LECTURE 3.

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1.3. Sard's theorem.

Fact. ¹ For smooth $f: M \to N$,					
	Almost every point of N is a regular value of f				

This means: {critical values} = $f({\text{critical points}})$ is a set of measure zero² in N. Equivalently: {regular values} $\subset N$ has full measure, so these points are "generic".

Cor. $\{regular values\} \subset N \text{ is dense.}$

Pf. Non-empty open sets in \mathbb{R}^n have measure > 0.

Rmk. M, N need not be compact. The result only uses that M is second countable.³

Fact. For C^k -maps⁴ $f: M^m \to N^n$, the above fact holds provided k > m - n. (Here M, N need not be smooth, just need C^k -mfds: the transition maps are C^k .)

Examples.

- (1) $f : \mathbb{R}^m \to \mathbb{R}, x \mapsto \sum x_i^2 1$ 0 regular value, so $f^{-1}(0) = S^{m-1}$ mfd of dim = m 1.
- (2) $f: Matrices_{n \times n} \to Symmetric Matrices_{n \times n}, A \mapsto A^T A$ I regular value, so $f^{-1}(0) = O(n)$ mfd of $\dim = n^2 - \frac{n(n+1)}{2}$. (3) Hwk.⁵ Sard \Rightarrow homotopy groups $\pi_i(S^n) = 0$ for i < n.

1.4. Transversality.

Motivation:

$q \in N$ regular value	\Rightarrow	$f^{-1}(q) \subset M$ submfd
① submfd $Q \subset N$ satisfying?	\Rightarrow	$f^{-1}(Q) \subset M$ submfd
$@$ submfds $Q_1, Q_2 \subset N$ satisfying?	\Rightarrow	$Q_1 \cap Q_2 \subset N$ submfd

① Pretend N/Q made sense ② ⇒ $F: M \xrightarrow{f} N \rightarrow N/Q \ni \overline{q} = Q/Q$

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¹If you are curious about its non-examinable proof, see Milnor's Topology from the Differentiable Viewpoint, or Guillemin & Pollack, Differential Topology.

²A subset S of \mathbb{R}^n has measure zero if $\forall \varepsilon > 0$, \exists countable covering of S by cubes C_i , with $\sum \operatorname{vol}(C_i) < \varepsilon$. A subset S of a mfd N has measure zero if for any chart $\varphi : U \to \mathbb{R}^n, \, \varphi(S \cap U)$ has measure 0 (it's enough to require this for a covering $\varphi_i : U_i \to \mathbb{R}^n$). Example: $\mathbb{Q} \subset \mathbb{R}$. Useful facts: countable unions of measure 0 sets have measure 0; C^1 -maps between subsets of \mathbb{R}^n always map measure 0 sets to measure 0 sets.

 $^{^{3}}Second \ countable =$ there is a countable covering by charts. This is always part of the definition of manifold. Consequence: any covering has a countable subcover.

⁴k-times continuously differentiable maps, with $k \ge 1$ so "regular/critical points" are defined. $^5Non-examinable:$ the proof essentially shows Sard implies the cellular approximation theorem.

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$$\begin{array}{l} \Rightarrow \ f^{-1}(Q) = F^{-1}(\overline{q}) \\ \Rightarrow \ f^{-1}(Q) \ \text{is mfd if } \overline{q} \ \text{regular value of } F \\ & \text{if } d_p F \ \text{surjective } \forall p \in F^{-1}(\overline{q}) \\ & \text{if } d_p F(T_p M) = T_{\overline{q}}(N/Q) \\ & \text{if } \hline d_p f(T_p M) + T_q Q = T_q N \qquad \forall p \in f^{-1}(q), \forall q \in Q \end{array}$$

Def. $f: M \to N$ is transverse to Q if the above box holds. Write $f \pitchfork Q$. Thus

$$f \pitchfork Q \Rightarrow \begin{cases} f^{-1}(Q) \subset M \text{ submfd of codim} = \operatorname{codim} Q\\ T_p f^{-1}(Q) = \ker(T_p M \xrightarrow{d_p f} TN \longrightarrow TN/TQ) = \ker(D_p f : T_p M \longrightarrow \nu_{Q,q}) \end{cases}$$

$$Pf. \text{ Locally } Q \subset N \text{ is}^6 \mathbb{R}^a \subset \mathbb{R}^n, \text{ so "}N/Q" \text{ is well-defined locally: } \mathbb{R}^n/\mathbb{R}^a. \square$$

Explanation: $\nu_Q = TN/TQ$ =normal bundle to $Q \subset N$, fibre $\nu_{Q,q} = T_q N/T_q Q$. $D_p f$ is abuse of notation:⁷ $Df_p \cdot X$ = vertical projection of $d_p f \cdot X$ at $q = f(p) \in Q$

② For
$$f: Q_1 \xrightarrow{} N$$
 and $Q = Q_2 \subset N$,
 $f^{-1}(Q) = Q_1 \cap Q_2 \subset N$



Examples. $N \pitchfork$ any submfd! Two vector subspaces $\subset \mathbb{R}^n$ are \pitchfork if they span \mathbb{R}^n .

