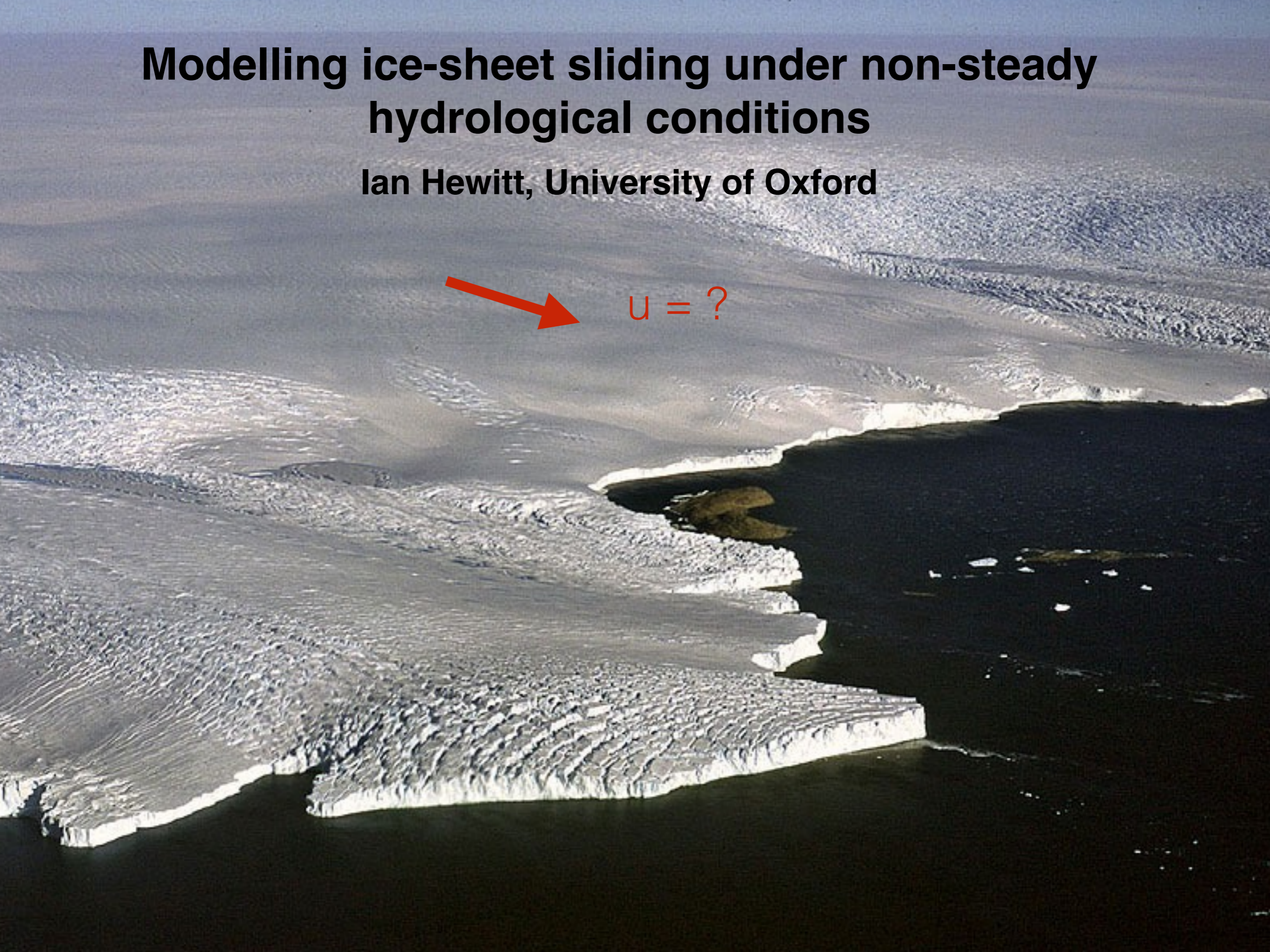


# Modelling ice-sheet sliding under non-steady hydrological conditions

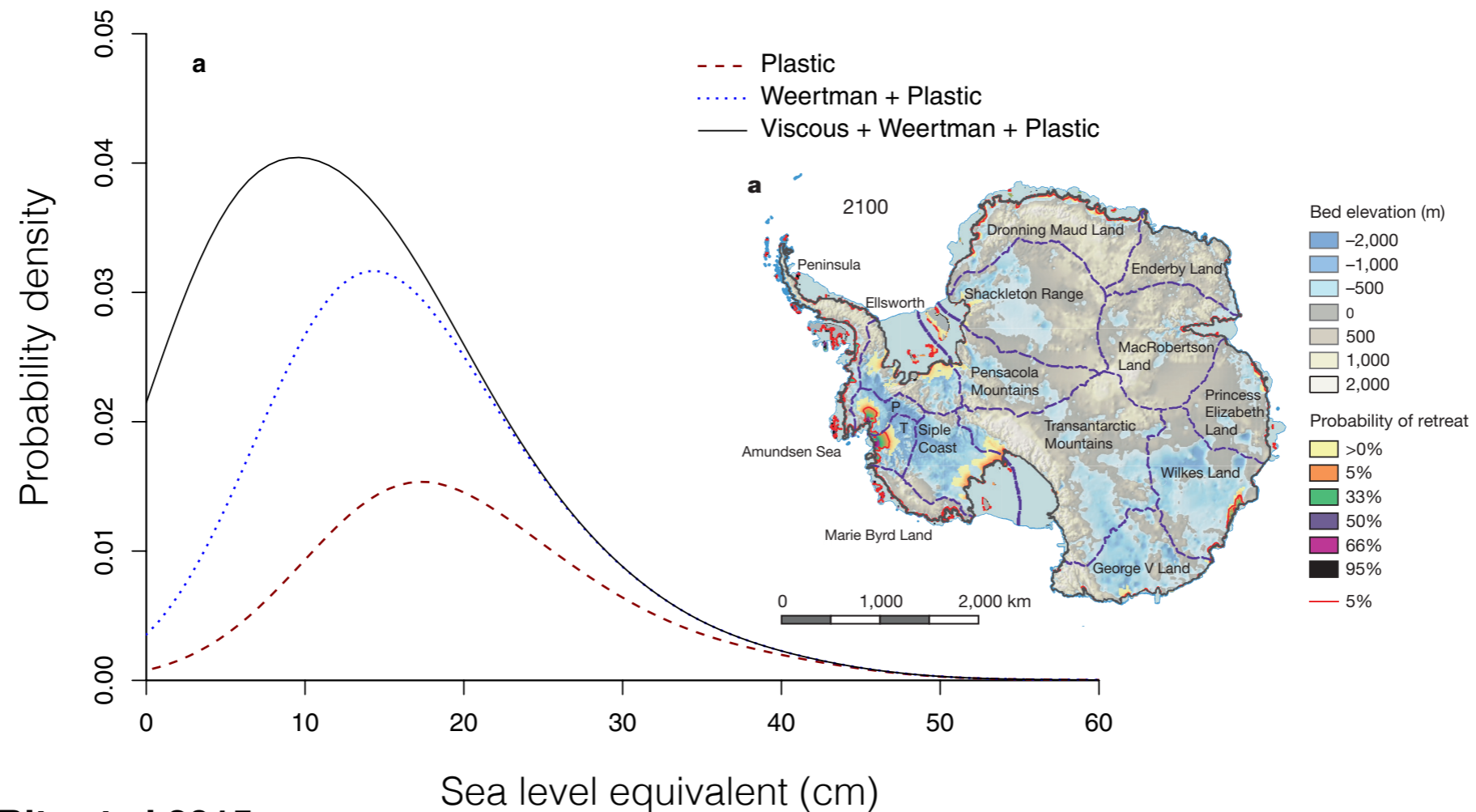
Ian Hewitt, University of Oxford



# Motivation: large-scale ice-sheet flow

The basal **sliding law / friction law** represents a (perhaps **the**) major uncertainty in current forecasts of sea-level rise.

Using different sliding laws results in different modelled behaviour.

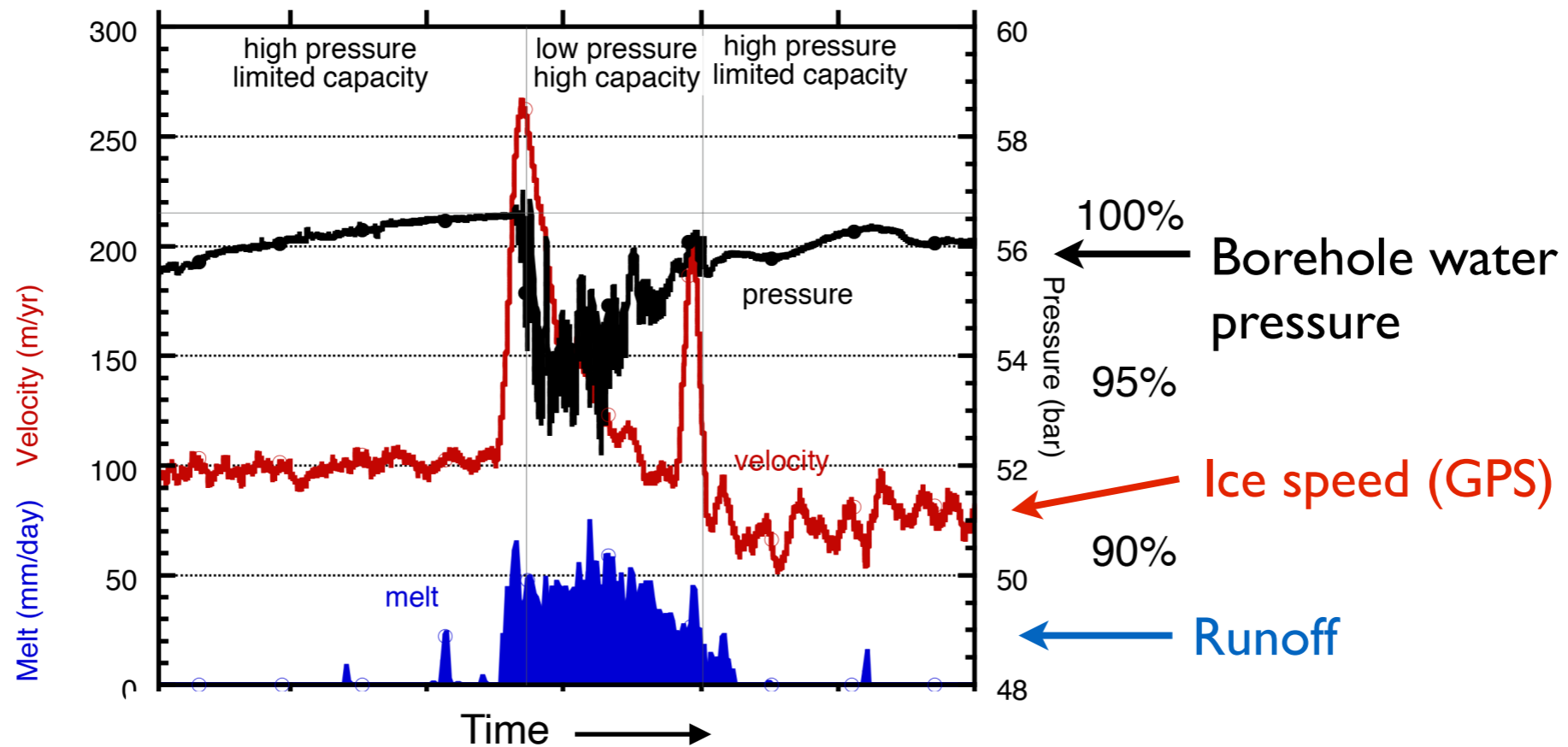


Ritz et al 2015

➔ We'd like to understand more about what controls ice-sheet sliding

# Motivation: subglacial water

Sliding is strongly affected by the presence of **water** at the ice-bed interface.



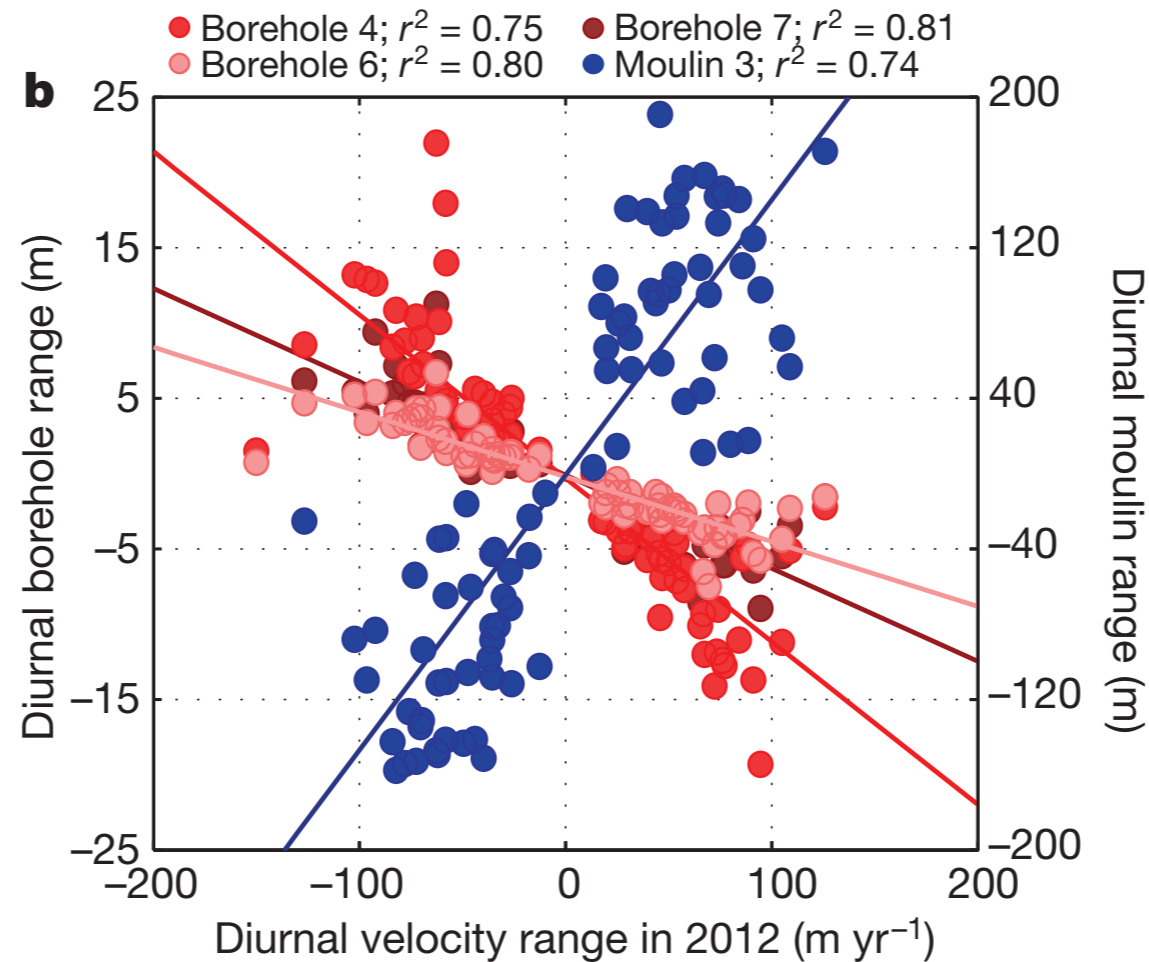
van de Wal et al 2015

Existing sliding models relate basal **shear stress** to **sliding speed** and **effective pressure**

