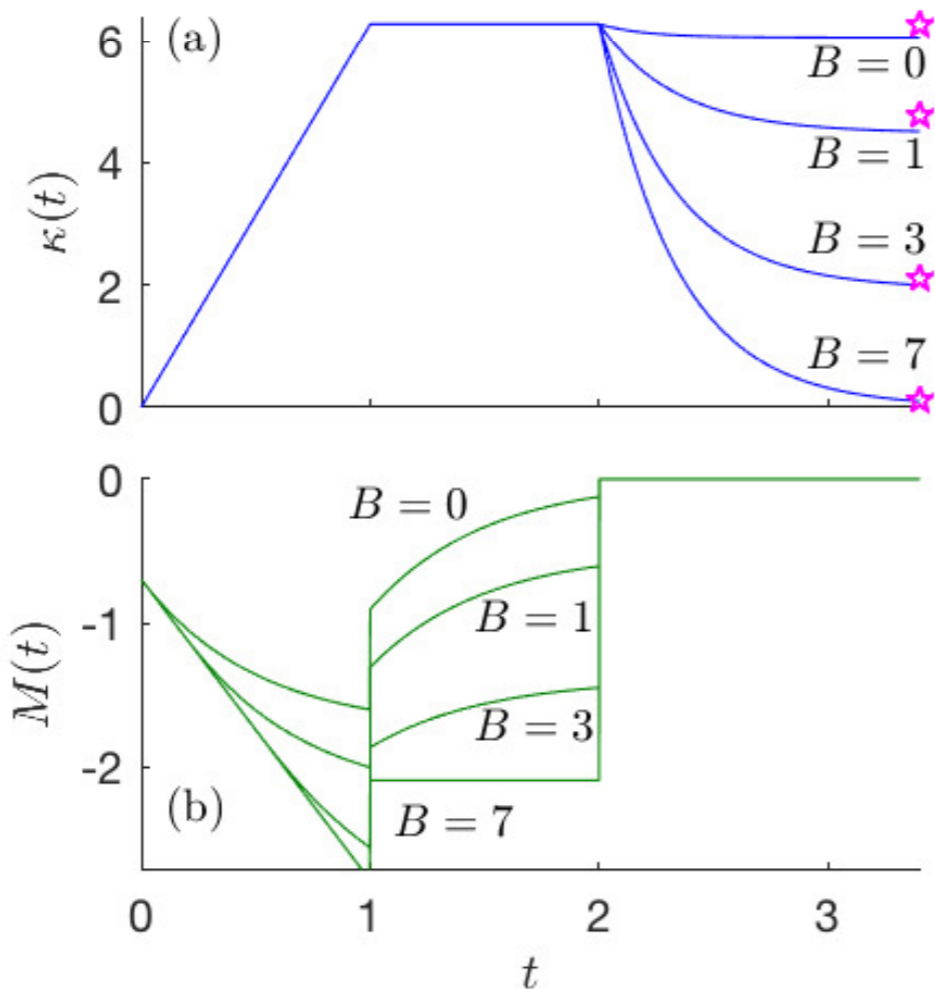
$$\frac{\partial \gamma_p}{\partial t} = -\frac{E}{\eta} \max \left( 0, |n\kappa + \gamma_p| - \frac{B}{2E} \right) \text{sgn}(n\kappa + \gamma_p)$$

