## Sigmoid Functions, Multiscale Resolution of Singularities, and hp-Mesh Refinement<sup>\*</sup>

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**Abstract.** In this short, conceptual paper we observe that closely related mathematics applies in four contexts with disparate literatures: (1) sigmoidal and RBF approximation of smooth functions, (2) rational approximation of analytic functions with singularities, (3) hp-mesh refinement for solution of PDEs, and (4) double exponential (DE) and generalized Gauss quadrature. The relationships start from the change of variables  $s = \log(x)$ , and they suggest possibilities for new analyses and new methods in several areas. Concerning (2) and (3), we show that both problems feature the same effect of "linear tapering" near the singularity—of clustered poles in rational approximation and of polynomial orders in hp-mesh refinement. Concerning (4), we note that the tapering effect appears here too, and that the change of variables interpretation sheds new light on why the DE and generalized Gauss methods are effective at integrating arbitrary singularities.

Key words. rational approximation, sigmoid function, logistic function, radial basis function, hp-mesh refinement, DE quadrature, generalized Gauss quadrature

MSC codes. 41A20, 65D15, 65D32

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**I. Introduction.** A longstanding theme in numerical computation is the effective treatment of singularities. In approximation theory, it is known that any branch point singularity can be approximated by rational functions with root-exponential convergence (i.e., convergence at a rate  $O(\exp(-C\sqrt{n}))$  for some C > 0, where n is the degree of the rational function), provided the poles are exponentially clustered near the singularity. The first observation of this paper is that the mathematics of this effect is the same as that of a seemingly very different well-known phenomenon: that smooth functions can be approximated with great efficiency by translates of a fixed smooth function such as a sigmoid or a radial basis function (RBF). This equivalence is the subject of section 2, where we give references about root-exponential convergence and consider implications for both rational approximation and smooth approximation by sigmoids, and of section 6, where we generalize sigmoids to RBFs.

Section 3 turns to another relationship: between approximation of singularities by rational functions and resolution of singularities (typically at corners) in hp-mesh refinement in the finite element method (hp-FEM). Recently it has been recognized that best and near-best rational approximations exploit a "linear tapering" effect, in

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which poles are exponentially clustered near singularities with a density that tapers off linearly on a log scale [42]. In section 3 we show that this linear tapering appears for the same reason that hp- rather than just h-mesh refinement is advantageous in FEM calculations. The tapering is linear in both cases (in a 1D setting), and brings a factor of 2 improvement over nontapered distributions. These observations lead to the suggestion of an alternative method of hp-mesh refinement that should achieve the same asymptotically optimal convergence rate.

We then go on to consider further aspects of the exponential resolution of singularities. Section 4 discusses quadrature formulas designed for efficient integration of functions with endpoint singularities, in particular the double exponential (DE) and generalized Gauss methods. In both cases, tapered exponential clustering is seen, and our analysis sheds a new light on why this happens and why both of these quadrature methods are effective at treating a range of singularities all at once, and not just a single targeted singularity such as  $x^{\alpha}$ .

The significance of the change of variables  $s = \log(x)$  is not just algebraic. Section 5 explores its physical interpretation, showing how multiscale separation of scales in the x variable is equivalent to the effect of exponential decay of influences along channels for elliptic PDEs.

The aim of this paper is to point out new relationships and to suggest new explorations. With the change of variables  $s = \log(x)$ , multiscale analysis becomes translation. Rational approximation, adaptive mesh refinement, and numerical quadrature may all benefit from a consideration of the implications of this relationship.