- the relationship does not agree all that well with observations

# Motivation: field measurements (Greenland ice sheet)

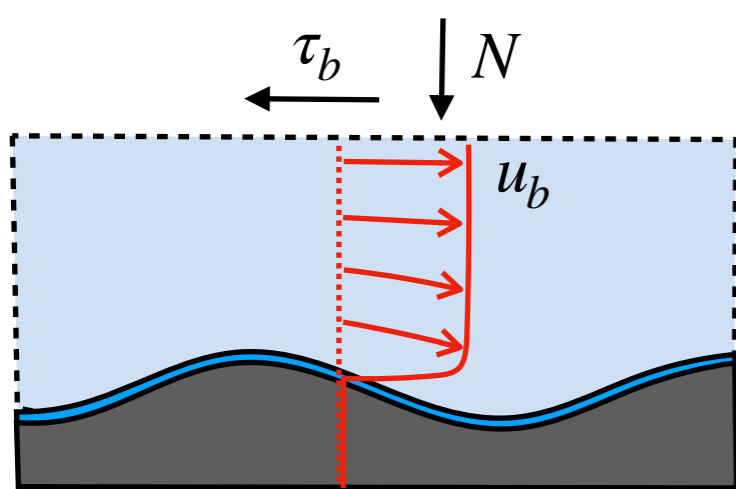
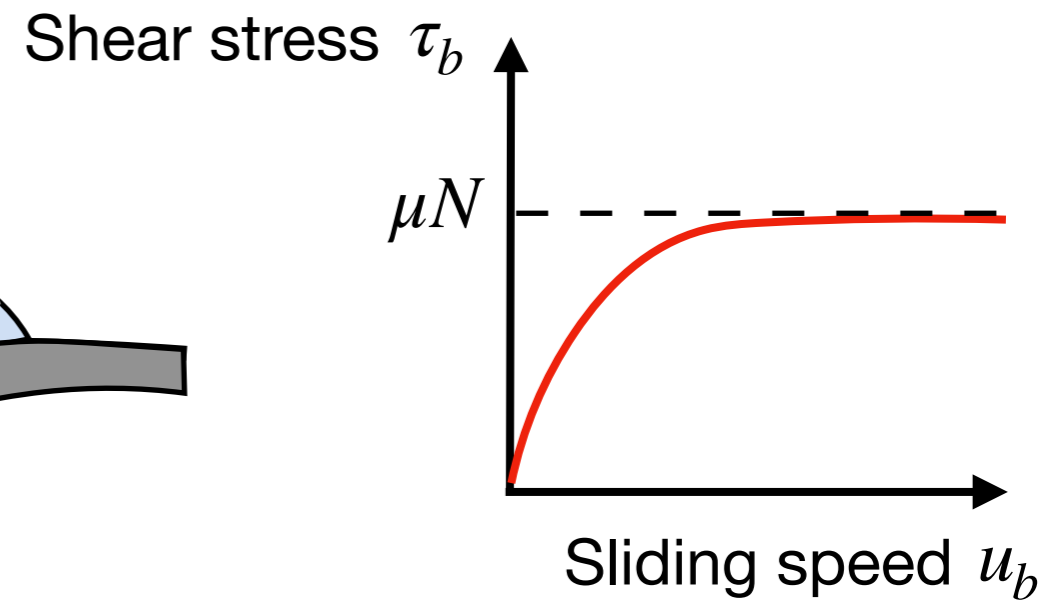
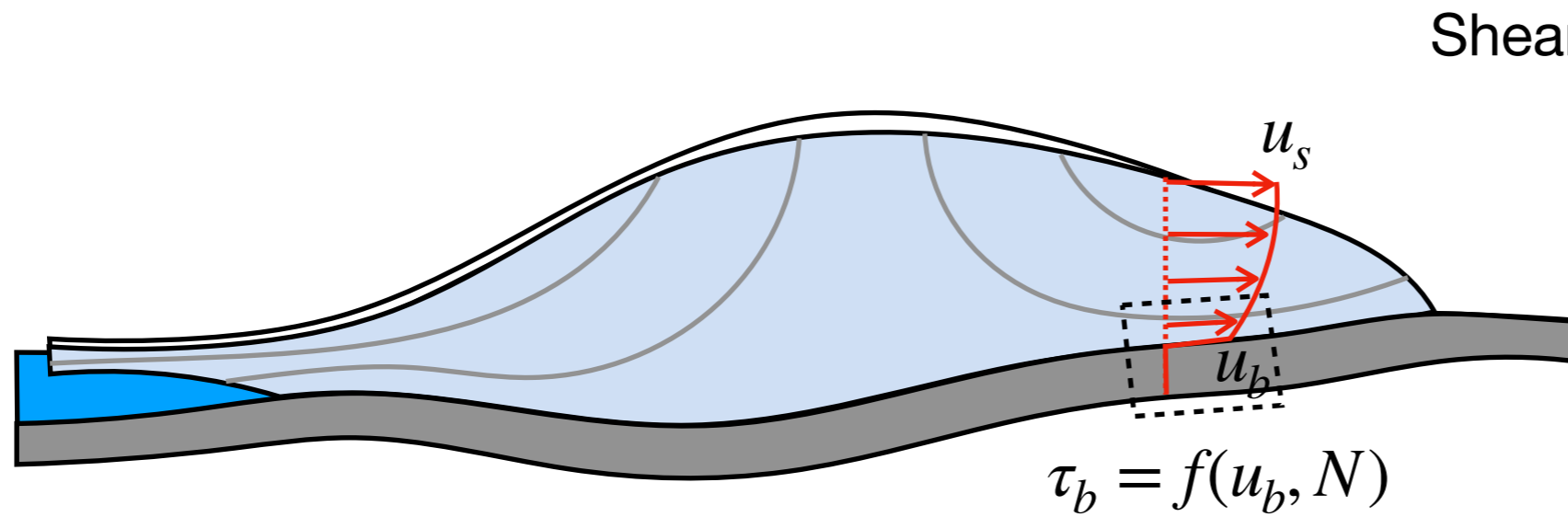
Velocity changes are roughly **in phase** with changes in moulin water pressure, but **out of phase** with changes in borehole water pressure



Andrews et al 2014

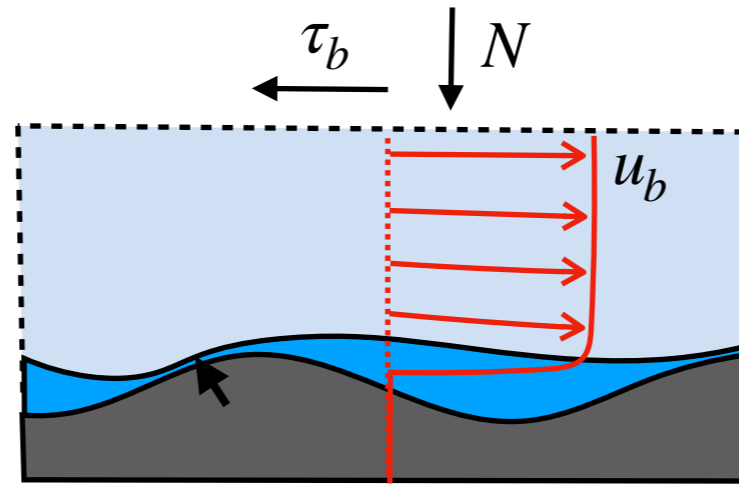
➔ Investigate hydrologically-controlled sliding in more detail

# The ice-sheet sliding law



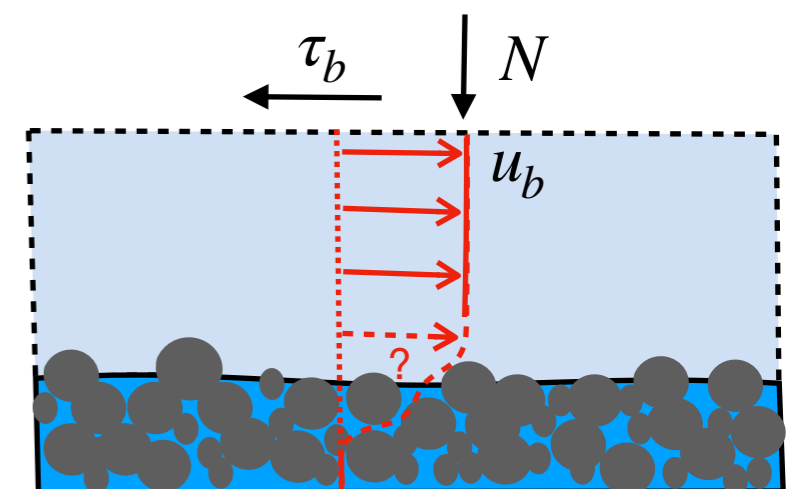
Hard-bed sliding ('Weertman')

$$\tau_b = C u_b^m$$



Hard-bed sliding ('Schoof')

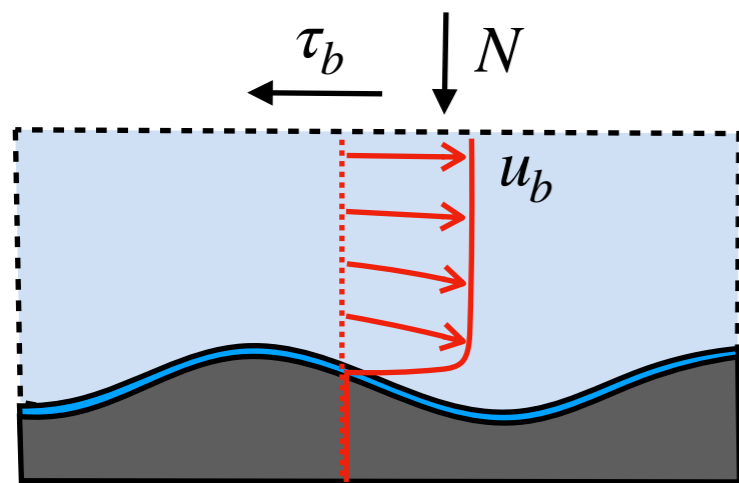
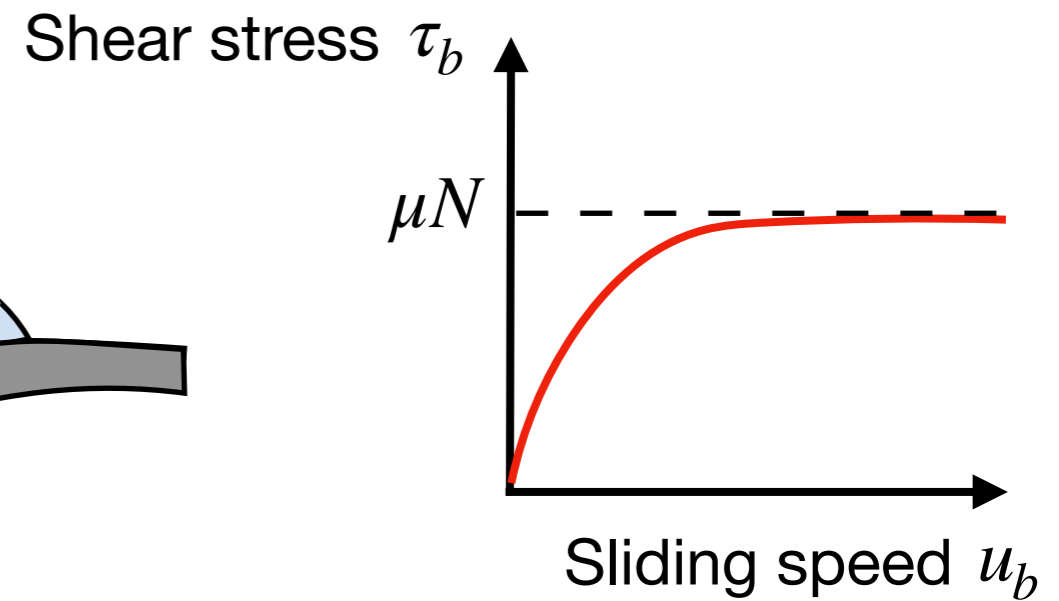
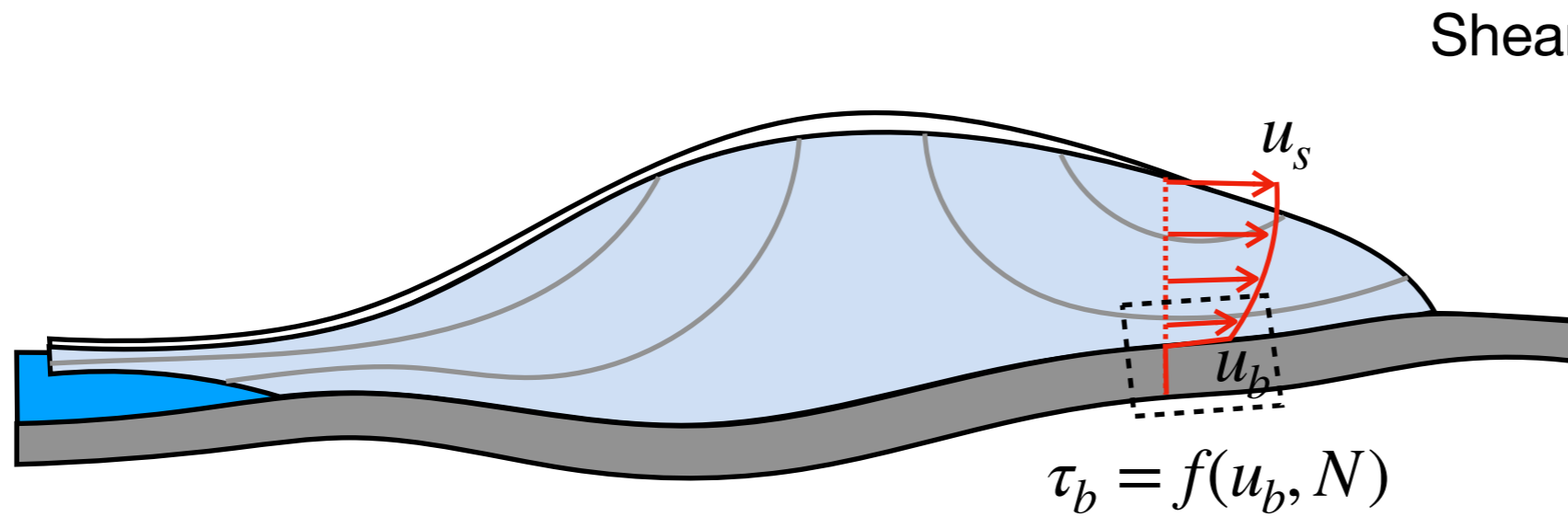
$$\tau_b = \mu N \left( \frac{u_b}{u_b + \lambda N^n} \right)^{1/n}$$



Soft-bed sliding

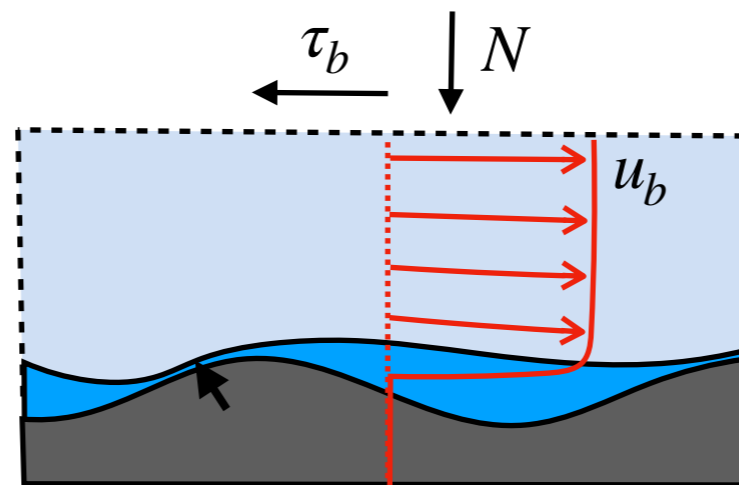
$$\tau_b = \mu N$$

# The ice-sheet sliding law



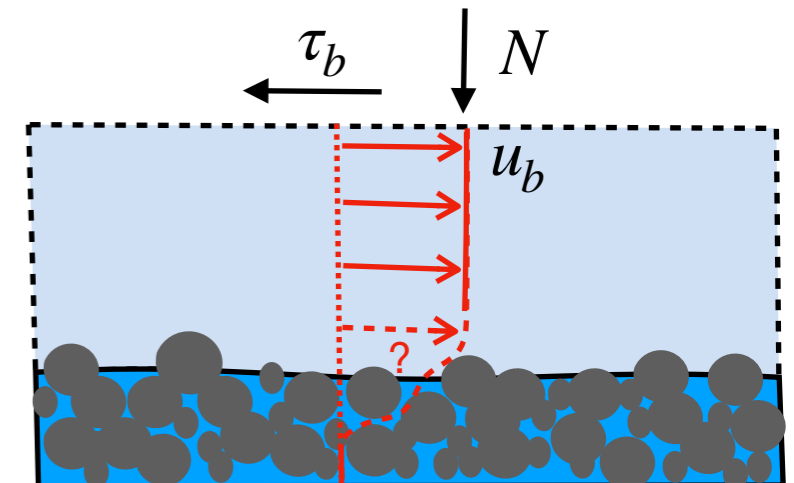
Hard-bed sliding ('Weertman')

$$\tau_b = C u_b^m$$



Hard-bed sliding ('Schoof')

