Multilevel Function Approximation (a work-in-progress)

Filippo De Angelis, Mike Giles, Christoph Reisinger

Mathematical Institute, University of Oxford

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Objective

Want to construct an approximation for a scalar function

$$f : [0,1]^d \to \mathbb{R}$$

with parametric dimension d in the range $1-8$, where $f(\theta)$ is one of the following:

- a functional of the solution $u(\theta; x)$ of a PDE, with θ dependence in the PDE coefficients, the boundary data and/or the functional
- a parametric expectation $\mathbb{E}_\omega[g(\theta;\omega)]$, where $g(\theta;\omega)$ is a functional of the solution of an SDE

Problem: in either case we must approximate $f(\theta)$, and the more accurate the approximation, the greater the computational cost.

Objective: for given ε, lowest cost approximation $\widetilde{f}$ with

$$\|\widetilde{f} - f\| < \varepsilon$$

Outline

- quick recap of key literature:
  - dense grid linear interpolation
  - sparse grid linear interpolation
  - convergence of PDEs
  - MLMC for SDEs, MIMC for SPDEs
  - MLMC for parametric integration (Heinrich)
- MLFA for PDEs
  - idea
  - dense grid linear interpolation
  - sparse grid linear interpolation
- MLFA for SDEs – extension of Heinrich's approach
  - randomised MLMC for SDE
  - randomised MLMC and sparse grids
  - MLMC decomposition for SDE
  - MLMC decomposition and sparse grids
- conclusions and references

Dense grid linear interpolation

For a 1-dimensional function, $f : [0,1] \to \mathbb{R}$, if we use a uniform grid $\theta_j = j\, 2^{-\ell},\ j = 0, 1, \ldots, 2^\ell$, then the piecewise linear interpolation of the values $f(\theta_j)$ has an error bound of the form

$$\|\widetilde{f} - f\| < c(f)\, 2^{-r\ell}$$

if $f \in C^r([0,1])$ for $r \in \{1,2\}$.

Using a tensor product grid in higher dimension d, this generalises to

$$\|\widetilde{f} - f\| < c(f)\, 2^{-r\ell}$$

if $f \in C^r([0,1]^d)$, but now the number of evaluation points is $O(2^{d\ell})$ so the expense is much greater

Sparse grid linear interpolation

To avoid that "curse of dimensionality" as d increases, can instead use a Smolyak sparse grid interpolation based on piecewise multi-linear functions in each direction.

This has an error bound of the form

$$\|\widetilde{f} - f\| < c(f)\; 2^{-r\ell}(\ell{+}1)^{d-1}$$

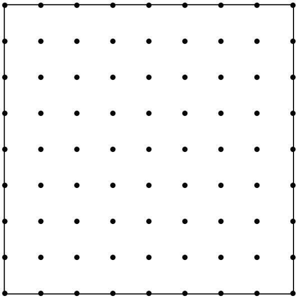
with the number of interpolation points being $O(2^{\ell}(\ell{+}1)^{d-1})$.

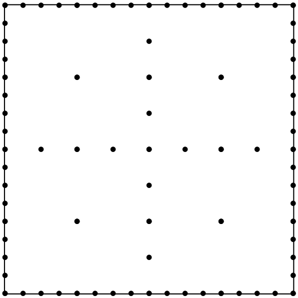
However, it needs more regularity in f, including mixed derivatives of degree up to r in each direction:

$$\frac{\partial^{\alpha_1+\alpha_2+\ldots} f}{\partial\theta_1^{\alpha_1}\;\partial\theta_2^{\alpha_2}\ldots}, \quad 0 \leq \alpha_j \leq r \leq 2.$$

Much better than dense grid interpolation for modest values of d, up to 8?

Dense versus sparse grid interpolation





Convergence of PDEs

If $f_h(\theta)$ is the functional which comes from the approximate solution of a PDE using a discretisation with spacing h, and input θ, then typically

$$\| f_h - f \| = O(h^q)$$

for some q, and the cost of evaluating $f_h(\theta)$ is $O(h^{-p})$ for some p.

Often, but not always, the θ derivatives of f_h will have the same rate of convergence.