**2. Sigmoids**  $\leftrightarrow$  **Rational Approximation.** An important result of rational approximation theory, which sets it far apart from polynomial approximation, is that functions with branch point singularities can be approximated with root-exponential convergence. For example, consider

(2.1) 
$$f(x) = \sqrt{x}, \quad x \in [0, 1].$$

Since Donald Newman in 1964 [30] it has been known that there are degree n rational functions

$$(2.2) r_n(x) = a_0 + \sum_{k=1}^n \frac{a_k}{1 + x/\varepsilon_k}, \quad a_k \in \mathbb{R}, \ \varepsilon_k > 0,$$

such that

(2.3) 
$$||f - r_n|| = O(\exp(-C\sqrt{n}\,)), \quad C > 0,$$

where  $\|\cdot\|$  is the supremum norm on [0, 1]. What makes this *root-exponential conver*gence possible is that the poles  $\{-\varepsilon_k\}$  are exponentially clustered near the singularity at x = 0. This effect and the estimate (2.3) apply at any branch point singularity [16, 21, 42] of a real or complex function and are the basis of "lightning PDE solvers" for the Laplace, biharmonic, and Helmholtz equations in domains with corners [1, 6, 16, 17, 43]. For a specific result spelling out some of the generality of the root-exponential convergence phenomenon, see Theorem 2.3 of [16]. Figure 1 illustrates root-exponential convergence and exponential clustering for this model problem.

The function  $1/(1 + x/\varepsilon_k)$  of (2.2) is monotonically decreasing for  $x \in [0, 1]$  and takes values  $\approx 1$  for  $x \ll \varepsilon_k$  and  $\approx 0$  for  $x \gg \varepsilon_k$ . If we introduce the change of variables

(2.4) 
$$s = \log(x) \in [-\infty, 0], \quad x = e^s \in [0, 1],$$



**Fig. 1** Root-exponential convergence (left,  $0 \le n \le 20$ ) and exponential clustering of poles near 0 in  $(-\infty, 0)$  (right, n = 20) for degree n minimax rational approximation of  $f(x) = \sqrt{x}$  on [0, 1]. Note that the horizontal axis in the first plot is  $\sqrt{n}$ . These effects generalize to rational approximation at any branch point singularity.

then this function is transformed into

(2.5) 
$$\frac{1}{1+e^s/\varepsilon_k} = \frac{1}{1+e^{s-s_k}},$$

where  $s_k = \log \varepsilon_k$ . This function, or more properly its flipped form  $1/(1 + e^{s_k - s})$  with  $s - s_k$  replaced by  $s_k - s$ , is the most basic example of a sigmoid function, known as the *logistic function*. In physics it goes by the name of the *Fermi* or *Fermi–Dirac function*, and it is an elementary transformation of the hyperbolic tangent. Functions of this kind are prototypical activation functions in neural networks, and the literature of this area is vast [8, 14, 22, 25, 32]. (We make no claim here to significant links with neural networks and machine learning, since the approximations of this paper are univariate, noise-free, and involve just a single hidden layer rather than a composition of several layers.)

With the change of variables (2.4), we may follow (2.1) and (2.2) to define

(2.6) 
$$F(s) = f(x) = e^{s/2}$$

and

(2.7) 
$$R_n(s) = r_n(x) = a_0 + \sum_{k=1}^n \frac{a_k}{1 + e^{s - s_k}}.$$

Equation (2.3) then implies that there are approximations (2.7) such that

(2.8) 
$$||F - R_n|| = O(\exp(-C\sqrt{n})), \quad C > 0,$$

where  $\|\cdot\|$  is now the supremum norm on  $[-\infty, 0]$ . Equation (2.8) is nothing more than a claim about root-exponential approximation of a smooth function on  $[-\infty, 0]$ by linear combinations of translates of a standard smooth function, plus a constant. Following results such as those of [11], this could be proved directly in this setting rather than in the setting of rational functions, where the standard proof technique is the relatively advanced Hermite contour integral formula [41]. The root-exponential rate results from balancing discretization errors associated with separations  $\Delta s_k = O(1/\sqrt{n})$  against truncation errors associated with a grid extent  $s_{\min} = \min s_k = O(\sqrt{n})$  [21]. Figure 2 illustrates the smooth functions in question for the problem of Figure 1.



**Fig. 2** In the  $s = \log(x)$  variable, the exponentially clustered poles of Figure 1 become sigmoid functions (2.5) translated to various center points  $s_k$ . Root-exponential convergence of rational approximations becomes a statement about approximation of smooth functions by linear combinations of translates of a fixed smooth function.