$$\tau_b = \mu N \left( \frac{u_b}{u_b + \lambda N^n} \right)^{1/n}$$

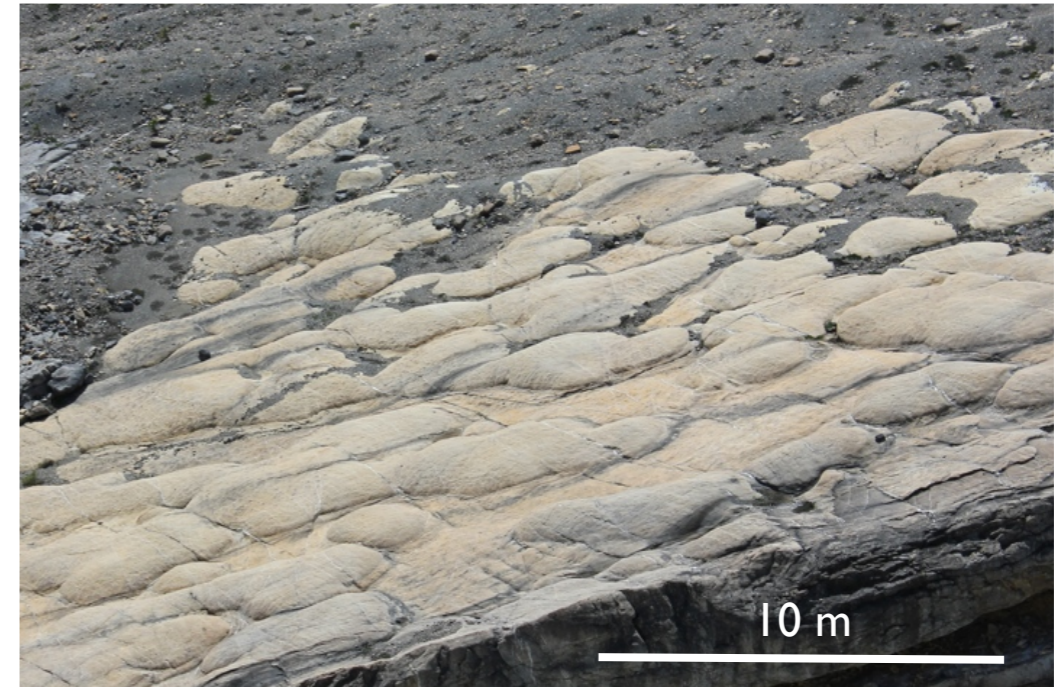
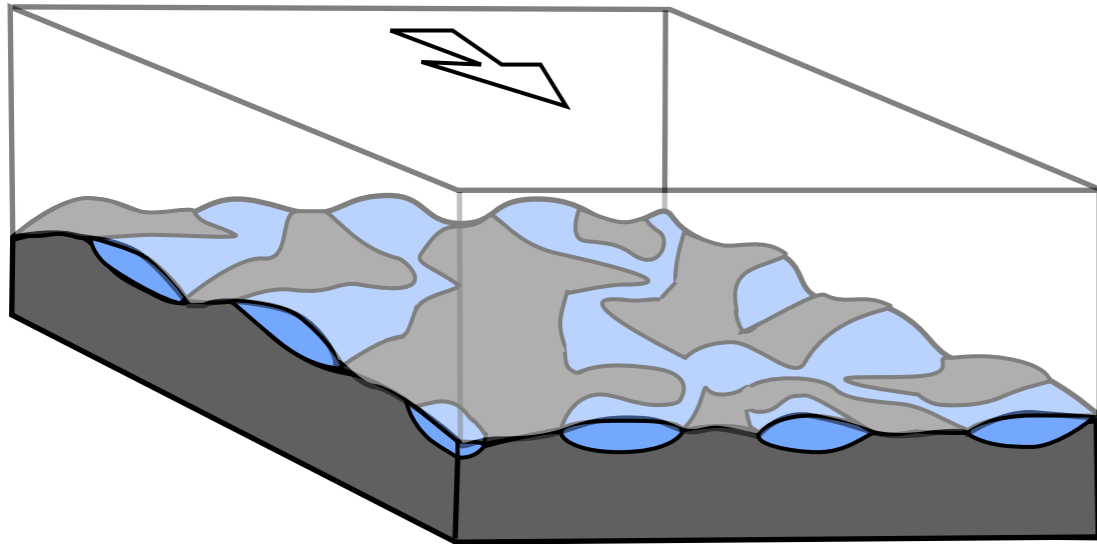


Soft-bed sliding

$$\tau_b = \mu N$$

# Subglacial cavitation

Water-filled cavities form downstream of bedrock bumps, where local normal stress is low



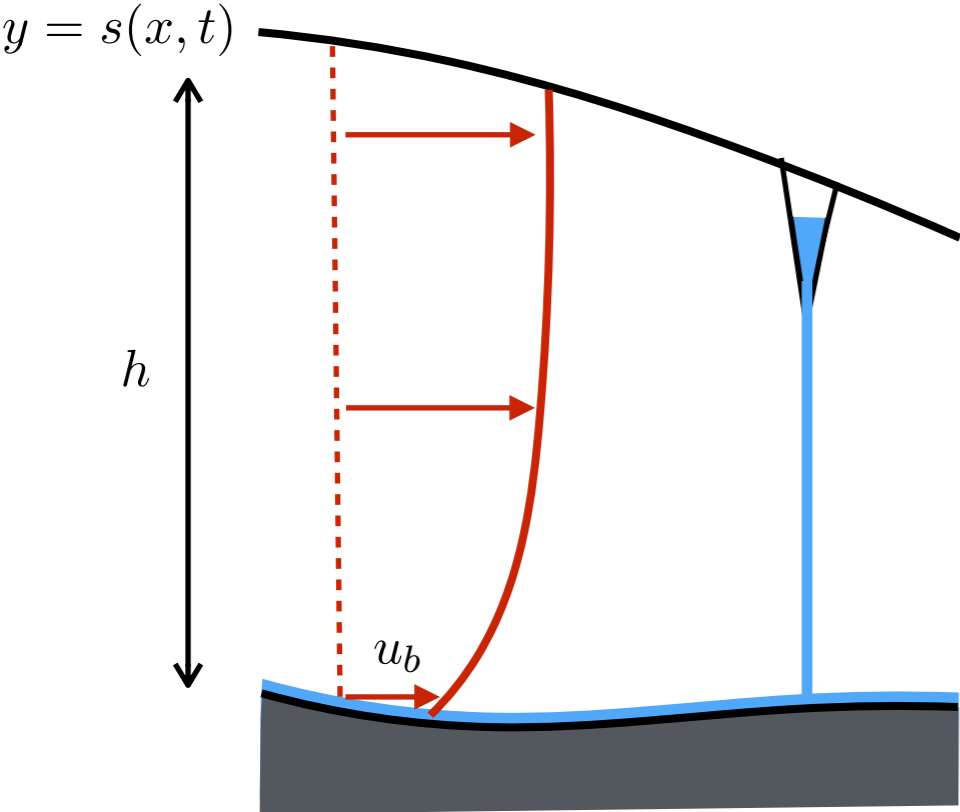
Previous **modelling** work: Lliboutry 1968, Iken 1981, Kamb 1987, Fowler 1986, 1987, Schoof 2005, Gagliardini et al 2007, Helanow et al 2019

Laboratory-based **experimental** work: Zoet & Iverson 2015

→ **Existing models assume a steady state**

This is inconsistent with an evolving subglacial hydrological system

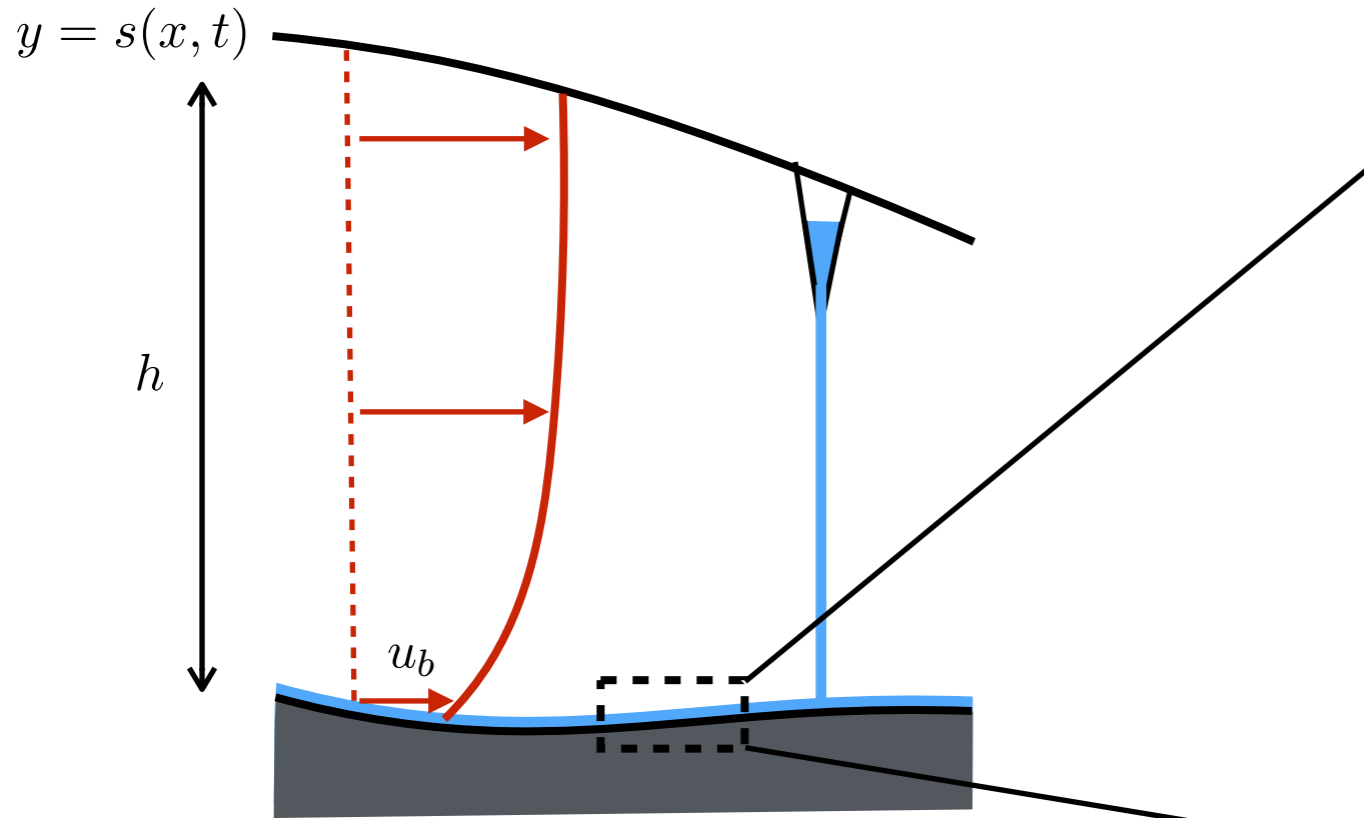
# Mathematical formulation



Sliding law

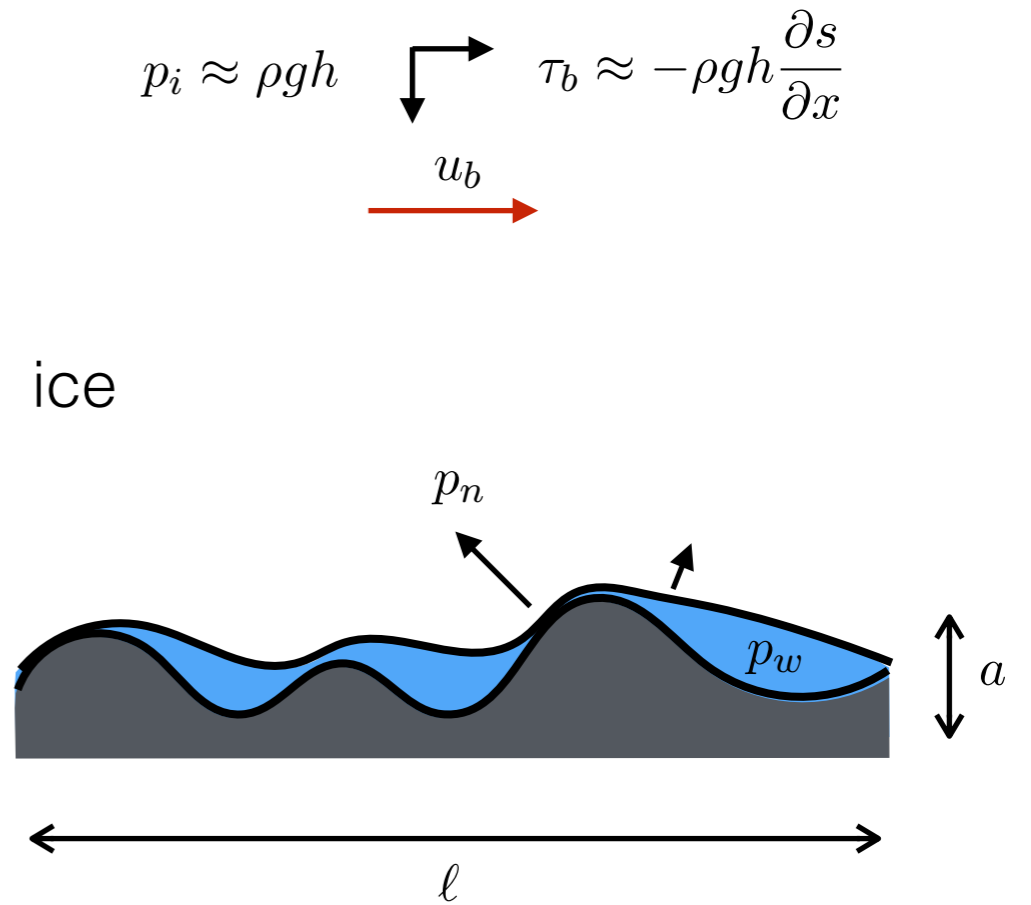
$$\tau_b = f(u_b, \dots)$$

# Mathematical formulation



Sliding law

$$\tau_b = f(u_b, \dots)$$



Assume zero shear stress microscopically

Macroscopic shear stress arises from local variations of normal stress:

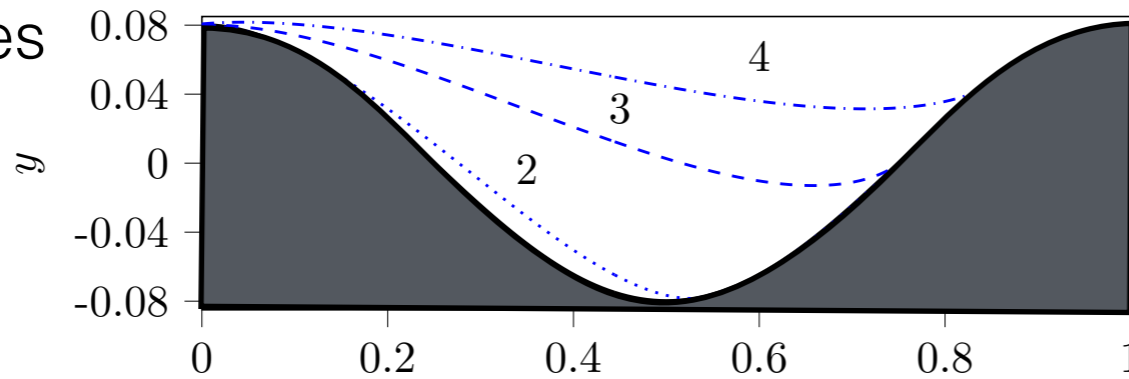
$$\tau_b = \frac{1}{l} \int_0^l p_n \frac{\partial b}{\partial x} dx$$

# Finite-element calculations

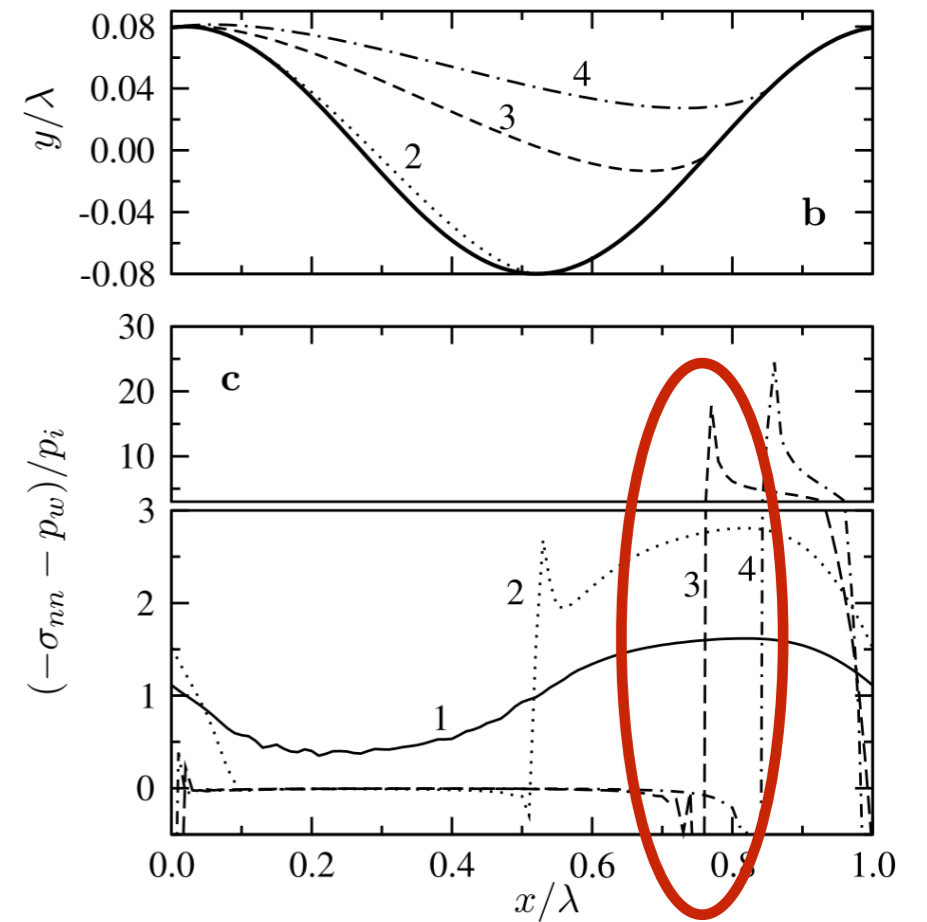
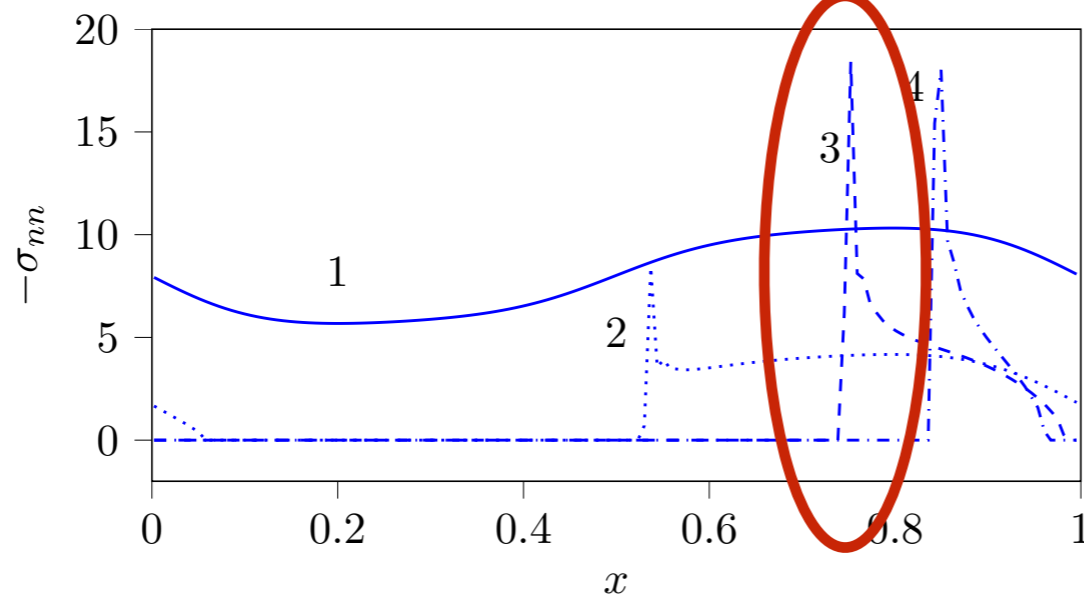
with Gonzalo Gonzalez de Diego & Patrick Farrell

Formulate **viscous contact problem** as a variational inequality.  
Contact conditions enforced using a Lagrange multiplier.