MLMC for SDEs

When estimating $\mathbb{E}[P]$, with P a functional of the solution of an SDE, MLMC is based on the telescoping sum

$$\mathbb{E}[\widehat{P}_L] = \sum_{\ell=0}^{L} \mathbb{E}[\Delta \widehat{P}_\ell], \qquad \Delta \widehat{P}_\ell \equiv \widehat{P}_\ell - \widehat{P}_{\ell-1}, \quad \widehat{P}_{-1} \equiv 0$$

where $\widehat{P}_\ell$ represents an approximation to output P on level ℓ using timestep $h_\ell = 2^{-\gamma \ell} h_0$. If there are also constants α, β such that

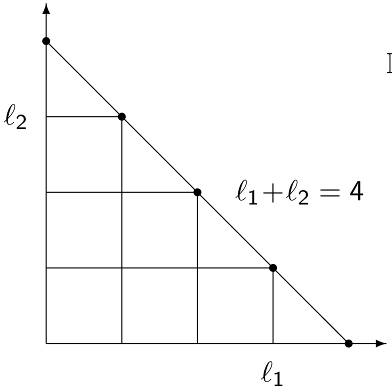
$$\mathbb{E}[\widehat{P}_\ell - P] = O(2^{-\alpha \ell}), \quad \mathbb{V}[\Delta \widehat{P}_\ell] = O(2^{-\beta \ell})$$

then the MLMC method chooses a near-optimal number of levels L, and number of samples $M_\ell, \ell = 0, 1, \ldots, L$ to obtain a r.m.s. accuracy of ε at a cost of order

$$\begin{array}{ll} \varepsilon^{-2}, & \beta > \gamma \\ \varepsilon^{-2} |\log \varepsilon|^2, & \beta = \gamma \\ \varepsilon^{-2-(\gamma-\beta)/\alpha}, & \beta < \gamma \end{array}$$

MIMC for SPDEs

Haji-Ali, Nobile & Tempone developed an important extension, MIMC (Multi-Index Monte Carlo), incorporating sparse grid ideas to separately refine multiple parameters.



$$\mathbb{E}[P] \approx \sum_{\ell_1+\ell_2\leq \ell} \mathbb{E}[\Delta_{\ell_1}\Delta_{\ell_2}\widehat{P}_\ell]$$

This increases the range of applications with $O(\varepsilon^{-2})$ complexity.

Randomised MLMC for SDEs

In another important extension, in the "good" MLMC case, $\beta > \gamma$, Rhee & Glynn developed the randomised MLMC estimator

$$p_L^{-1} \Delta \widehat{P}_L$$

where L is a random level, with $L = \ell$ with probability $p_\ell \propto 2^{-(\beta+\gamma)\ell/2}$.

Since

$$\begin{aligned} \mathbb{E}[p_L^{-1} \Delta \widehat{P}_L] &= \sum_{\ell=0}^{\infty} \mathbb{P}[L=\ell]\, \mathbb{E}\left[p_L^{-1} \Delta \widehat{P}_L \mid L = \ell \right] \\ &= \sum_{\ell=0}^{\infty} p_\ell\, \mathbb{E}\left[p_\ell^{-1} \Delta \widehat{P}_\ell \right] = \sum_{\ell=0}^{\infty} \mathbb{E}[\Delta \widehat{P}_\ell] = \mathbb{E}[P] \end{aligned}$$

it is an unbiased estimator, and it can be proved that the variance and expected cost are both finite if $\beta > \gamma$.

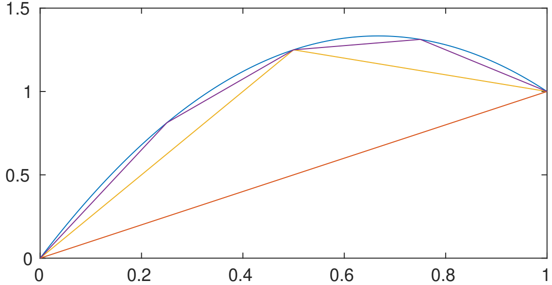
MLMC for parametric integration

Stefan Heinrich's original MLMC research concerned the approximation of $f(\theta) = \mathbb{E}[g(\theta;\omega)]$, given exact sampling of $g(\theta;\omega)$ at unit cost.

In his formulation, the MLMC telescoping sum is

$$f \approx I_L[f] = I_0[f] + \sum_{\ell=1}^{L} I_\ell[f] - I_{\ell-1}[f]$$

where $I_\ell[f]$ represents a level ℓ interpolation.