# Curling revisited



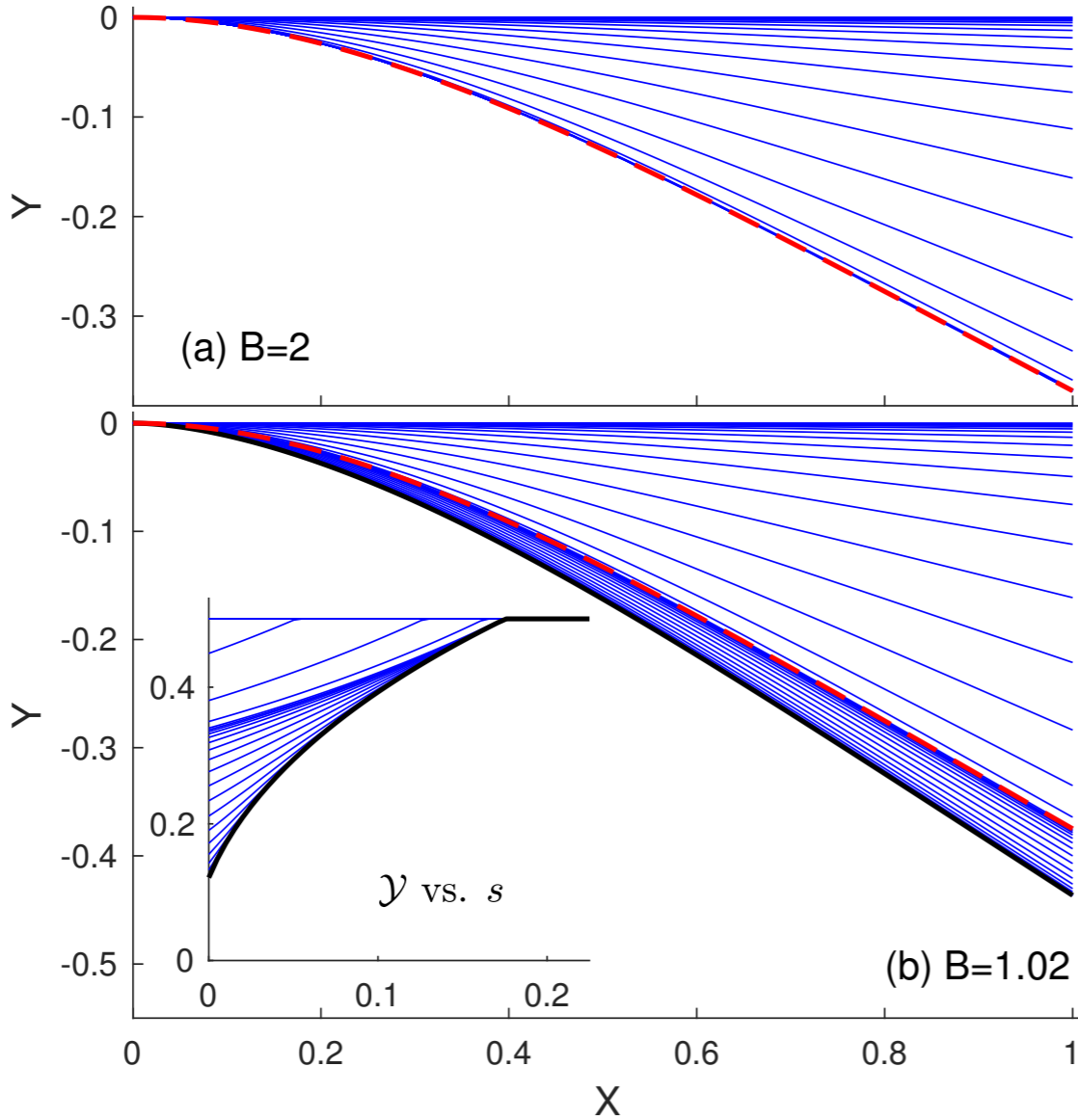
$$M = -\frac{1}{3}EH^3\kappa - \frac{1}{3}\eta_s H^3 \frac{\partial \kappa}{\partial t} - 4E \int_{-\frac{1}{2}H}^{\frac{1}{2}H} n\gamma_p \, dn$$

$$\frac{\partial \gamma_p}{\partial t} = -\frac{E}{\eta} \max\left(0, |n\kappa + \gamma_p| - \frac{B}{2E}\right) \text{sgn}(n\kappa + \gamma_p)$$