Cavity shapes



Local normal stress



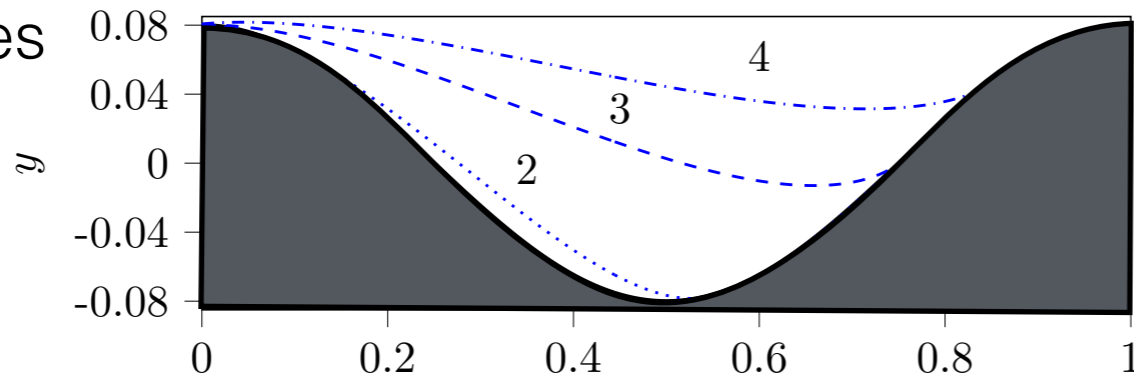
cf. **Gagliardini et al 2007**

# Finite-element calculations

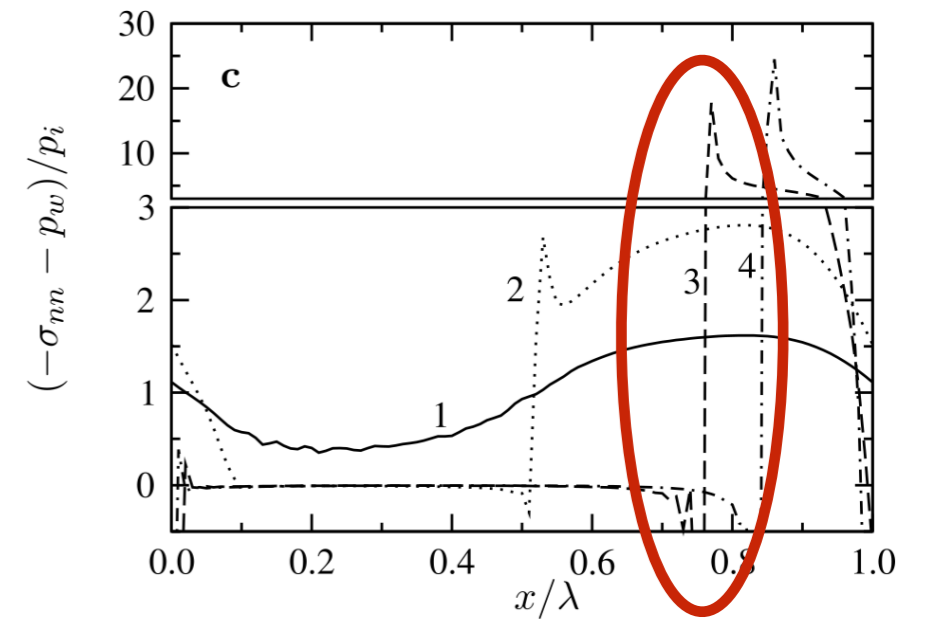
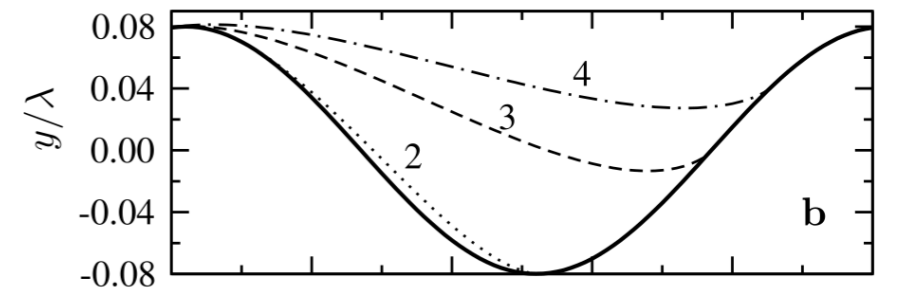
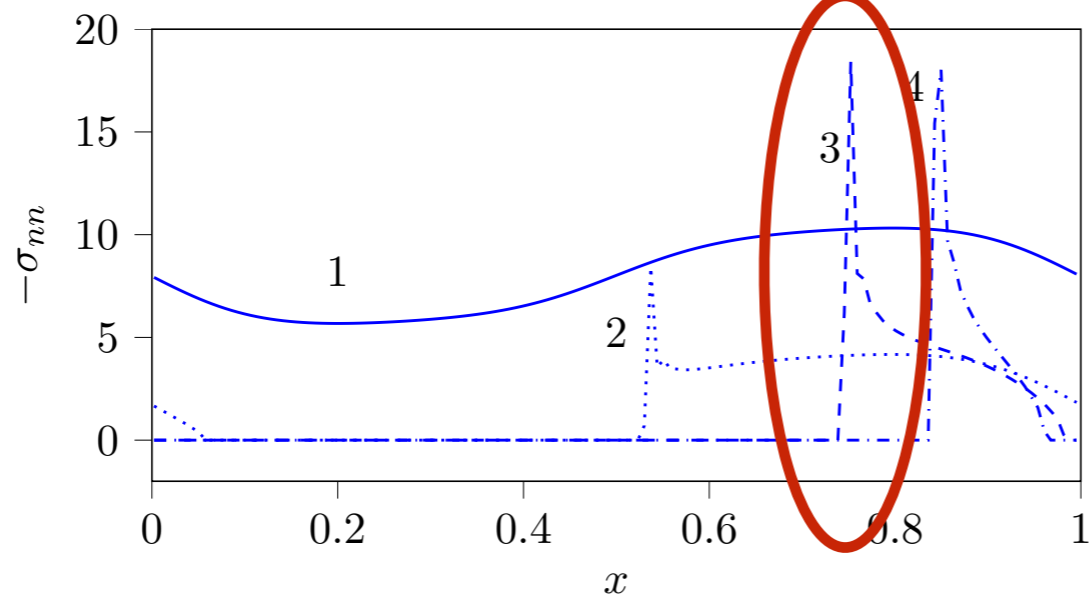
with Gonzalo Gonzalez de Diego & Patrick Farrell

Formulate **viscous contact problem** as a variational inequality.  
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Cavity shapes

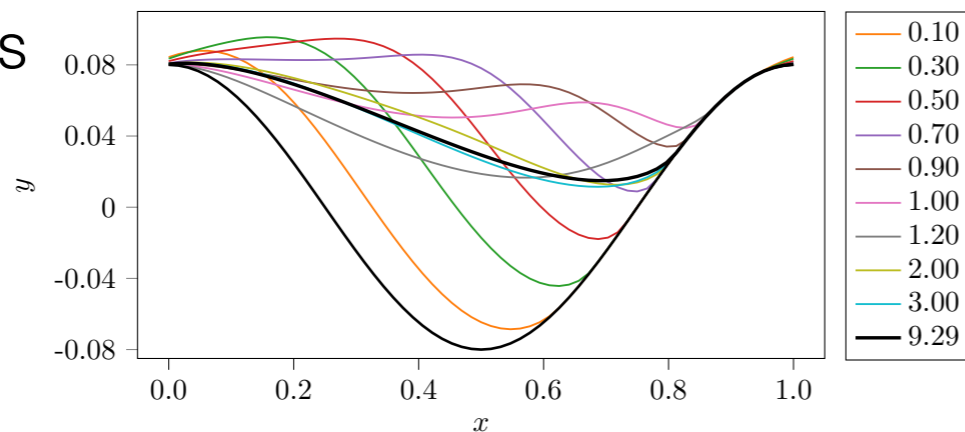


Local normal stress

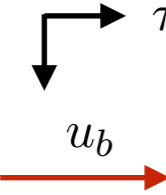


cf. **Gagliardini et al 2007**

Evolving cavities  
(in progress)



# Linearised problem

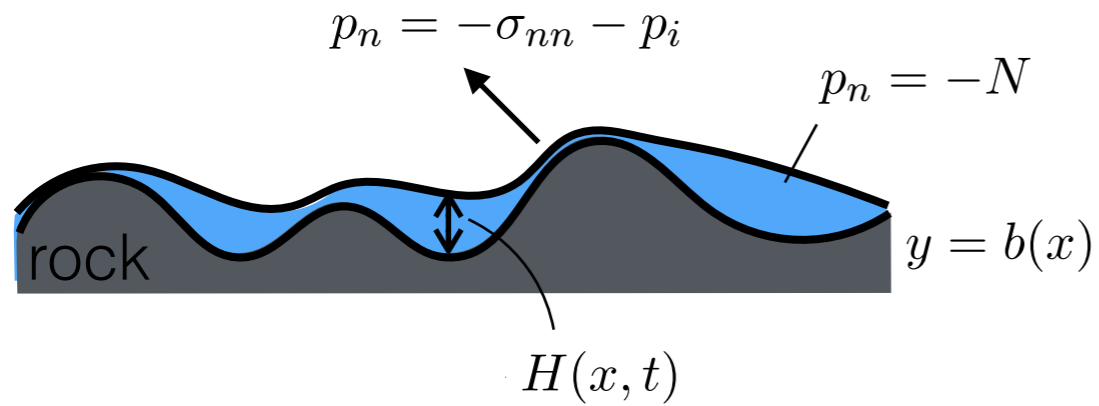
$$p_i \approx \rho g h \quad \tau_b \approx -\rho g h \frac{\partial s}{\partial x}$$


$u_b$

$$\nabla \cdot \mathbf{u} = 0$$

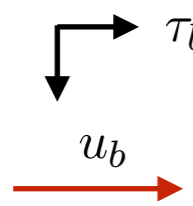
$$0 = -\nabla p + \eta \nabla^2 \mathbf{u}$$

ice



Effective pressure  $N = p_i - p_w$

# Linearised problem

$$p_i \approx \rho g h$$


$$\tau_b \approx -\rho g h \frac{\partial s}{\partial x}$$

Linearise

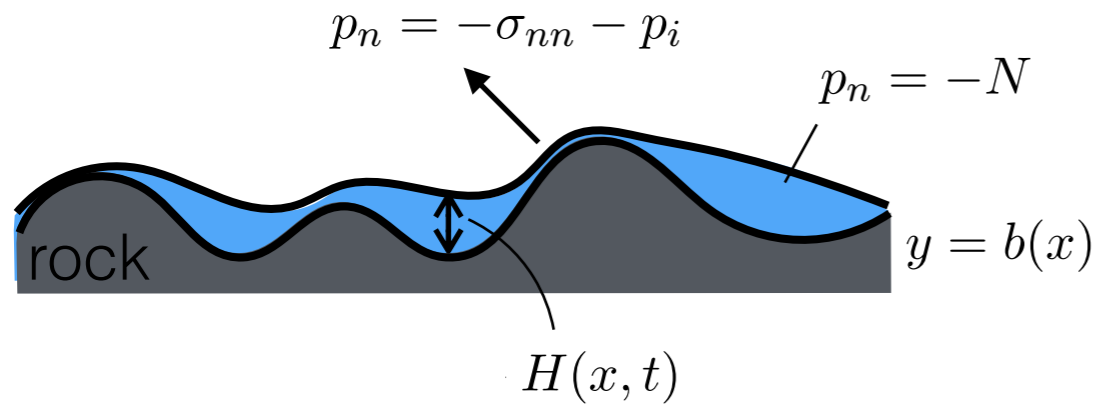
$$\mathbf{u} = (u_b, 0) + \mathcal{R}(u, v)$$

$$\mathcal{R} = \frac{a}{\ell} \ll 1$$

$$\nabla \cdot \mathbf{u} = 0$$

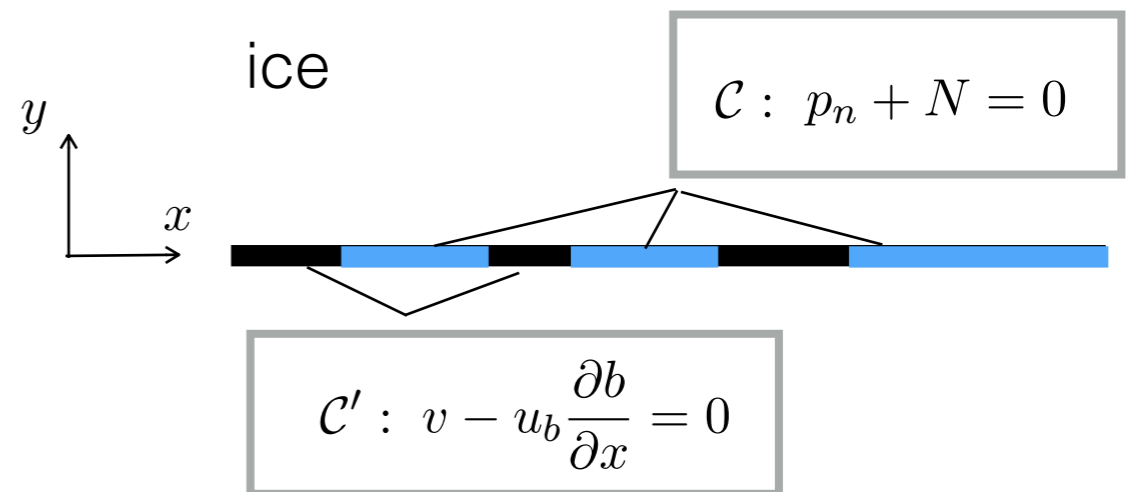
$$0 = -\nabla p + \eta \nabla^2 \mathbf{u}$$

ice



Effective pressure  $N = p_i - p_w$

Viscous flow in a half plane -  
solve using complex variable methods



Evolution of cavity depth

$$\frac{\partial H}{\partial t} + u_b \frac{\partial H}{\partial x} = v - u_b \frac{\partial b}{\partial x}$$