MLMC for parametric integration

Heinrich then approximates $(I_\ell - I_{\ell-1})[f]$ through Monte Carlo sampling at required values of θ:

$$(I_\ell - I_{\ell-1})[f] \approx \frac{1}{M_\ell} \sum_{m=1}^{M_\ell} (I_\ell - I_{\ell-1})[g(\,\cdot\,; \omega^{\ell,m})]$$

As $\ell \to \infty$, $(I_\ell - I_{\ell-1})[f] \to 0$ and $\mathbb{V}\left[\,(I_\ell - I_{\ell-1})[g]\,\right] \to 0$, so fewer MC samples needed on finer levels.

Analysis assumes the number of θ points increases exponentially with dimension (as with dense tensor product grid), so the resulting complexity for linear interpolation is of order

$$\begin{array}{rl} \varepsilon^{-2}, & d < 2r \\ \varepsilon^{-2}\,|\log \varepsilon|^2, & d = 2r \\ \varepsilon^{-d/r}, & d > 2r \end{array}$$

assuming $g(\theta;\omega)$ is sufficiently smooth w.r.t. θ

MLMC for parametric integration

Heinrich's work is the key starting point for our current work which extends it in several directions:

- PDEs with appropriate numerical approximation
- sparse grid interpolation to address curse of dimensionality
- weaker assumptions on smoothness of $g(\theta;\omega)$
- numerical approximation of $f(\theta) \equiv \mathbb{E}[g(\theta;\omega)]$ in cases without a finite variance, finite expected cost unbiased estimator

The PDE aspect also follows the outline in the excellent review article

"Smolyak's algorithm: a powerful black box for the acceleration of scientific computations", by Tempone & Wolfers

which presents a unifying framework and meta-analysis which includes multilevel methods.

MLFA for PDEs

The fundamental idea is very simple: building on Stefan Heinrich's approach, if the function f has an interpolation expansion

$$f \;=\; I_0[f] + \sum_{\ell=1}^{\infty} I_\ell[f] - I_{\ell-1}[f] \;=\; \sum_{\ell=0}^{\infty} \Delta I_\ell[f]$$

with $\Delta I_\ell \equiv I_\ell - I_{\ell-1}$, $I_{-1} \equiv 0$, and as $\ell \to \infty$, $\Delta I_\ell[f] \to 0$ and the cost per evaluation increases, then we will use an approximation

$$\widetilde{f} = \sum_{\ell=0}^{L} \Delta I_\ell[f_\ell]$$

where f_ℓ is based on a PDE approximation with grid spacing h_ℓ and

- h_ℓ is small for small ℓ – a few expensive accurate PDE calculations
- h_ℓ is large for large ℓ – lots of cheap PDE calculations

MLFA for PDEs

It follows from the triangle inequality that

$$\| \widetilde{f} - f \| \leq \| (I_L - I)[f] \| + \sum_{\ell=0}^{L} \| (I_\ell - I_{\ell-1})[f_\ell - f] \| .$$

If we assume second order accuracy in the interpolation so that

$$\| (I_L - I)[f] \| < c_1 \, 2^{-2L}, \qquad \| \Delta I_\ell [f_\ell - f] \| < c_2 \, 2^{-2\ell} h_\ell^q$$

and the cost C_ℓ of constructing $(I_\ell - I_{\ell-1})[f_\ell]$ on level ℓ is bounded by

$$C_\ell < c_3 \, 2^{d\ell} h_\ell^{-p}$$

then to achieve an accuracy of ε we can choose L s.t.

$$c_1 \, 2^{-2L} \approx \varepsilon / 2 \quad \Longrightarrow \quad L = O(|\log \varepsilon|)$$

and ...