Rmk.

1. dim $Q_1 + \dim Q_2 < \dim N$ then $Q_1 \pitchfork Q_2 \Leftrightarrow Q_1 \cap Q_2 = \emptyset$ 2. dim $Q_1 + \dim Q_2 = \dim N$ then $Q_1 \pitchfork Q_2 \Leftrightarrow \begin{cases} Q_1 \cap Q_2 \text{ finite set}^8 \\ TQ_1 \oplus TQ_2 \cong TN \text{ at } q \in Q_1 \cap Q_2 (*) \end{cases}$

In case 2. you can define an intersection number

$$Q_1 \cdot Q_2 = \#(Q_1 \cap Q_2) \mod 2 \in \mathbb{Z}/2\mathbb{Z}$$

If Q_1, Q_2, N oriented:⁹

$$Q_1 \cdot Q_2 = \#(Q_1 \cap Q_2) \in \mathbb{Z},$$

⁶Hwk 3: $Q \to N$ immersion \Rightarrow locally has form $(x_1, \ldots, x_a) \mapsto (x_1, \ldots, x_a, 0, \ldots, 0) \in \mathbb{R}^n$. ⁷f is not a section of ν_Q , but the construction of that vertical projection is analogous. ⁸assuming Q_1, Q_2 are compact submanifolds. Otherwise, replace with "discrete set".

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⁹Non-examinable: it suffices that Q_1 is oriented, and Q_2 is co-oriented (= normal bundle $\nu_{Q_2} = TN/TQ_2$ is oriented). Assign +1 to $p \in Q_1 \cap Q_2$ if an oriented basis of T_pQ_1 gives rise to an oriented basis of ν_{Q_2} , and -1 else. When Q_1, Q_2, N are oriented, this sign agrees with the one above, if we orient so that $TN|_{Q_2} \cong \nu_{Q_2} \oplus TQ_2$ preserves orientation ("normals first").

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where # counts with sign +1 if the iso (*) is orientation-preserving, -1 otherwise. Next time, we will deduce that one can always achieve $Q_1 \pitchfork Q_2$ after perturbing

 Q_1 (or Q_2), and in case 2. the value $Q_1 \cdot Q_2$ is independent of the perturbation.

Motivation for stability and genericity. Transversality is stable and generic: Stable: perturbing preserves the property, generic: it can be achieved by perturbing.



1.5. Stability.

Recall a (smooth) homotopy f_t of $f: M \to N$ means a smooth map

$$H: M \times [0,1] \to N$$
 with $\begin{cases} f_t(x) = H(x,t) \\ f_0 = f \end{cases}$

Call f_0, f_1 (smoothly) homotopic.

Def. A "property" P is stable for a class C of maps $f: M \to N$, if

 $\left. \begin{array}{l} f \in C \text{ satisfies } P \\ f_t \text{ homotopy} \end{array} \right\} \Rightarrow f_t \text{ satisfies } P \text{ for each } t < \varepsilon \quad (\varepsilon > 0 \text{ depending on } f, f_t) \end{array} \right.$

Rmk.

- (1) Locally stable means $\forall p \in M, \exists nbhd \ U \ni p \text{ such that } P \text{ is stable for the restrictions } \{f|_U : f \in C\}$
- (2) For compact M, one can often deduce stability from local stability, by covering M by such U, taking a finite subcover, taking min of ε 's.
- (3) Can use more general parameters $t \in S = metric space$.

Stability Theorem. M compact \Rightarrow the following classes are stable:

 $\{ local diffeos \} \\ \{ regular maps \} \\ \{ maps \ \Uparrow \ to \ a \ given \ topologically-closed \ submfd \ Q \subset N \}$

Pf. The definition of these classes locally involve the non-vanishing of some (sub) determinant of some differential. Use Rmk (2) to globalize. \Box

Cor. Transversality is stable and it is an open condition.