# Linearised problem

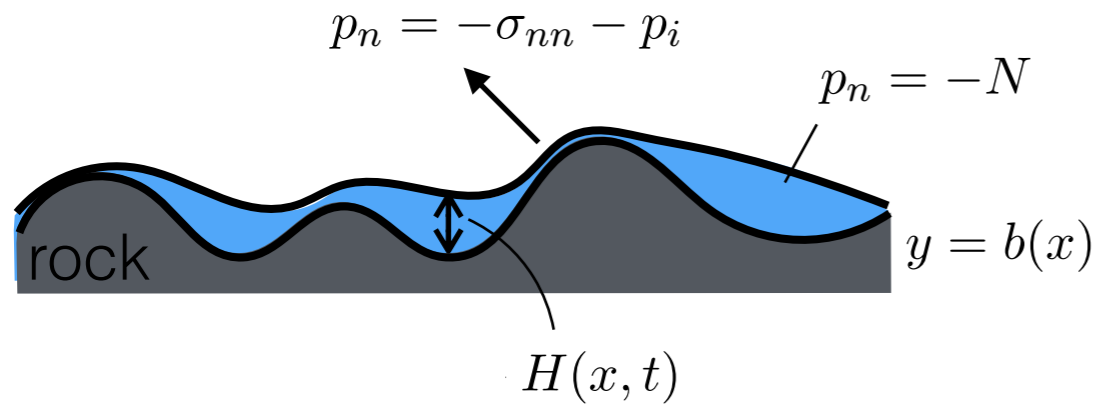
$$p_i \approx \rho g h \quad \tau_b \approx -\rho g h \frac{\partial s}{\partial x}$$

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ice



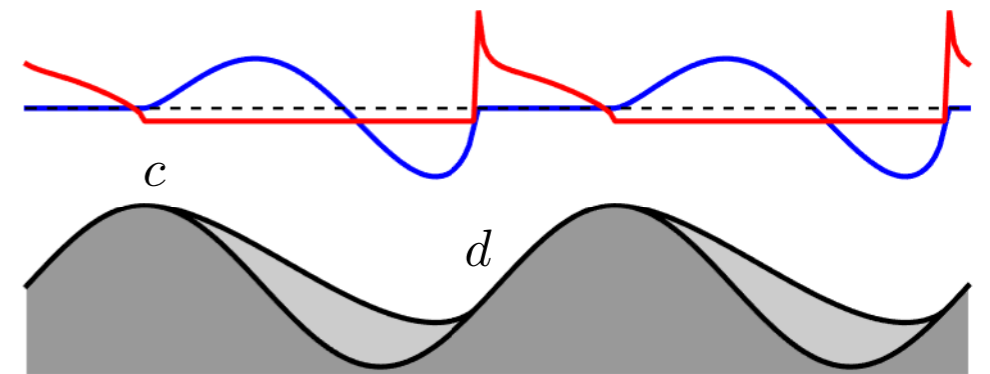
Effective pressure  $N = p_i - p_w$

Linearise

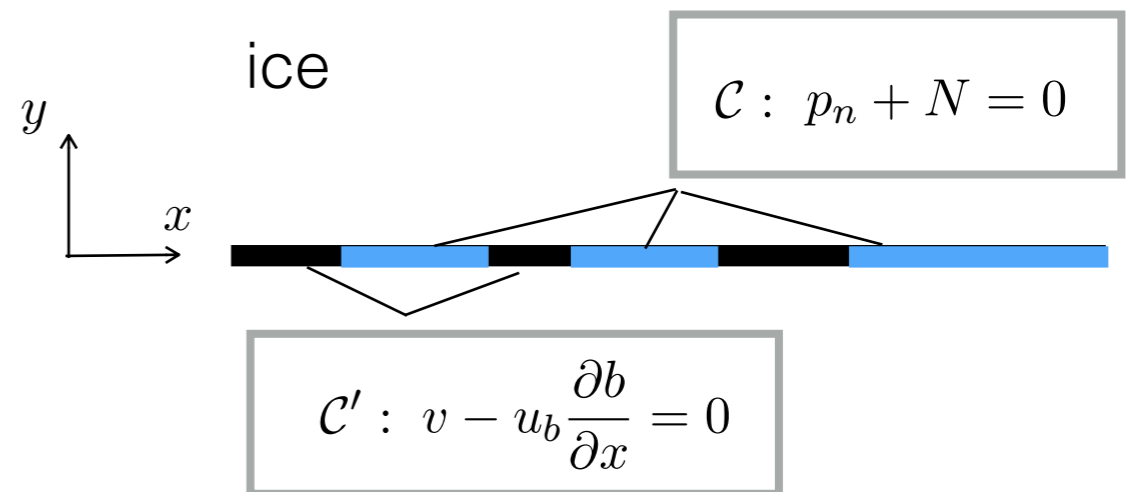
$$\mathbf{u} = (u_b, 0) + \mathcal{R}(u, v)$$

$$\mathcal{R} = \frac{a}{\ell} \ll 1$$

Normal stress      Opening velocity

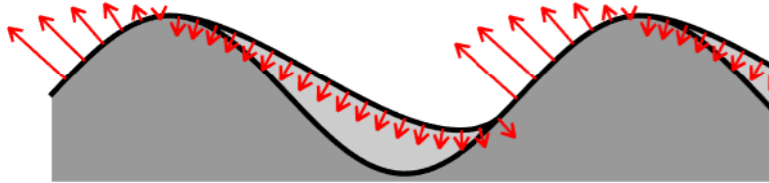
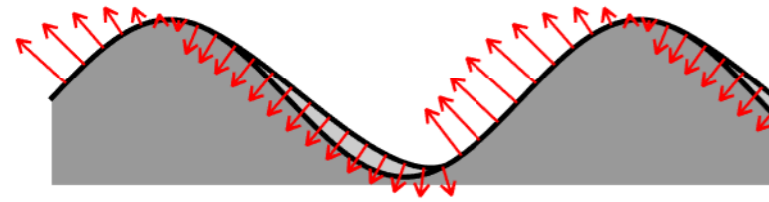
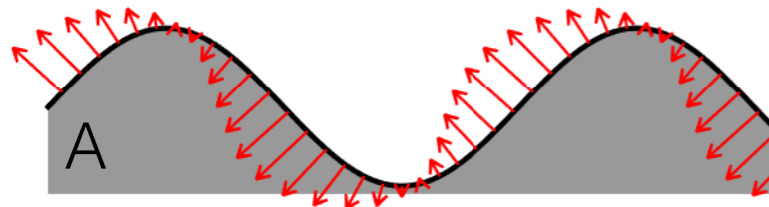
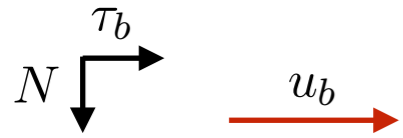


Viscous flow in a half plane - solve using complex variable methods

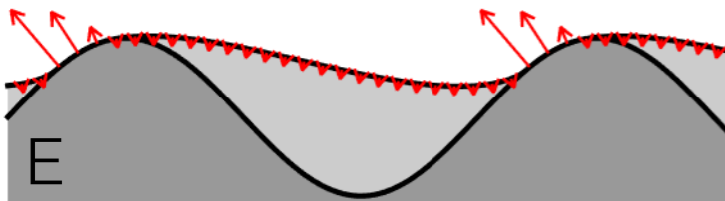
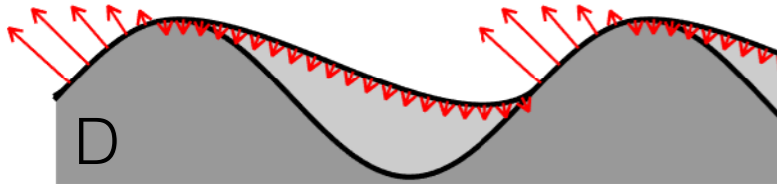


Evolution of cavity depth  $\frac{\partial H}{\partial t} + u_b \frac{\partial H}{\partial x} = v - u_b \frac{\partial b}{\partial x}$

# Steady-state cavities

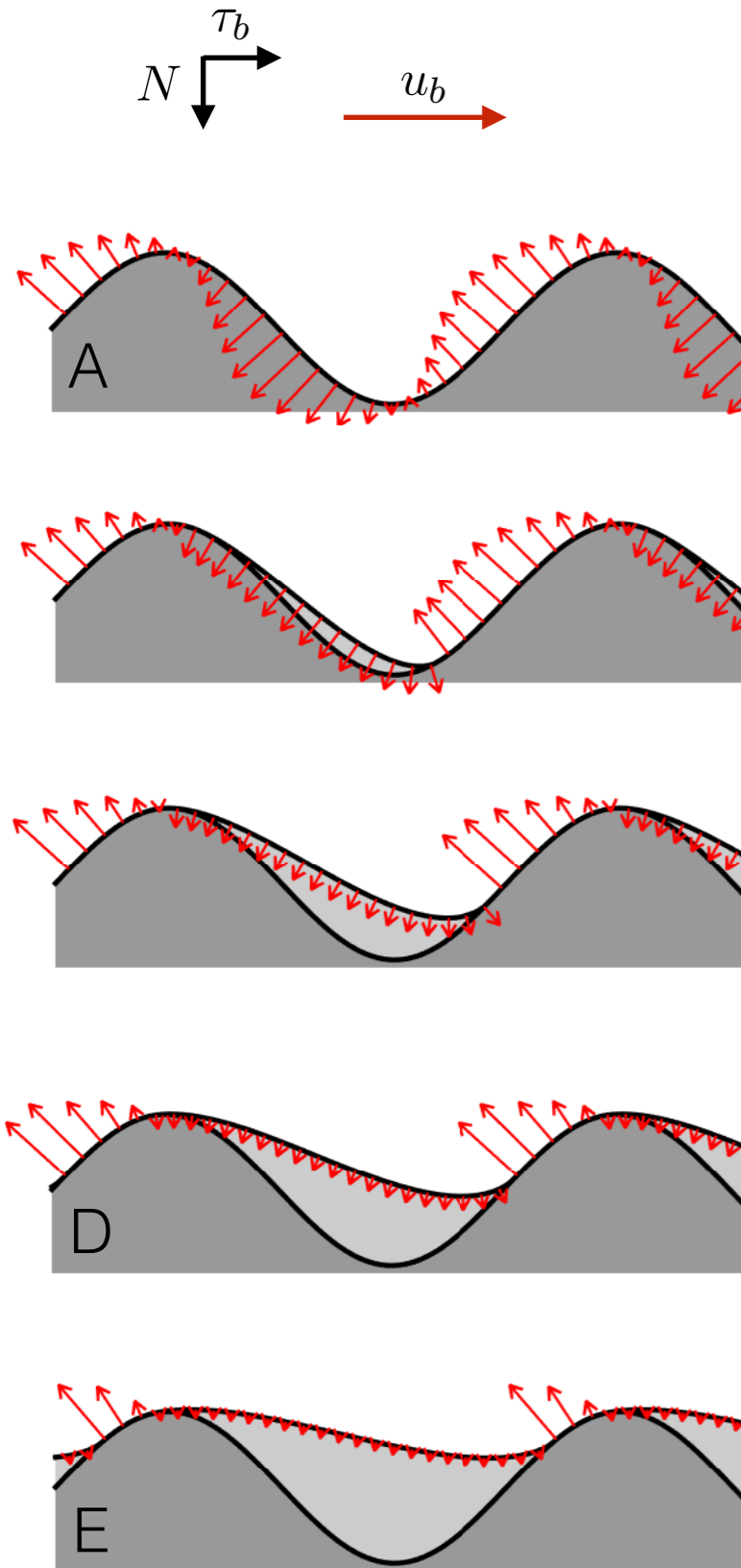


Increasing  
water  
pressure

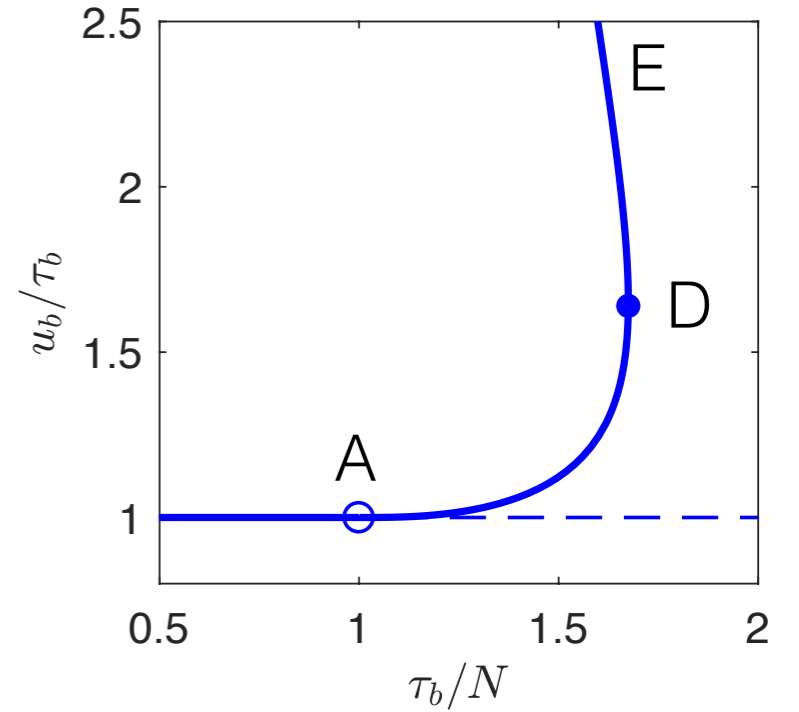
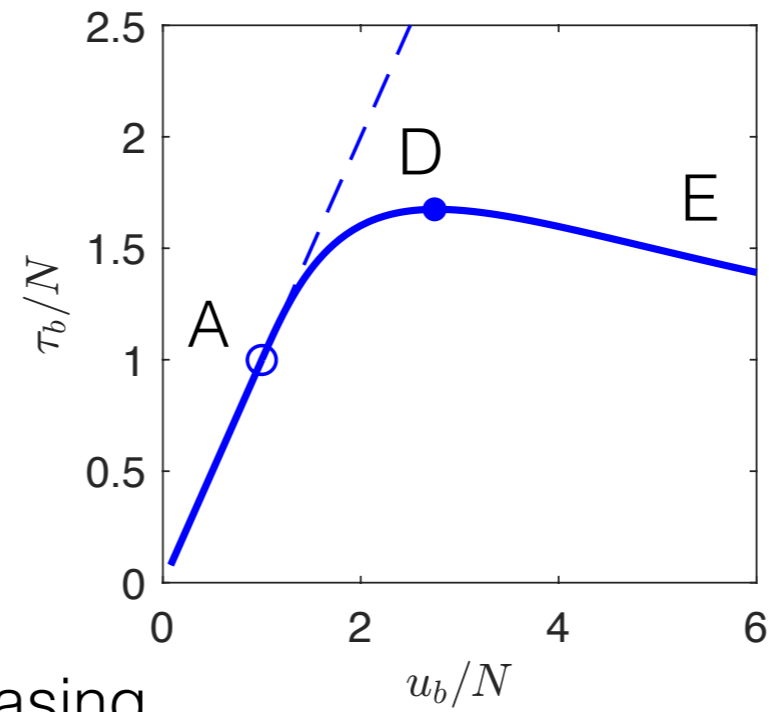