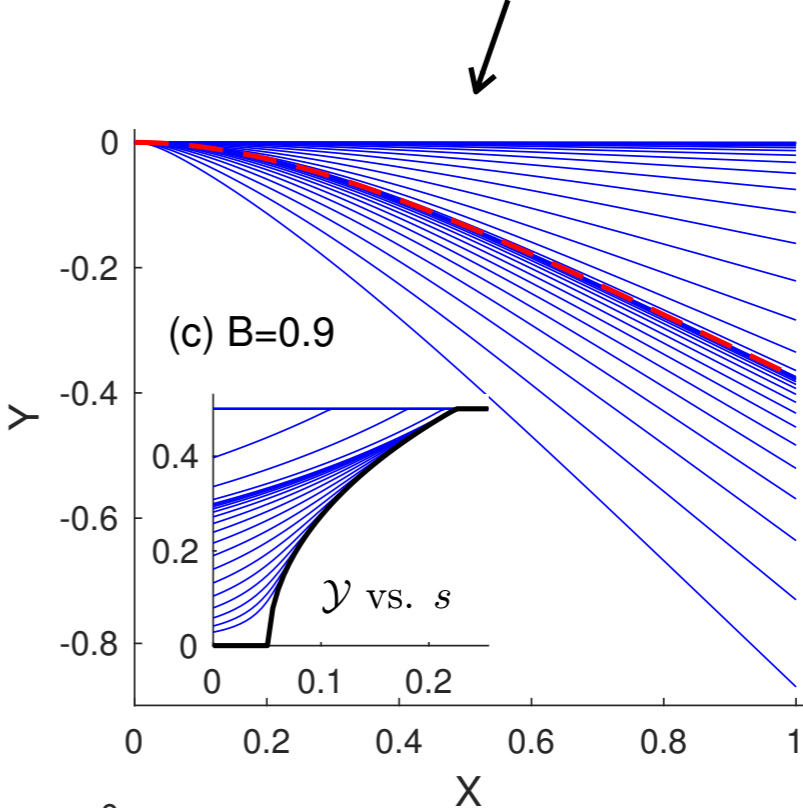
# Sagging revisited

**High** yield stress - sags to elastic solution

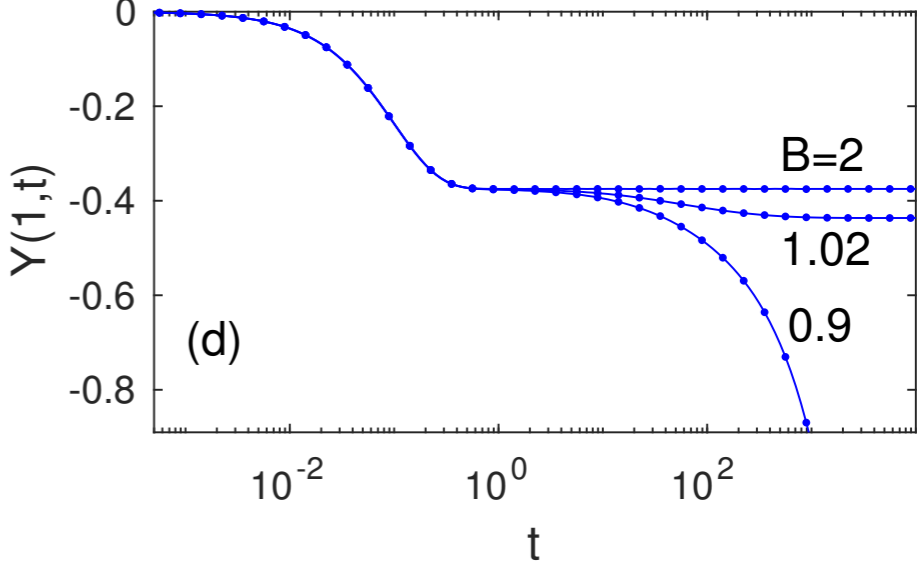


**Intermediate** yield stress - creeps towards an elasto-plastic equilibrium

**Low** yield stress - continues to creep



Vertical end displacement



# Summary

We can derive beam-like models using a variety of microscopic fluid rheologies.

The models reduce to standard equations for an elastica or viscida in the appropriate limits.

The visco-elastic model allows for a simple description of curling and sagging.

The visco-elasto-plastic model generalises previous visco-elastic and visco-plastic models that have been used to explain the curling of ribbons.

The models behave quite differently for small curvature, when tension becomes more important.