Pf. Stability by Thm. Open: if not, find non-transverse $f_n \to f$ as¹⁰ $n \to \infty$. Produce a homotopy *H* of *f* with $H(1/n, t) = f_n(t)$. *H* contradicts stability. \Box

Rmk. Here is a more direct proof that transversality is an open condition: **Claim 1.** regular points of any smooth map f of mfds forms an open set. **Pf.** Locally at regular p, $d_p f = (I \ 0)$. So for q close to p, $d_q f = (T \ *)$ for some invertible T since invertibility is an open condition.¹¹ So q is regular. \Box Transversality can be expressed as a regularity condition, so it is also open.

¹⁰the convergence is in C^{∞} . Also C^1 is enough: we just need the derivatives to converge.

¹¹If s is an operator with small norm (||s|| < 1 is enough), then $(I+s)^{-1} = I - s + s^2 - s^3 + \cdots$ is a well-defined operator. If L is invertible and ||s|| < ||L|| then $(L+s)^{-1} = (I+L^{-1}s)^{-1}L^{-1}$.

1.6. Local to global examples.

Thm. Any compact mfd N can be embedded in some \mathbb{R}^k .

Pf. Cover N by all possible charts¹² $\varphi : B(2) \to N$.

Pick finitely many φ_i for which $\varphi_i(B(1))$ cover N.

Let $\beta = \text{bump function}^{13} B(2) \rightarrow [0, 1], \beta = 1 \text{ on } B(1), \beta = 0 \text{ near } \partial B(2).$ $\Rightarrow N \hookrightarrow \mathbb{R}^{(n+1) \cdot \# \text{charts}}$

 $p \mapsto (\beta(\varphi_i^{-1}(p)) \cdot \varphi_i^{-1}(p), \beta(\varphi_i^{-1}(p)))_{i=1,2,\dots}$ (zero entry for *i* if $p \notin im\varphi_i$). Note we are keeping track of the β values to ensure global injectivity. \Box

Cultural Rmk. Whitney proved $N^n \hookrightarrow \mathbb{R}^{2n}$. Transversality techniques from this course can easily prove $N^n \hookrightarrow \mathbb{R}^{2n+1}$ (if you're curious, see Guillemin & Pollack).

Def. A tubular neighbourhood is a nbhd U of S with a regular retraction

 $\pi: U \to S.$

(Retraction just means $\pi|_S = id_S$).

Thm. Any submanifold $S \subset M$ has a tubular nbhd $U \subset M$.

Pf. Pick a Riemannian metric for M, use exp map. \Box



Rmk.

- (1) $U \stackrel{exp^{-1}}{\cong} nbhd \text{ of zero section of normal bundle } \nu_S$ $\pi \cong projection$
- (2) Converse:¹⁴ A closed subset $S \subset \mathbb{R}^k$ is a submfd $\Leftrightarrow S$ is a smooth retract¹⁵

Pf. implicit function theorem for regular $\pi: U \to S$. Non-examinable details of Pf:



For $p \in U$ near S, let $X = d_p \pi(T_p U) \subset \mathbb{R}^k$ a v.subspace (secretly $T_{\pi(p)}S$). Then $\mathbb{R}^k = X \oplus Y$ some v.subspace Y. After lin change of coords,

$$d_p \pi = \begin{bmatrix} I & 0 \\ 0 & 0 \end{bmatrix} : X \oplus Y \to X \oplus Y,$$

with $p = (0,0) \in X \oplus Y = \mathbb{R}^k$. Define
 $F : X \oplus Y \to X \oplus Y, F(x,y) = \pi(x,y) + y.$
 $d_p F = I \Rightarrow InvFnThm \Rightarrow F^{-1}(s) = (g(s,0),0)$
for $s \in S$ defines chart $s \mapsto g(s,0)$ at $\pi(p) \in S$.

 $^{{}^{12}}B(r) = \text{open ball of radius } r, \text{ centre } 0, \text{ in } \mathbb{R}^n.$

¹³You gain nothing from writing out explicitly a bump function you already know exists: Non-examinable: for b > a > 0, let $\alpha(x) = e^{-1/x}$ for x > 0, 0 for $x \le 0$; let $\gamma(x) = \alpha(x-a) \cdot \alpha(b-x)$; let $\delta(x) = \int_x^b \gamma / \int_a^b \gamma$. Then $\beta(x) = \delta(|x|)$ is 1 on $|x| \le a$, 0 on $|x| \ge b$, $\beta(x) \in (0, 1)$ for a < |x| < b. ¹⁴the same proof shows this holds for C^r -mfds, $\pi \neq C^r$ -map, $r \ge 1$ (not just $r = \infty$). ¹⁵Smooth retract= \exists open nbhd U of S, \exists smooth $\pi : U \to \mathbb{R}^k$ with $\pi(U) \subset S$, $\pi|_S = \mathrm{id}_S$.