# Steady-state cavities

➔ Relationship between  $\tau_b$ ,  $u_b$ , and  $N$

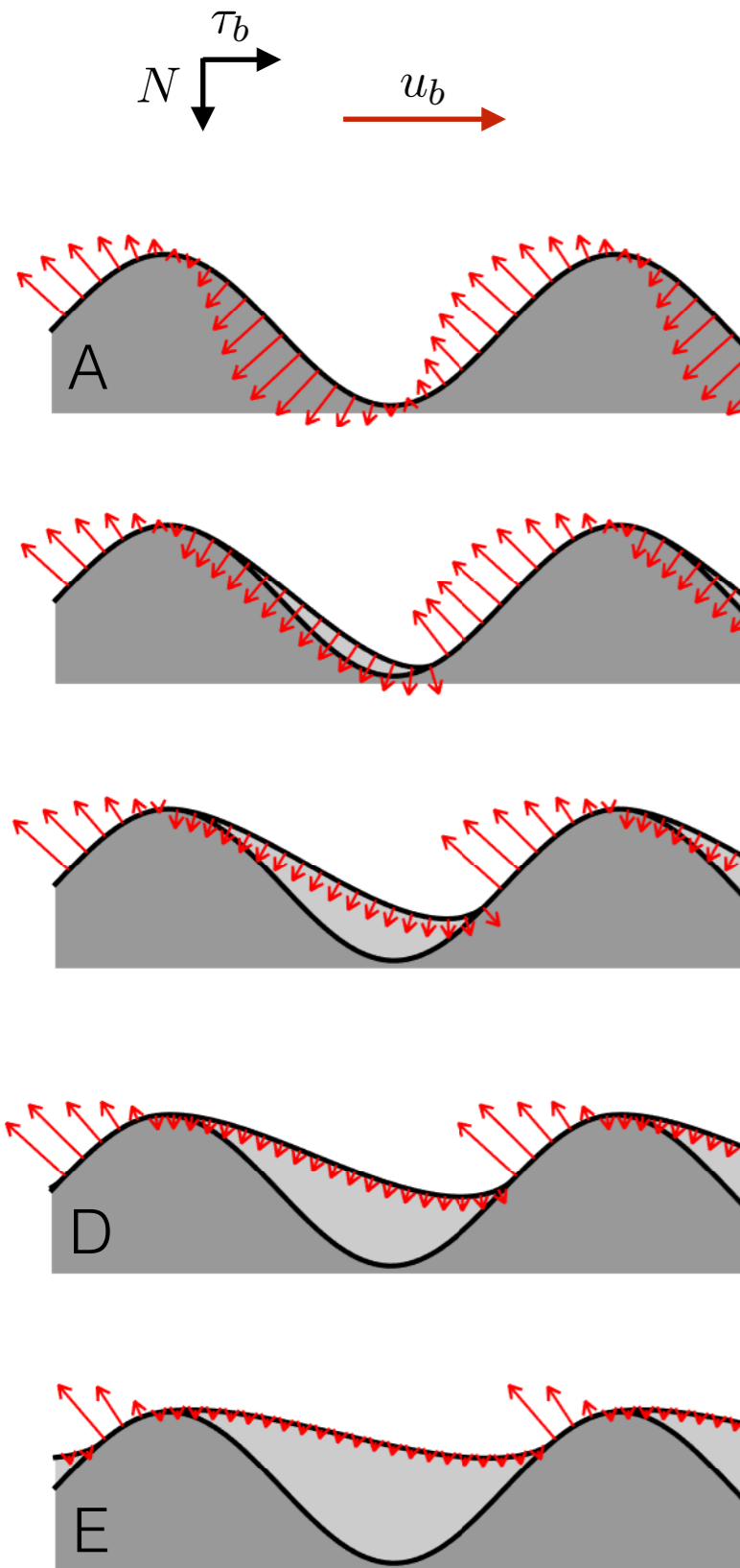


Increasing  
water  
pressure

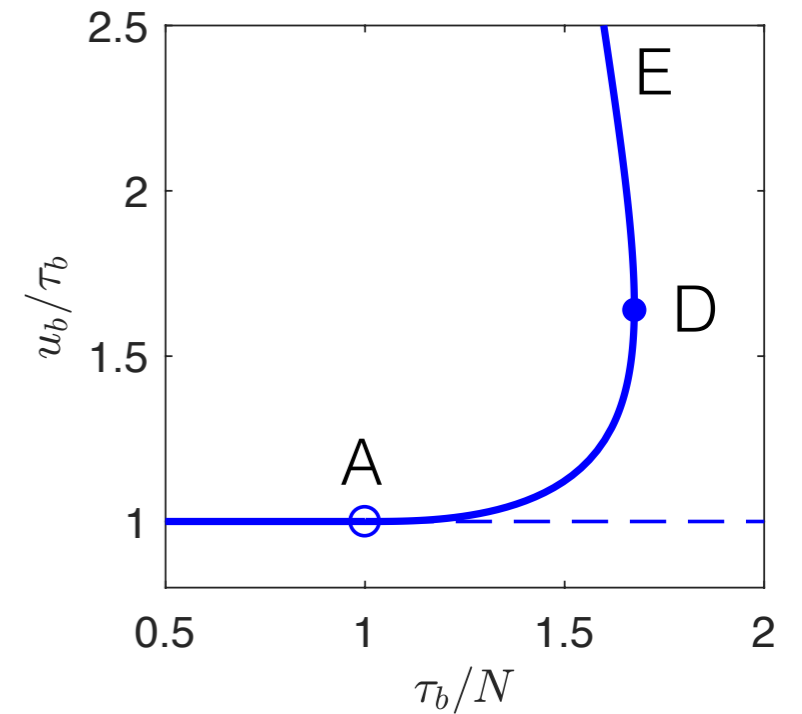
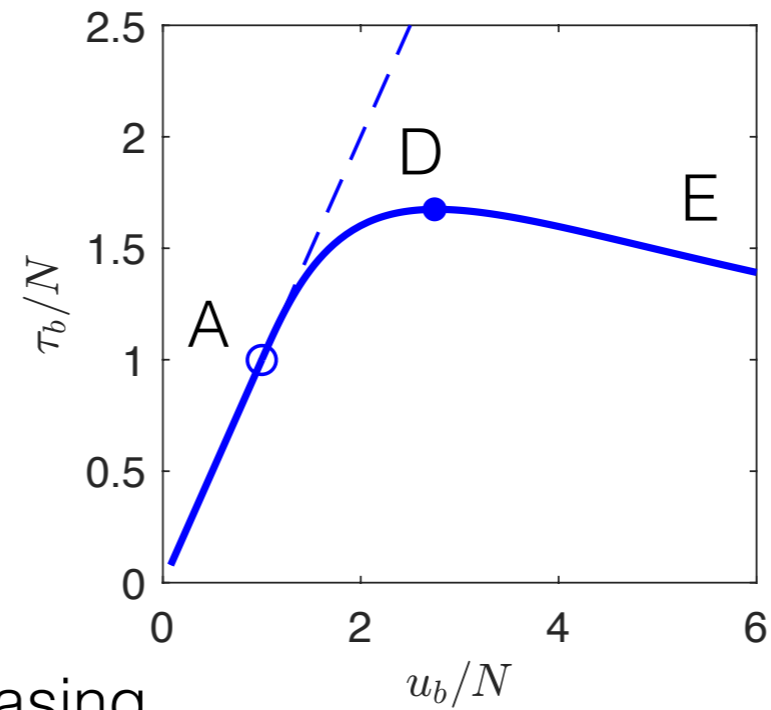


# Steady-state cavities

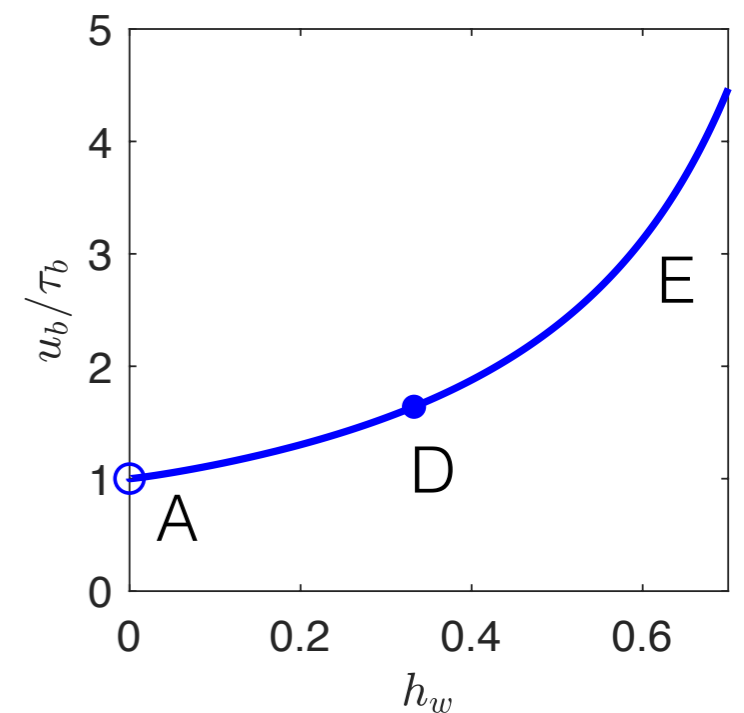
➔ Relationship between  $\tau_b$ ,  $u_b$ , and  $N$



Increasing  
water  
pressure

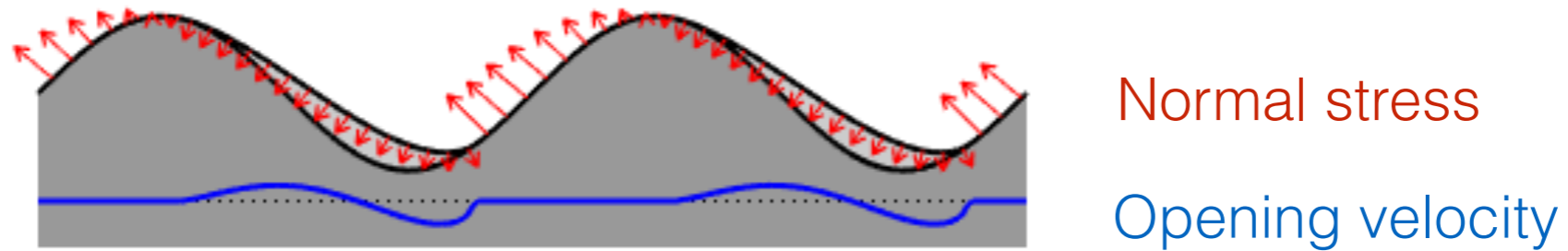


Alternatively, in terms of cavity volume (average water sheet thickness  $h_w$ )

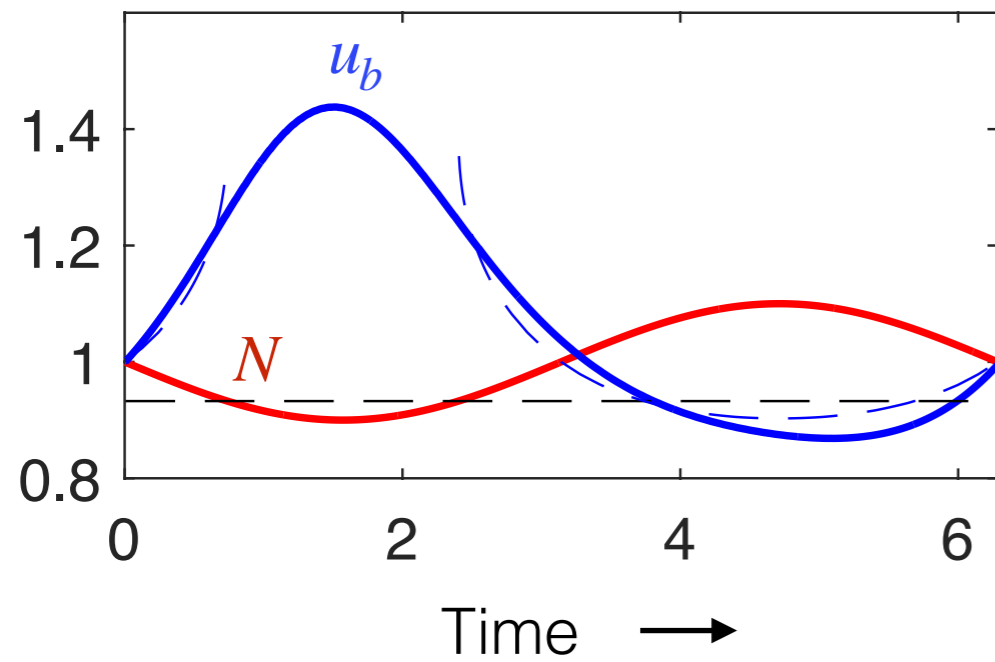


# Time-dependent fluctuations

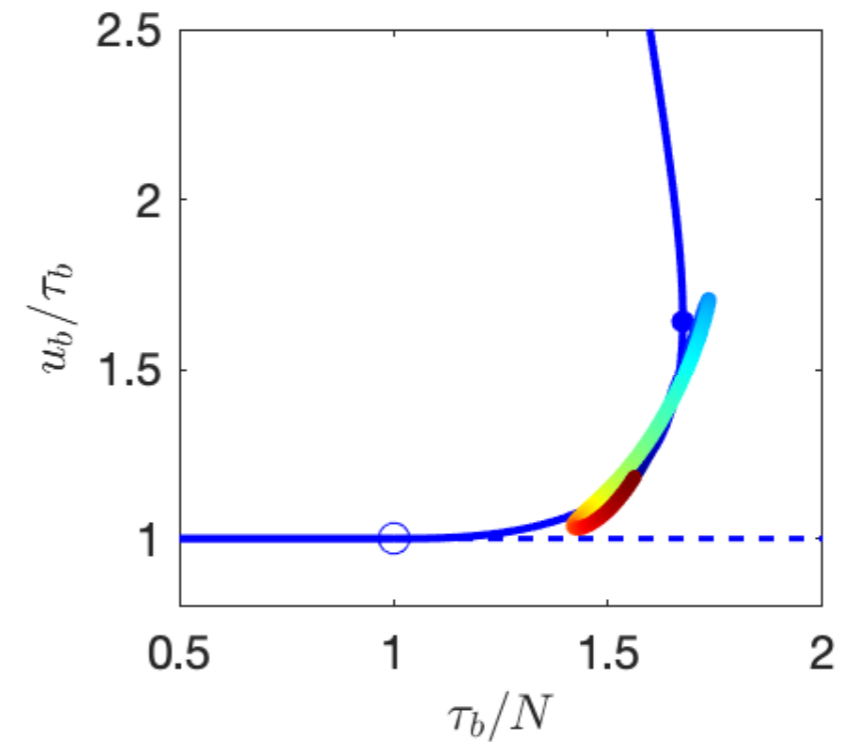
Effective pressure forced to oscillate, basal shear stress held constant.



Causes oscillations in sliding speed:

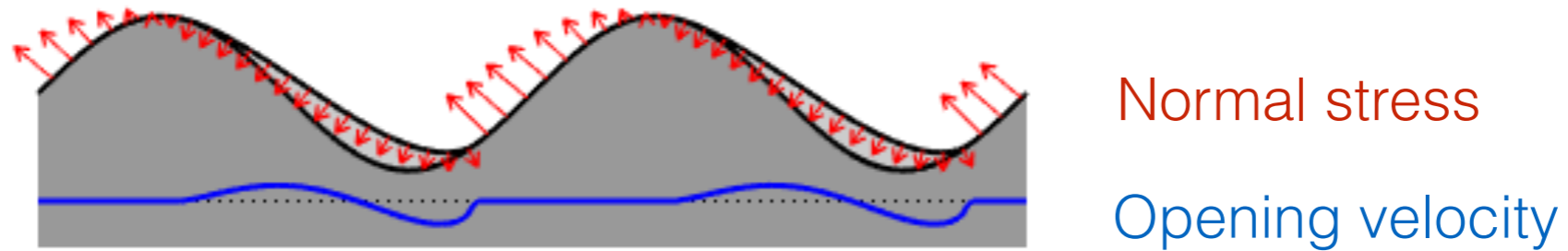


Compare to steady-state sliding law:

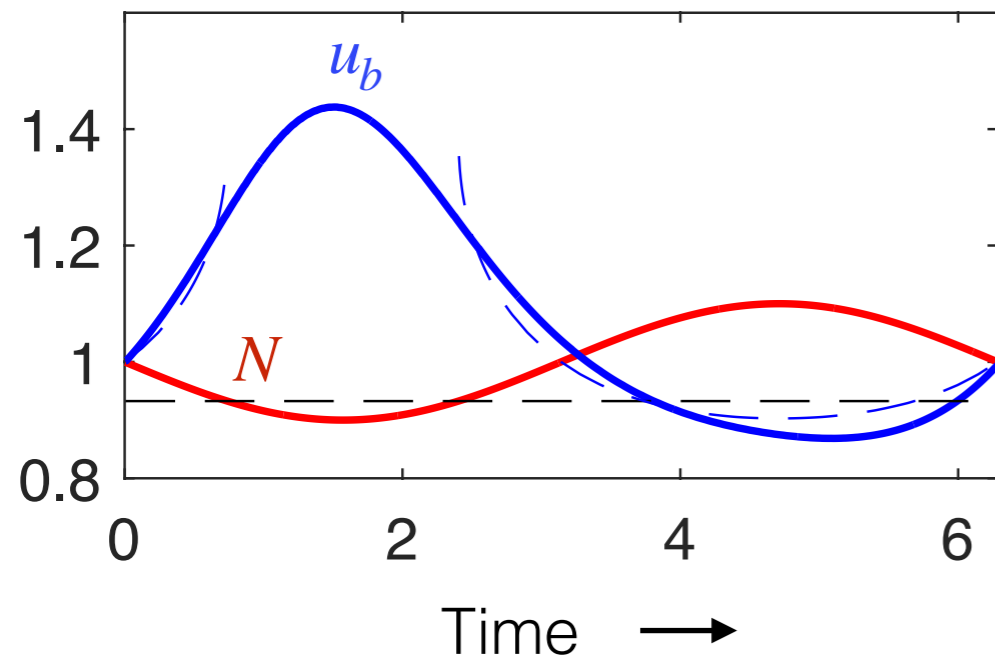


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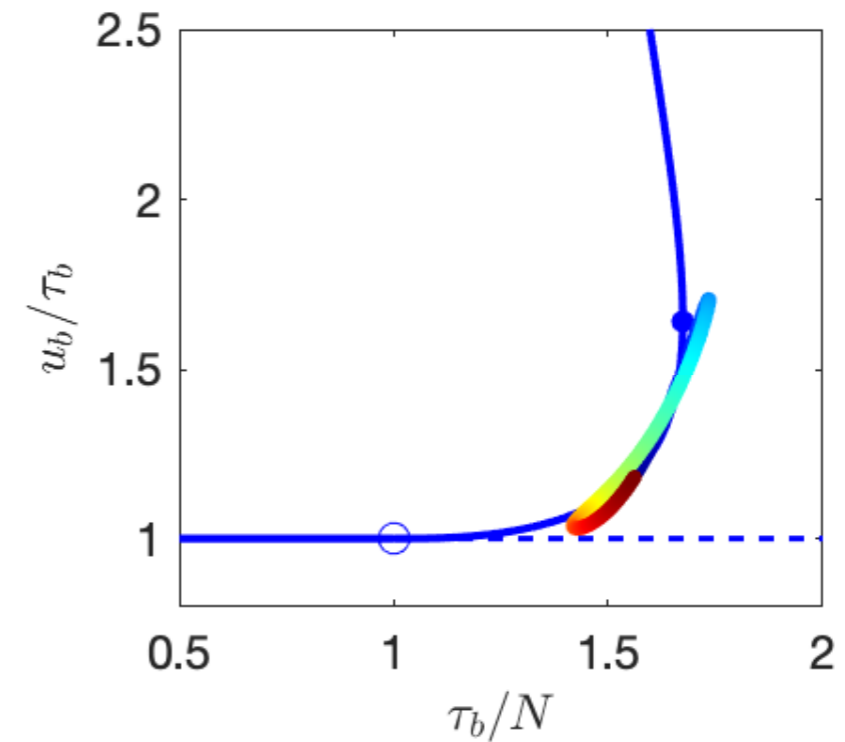
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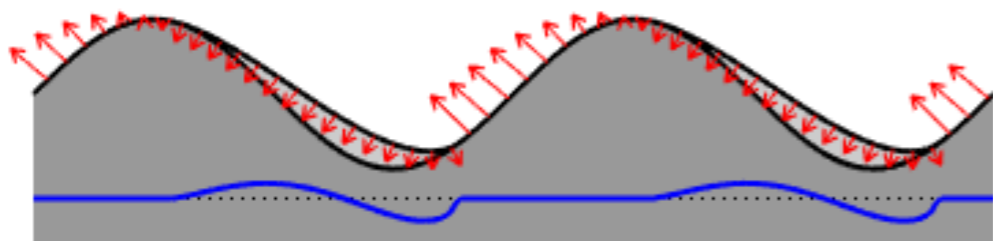