To summarize this section: with the change of variables  $s = \log(x)$ , the approximation of a smooth function by linear combinations of translates of a logistic function becomes equivalent to the approximation of a function with a branch point singularity by rational functions with exponentially clustered poles.

**3. Rational Approximation**  $\leftrightarrow$  *hp*-mesh Refinement. Rational approximation with poles exponentially clustered near singularities seems akin to the resolution of functions near singularities by piecewise polynomials on exponentially refined meshes. Such techniques of *mesh refinement* are well known in the literature of the FEM and associated approximation theory [9, 19, 20, 26, 34, 35].

Exponential clustering of poles is reflected in the approximately uniform spacing on the semilogx scale in the right image of Figure 1 or, equivalently, the approximately uniform spacing of the sigmoid functions (2.5) in Figure 2. However, it is notable that in both of these images the spacing is only approximately uniform, growing sparser toward the left. This is the phenomenon of *tapered exponential clustering* investigated in [42]. Quantitatively, one finds that the density of poles with respect to the *s* variable decreases linearly as *s* decreases to some value  $s_{\min}$ . This distribution brings a factor of 2 improvement in convergence rate as a function of *n*—because a uniform density would have the same convergence rate but twice as many poles. (The more local sparsification in the rightmost few points of Figures 1 and 2 is investigated in [21] with an appeal to the asymptotic results of Stahl [36].)

Comparison reveals that this tapered exponential clustering corresponds closely to what is known as hp-mesh refinement (h stands for grid spacing, p for order of approximation). In particular, the standard hp-mesh refinement formula in one dimension has the same linear pattern described above, with polynomial order taking the role of pole density on the logarithmic scale. A singular function such as  $\sqrt{x}$ on [0, 1] is approximated by piecewise polynomials on intervals of lengths decreasing exponentially toward the singularity, with polynomial representations of linearly decreasing degrees ..., 3, 2, 1, 0. It is the same pattern, and it brings the same factor of 2 speedup for the same reason.

One can explain linear tapering for hp-FEM in various ways in various settings. In [42] an argument is given based on potential theory. Here is an outline of the simpler argument that originates with DeVore and Scherer [9, 34] in the study of piecewise polynomial approximations of  $x^{\alpha}$  on exponentially graded meshes on [0, 1]. For precise statements, see Theorem 1 of [9] and Theorem 3 of [34]. These authors started from the consideration of a type of spline approximation with free knots and showed that exponential clustering of knots was the optimal strategy. We speak for simplicity in terms of mesh refinement by factors of 1/2, though the optimal factor is actually  $(\sqrt{2} - 1)^2 \approx 0.172$ . We show the reasoning for  $\sqrt{x}$ , though the same argument (with different constants) applies to  $x^{\alpha}$  for any positive noninteger  $\alpha$ . The observations of DeVore and Scherer were generalized to ODE and PDE discretizations a few years later by Babuška and his collaborators [19, 20]. In multiple dimensions, the details change.

- 1. Approximation of  $\sqrt{x}$  on [1/2, 1] is the same as approximation of  $\sqrt{2x}$  on [1/4, 1/2].
- 2. Therefore, approximation of  $\sqrt{x}$  on [1/4, 1/2] is the same problem too, but with an accuracy criterion loosened by a factor  $\sqrt{2}$ .
- 3. Functions like these, bounded away from singularities, can be approximated by polynomials with exponential convergence.
- 4. Therefore, that loosening by the factor  $\sqrt{2}$  allows one to lower the degree of the polynomial by a constant increment and still obtain the same accuracy.
- 5. Repeat on  $[1/8, 1/4], [1/16, 1/8], \ldots$

Note that if we skipped step 4 and fixed the same polynomial degree on all intervals, the same overall accuracy would still be achieved but in an unbalanced manner, with errors on [1/2, 1] dominating those on the other subintervals. The number of free parameters would approximately double.