MLFA for PDEs

... choose h_ℓ to minimise

$$c_3 \sum_{\ell=0}^{L} 2^{d\ell} h_\ell^{-p}$$

subject to the requirement that

$$c_2 \sum_{\ell=0}^{L} 2^{-2\ell} h_\ell^{q} \approx \varepsilon/2.$$

Using a Lagrange multiplier gives the optimal h_ℓ as

$$h_\ell = 2^{(d+2)\ell/(p+q)}\, h_0$$

The accuracy requirement then becomes

$$c_2\, h_0^q \sum_{\ell=0}^{L} 2^{-\nu\ell} \approx \varepsilon/2, \quad \nu \equiv (2p{-}dq)/(d{+}2)$$

MLFA for PDEs

$\nu > 0$ leads to $h_0 = O(\varepsilon^{1/q})$ and a total cost of $O(\varepsilon^{-p/q})$,

$\nu = 0$ leads to $h_0 = O(\varepsilon^{-1/q} L^{1/q})$ and a cost of $O(\varepsilon^{-p/q} |\log \varepsilon|^{1+p/q})$.

$\nu < 0$ leads to $h_0 = O(\varepsilon^{-1/q} 2^{\nu L/q})$ and a cost of $O(\varepsilon^{-d/2})$.

Thus the total cost is of order

$$\begin{array}{cl} \varepsilon^{-p/q}, & p/q > d/2 \\ \varepsilon^{-p/q} \, |\log \varepsilon|^{1+p/q}, & p/q = d/2 \\ \varepsilon^{-d/2}, & p/q < d/2 \end{array}$$

Note:

- $O(\varepsilon^{-p/q})$ is the cost of a single ε-accurate PDE calculation
- $O(\varepsilon^{-d/2})$ is the cost of an ε-accurate interpolation of unit cost data

In this sense the method has near-optimal asymptotic efficiency

MLFA for PDEs with sparse interpolation

With sparse interpolation the accuracy requirement becomes

$$c_2 \sum_{\ell=0}^{L} 2^{-2\ell} (\ell+1)^{d-1} h_\ell^q \;\approx\; \varepsilon/2.$$

and the cost bound becomes

$$C = c_3 \sum_{\ell=0}^{L} 2^{\ell} (\ell+1)^{d-1} h_\ell^{-p}$$

Optimising this results in the total cost being of order

$$\begin{array}{rl} \varepsilon^{-p/q}, & p/q > 1/2 \\ \varepsilon^{-p/q}\,|\log\varepsilon|^{3d/2}, & p/q = 1/2 \\ \varepsilon^{-1/2}\,|\log\varepsilon|^{3(d-1)/2}, & p/q < 1/2 \end{array}$$

Note:

- $O(\varepsilon^{-p/q})$ is again the cost of a single ε-accurate PDE calculation
- $O(\varepsilon^{-1/2}\,|\log\varepsilon|^{3(d-1)/2})$ is the cost of an ε-accurate sparse interpolation of unit cost data

MLFA for SDEs

If $\beta > \gamma$ in the standard SDE discretisation sense, then randomised MLMC can be used to give an unbiased estimator Y, with $\mathbb{E}[Y(\theta;\omega)] = f(\theta)$ and finite variance and expected cost. If

$$\begin{aligned} \| (I_\ell - I)\,[f]\,\| &< c_1\, 2^{-r\ell} \\ \mathbb{V}\,[(I_\ell - I_{\ell-1})\,[Y]\,] &< c_2\, 2^{-s\ell} \end{aligned}$$

and the total expected cost is bounded by $c_3 \sum_0^L 2^{d\ell} M_\ell$, for M_ℓ samples per level, then ε r.m.s. accuracy can be achieved with cost of order

$$\begin{array}{ll} \varepsilon^{-2}, & s > d \\ \varepsilon^{-2} |\log \varepsilon|^2, & s = d \\ \varepsilon^{-2-(d-s)/r}, & s < d \end{array}$$

MLFA for SDEs

The previous result is a slight generalisation of Heinrich's analysis which assumed $s = 2r$.

With sparse interpolation, the cost is reduced to order

$$\begin{cases} \varepsilon^{-2}, & s > 1 \\ \varepsilon^{-2} |\log \varepsilon|^{2+3(d-1)}, & s = 1 \\ \varepsilon^{-2-(1-s)/r} |\log \varepsilon|^{(3+(1-s)/r)(d-1)}, & s < 1 \end{cases}$$

MLFA for SDEs

If $\beta \leq \gamma$, then we can use a MIMC combination of path-based MLMC and Heinrich's MLMC. The starting point is the interpolation decomposition:

$$f \approx \sum_{\ell=0}^{L} (I_\ell - I_{\ell-1})[f], \qquad I_{-1}[f] \equiv 0,$$

where I_ℓ uses a dense interpolation with spacing proprtional to $2^{-\ell}$.