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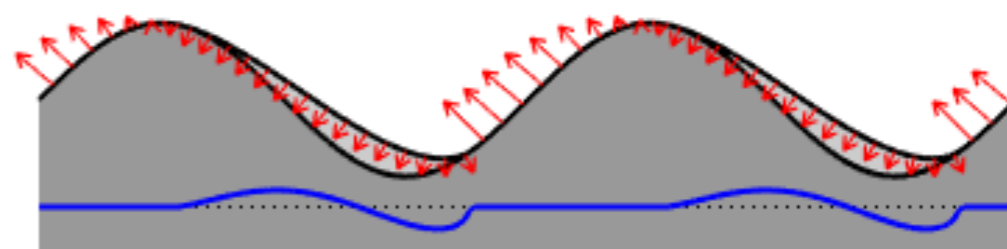
# Frequency of fluctuations

Slower fluctuations

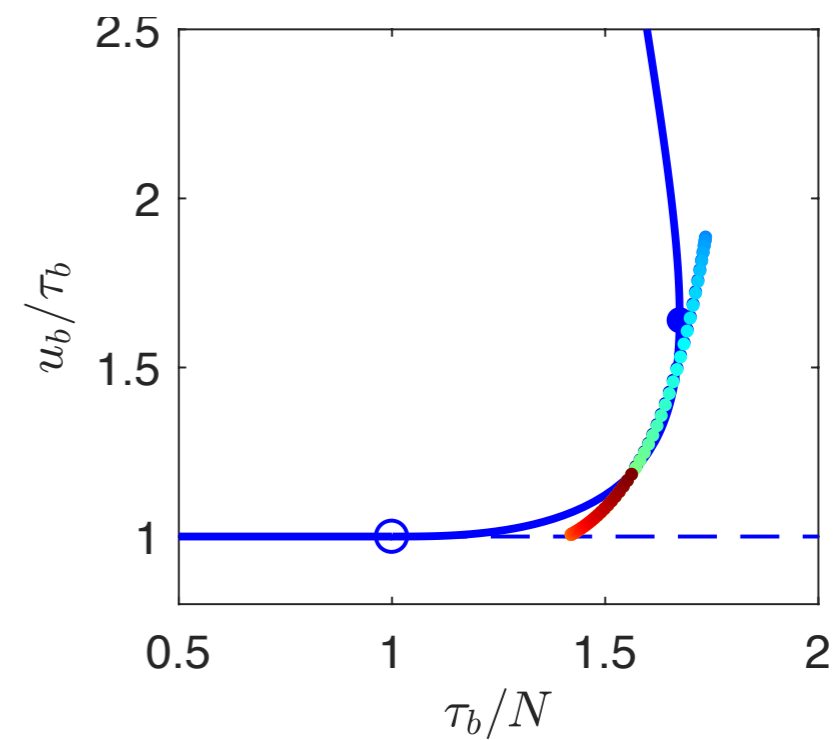
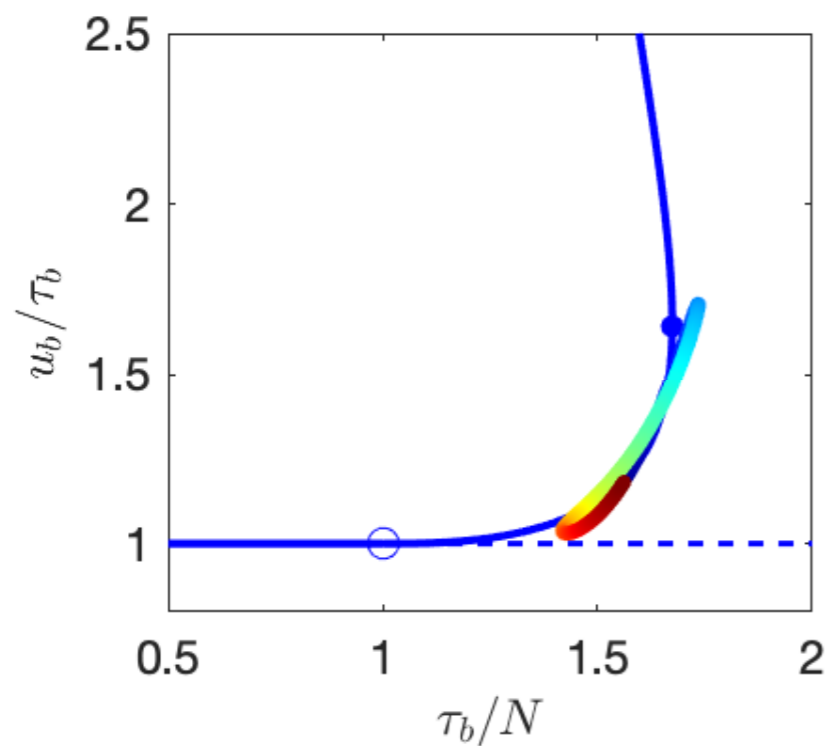
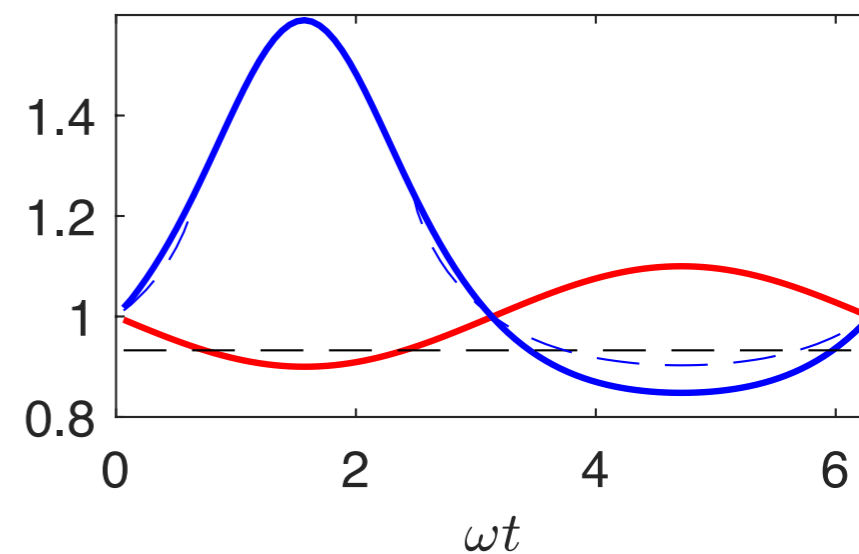
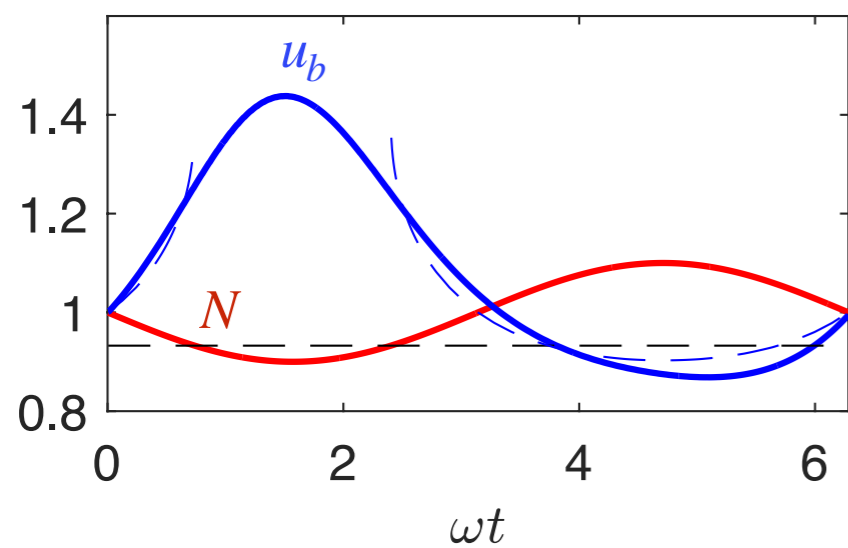


Normal stress  
Opening velocity

More rapid fluctuations

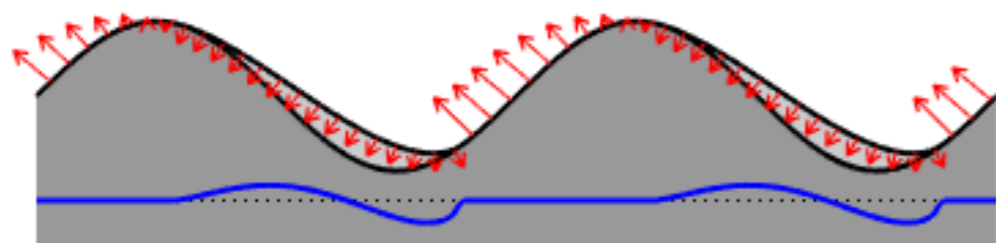


➔ Minimal change in cavity size



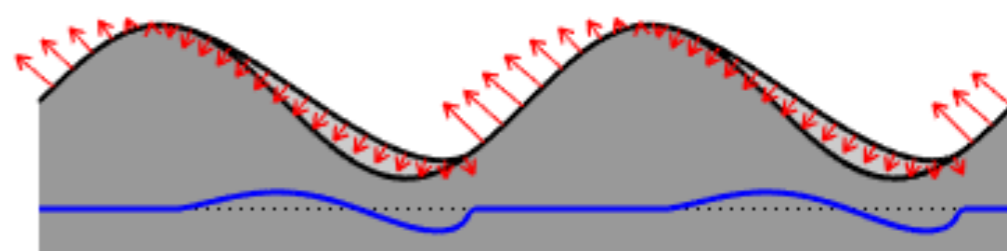
# Frequency of fluctuations

Slower fluctuations

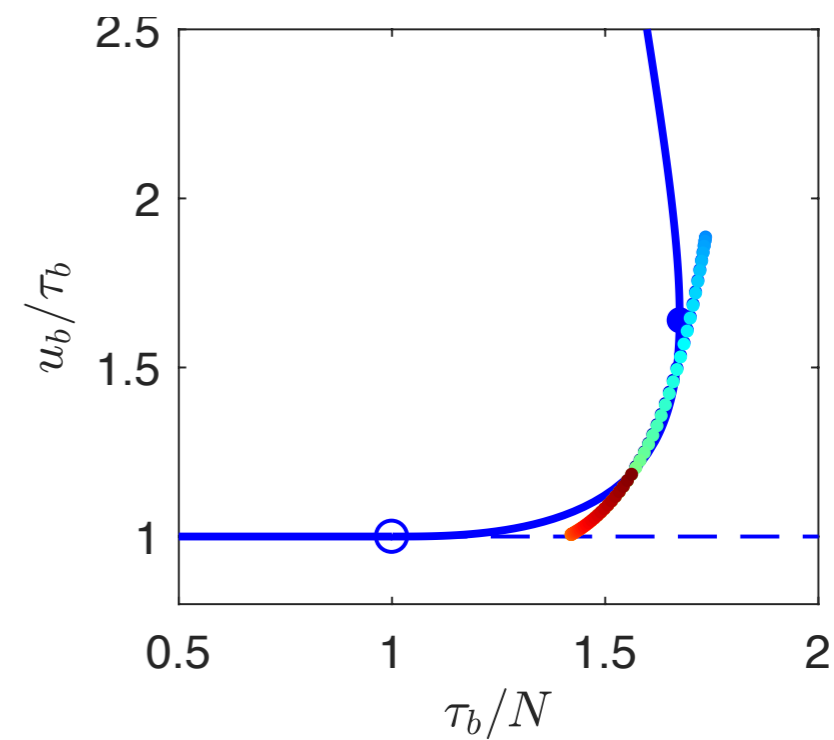
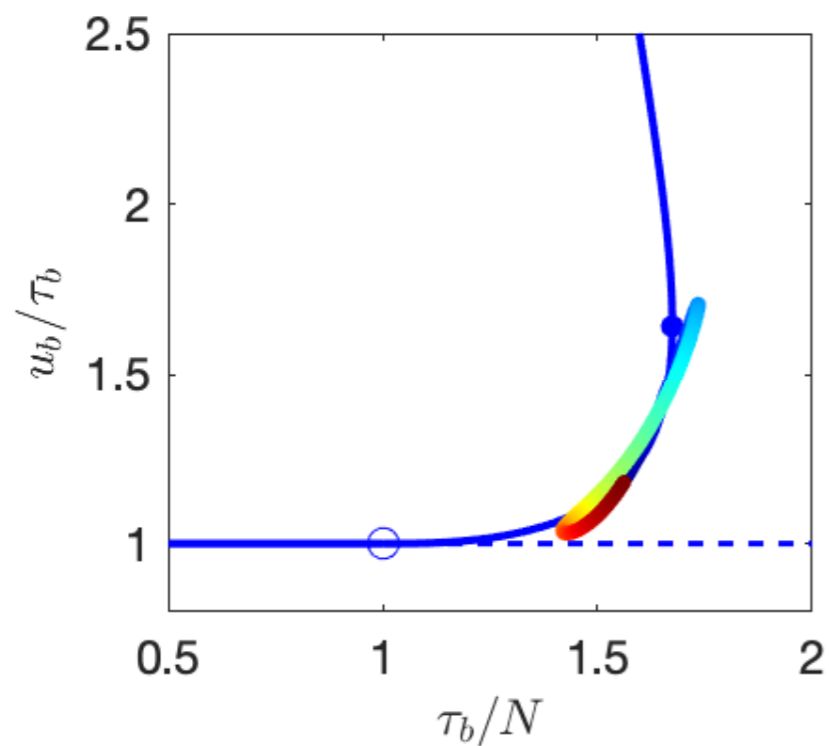
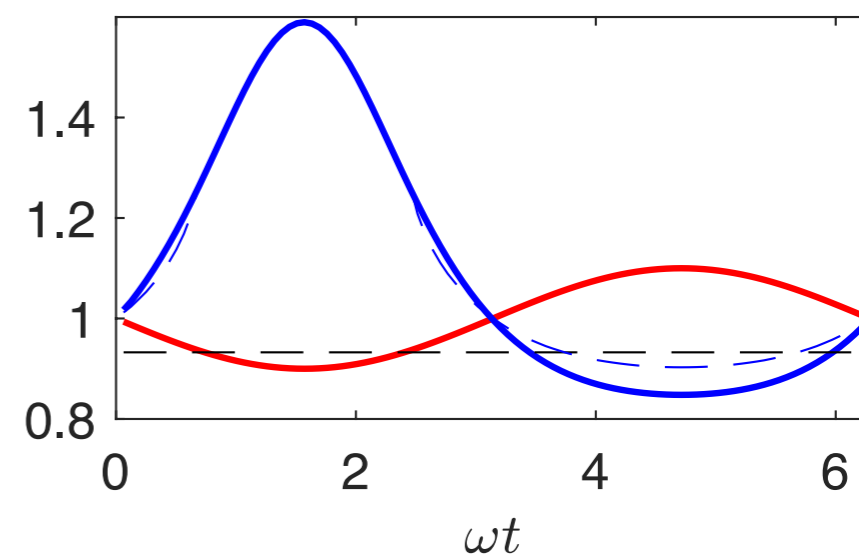
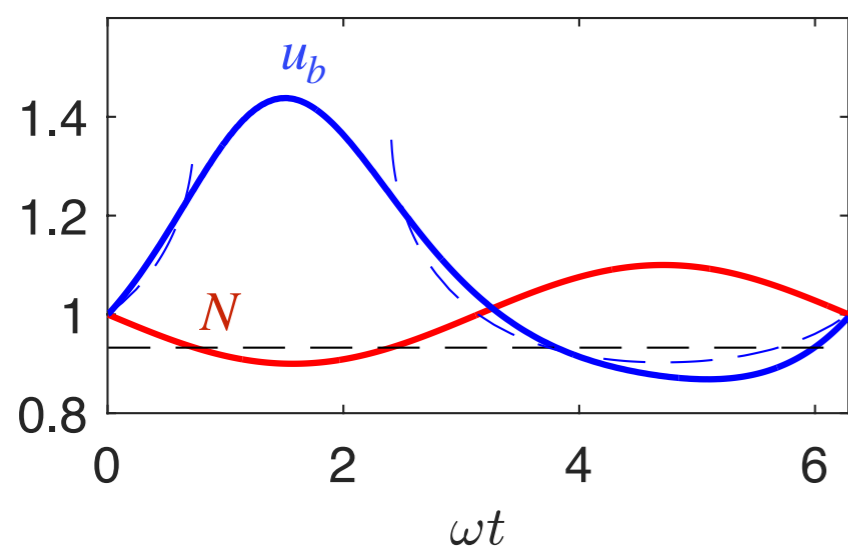