To summarize this section: the standard formula for hp-mesh refinement in 1D involves a linear decrease of the polynomial degree toward the singularity, and this corresponds to the linear decrease of the pole density on a logarithmic scale in tapered exponential clustering of poles in rational approximation, resulting in the same factor-of-2 speedup.

The link with rational functions highlights that the standard hp-mesh refinement strategy is not the only way to achieve linear tapering. An alternative would be to hold the polynomial degree p fixed and instead refine h superexponentially at the singularity. We do not know whether such a prescription has been used in finite element calculations.

There are many other aspects of approximation theory that might be related to this discussion. For example, Saff and coauthors showed the existence of polynomial approximations that are exponentially good everywhere on a domain except near singularities [23, 33]. There is an extensive literature of methods for "overcoming the Gibbs phenomenon," typically at points where f is discontinuous, which often start from a Fourier representation that is then enhanced by nonlinear postprocessing [10, 18, 38]. There are also situations, arising, for example, in certain PDE problems on domains with edges or corners, where the function to be approximated is unbounded. Singularities are ubiquitous in computational mathematics, and many methods have been advanced to treat them.

4. Double Exponential and Generalized Gauss Quadrature. In the area of quadrature or numerical integration, many methods have been developed for dealing with singularities. When a fixed endpoint singularity like  $x^{\alpha}$  is known, a targeted quadrature formula can be derived: the prototype is a Gauss–Jacobi formula. For dealing with more complicated, mixed, or unknown singularities, however, more general techniques have been proposed. One is *double exponential* or *tanh-sinh* quadra-



Fig. 3 Nodes of a double exponential quadrature formula with standard parameters, showing tapered exponential clustering near a singularity. (Figure adapted from Figure 13 of [42].)

ture [2, 29, 39]. As illustrated in Figure 3, the tanh-sinh formula with standard parameter choices produces a tapered exponentially clustered distribution of quadrature points. This figure is adapted from Figure 13 of [42], where full details can be found. Such results indicate that DE quadrature is probably related to what is seen with rational approximation and hp-mesh refinement, but as far as we know, no analysis of this effect has yet been carried out.

Kirill Serkh (private communication) has shown us that similar effects also arise with generalized Gauss and universal quadrature formulas [4, 5]. These are quadrature formulas that are constructed by linear algebra methods related to Gauss quadrature so as to be efficient at integrating not just a single singularity such as a fixed power  $x^{\alpha}$ , but also a range of singularities such as  $x^{\alpha}$ ,  $\alpha \in [0, 1]$ . Again it appears that in important cases, the nodes are exponentially clustered near the singularity with a tapered distribution. The arguments of this paper reveal that the ability of a single such formula to handle a wide range of singularities is related to the ability of a fixed set of exponentially clustered poles for a rational function to resolve arbitrary branch point singularities [16, 21, 42].

In a similar vein one can compute Gaussian quadrature rules for spaces of rational functions with fixed clustered poles, such as those in Figure 1, using, for example, the algorithm for rational quadrature of Gautschi [13]. One again observes root-exponential convergence and, by now unsurprisingly, an exponential distribution of the quadrature points with linear tapering. The difference between DE and the Gaussian rules is that the former is optimized by tuning parameters, whereas Gaussian quadratures are inherently optimal or optimized by linear algebra calculations—yet both lead to similar distributions.

5. The Physics of  $s = \log(x)$ : Separation of Scales. The change of variables  $s = \log(x)$  is not just an algebraic trick. It also has a physical interpretation alluded to in section 5 of [42]; see, for example, Figure 11 of that paper.