We then replace f with a timestep approximation expansion

$$f \approx \sum_{\ell=0}^{L} \sum_{\ell'=0}^{L'_\ell} \Delta I_\ell[\Delta f_{\ell'}], \qquad \Delta I_\ell[\Delta f_{\ell'}] \equiv (I_\ell - I_{\ell-1})[f_{\ell'} - f_{\ell'-1}]$$

in which L'_ℓ is a decreasing function of ℓ, since $\Delta I_\ell[f]$ becomes smaller as ℓ increases and so less relative accuracy is required in its approximation.

MLFA for SDEs

The final step is to replace $\Delta I_\ell[\Delta f_{\ell'}]$ by a Monte Carlo estimate, giving the MIMC-style estimator

$$\widetilde{f} = \sum_{\ell=0}^{L} \sum_{\ell'=0}^{L'_\ell} \left(\frac{1}{M_{\ell,\ell'}} \sum_{m=1}^{M_{\ell,\ell'}} \Delta I_\ell[\Delta g_{\ell'}(\cdot;\omega^{\ell,\ell',m})] \right)$$

We now need to choose $L, L'_\ell, M_{\ell,\ell'}$ to achieve the desired accuracy at the minimum cost.

$$\begin{aligned} \mathbb{E}[\widetilde{f}-f] &= (I_L - I)[f] + \sum_{\ell=0}^{L} (I_\ell - I_{\ell-1})[f_{L'(\ell)} - f] \\ \Longrightarrow \quad \left\| \mathbb{E}[\widetilde{f}-f] \right\| &\leq \|(I_L - I)[f]\| + \sum_{\ell=0}^{L} \|(I_\ell - I_{\ell-1})[f_{L'(\ell)} - f]\| \end{aligned}$$

and

$$\mathbb{V}[\widetilde{f}] = \sum_{\ell=0}^{L} \sum_{\ell'=0}^{L'_\ell} \left(\frac{1}{M_{\ell,\ell'}} \mathbb{V}\left[\Delta I_\ell[\Delta g_{\ell'}(\cdot;\omega)]\right] \right)$$

MLFA for SDEs

If we have

$$\|\Delta I_\ell[\Delta f_{\ell'}]\| \quad < \quad c_1\, 2^{-r\ell-\alpha\ell'}$$

$$\mathbb{V}\,[\Delta I_\ell[\Delta g_{\ell'}]] \quad < \quad c_2\, 2^{-s\ell-\beta\ell'}$$

and the total cost is bounded by

$$c_3 \sum_{\ell=0}^{L} \sum_{\ell'=0}^{L'_\ell} 2^{d\ell+\gamma\ell'} M_{\ell,\ell},$$

then ε RMS accuracy can be achieved at a computational cost of order

$$\begin{array}{ll} \varepsilon^{-2}, & \eta < 0 \\ \varepsilon^{-2-\eta}\,|\log \varepsilon|^p, & \eta \geq 0 \end{array}$$

for some p (see MIMC analysis by [HNT16]), where

$$\eta = \max\left(\frac{\gamma-\beta}{\alpha}, \frac{d-s}{r}\right).$$

MLFA for SDEs

Note: in the best case when $\eta < 0$, the dominant contribution to the total cost comes from the base level $\ell = \ell' = 0$, which is why there are no log terms in its complexity.

With sparse interpolation the corresponding cost is of order

$$\begin{array}{ll} \varepsilon^{-2}, & \eta < 0 \\ \varepsilon^{-2-\eta}\, |\log \varepsilon|^q, & \eta \geq 0 \end{array}$$

for some q, where now

$$\eta = \max\left(\frac{\gamma - \beta}{\alpha}, \frac{1-s}{r} \right).$$

Conclusions and future work

Conclusions:

- excellent asymptotic efficiency in approximating parametric functions arising from PDEs and SDEs – nearly optimal in some cases
- meta-theorems make various assumptions which need to be verified, especially for mixed derivatives when using sparse grid interpolation

On-going work:

- numerical results
- numerical analysis of PDEs to prove validity of mixed derivative assumptions in specific cases (building on prior research within the sparse grid community)
- numerical analysis of SDEs to prove validity of mixed derivative assumptions in specific cases (building on prior analysis by Giles and Sheridan-Methven)

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