Normal stress  
Opening velocity

More rapid fluctuations

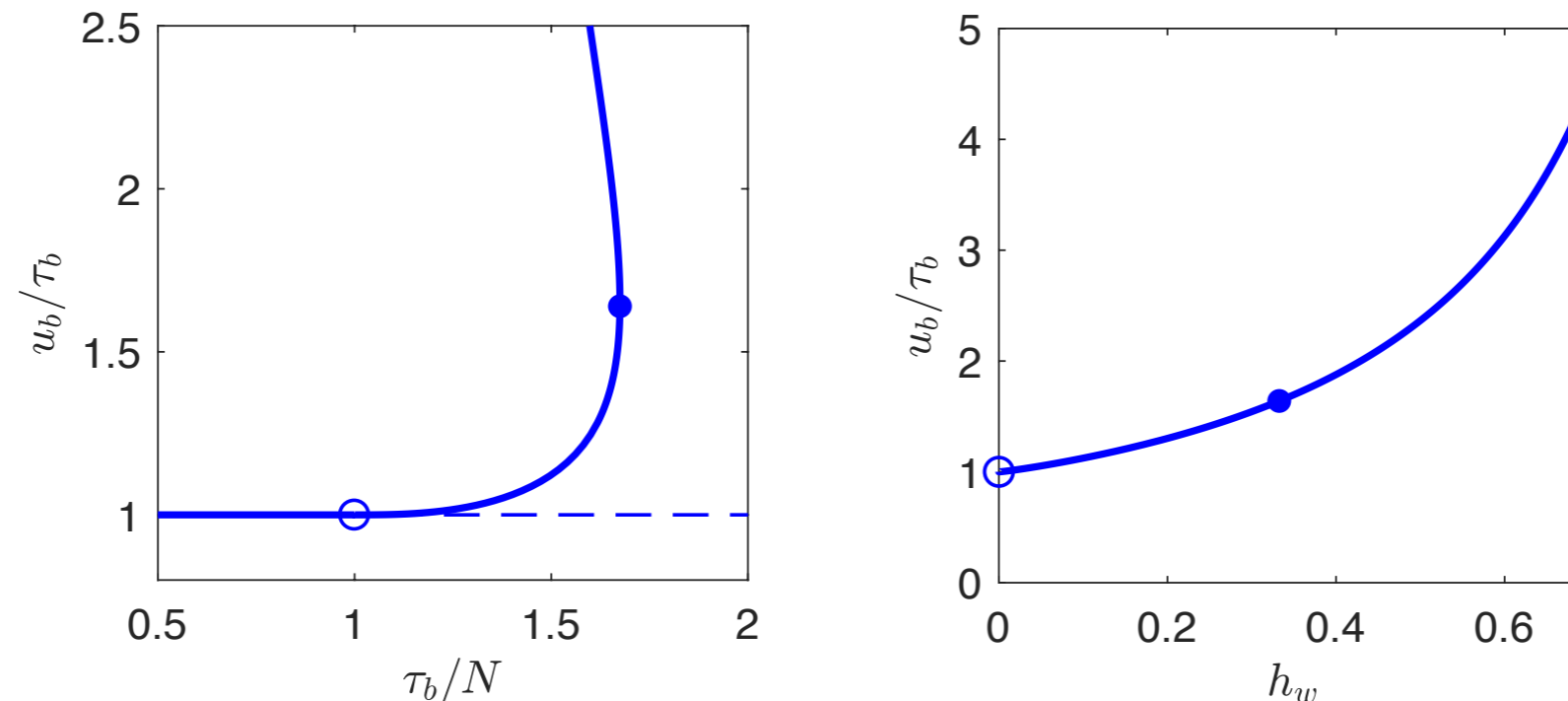


➔ Minimal change in cavity size



# Summary

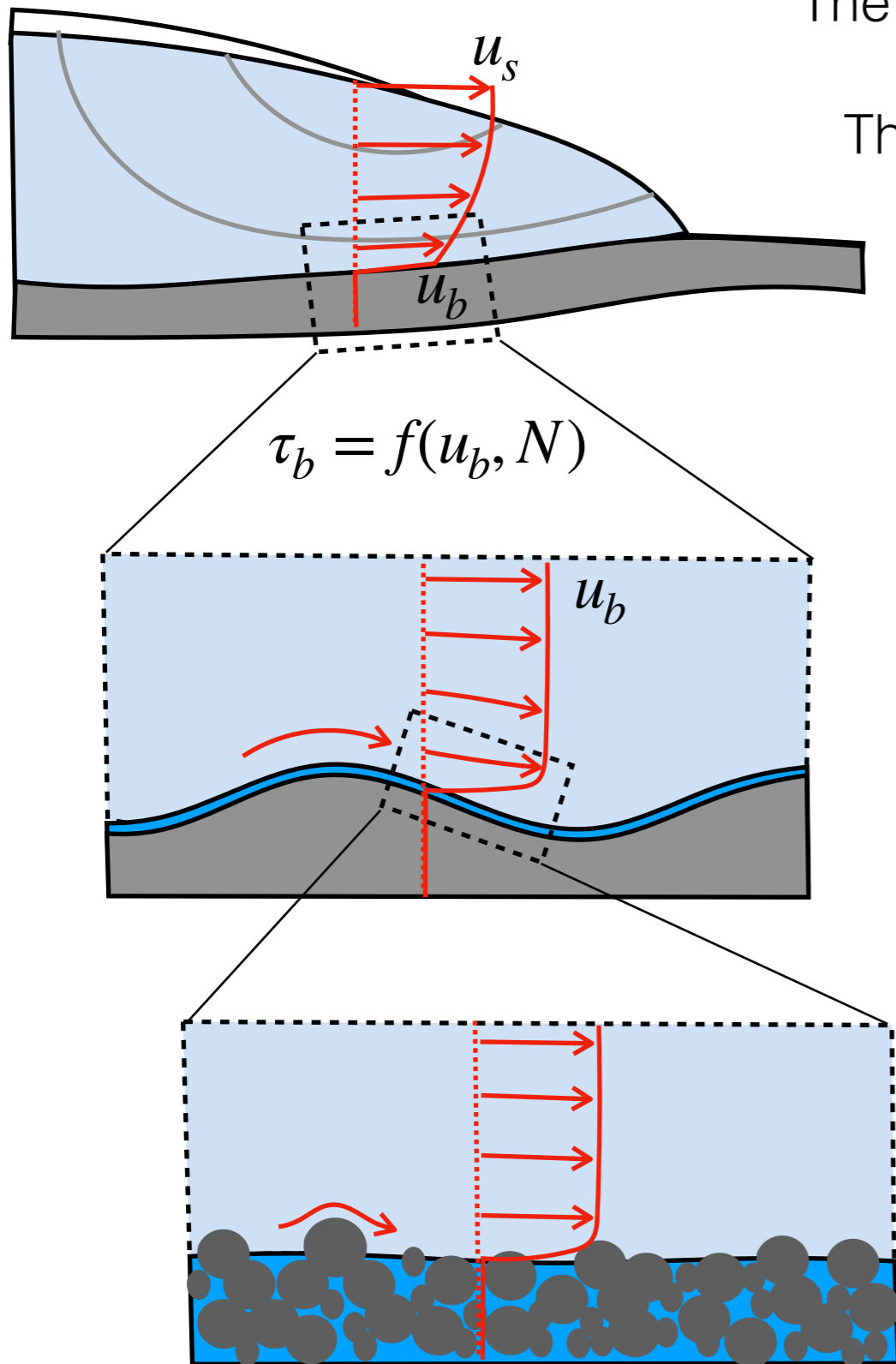
The usual 'steady-state' sliding law relates **shear stress** and **sliding speed** for given **effective pressure** or given **cavity volumes**.



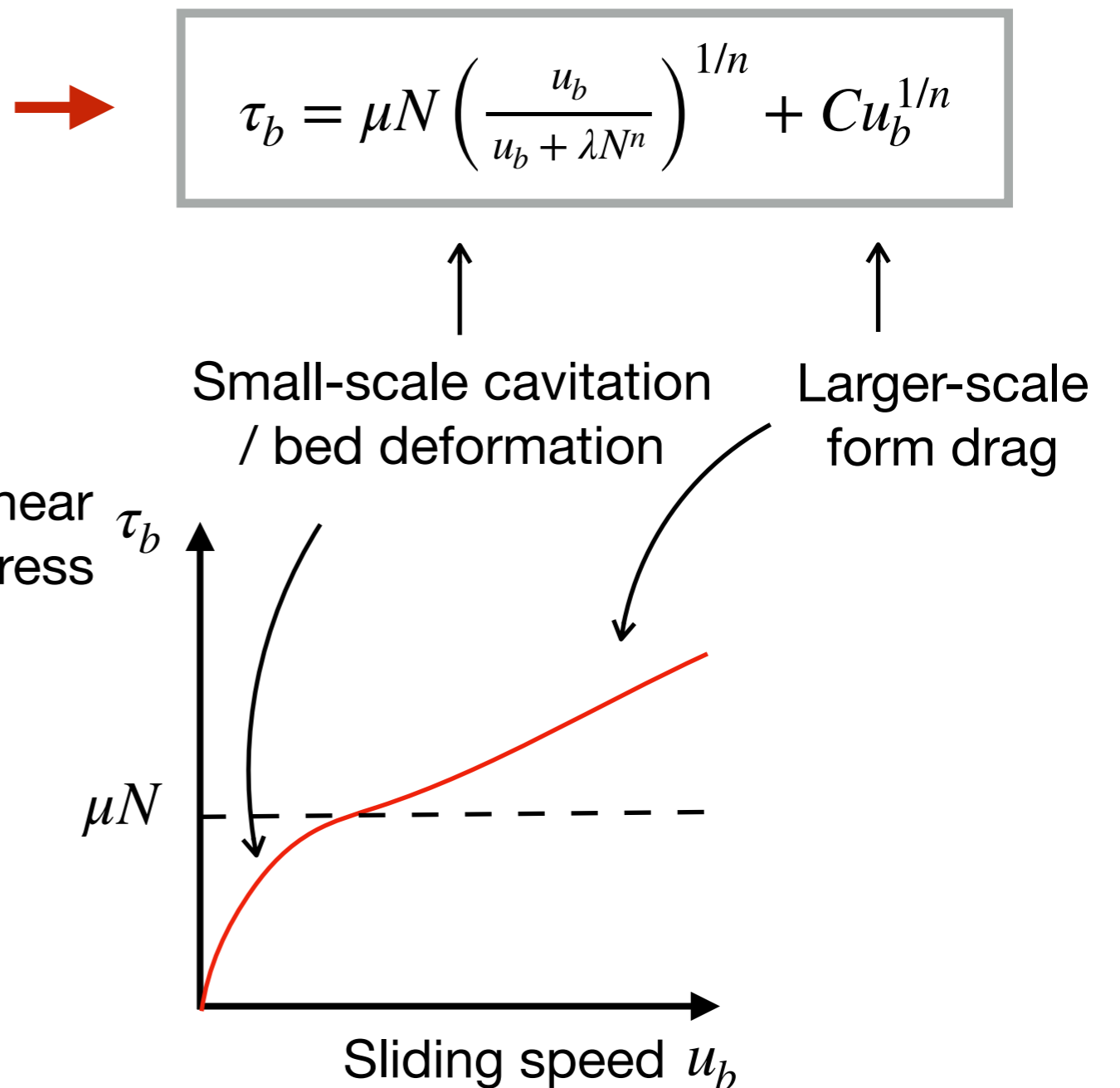
Forced **fluctuations** in water pressure do not seem to result in too large perturbations from the steady-state law.

However, many cavities may be hydraulically isolated, and are **constrained by cavity volume**, rather than effective pressure. This acts as a 'brake' on surface-meltwater-driven velocity changes.

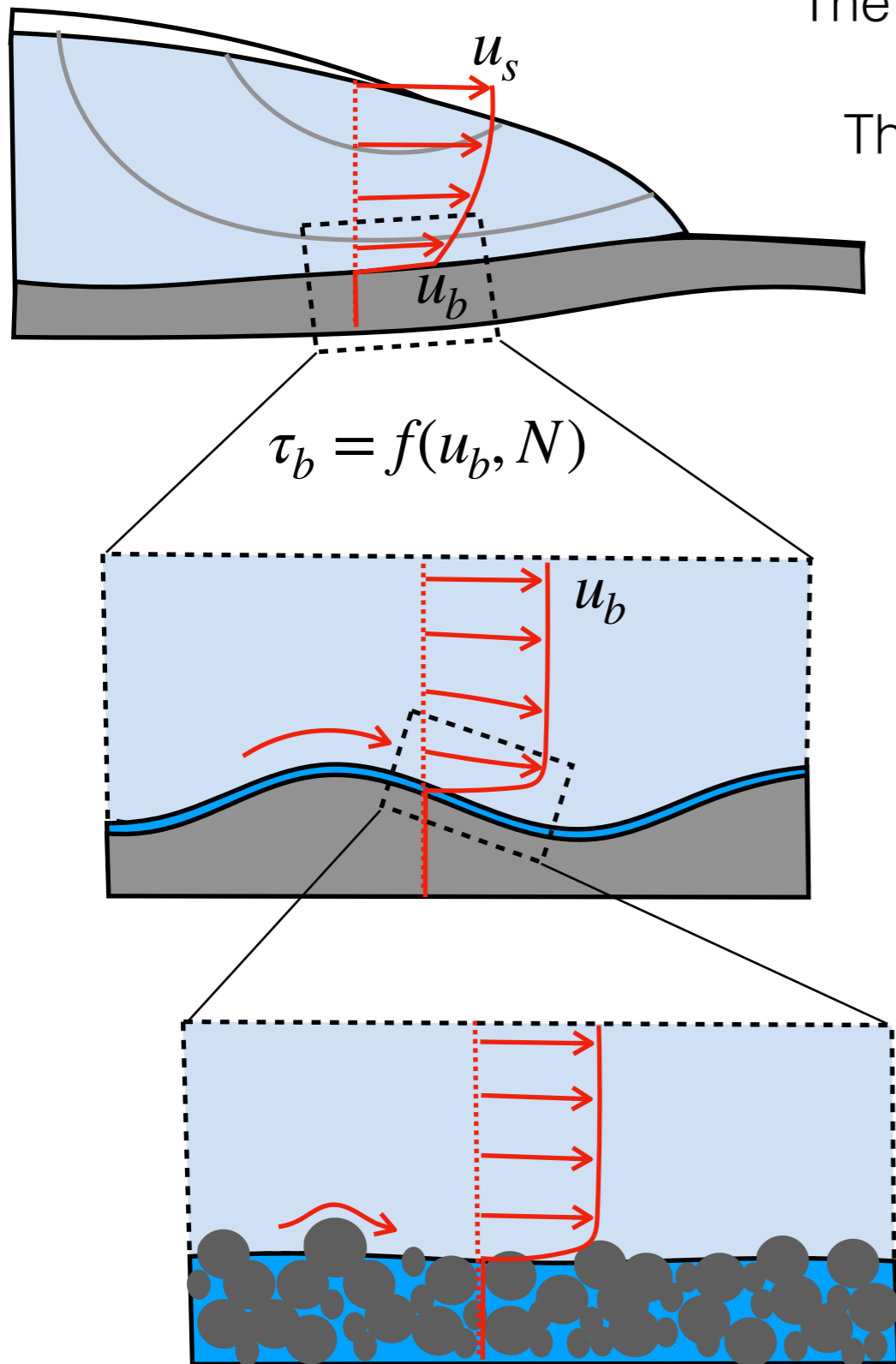
# The importance of 'form drag'



The sliding law in numerical models needs to account for **all sub-grid scale 'roughness'**.  
That often includes larger scales than those for which cavitation / bed deformation are relevant.



# The importance of 'form drag'



The sliding law in numerical models needs to account for **all sub-grid scale 'roughness'**.  
That often includes larger scales than those for which cavitation / bed deformation are relevant.

$$\tau_b = \mu N \left( \frac{u_b}{u_b + \lambda N^n} \right)^{1/n} + C u_b^{1/n}$$