Even before introducing the change of variables, the point can be seen in the x variable. The function  $1/(1 + x/\varepsilon_k)$ , with its pole at distance  $\varepsilon_k$  to the left of x = 0, is essentially constant and hence inactive to the right of x = 0 for  $x \ll \varepsilon_k$  (taking the value 1) and  $x \gg \varepsilon_k$  (taking the value 0). It is only for  $x \approx \varepsilon_k$  that this function is active. Thus, exponentially separated poles  $\{-\varepsilon_k\} \subseteq (-\infty, 0)$  are



**Fig. 4** Sketch of the "physics" of the change of variables  $s = \log(x)$ . This is a conformal map of the upper half x-plane to an infinite strip in the s-plane, with poles  $-\varepsilon_k$  and sample locations  $\varepsilon_k$  on exponentially separated scales mapping to poles  $s_k + \pi i$  and sample locations  $s_k$  on opposite sides of the strip. The well-known exponential decay of influences along strips explains why a pole at  $s_k + \pi i$  has a significant effect at  $s_k$  but a much smaller effect at a different point  $s_i$  with  $|s_i - s_k| \gg 1$ .

physically decoupled, operating in independent regimes, with each pole at  $-\varepsilon_k < 0$  affecting the approximation on  $(0, \infty)$  nontrivially only for  $x \approx \varepsilon_k$ .

The change of variables  $s = \log(x)$  suggests a physical explanation of this separation of scales effect. A problem with a singularity at x = 0 can be motivated as a model of a corner singularity in a PDE problem. Specifically, suppose a Laplace problem is posed in the upper half complex x-plane with a singularity at x = 0. Changing to  $s = \log(x)$  transplants this problem to the infinite strip  $0 < \text{Im} s < \pi$  in the s-plane. The problem is now smooth, with the singularity moved to  $-\infty$ . Exponentially clustered poles  $-\varepsilon_k \in (-\infty, 0)$  become well-separated poles  $s_k + \pi i$  on the upper side of the strip. And now, as sketched in Figure 4, it is a well-known effect of potential theory (or elasticity, where it is called the Saint-Venant principle [40]) that influences decay exponentially with distance along a strip. In the field of numerical conformal mapping, this goes by the name of the crowding phenomenon; see Theorems 2–5 of [15].

The argument made above is tied to the Laplace equation, whose solutions are conformally invariant. However, the essence of the matter will be the same for any problem whose highest order derivative is the Laplacian, because close to a singularity, this term will dominate. With the Helmholtz equation  $\Delta u + k^2 u = 0$ , for example, the influence of the  $k^2 u$  term quickly shuts off to zero relative to that of the  $\Delta u$  term as one comes exponentially close to a corner [17].

6. Radial Basis Functions and Other Activation Functions. A rational function r(x) as in (2.2) is a sum of simple poles, which in the *s* variable becomes a linear combination of sigmoids as in Figure 2. The picture changes little for other activation functions. For example, if the poles  $(x + \varepsilon_k)^{-1}$  in (2.2) are replaced by powers  $(x + \varepsilon_k)^{-a}$  for an arbitrary a > 0, Figure 2 does not change very much. This echoes theoretical and experimental results in neural networks, where choices between activation functions are typically based more on the efficiency of optimization algorithms such as stochastic gradient descent than on approximation power.

As many authors have noted, a closely related topic is that of approximation by radial basis functions (RBFs). Here again one approximates a complicated function by a linear combination of translates of a simple fixed function, and convergence may be very fast when the latter is smooth [7, 11, 12, 27, 28, 31]. For a specific result, see Theorem 4.1 of [28]. To illustrate the application of the duality between  $x \in [0, 1]$  and  $s \in [-\infty, 0]$  to RBFs, Figure 5 constructs approximations to  $\sqrt{x}$  on [0, 1] in the



**Fig. 5** Curves as in Figures 1 and 2 for the approximation of  $\sqrt{x}$  for  $x \in [0,1]$ . The approximating functions are transplants to  $x \in [0,1]$  of Gaussians  $\exp(-(s-s_k)^2)$  for  $s \in [-\infty,0]$ , with the centers  $s_k$  distributed in a tapered manner as specified in (6.1). Clean root-exponential resolution of the singularity is observed.

form of transplants to  $x \in [0,1]$  of Gaussians  $\exp(-(s-s_k)^2)$  for  $s \in [-\infty,0]$ . The centers  $s_k$  are spaced in a tapered manner following the formula

(6.1) 
$$s_k = \log 2 + 3(\sqrt{k} - \sqrt{n}), \quad 1 \le k \le n,$$

as is shown for the case n = 20 in the right-hand image. Approximation is carried out by linear least-squares fitting in the x variable in [0, 1] in 2000 sample points logarithmically spaced from  $10^{-12}$  to 1. The matrix involved is of dimensions  $2000 \times$ (n + 1) since a column is included to include constant functions in the fitting space as in (2.2). Clean root-exponential convergence is observed for this very nonstandard system of basis functions near a singularity.

As mentioned in section 2, although sigmoidal and other activation functions are important in neural networks and deep learning, the present paper touches only the surface of that discipline. The approximation (2.7) is not composite, but involves only what is conventionally called a single hidden layer. Smooth activation functions have accuracy advantages for single-layer approximation, but in the multilayer setting of deep learning, that advantage diminishes and the simpler nonsmooth function known as ReLU is used more often [25, 37]. We cannot resist mentioning that the universal approximation power of ReLU units was exploited by Henri Lebesgue at age 23 in his first published paper, in which he presented a new proof of the Weierstrass approximation theorem [24].

7. Conclusion. This paper started from a fundamental equivalence:

(\*) The change of variables  $s = \log(x)$  gives an equivalence between smooth approximation for  $s \in [-\infty, 0]$  and approximation with a singularity at x = 0 for  $x \in [0, 1]$ .

Considering this relationship in various contexts has led us to a number of observations and proposals.

1. Rational approximation near singularities and smooth sigmoidal approximation. In the simplest case, (\*) gives an equivalence between rational approximation of  $x^{\alpha}$  and other functions with branch point singularities on [0, 1] and approximation of smooth functions rapidly approaching a constant as  $s \to -\infty$  on  $[-\infty, 0]$  by linear combinations of translates of a smooth sigmoidal function (Figure 1). The literatures of these fields are largely disjoint, and this connection opens up the prospect that techniques used in one area, such as the Hermite contour integral in rational approximation, could be applied to obtain new results in the other.

2. The "tapering" effect in rational approximation is the same as the "p" part of hp-FEM. hp-mesh refinement dates back 40 years, whereas recognition of tapered exponential clustering of poles in rational approximation is recent [42]. We have shown that the mechanisms behind these effects are the same, and that, in particular, each brings a factor-of-2 speedup (in 1D) for the same reason (Figures 1 and 2). This analysis of the source of the factor of 2 reveals that other strategies of hp-FEM should be able to achieve the same optimal asymptotic convergence rate. In particular, instead of regular exponential mesh refinement combined with linearly tapered polynomial order, one could use fixed polynomial order combined with a tapered schedule of exponential refinement.

3. Multiscale separation of scales at a singularity can be interpreted as the Saint-Venant or "crowding" phenomenon of elliptic PDEs (Figure 4). Two points at distances  $10^{-10}$  and  $10^{-5}$  from a corner singularity may seem to be close together, for example, but in fact they are only weakly coupled in the same way as the points  $s = \log(10^{-10}) \approx -23.0$  and  $s = \log(10^{-5}) \approx -11.5$  on the side of an infinite strip of width  $\pi$  (Figure 4).

4. Singularities can be approximated with root-exponential convergence by many different kinds of exponentially clustered RBFs. Sigmoid functions are the archetype, corresponding to poles  $1/(x - x_j)$  of a rational function, but as shown in section 6, other smooth functions of s correspond to other singular functions of x, and the approximation powers are comparable (Figure 5).

5. *DE and generalized Gauss quadrature*. Quadrature of functions with endpoint singularities can exploit the same principles of tapered exponential clustering and insensitivity to the precise nature of a branch point singularity (Figure 3).

Our arguments have been univariate, whereas both approximation and solution of PDEs are also important problems in multiple dimensions. In the case of PDEs, this side of the subject is highly developed, and it would be interesting to see whether results in this area could be transferred to new ideas for multivariate rational or related approximation. Conversely, one approach to the use of rational functions for multivariate approximation is presented in [3].

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